

ESTIMATION OF THE LINEAR FRACTIONAL STABLE MOTION. NUMERICAL RESULTS.

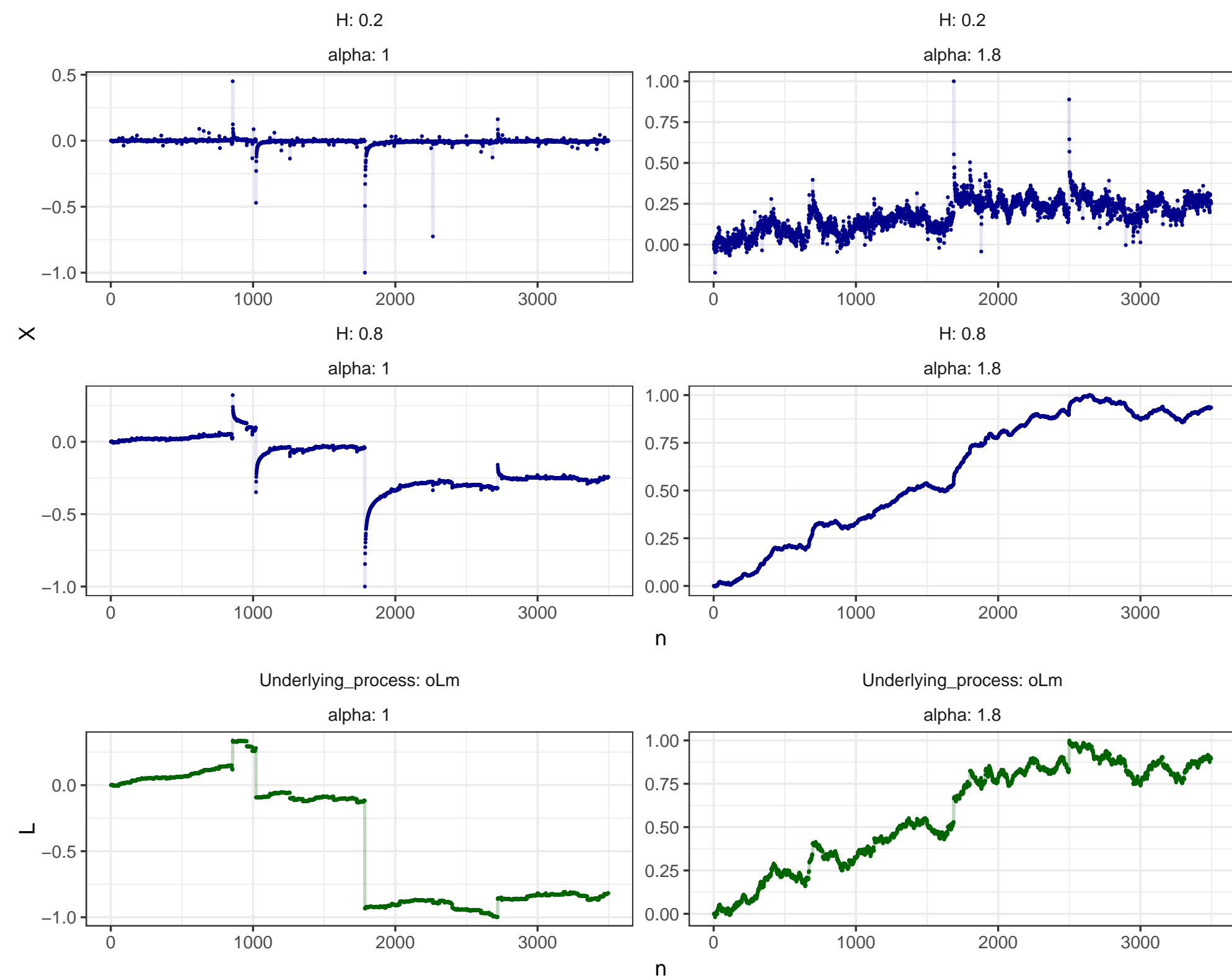
Dmitry Otryakhin. Joint work with Stepan Mazur and Mark Podolskij.

d.otryakhin@math.au.dk

THE MODEL

$$X_t = \int_R \left\{ (t-s)_+^{H-1/\alpha} - (-s)_+^{H-1/\alpha} \right\} dL_s, \quad (1)$$

where L is a symmetric α -stable Lévy motion, $\alpha \in (0, 2)$, with scale parameter $\sigma > 0$ and $H \in (0, 1)$.



