

# Clinical Gait Analysis

**Artificial intelligence for data science  
SIC7002**

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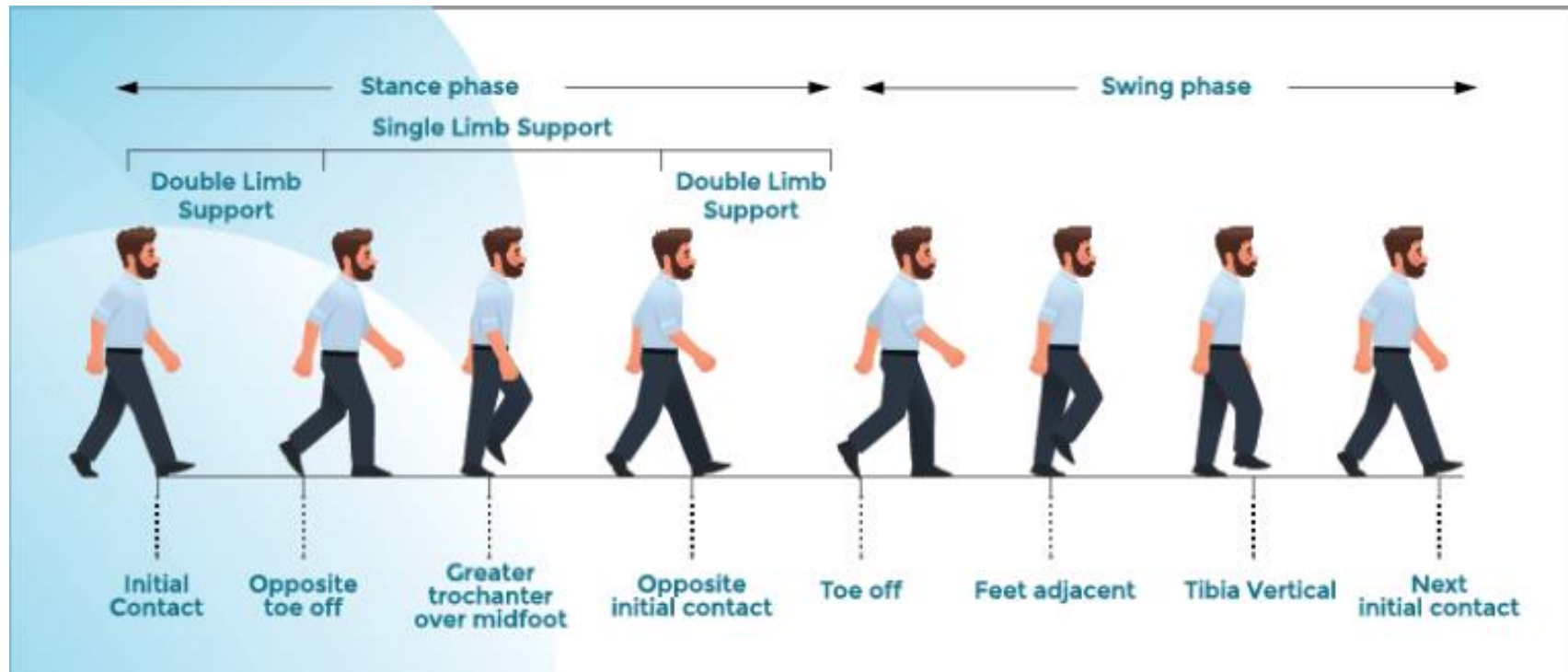
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# Introduction



Gait cycle

# State of the art

**Kinematics:** study of motion without considering the forces that cause it

**Kinetics:** study of the forces and moments that cause motion

## Measures for clinical gait analysis

→ Obtain information for establishing the level of functional limitation due to pathology

- Normalcy index (NI)
- Hip flexor index (HIP)
- Gait deviation index (GDI)
- Gait abnormality index (GAI)

# Experiment

52 participants, with no neuro-orthopaedic troubles, has been asked to walk under five different speed constraints.

