The Swarm at the Edge of the Cloud

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Presented by: Andrew Nguyen

Sensory Swarm

- Wirelessly interconnected and interact with the cyber-cloud
- Necessary is a three level model:
 - cloudbackbone
 - personal devices
 - swarm devices
- Something along the lines of an "app" is needed

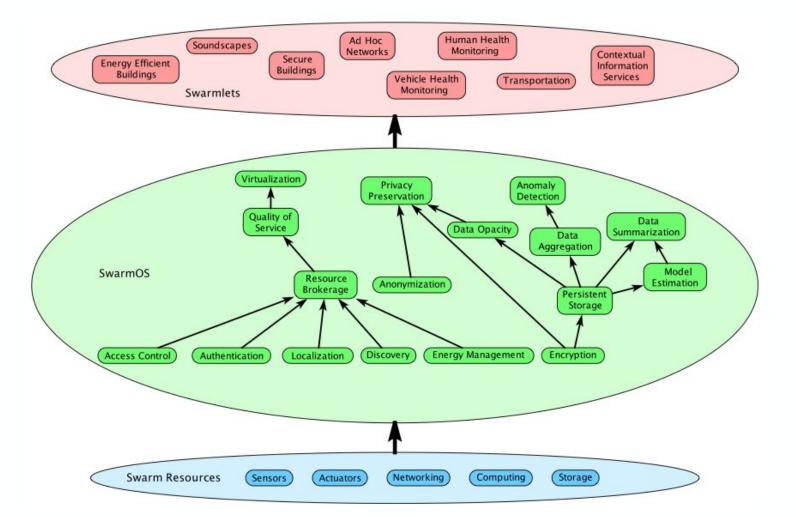


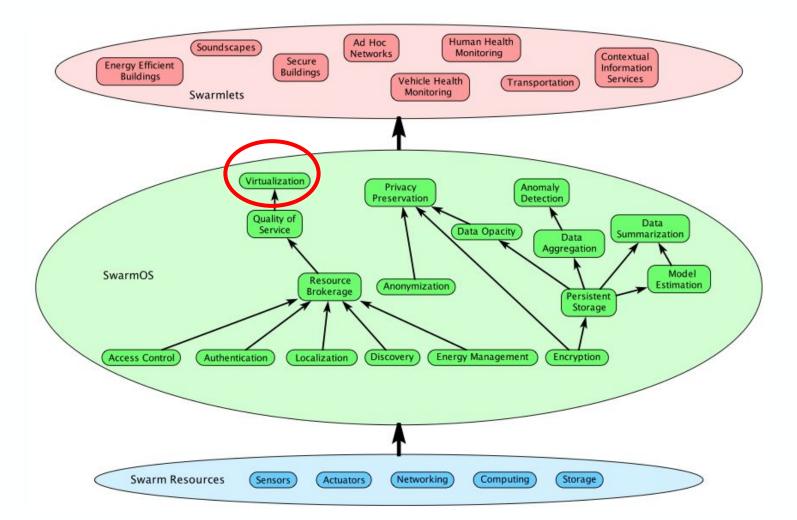
Terraswarm

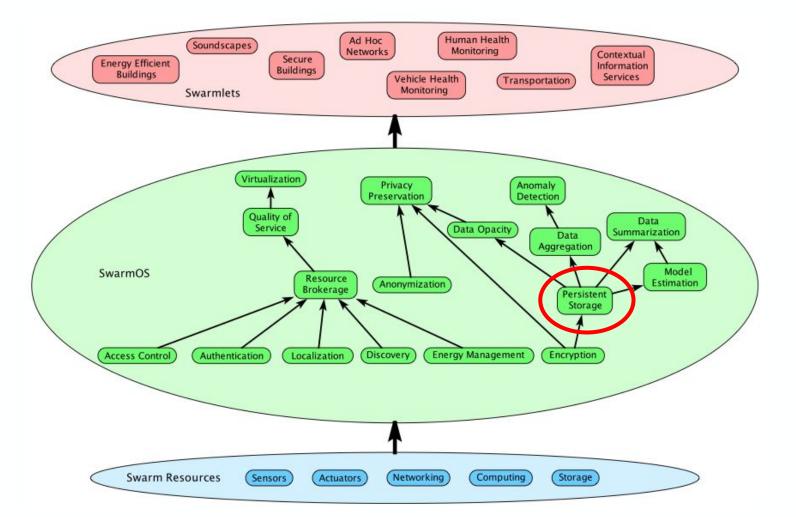
- Terraswarm: encompassing trillions of sensors and actuators deployed across the earth
 - Dynamically recruit resources
 - Aggregate and use that info
 - Dynamically recruit actuation resources
- Deploy readily and rapidly