CONTINUOUS CASE

Low frequency k th order increments of X :

$$\Delta_{i,k}^r X := \sum_{j=0}^k (-1)^j \binom{k}{j} X_{(i-rj)}, \quad i \geq rk \quad (2)$$

$$\varphi_{\text{low}}(t, k)_n := \frac{1}{n} \sum_{i=k}^n \cos(t \Delta_{i,k}^{r=1} X) \xrightarrow{\mathbb{P}} \quad (3)$$

$$\xrightarrow{\mathbb{P}} \varphi(t, k) := \exp(-|\sigma| \|h_k\|_\alpha t^\alpha) \quad (4)$$

$$R_{\text{low}}(p, k)_n := \frac{\sum_{i=2k}^n \left| \Delta_{i,k}^2 X \right|^p}{\sum_{i=k}^n \left| \Delta_{i,k}^1 X \right|^p} \xrightarrow{\mathbb{P}} 2^{pH} \quad (5)$$

When $H - 1/\alpha > 0$, X_t is continuous and we can take $k = 2, p \in (0, 1/2)$ and use the estimators

$$\hat{H}_{\text{low}}(p, k)_n := \frac{1}{p} \log_2(R_{\text{low}}(p, k)_n)$$

$$\hat{\alpha}_{\text{low}} := \frac{\log |\log \varphi_{\text{low}}(t_2; k)_n| - \log |\log \varphi_{\text{low}}(t_1; k)_n|}{\log t_2 - \log t_1}$$

$$\hat{\sigma}_{\text{low}} := (-\log \varphi_{\text{low}}(t_1; k)_n)^{1/\hat{\alpha}_{\text{low}}} / (t_1 \|h_{k,1}\|_{\hat{\alpha}_{\text{low}}})$$

GENERAL CASE

$\varphi_{\text{low}}(t, k)_n$, $R_{\text{low}}(p, k)_n$ have normal asymptotic distributions and convergence rates \sqrt{n} if $k > H + 1/\alpha$ (\Rightarrow the same holds for hats). Therefore, in the general case we consider the preliminary estimator of α with $k = 1$, that is consistent, given by

$$\hat{\alpha}_{\text{low}}^0(t_1, t_2)_n = \hat{\alpha}_{\text{low}}(t_1, t_2, k_0 = 1)_n.$$

then, estimate k_{low}

$$\hat{k}_{\text{low}}(t_1, t_2)_n := 2 + \lfloor \hat{\alpha}_{\text{low}}^0(t_1, t_2)_n^{-1} \rfloor.$$

and use it to obtain the parameters

$$\tilde{H}_{\text{low}} = \hat{H}_{\text{low}}(-p, \hat{k}_{\text{low}})_n, \quad (6)$$

