```
In [1]: ! pip install fipy
      Collecting fipy
        Downloading fipy-4.0.1-py3-none-any.whl.metadata (9.0 kB)
      Requirement already satisfied: numpy in /usr/local/lib/python3.12/dist-packages
       (from fipy) (2.0.2)
      Requirement already satisfied: scipy in /usr/local/lib/python3.12/dist-packages
       (from fipy) (1.16.2)
      Requirement already satisfied: matplotlib in /usr/local/lib/python3.12/dist-pac
      kages (from fipy) (3.10.0)
      Requirement already satisfied: typer in /usr/local/lib/python3.12/dist-packages
       (from fipy) (0.19.2)
      Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.12/di
      st-packages (from matplotlib->fipy) (1.3.3)
      Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.12/dist-p
      ackages (from matplotlib->fipy) (0.12.1)
      Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.12/d
      ist-packages (from matplotlib->fipy) (4.60.1)
      Requirement already satisfied: kiwisolver>=1.3.1 in /usr/local/lib/python3.12/d
      ist-packages (from matplotlib->fipy) (1.4.9)
      Requirement already satisfied: packaging>=20.0 in /usr/local/lib/python3.12/dis
      t-packages (from matplotlib->fipy) (25.0)
      Requirement already satisfied: pillow>=8 in /usr/local/lib/python3.12/dist-pack
      ages (from matplotlib->fipy) (11.3.0)
      Requirement already satisfied: pyparsing>=2.3.1 in /usr/local/lib/python3.12/di
      st-packages (from matplotlib->fipy) (3.2.5)
      Requirement already satisfied: python-dateutil>=2.7 in /usr/local/lib/python3.1
      2/dist-packages (from matplotlib->fipy) (2.9.0.post0)
      Requirement already satisfied: click>=8.0.0 in /usr/local/lib/python3.12/dist-p
      ackages (from typer->fipy) (8.3.0)
      Requirement already satisfied: typing-extensions>=3.7.4.3 in /usr/local/lib/pyt
      hon3.12/dist-packages (from typer->fipy) (4.15.0)
      Requirement already satisfied: shellingham>=1.3.0 in /usr/local/lib/python3.12/
      dist-packages (from typer->fipy) (1.5.4)
      Requirement already satisfied: rich>=10.11.0 in /usr/local/lib/python3.12/dist-
      packages (from typer->fipy) (13.9.4)
      Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.12/dist-packa
      ges (from python-dateutil>=2.7->matplotlib->fipy) (1.17.0)
      Requirement already satisfied: markdown-it-py>=2.2.0 in /usr/local/lib/python
      3.12/\text{dist-packages} (from rich>=10.11.0->typer->fipy) (4.0.0)
      Requirement already satisfied: pygments<3.0.0,>=2.13.0 in /usr/local/lib/python
      3.12/dist-packages (from rich>=10.11.0->typer->fipy) (2.19.2)
      Requirement already satisfied: mdurl~=0.1 in /usr/local/lib/python3.12/dist-pac
      kages (from markdown-it-py>=2.2.0->rich>=10.11.0->typer->fipy) (0.1.2)
      Downloading fipy-4.0.1-py3-none-any.whl (449 kB)
                                               --- 449.0/449.0 kB 4.0 MB/s eta 0:00:00
      Installing collected packages: fipy
      Successfully installed fipy-4.0.1
```

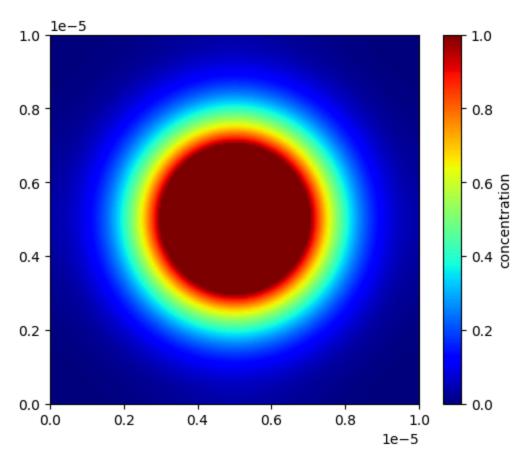
In [3]: # Define mesh
L = 10e-6 # 10 μm domain

In [2]: **from** fipy **import** CellVariable, Grid2D, DiffusionTerm, TransientTerm, Viewer

