In [1]:
```python
import matplotlib
import matplotlib.pyplot as plt
import cvxopt
```

Question 1

In [2]:
```python
# -*- coding: utf-8 -*-

import numpy as np

#%%
#########################################################
######## X-MAC: Trade_off Energy with Delay using GT
#########################################################
# Radio subsystem varaible definition

P     = 32.             # Payload [byte]
R     = 31.25           # CC2420 Radio Rate [kbyte/s = Byte/ms]
D     = 8               # number of levels
C     = 5               # neighbors size (connectivity)
N     = C*(D^2)          # number of nodes
#### BE CAREFUL:  Times are in milliseconds (ms)
Lmax  = 5000.           # Maximal allowed Delay (ms)
Emax  = 1.             # MAximal Energy Budjet (J)

L_pbl = 4.              # preamble length [byte]
L_hdr = 9. + L_pbl      # header length [byte]
L_ack = 9. + L_pbl      # ACK length [byte]
L_ps  = 5. + L_pbl      # preamble strobe length [byte]

Tal  = 0.95             # ack listen period [ms]
Thdr = L_hdr/R          # header transmission duration [ms]
Tack = L_ack/R          # ACK transmission duration [ms]
Tps  = L_ps/R           # preamble strobe transmission duration [ms]
Tcw  = 15*0.62          # Contention window size [ms]
Tcs  = 2.60             # Time [ms] to turn the radio into TX and probe the channel (carrier sense)
Tdata = Thdr + P/R + Tack # data packet transmission duration [ms]

### Sampling frequency
Fs   = 1.0/(60*30*1000)    # e.g. Min traffic rate 1 pkt/half_hour = 1/(60*30*1000) pk/ms

# Sleep period: Parameter Bounds
Tw_max  = 500.       # Maximum Duration of Tw in ms
Tw_min  = 100.       # Minimum Duration of Tw in ms
```

1-1 Finding the values of alpha1, alpha2 and alpha 3 for 1pckt/5min

We need to find the values of the frequencies

In [14]:
```python
### Sampling frequency
Fs   = 1.0/(60*5*1000)    # e.g. Min traffic rate 1 pkt/ 5 min
```

In [15]:
```python
d=1 #to eliminate the max in the equation
Fout=Fs*(((D**2)-(d**2)+(2*d-1))/(2*d-1)) #Node’s Output Traffic Frequency at level d
Fi=Fs*((D^2)-(d^2))/(2*d-1) #Node’s Input Traffic Frequency at level d
I= (2*d+1)/(2*d-1)
Fb=(C-I)*Fout
```

In [16]:
```python
alpha1= Tcs+Tal+1.5*Tps*(((Tps+Tal)/2)+Tack+Tdata)*Fb
alpha1
```

