# Parallel Optimization for Simulation Data Based on "DASK"

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MACSS Project Proposal

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Github: https://github.com/Otamio/DASKopt

## Introduction

Why do we need parallel computing?

Why choose to parallel optimization based on "DASK"?

- Are there any needs to improve the "DASK" Module?
- Goal: Improve parallel performance for large scale simulation data by balancing and optimizing the "DASK" scheduler

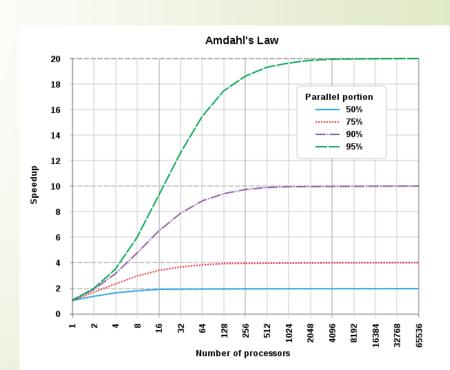
INTRO THEORY METHODS CONCLUSION

# Basic Theory of Parallel Computing

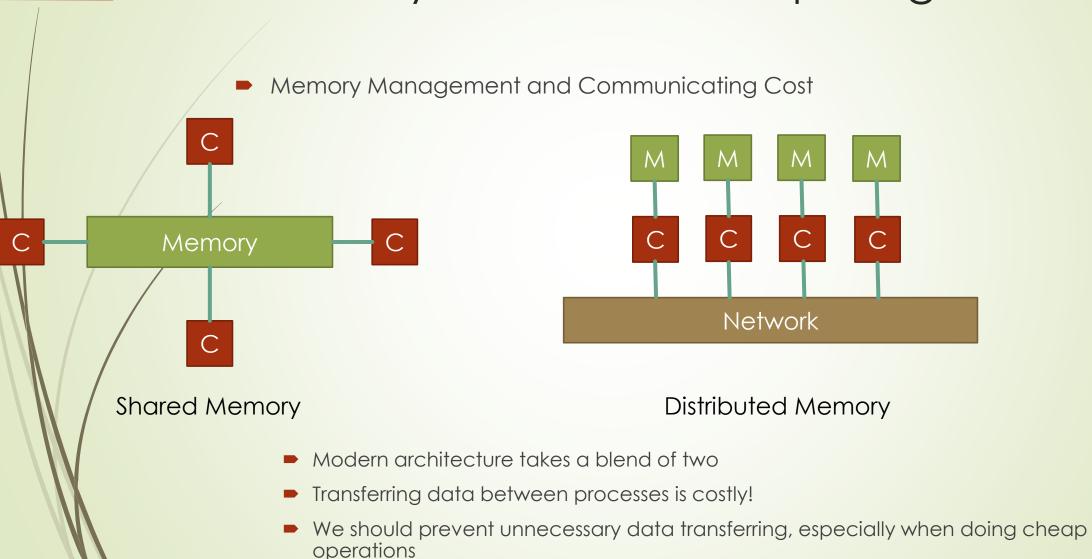
Amdahl's Law?

$$S_{ ext{latency}}(s) = rac{1}{1-p+rac{p}{s}}$$

- p: Execution time of parallelizable part
- s: Speed up of the parallelized part
- S: Speed up of the whole part
- ► Let p=.8, s=4, we would have S=2.5
- $\blacksquare$  Let p=0.9, s =16, we would have S=6.4
- Normally, S would reach a ceiling of 20x



# Basic Theory of Parallel Computing



- Scheduler: The work needs to be serialized and distributed to different processes before they are executed
- DASK Scheduler is a graph
  - E.g.