## Dataset

The study focused on **knee flexion**, using 101 points to characterize each cycle, with 10 cycles per person

5 different speed conditions :

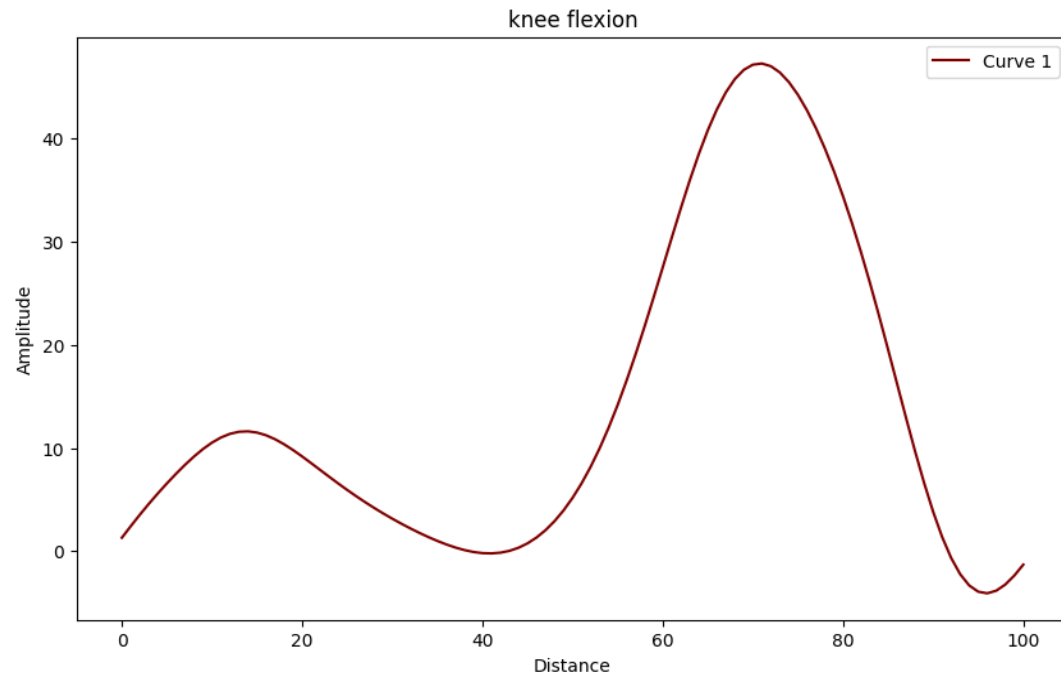
- Speed 1 : 0 - 0.4 m/s
- Speed 2 : 0.4 - 0.8 m/s
- Speed 3 : 0.8 - 1.2 m/s
- Speed 4 : Spontaneous
- Speed 5 : High

## Objective

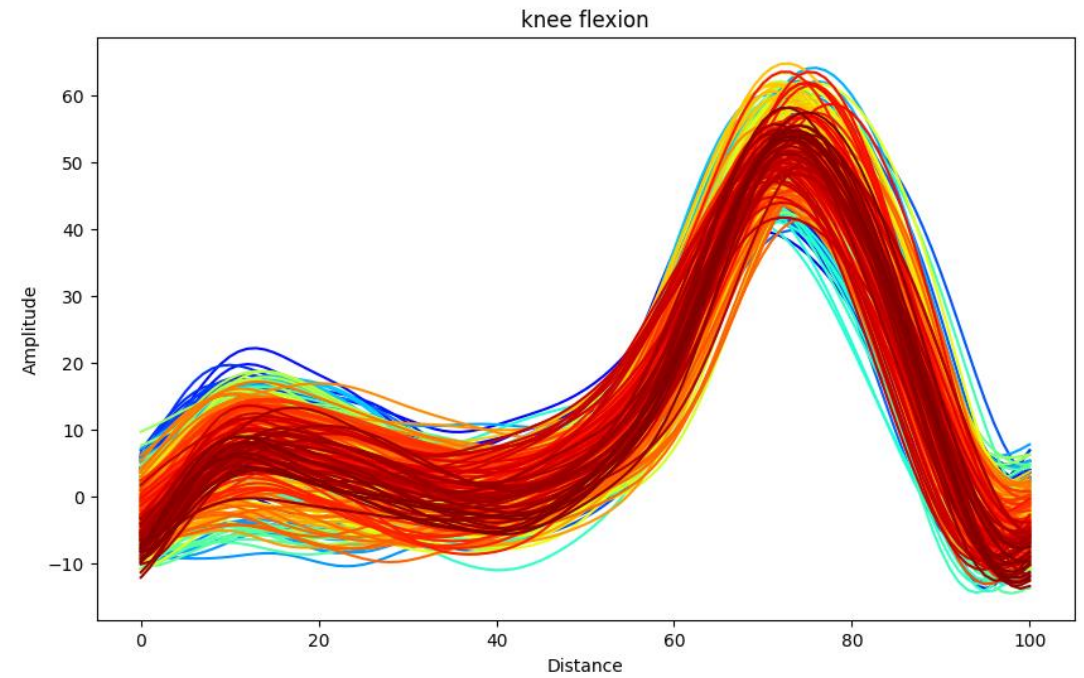
→ Study and analyse the impact of speed constraints on the gait