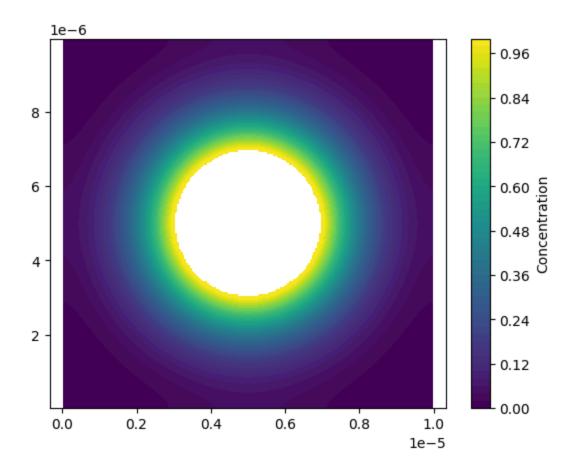
import numpy as np

```
nx = 200
        ny = 200
        mesh = Grid2D(dx=L/nx, dy=L/ny, nx=nx, ny=ny)
        # Define spatial coordinates
        x, y = mesh.cellCenters
        r = np.sqrt((x - L/2)**2 + (y - L/2)**2) # radial distance from center
In [4]: # Define concentric regions
        core radius = 2e-6
        shell1 radius = 3e-6
        shell2 radius = 4e-6
        # Create masks for layers
        core = (r < core radius)</pre>
        shell1 = (r >= core radius) & (r < shell1 radius)</pre>
        shell2 = (r >= shell1 radius) & (r < shell2 radius)
In [5]: D core = 1e-9
                          \# m^2/s
        D shell = 1e-12 # m^2/s
        # Spatially varying diffusion
        D = np.where(core, D_core, np.where(shell1, D_shell, D_shell))
In [6]: # Create variable for concentration
        C = CellVariable(name="concentration", mesh=mesh, value=0.0)
        # Boundary condition: high concentration at center (simulate dye injection)
        C.constrain(1.0, where=core)
        # Define equation
        eq = TransientTerm() == DiffusionTerm(coeff=D)
In [7]: from fipy import CellVariable, Grid2D, DiffusionTerm, TransientTerm, Viewer
        import numpy as np
        # Define mesh
        L = 10e-6
        nx = 200
        ny = 200
        mesh = Grid2D(dx=L/nx, dy=L/ny, nx=nx, ny=ny)
        # Define coordinates
        x, y = mesh.cellCenters
        r = np.sqrt((x - L/2)**2 + (y - L/2)**2)
        # Define regions
        core radius = 2e-6
        shell1 radius = 3e-6
        shell2 radius = 4e-6
        core = (r < core radius)</pre>
```

```
shell1 = (r >= core radius) & (r < shell1 radius)</pre>
shell2 = (r >= shell1_radius) & (r < shell2_radius)</pre>
# Define diffusion coefficients
D core = 1e-9
D \text{ shell} = 1e-12
# 🖊 Create FiPy CellVariable for D
D value = np.where(core, D core, np.where(shell1, D shell, D shell))
D = CellVariable(mesh=mesh, value=D value)
# Define concentration
C = CellVariable(name="concentration", mesh=mesh, value=0.0)
# Boundary condition (high concentration in core)
C.constrain(1.0, where=core)
# Define PDE
eq = TransientTerm() == DiffusionTerm(coeff=D)
# Time stepping
time step = 1e-3
steps = 1000
viewer = Viewer(vars=(C,), datamin=0, datamax=1)
for step in range(steps):
    eq.solve(var=C, dt=time step)
    if step % 50 == 1:
        viewer.plot()
```



```
In [10]: np.savetxt("myelin_diffusion_profile.txt", np.c_[x, y, C.value])
In [11]: import matplotlib.pyplot as plt
    plt.tricontourf(x, y, C.value, levels=50, cmap='viridis')
    plt.colorbar(label='Concentration')
    plt.axis('equal')
    plt.show()
```



```
In [12]: # myelin fipy flux compare.py
         import numpy as np
         import matplotlib.pyplot as plt
         from fipy import Grid2D, CellVariable, TransientTerm, DiffusionTerm, Viewer
         # PARAMETERS
         # ------
         L_domain = 10e-6  # domain size (m) - domain is square L_domain x L_domain
         nx = 200
                            # cells in x
         ny = 200
                             # cells in y
                            # axial length (m) used in analytic formula (use 1 for p
         L axial = 1.0
         # Radii (meters) - concentric shells
         r0 = 1.0e-6 # inner boundary (core radius)
         r1 = 2.0e-6 # shell 1 outer
         r2 = 3.0e-6 # shell 2 outer
         r3 = 4.0e-6 # outer boundary (domain radius for BC)
         # Diffusion coefficients in each radial region (m^2/s)
         D core = 1e-9
         D \text{ shell1} = 1e-12
         D \text{ shell2} = 5e-13
         # Boundary concentrations
         C inner = 1.0
```

```
C \text{ outer} = 0.0
# Time stepping parameters (we'll time-step to steady state)
dt = 1e-6
nsteps = 2000
# ------
# MESH and RADIAL MASKS
mesh = Grid2D(dx=L domain/nx, dy=L domain/ny, nx=nx, ny=ny)
x, y = mesh.cellCenters # vectors of cell center coords
xc = np.array(x) # convert to numpy arrays
yc = np.array(y)
# center the circular geometry in the square domain
x0 = L domain / 2.0
y0 = L domain / 2.0
r = np.sqrt((xc - x0)**2 + (yc - y0)**2)
# Masks for regions
core mask = (r \ll r0)
shell1 mask = (r > r0) \& (r <= r1)
shell2 mask = (r > r1) \& (r <= r2)
outside mask = (r > r2) & (r <= r3) # we will set outer BC at r3