SwarmOS

- "SwarmOS" highly distributed infrastructure that touches every node in the system
 - Efficiently allocate resources based on complex optimization strategies
 - Allows continual reconfiguration of applications







SwarmBox Hardware

Applications

Swarm Services

SwarmOS Essential Services

Global Data Plane

COTS System Software

SwarmBox Hardware



- · Fanless Industrial Computer
- Intel 5th Generation i5 Processor
- · IEEE 1588 Ethernet port(s)
- · BLE and WiFi
- · 8GB DRAM
- · 64GB SSD or 1 TB disk drive
- USB

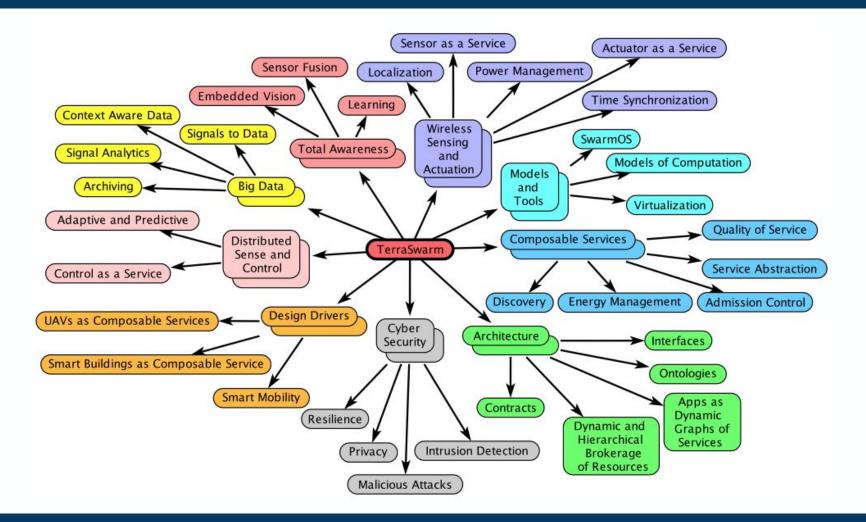
 $\underline{https://swarmlab.berkeley.edu/research/industrial-cyber-physical-systems/global-data-plane/swarm-box}$

Terraswarm Challenges

- Large-scale
- Distributed
- Cyber-physical
- Dynamic
- Adaptive
- Heterogeneous

Solutions

- Data doesn't need to be communicated or stored if it can be predicted from models
 - o if its learned, terraswarm can be self sufficient and monitor other devices
- Privacy may be easier to preserve with more data than with less
 - <u>Differential privacy</u>

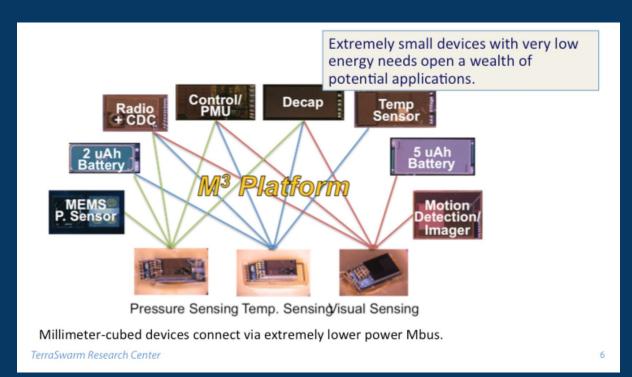


Problem Definition

How can data be efficiently accessed and stored along <u>without</u> compromising costs, privacy, & accuracy?