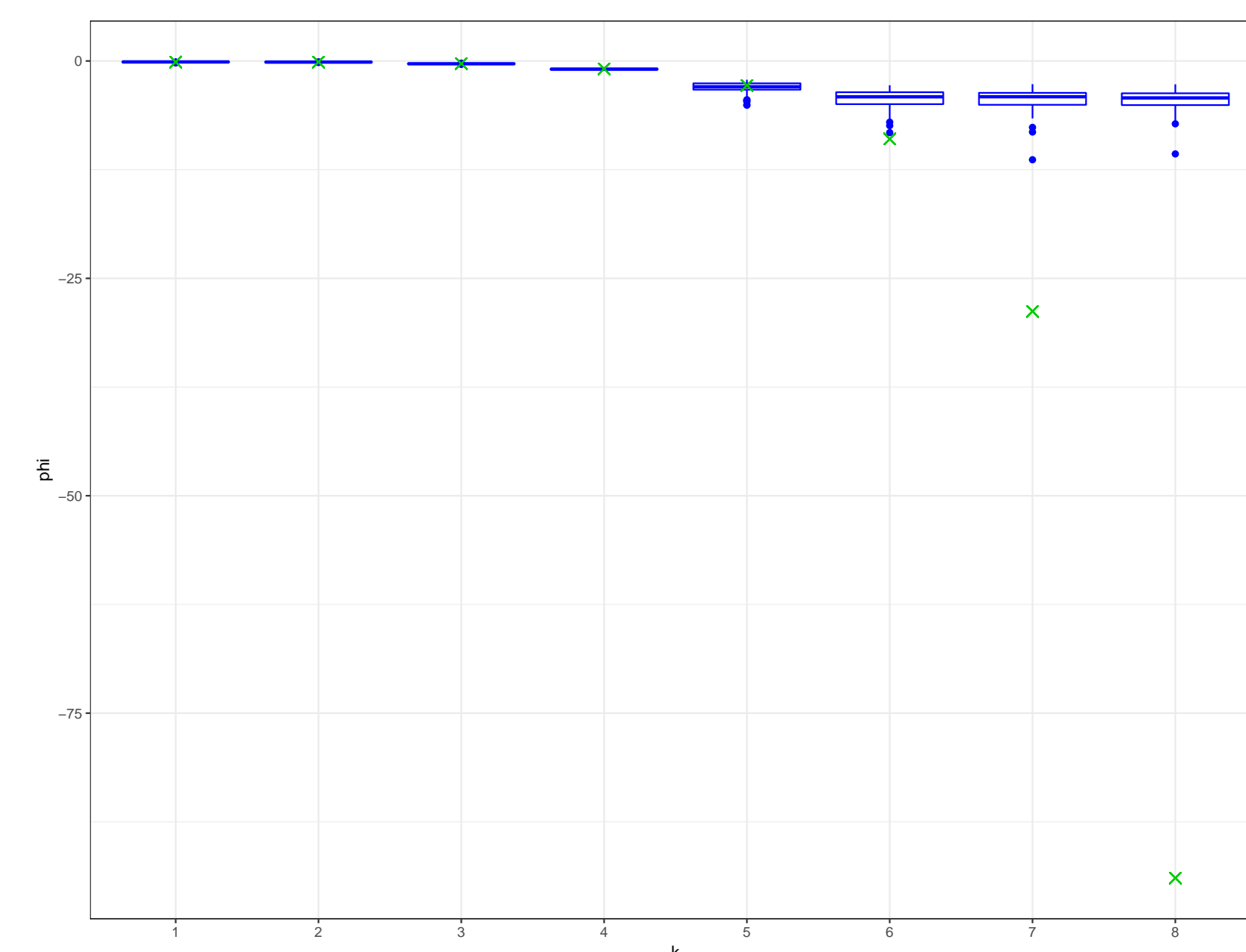
$$\tilde{\alpha}_{\text{low}} = \hat{\alpha}_{\text{low}}(\hat{k}_{\text{low}}; t_1, t_2)_n, \quad (7)$$

$$\tilde{\sigma}_{\text{low}} = \hat{\sigma}_{\text{low}}(\hat{k}_{\text{low}}; t_1, t_2)_n \quad (8)$$

When $\alpha^{-1} \notin \mathbb{N}$ tilde estimators have the same convergence rate $(\sqrt{n}, \sqrt{n}, \sqrt{n})$ and normal asymptotic distribution.

CONVERGENCE OF $\varphi_{\text{LOW}}(t, k)_n$

Function $\varphi(t, k)$ used to extract α and σ from data is very sensitive to k . As k increases $|\varphi_{\text{low}}(t, k)_n - \varphi(t, k)|$ grows, which leads to generally worse performance of the tilde estimators compared to that of the hat estimators.