# Create a FiPy CellVariable for spatially varying diffusion coefficient
D values = np.zeros like(r)
D values[core mask] = D core
D values[shell1 mask] = D shell1
D_values[shell2_mask] = D_shell2
# Outside region set to the largest D (or same as shell2) to avoid singulariti
D values[outside mask] = D shell2
D = CellVariable(mesh=mesh, name='D', value=D values)
# CONCENTRATION VARIABLE and BCs
# ------
C = CellVariable(mesh=mesh, name='C', value=0.0)
# Apply Dirichlet constraints:
# - Inner: set C=1 for cells inside core mask (approximate inner radius BC)
# - Outer: set C=0 for cells with r >= r3*0.999 (approximate outer boundary)
C.constrain(C inner, where=core mask)
C.constrain(C outer, where=(r >= r3))
# EQUATION (Transient -> steady)
# ------
eq = TransientTerm() == DiffusionTerm(coeff=D)
# Optional viewer (works if you have X server)
try:
```

```
viewer = Viewer(vars=(C,), datamin=0.0, datamax=1.0)
except Exception:
   viewer = None
# Time-stepping to steady state
for step in range(nsteps):
   eq.solve(var=C, dt=dt)
   if viewer and (step % 200 == 0):
       viewer.plot()
print("Time-stepping finished.")
# -----
# POSTPROCESS: radial binning to compute numerical flux
# Create radial bins from a small radius (just outside inner BC) to r3
nbins = 200
r bins = np.linspace(0, r3, nbins+1)
r_{centers} = 0.5 * (r_{bins}[:-1] + r_{bins}[1:])
dr = r bins[1] - r bins[0]
# Average concentration and D in each annulus
Cvals = np.array(C.value) # values at cell centers
Dvals = np.array(D.value)
C radial avg = np.zeros(nbins)
D radial avg = np.zeros(nbins)
count = np.zeros(nbins)
for i bin in range(nbins):
   mask bin = (r \ge r bins[i bin]) \& (r < r bins[i bin+1])
   if np.any(mask bin):
       C radial avg[i bin] = Cvals[mask bin].mean()
        D radial avg[i bin] = Dvals[mask bin].mean()
        count[i bin] = mask bin.sum()
   else:
        C radial avg[i bin] = np.nan
        D radial avg[i bin] = np.nan
# Remove empty bins
valid = ~np.isnan(C radial avg)
r centers = r centers[valid]
C radial avg = C radial avg[valid]
D radial avg = D radial avg[valid]
# Compute dC/dr (numerical derivative w.r.t r)
dCdr = np.gradient(C radial avg, r centers)
# Radial flux density (per unit axial length) J(r) = -2*pi * r * D(r) * dC/dr
# Total flux (per unit axial length) should be approximately constant; evaluat
J radial = -2.0 * np.pi * r centers * D radial avg * dCdr
# Estimate total flux as average over a small radial range just outside r0
probe mask = (r \text{ centers} > r0) \& (r \text{ centers} < (r0 + 0.5*(r1 - r0)))
```

```
J numeric = np.nanmean(J radial[probe mask])
print("Numerical flux (per unit axial length) J numeric =", J numeric)
# ANALYTIC FLUX (resistance-sum)
# -----
# We set Ca = 1 (at r0) and Cb = 0 (at r3)
Ca, Cb = C inner, C outer
# Define the radial interfaces and D i arrays used in analytic formula
r interfaces = np.array([r0, r1, r2, r3]) \# r0...r3
D layers = np.array([D core, D shell1, D shell2]) # three layers between r0-r
# Compute denominator sum {i} (1/D i) * ln(r i / r {i-1})
den = 0.0
for i in range(len(D layers)):
   den += (1.0 / D layers[i]) * np.log(r interfaces[i+1] / r interfaces[i])
J analytic = 2.0 * np.pi * L axial * (Ca - Cb) / den
print("Analytic flux (per unit axial length) J analytic =", J analytic)
# Relative error
rel err = (J numeric - J analytic) / J analytic
print("Relative error (numeric vs analytic): {:.3e}".format(rel err))
# PLOTTING radial profile and flux
# ------
fig, axes = plt.subplots(1, 2, figsize=(12, 4))
axes[0].plot(r centers * 1e6, C radial avg, '-o', markersize=3)
axes[0].set xlabel('radius (μm)')
axes[0].set ylabel('C (avg)')
axes[0].set title('Radial concentration profile')
axes[1].plot(r centers * 1e6, J radial, '-o', markersize=3)
axes[1].axvline(r0 * 1e6, color='k', linestyle='--')
axes[1].axvline(r1 * 1e6, color='k', linestyle='--')
axes[1].axvline(r2 * 1e6, color='k', linestyle='--')
axes[1].set xlabel('radius (μm)')
axes[1].set ylabel('Radial flux (per unit length)')
axes[1].set title('Local radial flux estimate')
plt.tight layout()
plt.show()
```

Time-stepping finished.

Numerical flux (per unit axial length) $J_numeric = 1.3567036111989923e-11$ Analytic flux (per unit axial length) $J_numeric = 6.401469091228763e-12$ Relative error (numeric vs analytic): 1.119e+00