# Visualization of the dataset

Example for Speed 3 :



One cycle



All cycles

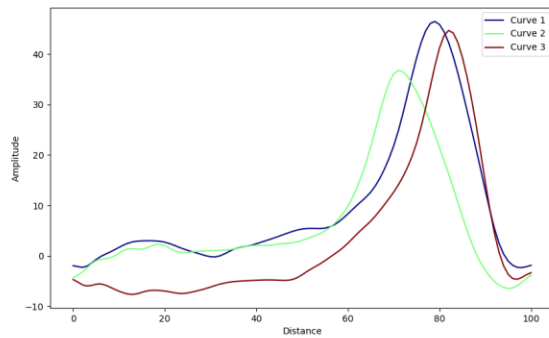
# Methods

1. K-Medoids algorithm using DTW with  $k = 3$ .
2. 3D-visualisation of cycles based on a distance with a reference (Medoids of speed 4).
3. K-Means algorithm with  $k = 5$  on the distances of each cycle with the reference .
4. Calculate the variance of one person's cycles and average over all persons for each speed.

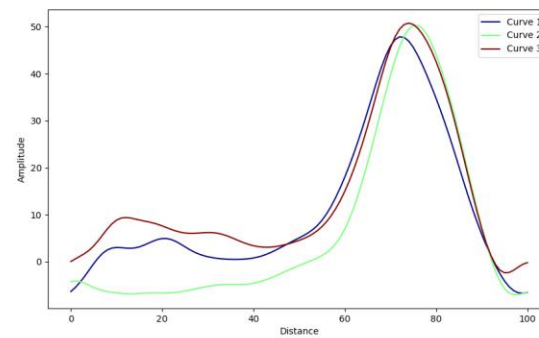
# Results

K-Medoids algorithm using DTW with  $k = 3$  for each speed.

