

b) lead olerer Jettrong -> Test tet uped deter of divided into some set of equipment input dete. If is used that of one from a set is OK, then all of that let shifting the enteria. If one is giving eror, then all of that portition will give error. Thuse very one condition from each pratition is retudly tested. fuch form I I to some mails -· Trut let foot from an -Briefs · methodolog-Sets -> - delingthe: Dite) Current student 9) Previous Student 11) Dupt head poor IN) Other teathers y st staff M) BITS Admin member

spot is for all, the login credentials et and check whether they can login and perform their tasks.

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c) Detect rate > number of detects in a project.

Detect density > brivoverage value of detects in a unit of code length or size is of whom the checklists are a voy to maintain that all exertical compensates are furtional and every requirement is softistical.

Original as the hordest eners to find as the force is not something, how can we find?

Ochecklists are helpful in remarking armission emory, that means the day out whether everything is included or not.

220) State Teldern, IBehovour of the Merface of the others one the doller that will also implement this interface.

public statece l'Behoniourd palie und action (Robot r. Portion p. Boolem obstable) Jubbe eles Aggretive implements Behaviour public void action (Pobot &, Position p, Booken obstacle) & 6 System. out, printle (r. get Nomel) + " is attacking)) public elys Defonsible implements IBehaviour 20 dets (010 public void action (Robot r, Porition P. Booker ohs)? Silv if (obs = = true) \ . It of what jet hoursign ! system. out, printle r. getreme ()+ " ransing mon

publicative Normal inflements Metadour 2 mg public mid cotion (Robot to Parties po Baston 10hp) 1

Tobe - tour) 2 11 do rolling Systim, and proble (tragetheret) of the olege dolm): cler Robot 5 privete story name;
private JBehaviour by mistralby Robot (Stay or Abotomor b) ALT: rome = 75 private public vora set stote (I belower b) { HA. b = b'

public along Derro James probe Actic void men (stong [] rigg) of Robot rt = new Robot ("Big Robot", new Aggrosine()): Robot (82 = new Robot ("George v. Q. 1"); Robot r3 = nen Pohot (npom); 18 Lovour a 2 new Aggressive (); a. do Action (of, (2,3), True);

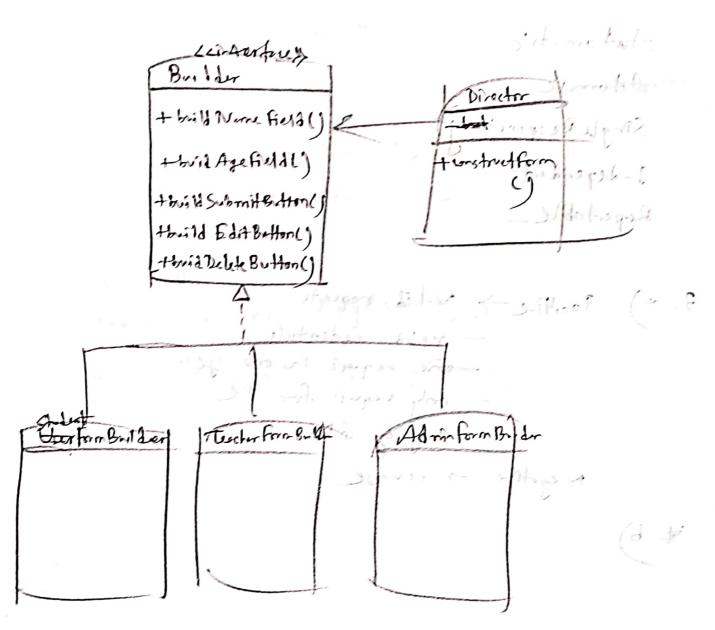
2. B Sha - Trougher... Automotic Atomic Man Single langer whiley J-degerdent Repetoble Positie > Volid requests - volis crodentuls - one regult in one year - only request for PC - only by GM regettre - reverse

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The order Administrator arranging obey.



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In Tucker Form, Det delet Button step ull ke blank.
In orden Admir Form , everytting olog.

c) Coherron of Comments among internal components Coupling of Connection among different dollers We want high wherion, low coupling

software I hardware und work properly when they are integrated into a longe system. That means it was fests the correlation among different units Belo testing to the providing some wears a advance partion of full tree wession of the product to first out stows. Users report bugs as they wish about a specific formal. It is low cost.

Violating testing to testing how well to user an learn to use the interface.

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posite due Bird t publical figilit Aggregation - To Frant Confortion or sufferely more of talk drowing Video Retal Store Castoria Tentral Trence Flack But Corem