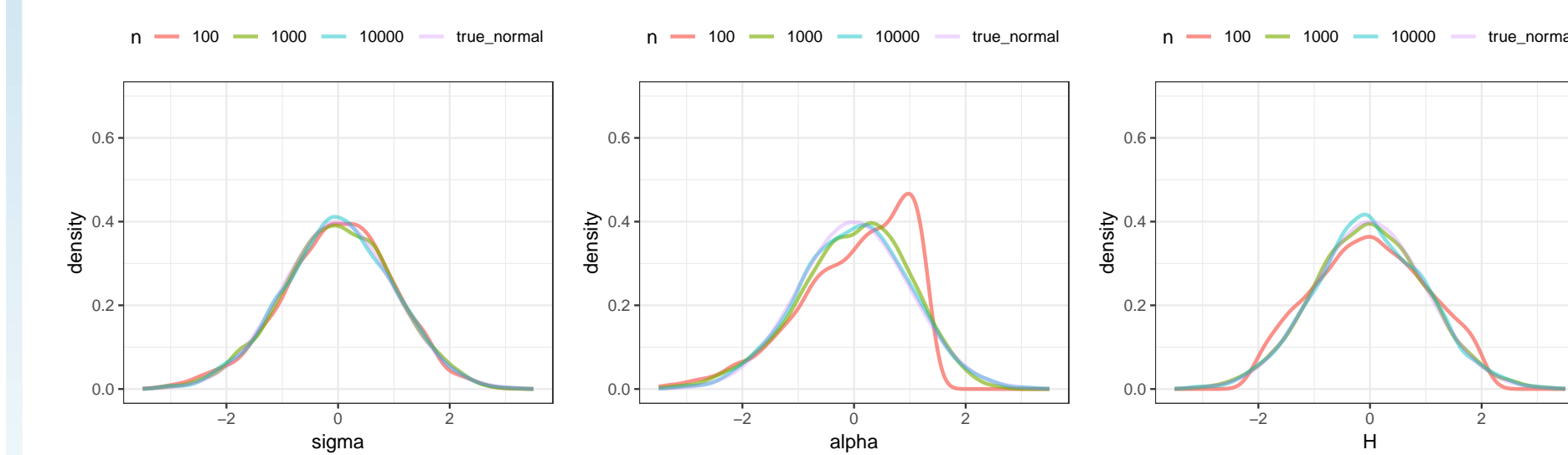


Logarithmic scale. $n = 1000, (\sigma, \alpha, H) = (0.3, 1.8, 0.8)$. Dependences of $\varphi_{\text{low}}(t, k)_n$ (blue box plot) and $\varphi(t, k)$ (green crosses) on k . For the former, a Monte Carlo experiment with $2 \cdot 10^2$ trials was setup.

PERFORMANCE OF $(\hat{\sigma}_{\text{low}}, \hat{\alpha}_{\text{low}}, \hat{H}_{\text{low}})$

n	$\hat{\sigma}_{\text{low}}$	$\hat{\alpha}_{\text{low}}$	\hat{H}_{low}
100	-0.024/0.06	-0.038/0.18	-0.05/0.12
1000	-8e-4/0.02	0.012/0.068	-0.012/0.05
10000	1.4e-4/6e-3	5e-4/0.022	-5e-3/0.016

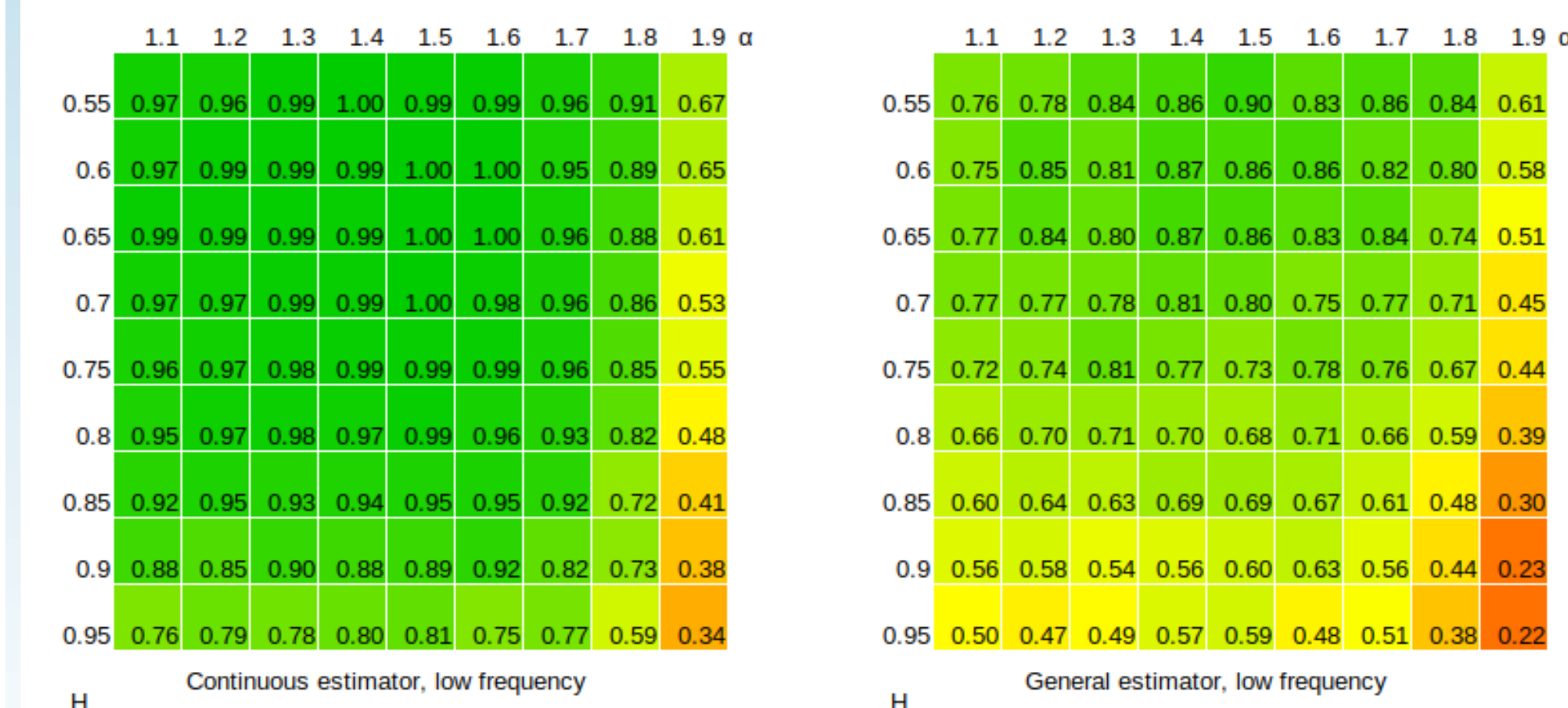
Bias/standard deviation of the estimators $(\hat{\sigma}_{\text{low}}, \hat{\alpha}_{\text{low}}, \hat{H}_{\text{low}})$. $p = 0.4, k = 2, (\sigma, \alpha, H) = (0.3, 1.8, 0.8)$.