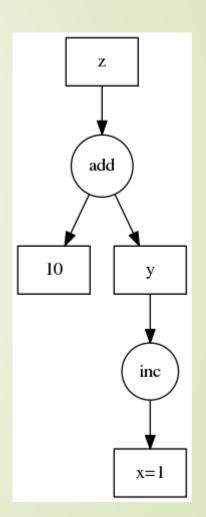
```
def inc(i):
    return i + 1

def add(a, b):
    return a + b

x = 1
y = inc(x)
z = add(y, 10)
```

Which is encoded as a Python Dictionary:

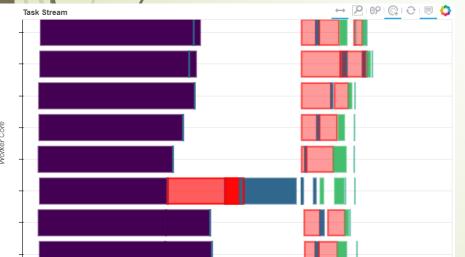
```
d = {'x': 1,
    'y': (inc, 'x'),
    'z': (add, 'y', 10)}
```



- Some Issues with the default "DASK" Scheduler
  - Python GIL (Global Interpreter Lock)
    - A "Pain" of CPython when computing with Python data structures
    - Consider the following code:

```
a = da.random.random(size=(10000, 1000), chunks=(1000, 1000))
q, r = da.linalg.qr(a)
a2 = q.dot(r)
```

out = a2.compute()



- We have the following performance analysis:
  - Purple: da.random.random()
  - Red: Transferring Cost
  - Blue: da.linalg.qr()
  - Green: da.array.dot()

- Data Simulation: Get annual income 40 years later
  - Compare "DASK" and numpy. Which is faster? (Use %time callable)

```
def simulation_dask(init, years):
    y = da.from_array(np.log(init), chunks=(1000000, 1))
    for i in range(years+1):
        n_{errors} = da.random.normal(0, 0.1, size=(1000000,1), chunks=(1000000, 1))
        y = (1 - 0.2) * (np.log(init) + 0.03 * i) + 0.2 * y + n errors
    y = da.exp(y)
    return y
def simulation_numpy(init, years):
    y = np.full((1000000, 1), np.log(init))
    for i in range(years+1):
        n = np.random.normal(0, 0.1, (1000000, 1))
        y = (1 - 0.2) * (np.log(init) + 0.03 * i) + 0.2 * y + n_errors
    y = np.exp(y)
    return y
```

```
Result:
    %time simulation_numpy(80000, 40).mean()
    Wall time: 3.03 s
    264957.69206603663
                                  Reasons?
                                    Dependency
def simulation_dask(init, years):
  y = da.from_array(np.log(init), chunks=(1000000, 1))
   for i in range(years+1):
     n_errors = da.random.normal(0, 0.1, size=(1000000,1), chunks=(1000000, 1))
      y = (1 - 0.2) * (np.log(init) + 0.03 * i) + 0.2 * y + n errors
  y = da.exp(y)
   return y
```

```
%time simulation_dask(80000, 40).mean().compute()
Wall time: 5.23 s
264970.07779333438
```



# Methods: Graph Optimization

- Some possible solutions:
  - Reduce Dependency (Avoid recursion and iteration).
  - Fuse

print\_and\_return

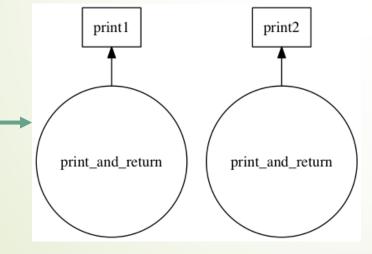
format

print\_and\_return

out2

format

count2



Advanced: User defined graph (using dictionaries)

from dask.optimization import fuse
dsk4, dependencies = fuse(dsk3)
results = get(dsk4, outputs)

## Conclusion

- Research Question: Improve DASK's efficiency for large scale data analysis in simulation research
  - Most emphasis will be placed on optimizing the DASK scheduler
- Schedule:
  - A mini Python project to be completed reducing the data transferring costs between processes
  - A project (mostly Python) to deal with schedulers, dependencies, GIL, and possibly, code rewrite and compilers
- References:
  - http://dask.pydata.org/en/latest/docs.html
- Slides and some example codes will be posted on https://github.com/Otamio/DASKopt
- Thanks for your attention!