System Design

- design and run time are blurred
- non-interface properties are key
 - i.e node joins or leaves it doesn't interrupt a service



Platform Architecture & Operating Systems

- Service-oriented architecture (SOA)
 - Loose coupling
 - Service abstraction
 - Discoverability
 - Composability
- Virtualization of computing resources is not in conflict with time sensitive and real time services
 - Simulation models will be needed to integrate with deployed systems to adapt in times of stress

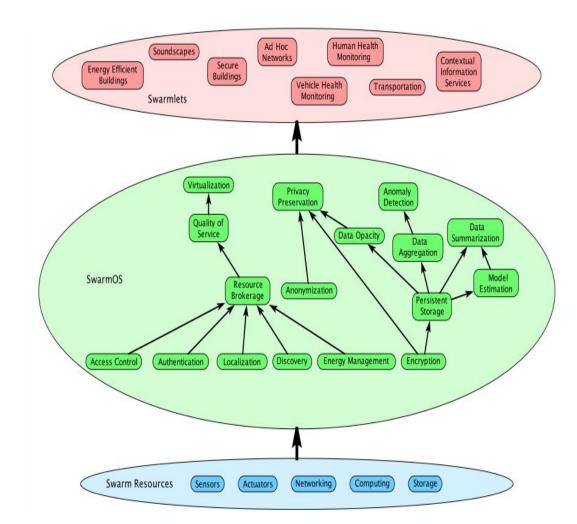
Evaluation: Terraswarm Models

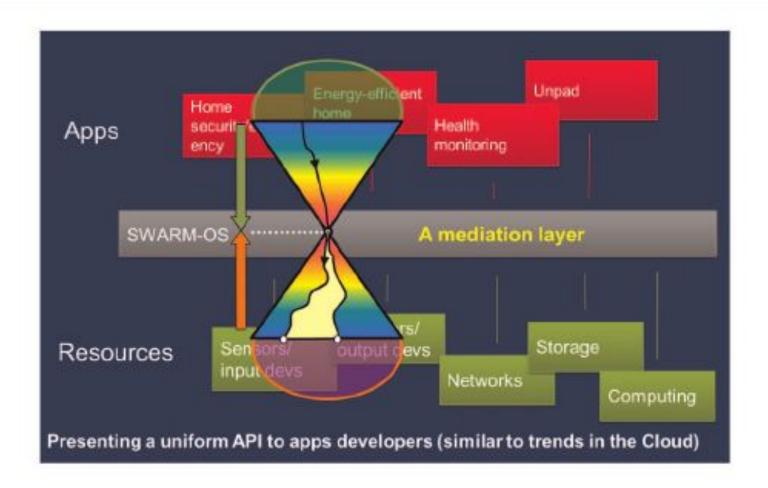
Terraswarm models are designed in hierarchical graphs of components

The edges represent:

- 1. Communication paths between components
- 2. Authority relations between components
- 3. Use relationships (i.e., service x uses service y)
- 4. Ownership relations
- 5. Coordination
- 6. Controllability
- 7. Observability

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Critique

- There should be more info on the specifics of how the devices would function
- It seems up in the air and a lot of hypothesis and assumptions
 - The backbone of the entire paper
- There has been not a lot of recent research to provide more information and progress
- The lack of discussing potential risks is somewhat concerning

Conclusion

- Terraswarm introduces a concept that brings wireless sensor networks to the next level
- Ambitious concept with general high level ideas and thought out components of
 - Privacy
 - Storage
 - User Interactions
- Dynamic change in daily cloud based operations

Discussion

- What is the incentive for IoT device makers to join this?
- If there are two nodes providing conflicting information, how does it choose which one to believe?
- Can we adapt other existing IoT abstractions to work with the swarm concept? For example, how does edge computing fit into all of this?
- How will the swarmOS be able to interface with all the types of embedded devices and cloud providers in order to have a unique platform? Are they expecting everyone to accept and migrate to their solution?