Out[16]: 3.55053286912

In [17]:
```python
alpha2=Fout/2
alpha2
```

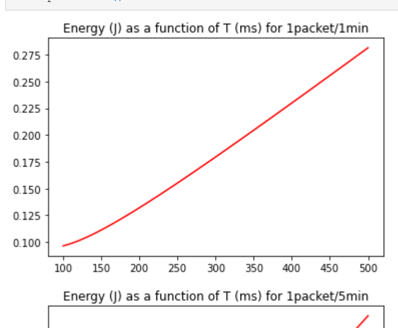
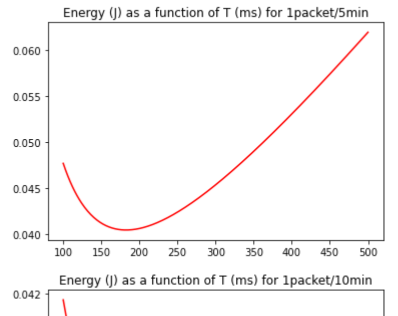
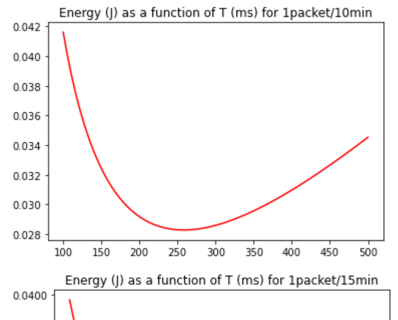
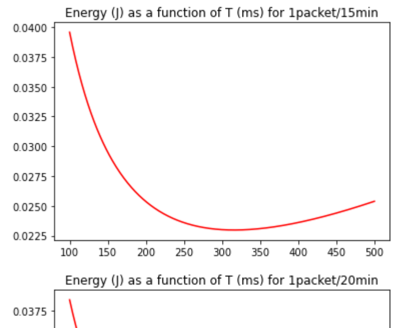
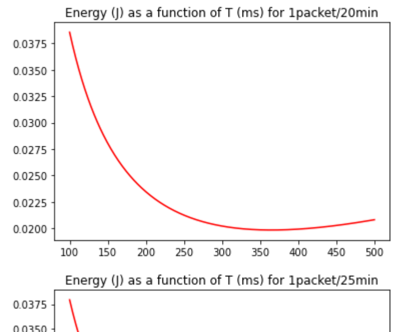
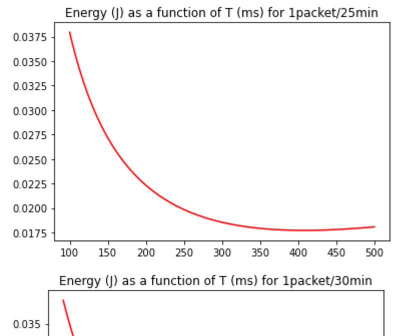
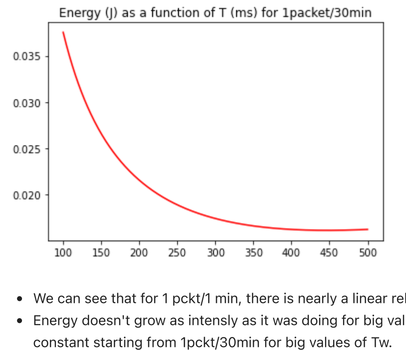
Out[17]: 0.00010666666666666667

In [18]:
```python
a1=(0.5*(Tps+Tal)+Tcs+Tal+Tack+Tdata)*Fout
a2=((1.5*Tps+Tack+Tdata)*Fi)+(0.75*Tps*Fb)
alpha3=a1+a2
alpha3
```

Out[18]: 0.0015293333333333335

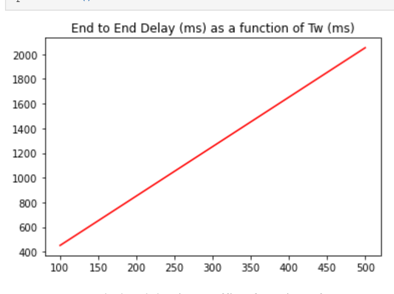
1-2 Plotting Energy as a function of T for different pckt/min rates :

In [19]:
```python
for x in [1,5,10,15,20,25,30]:
    Fs    = 1.0/(60*x*1000)
    d=1 #to eliminate the max in the equation
    Fout=Fs*(((D**2)-(d**2)+(2*d-1))/(2*d-1)) #Node’s Output Traffic Frequency at level d
    Fi=Fs*((D^2)-(d^2))/(2*d-1) #Node’s Input Traffic Frequency at level d
    I= (2*d+1)/(2*d-1)
    Fb=(C-I)*Fout
    alpha1= Tcs+Tal+1.5*Tps*(((Tps+Tal)/2)+Tack+Tdata)*Fb
    alpha2=Fout/2
    alpha3=(0.5*(Tps+Tal)+Tcs+Tal+Tack+Tdata)*Fout+((1.5*Tps+Tack+Tdata)*Fi)+(0.75*Tps*Fb)


    # 400 linearly spaced numbers
    Tw = np.linspace(100,500,400)

    # The function that we want to plot
    E=(alpha1/Tw)+alpha2*Tw+alpha3

    # setting the axes at the centre
    fig = plt.figure()

    # plot the function
    plt.plot(Tw,E, 'r')

    plt.title("Energy (J) as a function of T (ms) for 1packet/"+str(x)+"min")

    # show the plot
    plt.show()
```