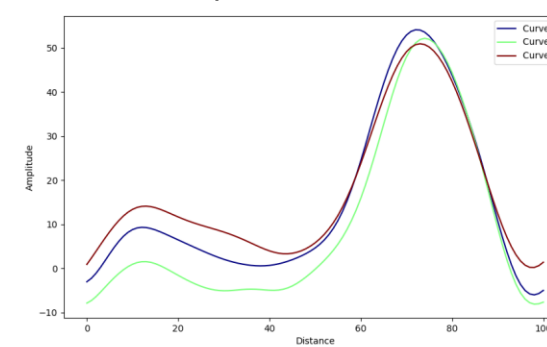
Speed 1 : 0 - 0.4 m/s



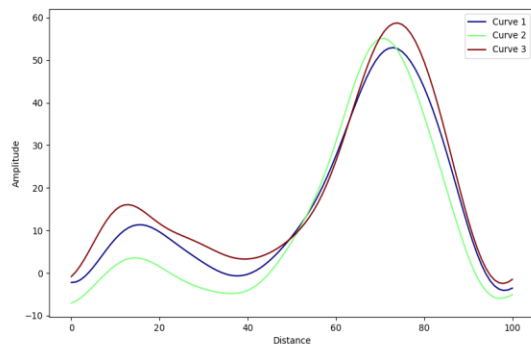
Speed 2 : 0.4 - 0.8 m/s



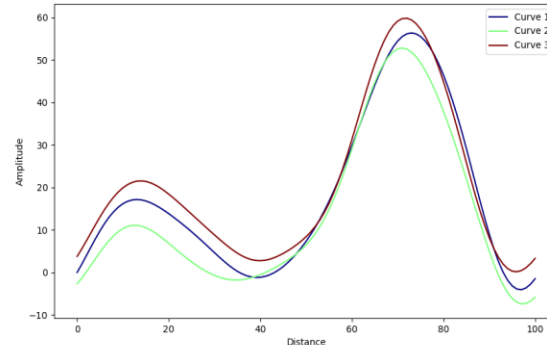
Speed 3 : 0.8 - 1.2 m/s



Spontaneous Speed



High Speed



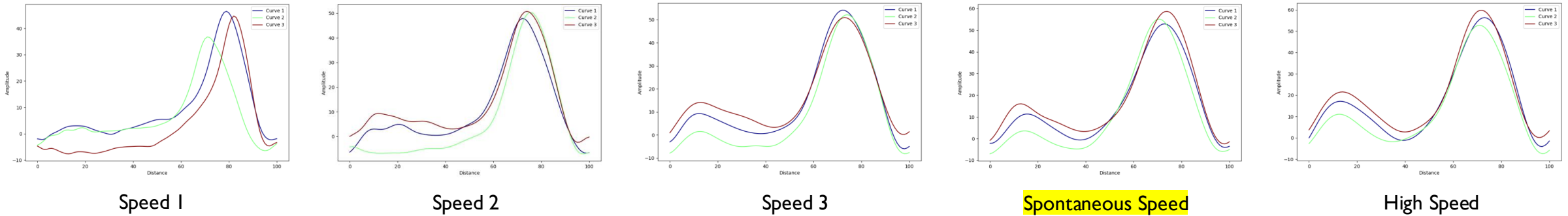
## Interpretation

- The slower the speed constraint, the smaller the first bump.

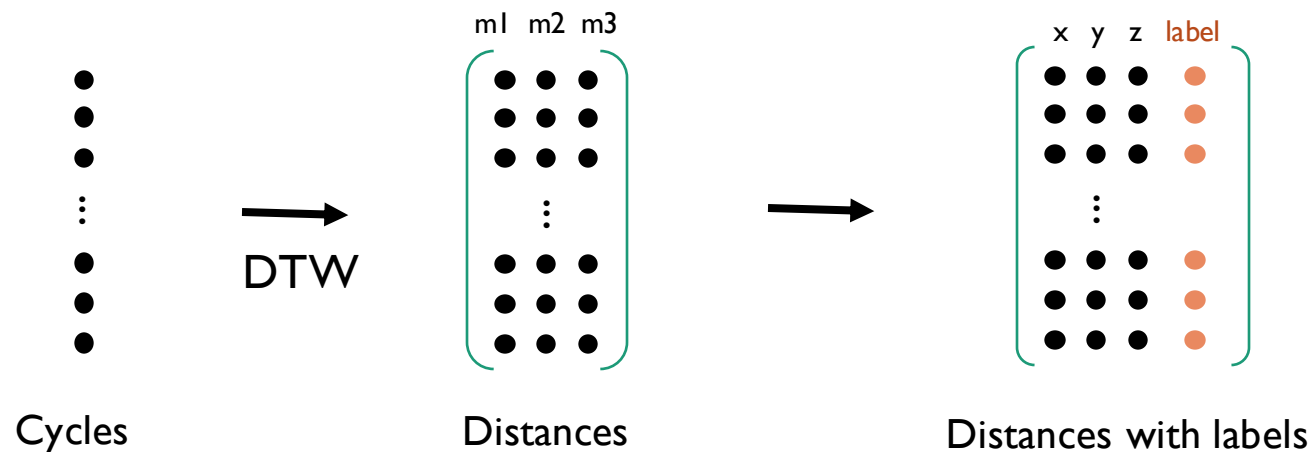


# Results

## 3D-visualisation of cycles

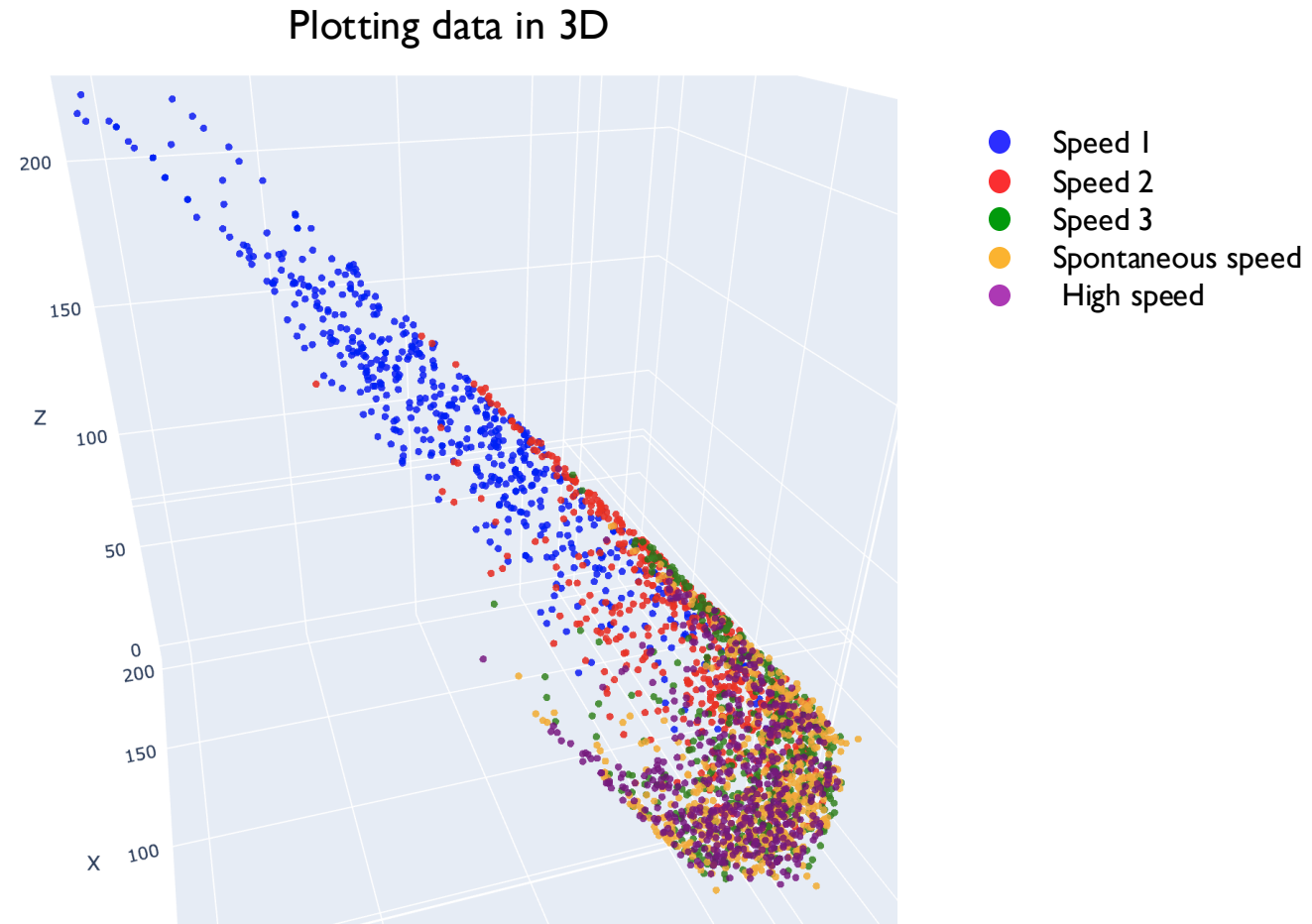


Calculate the **DTW distance** of all cycles to the 3 medoid cycles (m1, m2 and m3) of the spontaneous speed.