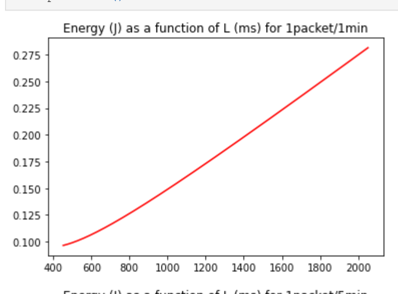
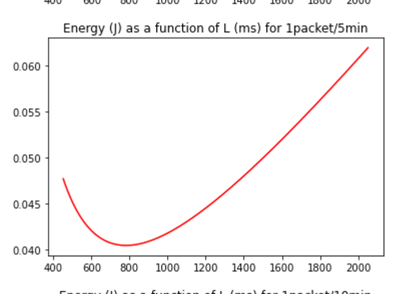
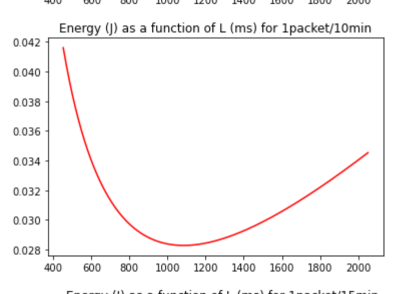
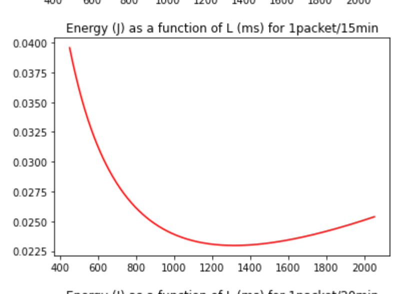
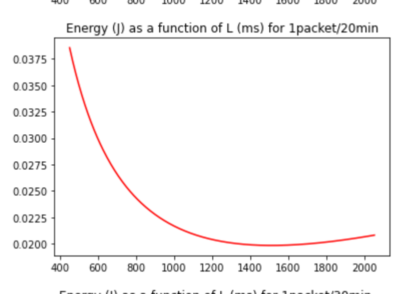
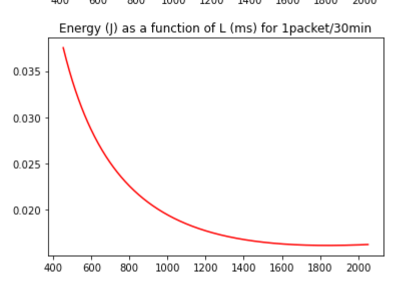








1-3 Finding the values of betal and beta 2

1-4 Plotting End to End Delay (ms) as a function of Tw (ms)

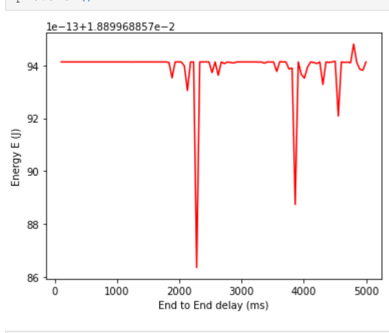


1-5 Plotting the curve E-L for different pckt/min rates

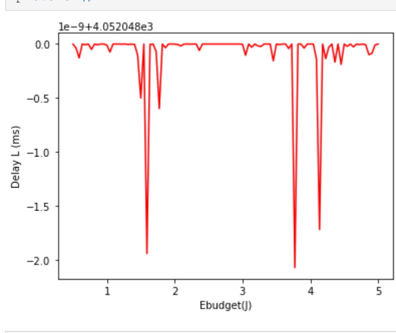
Question 2

2-1 Optimal energy for several values of L



2-2 Optimal values of L for several values of Ebudget

```python
fig.subplots_adjust(top=2)
ax1 = fig.add_subplot(211)
ax1.set_ylabel('Delay L (ms)')
ax1.set_xlabel('Ebudget(J)')
plt.plot(E_budget,minimums_2, 'r')
plt.show()
```



In [36]:
```python
L_best=np.amin(minimums_2);L_best
```

Out[36]: 4052.0479999979316

In [37]:
```python
L_average=np.average(minimums_2);L_average
```

Out[37]: 4052.047999999912

- We can see that there are some minimal energy values attained for some values of Ebudget, especially for Ebudget approximately equal to 1.6 and 3.8 where the value of L is approximately smaller by 2*(10**-9)ms than the average

I tried with the CVXPY method in order to see if my results are logical but it showed me that there is an arethmetical error, you can see my code below. I can't see why I have this error