# Results

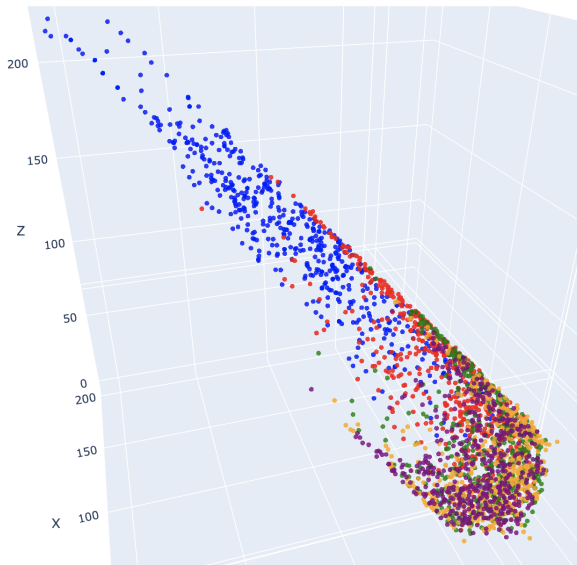
## 3D-visualisation of cycles



# Results

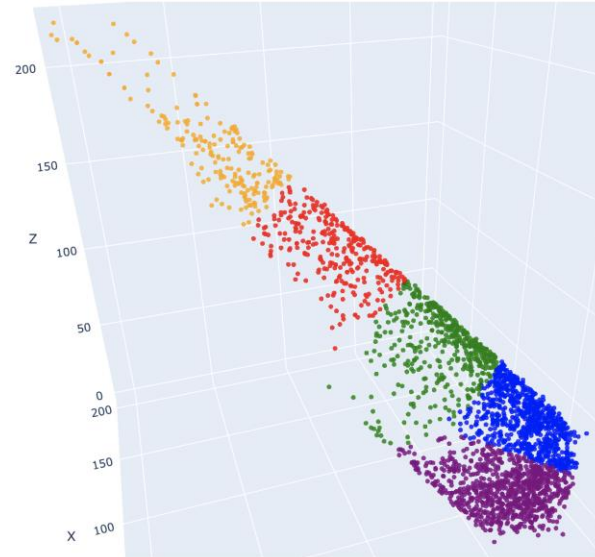
## K-Means algorithm

Plotting data in 3D



- Speed 1
- Speed 2
- Speed 3
- Spontaneous speed (Ref)
- High speed

K-Means (k=5)



Distribution of cycles

Clusters	Speed 1	Speed 2	Speed 3	Ref	High speed
●	0	42	224	293	306
●	11	185	207	191	151
●	88	211	76	30	46
●	229	71	3	0	1
●	192	3	0	0	0

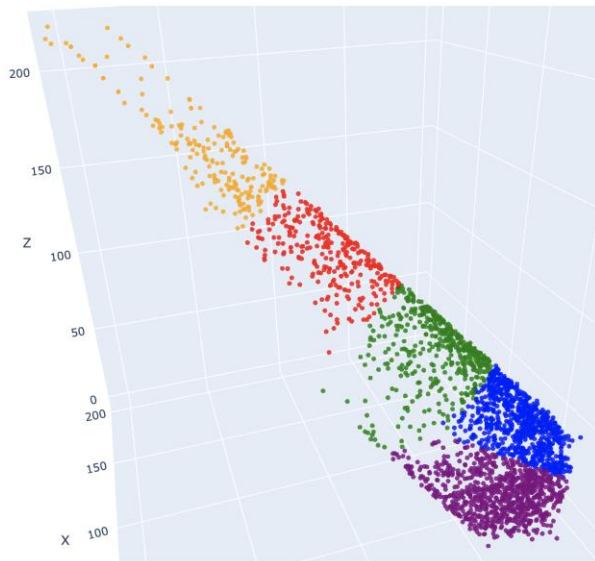
## Interpretation

- The slower the gait is imposed, the more the cycles are distant from the cycles of spontaneous walking.
- With the constraint of slow speed, cycles become more individual-specific and different from one another.






# Results

## K-Means algorithm

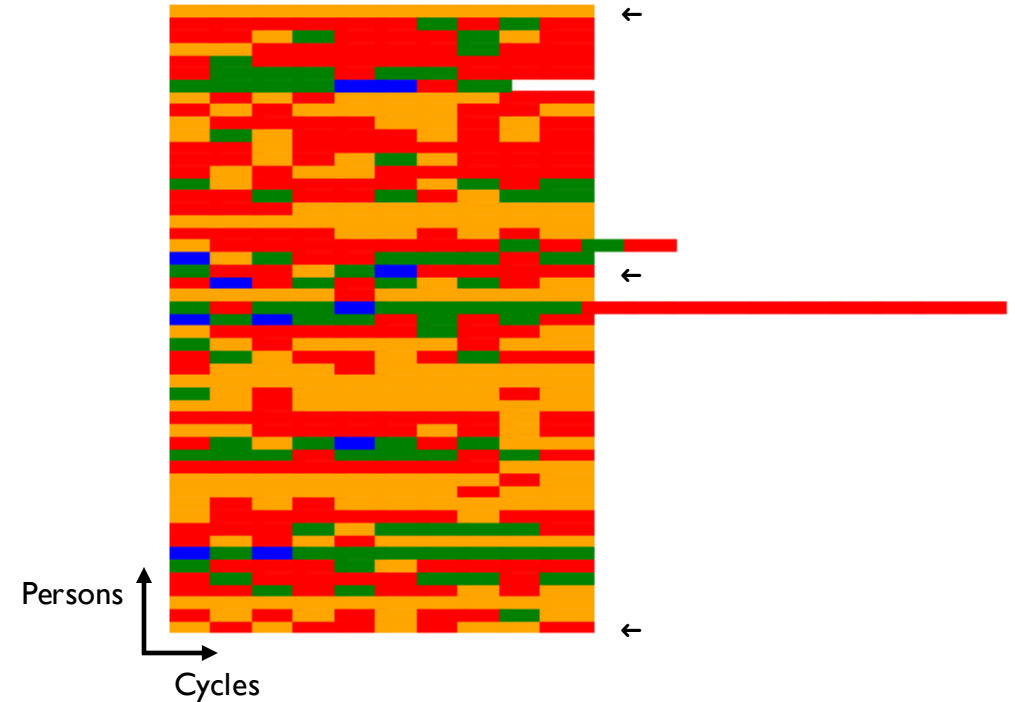
K-Means (k=5)



Distribution of cycles

Clusters	Speed 1
	0
	11
	88
	229
	192

For the slowest speed



## Interpretation

- With the slow speed constraint, individuals do not have similar cycles.