In [211…
```python
import cvxpy as cp
from cvxpy import *
```

In [228…
```python
L_max=1200
from cvxopt import matrix, solvers
A = matrix([ [beta1, -1.0 , 0.0], [0, 0, 0] ])
b = matrix([ -beta2+L_max, -Tw_min, -5*Etx+0.25 ])
c = matrix([ alpha1, alpha2 ])
sol=solvers.lp(c,A,b)
```

```
---------------------------------------------------------------------------
ArithmeticError                           Traceback (most recent call last)
~/opt/anaconda3/lib/python3.8/site-packages/cvxopt/misc.py in factor(W, H, Df)
   1428             if type(F['S']) is matrix:
-> 1429                 lapack.potrf(F['S'])
   1430             else:

ArithmeticError: 2

During handling of the above exception, another exception occurred:

ArithmeticError                           Traceback (most recent call last)
~/opt/anaconda3/lib/python3.8/site-packages/cvxopt/coneprog.py in conelp(c, G, h, dims, A, b, primalstart, dualstart, kktsolver, xnewcopy, xdot, xaxpy, xscal, ynewcopy, ydot, yaxpy, yscal, **kwargs)
    679         for rti in W['rti']: rti[::rti.size[0]+1 ] = 1.0
--> 680         try: f = kktsolver(W)
    681         except ArithmeticError:

~/opt/anaconda3/lib/python3.8/site-packages/cvxopt/coneprog.py in kktsolver(W)
    584         def kktsolver(W):
--> 585             return factor(W)
    586

~/opt/anaconda3/lib/python3.8/site-packages/cvxopt/misc.py in factor(W, H, Df)
   1443             if type(F['S']) is matrix:
-> 1444                 lapack.potrf(F['S'])
   1445             else:

ArithmeticError: 2

During handling of the above exception, another exception occurred:

ValueError                                Traceback (most recent call last)
<ipython-input-228-618aa1f9d7b1> in <module>
      4 b = matrix([ -beta2+L_max, -Tw_min, -5*Etx+0.25 ])
      5 c = matrix([ alpha1, alpha2 ])
----> 6 sol=solvers.lp(c,A,b)

~/opt/anaconda3/lib/python3.8/site-packages/cvxopt/coneprog.py in lp(c, G, h, A, b, kktsolver, solver, primalstart, dualstart, **kwargs)
   3007             'primal slack': pslack, 'dual slack': dslack}
   3008
-> 3009     return conelp(c, G, h, {'l': m, 'q': [], 's': []}, A,  b, primalstart,
   3010         dualstart, kktsolver = kktsolver, options = options)
   3011

~/opt/anaconda3/lib/python3.8/site-packages/cvxopt/coneprog.py in conelp(c, G, h, dims, A, b, primalstart, dualstart, kktsolver, xnewcopy, xdot, xaxpy, xscal, ynewcopy, ydot, yaxpy, yscal, **kwargs)
    680         try: f = kktsolver(W)
    681         except ArithmeticError:
--> 682             raise ValueError("Rank(A) < p or Rank([G; A]) < n")
    683
    684     if primalstart is None:

ValueError: Rank(A) < p or Rank([G; A]) < n
```

Question 3

In [31]:
```python
E_worst=np.amax(minimums);E_worst
```

Out[31]: 0.018899688579481086

In [32]:
```python
L_worst=np.amax(minimums_2);L_worst
```

Out[32]: 4052.048

We will formalize the optimization problem:

In [34]:
```python
def f_0(x):
    return np.log(np.abs(E_worst-x[0]))+np.log(np.abs(L_worst-x[1]))
def f_1(x):
    return (alpha1/x[2])+alpha2*x[2]+alpha3-E_worst
def f_2(x):
    return (alpha1/x[2])+alpha2*x[2]+alpha3-x[0]
def f_3(x):
    return beta1*x[2]+beta2-L_worst
def f_4(x):
    return beta1*x[2]+beta2-x[1]
def f_5(x):
    return Tw_min-x[2]
def f_6(x):
    return 0.25-5*Etx
#cons = ({'type': 'ineq','fun' : f_1},{'type': 'ineq','fun' : f_2})
cons = ({'type': 'ineq','fun' : f_1},{'type': 'ineq','fun' : f_2},{'type': 'ineq','fun' : f_3},{'type': 'ineq',
x0=[5,2000,300]
optimize.minimize (f_0,x0,constraints= cons)
```

Out[34]:
```
     fun: 1.1094015331840739
     jac: array([-6.76679065e+02, -4.87327576e-04,  0.00000000e+00])
 message: 'Positive directional derivative for linesearch'
    nfev: 34
     nit: 10
    njev: 6
  status: 8
 success: False
       x: array([1.74218757e-02, 2.00000000e+03, 3.00000000e+02])
```

We consequently find this result for this opimization problem