# Results

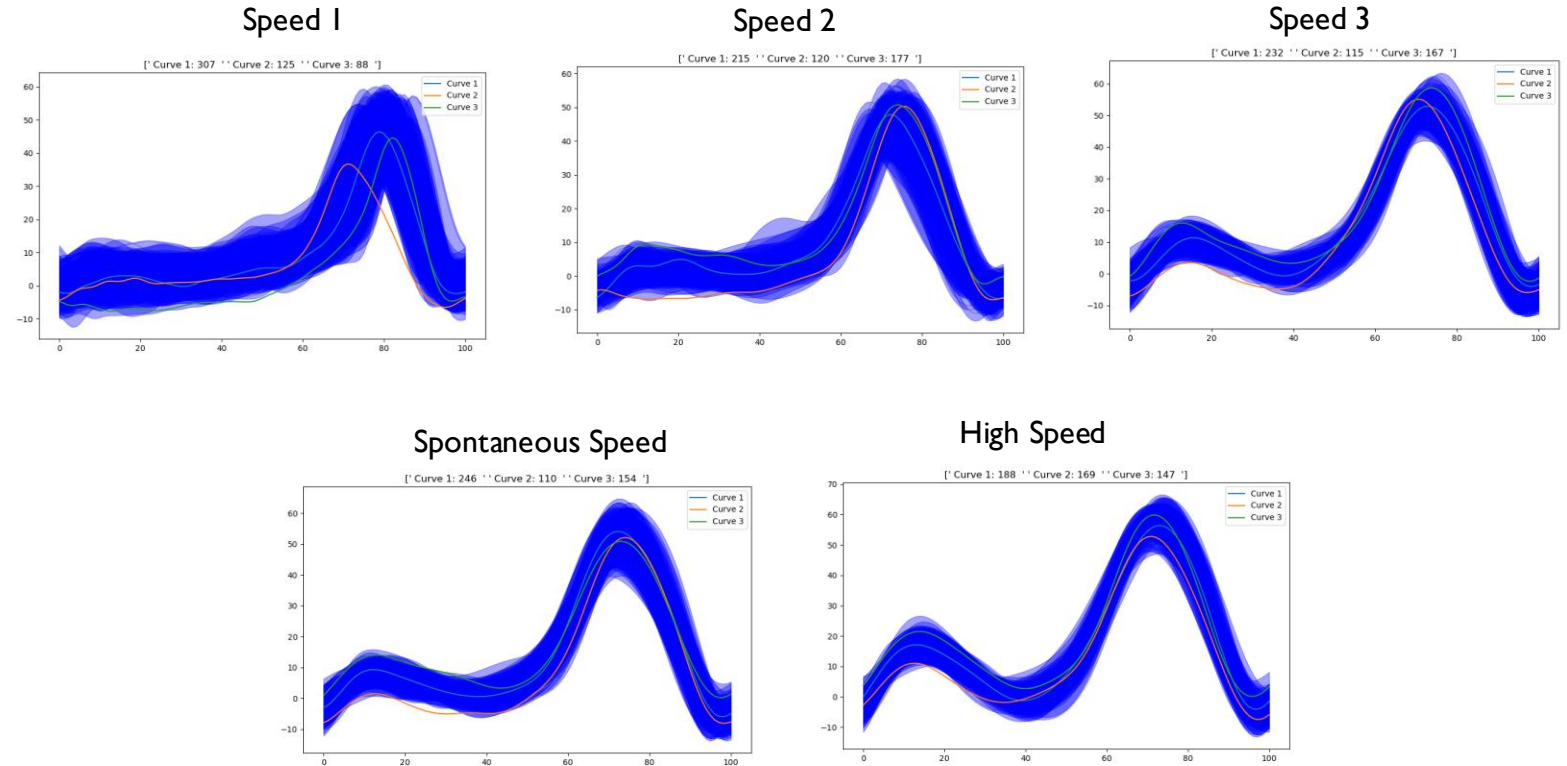
## Variance of cycles

Speed	Variance
0-0.4 m/s	26.88
0.4-0.8 m/s	17.67
0.8-1.2 m/s	18.21
Spontaneous	13.56
High	8.31

Variance of one person's cycles and average over all persons for each speed

## Interpretation

- The speed constraint weakened the walk. The slower the speed, the more different a person's cycles.
- It looks like the stance phase is the most disturbed. Search of balance ? The walker has to force the process which highlights his gait flaws.



Area of all cycles within a cluster found with K-Medoids

# Conclusion

## Main results

- Deformation of cycle shape under speed constraint
- With the constraint of slow speed, cycles become more individual-specific and different from one another.
- To discriminate pathologies in diseased people, it is useful to apply stresses with slow speeds

## Future research

- Take into account individual characteristics such as size and age to assess whether they influence cycle variability.

# **Thank you for your attention**

Feel free to ask questions !