Empirical distributions of estimates $(\hat{\sigma}_{\text{low}}, \hat{\alpha}_{\text{low}}, \hat{H}_{\text{low}})$. $p = 0.4, k = 2, (\sigma, \alpha, H) = (0.3, 1.8, 0.8)$.

DETERIORATION OF $(\tilde{\sigma}_{\text{low}}, \tilde{\alpha}_{\text{low}}, \tilde{H}_{\text{low}})$

Due to the nature of plug-in estimators, the low-frequency continuous case estimator encounters (much) less numerical errors than the general low-frequency one. Here, a Monte-Carlo experiment was performed to compute probabilities of obtaining an estimate. The picture below shows the comparison of success rates for ContinEstim and GenLowEstim.



Path length $N = 200$, number of sample paths $N_{MC} = 300$; $t_1 = 1, t_2 = 2, k = 2, p = 0.4, \sigma = 0.3$.

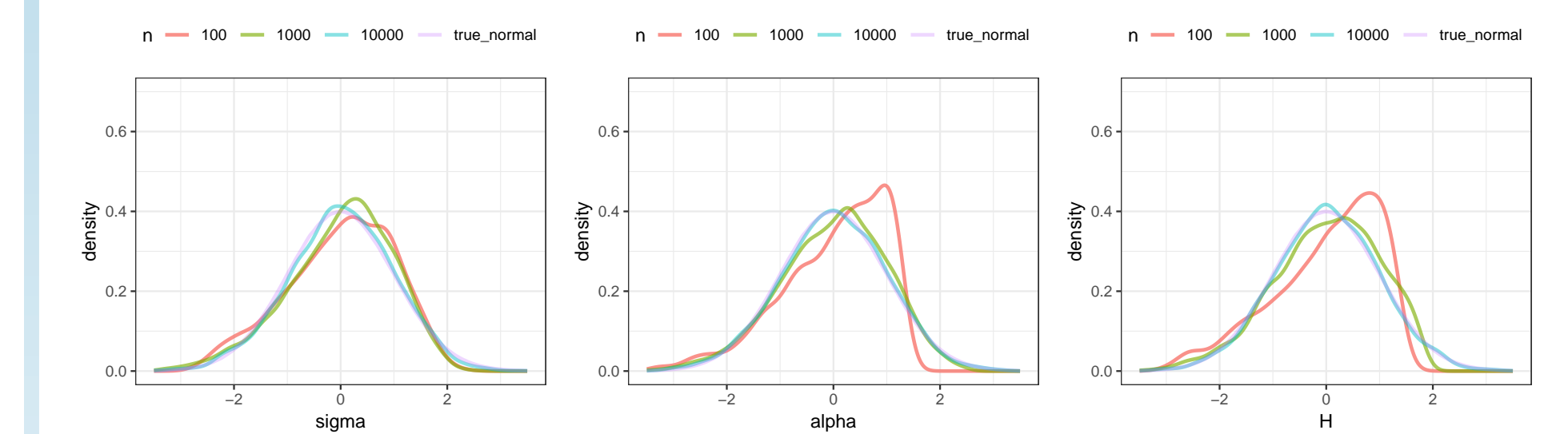
REFERENCES

- [1] A. Basse-O'Connor, R. Lachièze-Rey and M. Podolskij (2016): Limit theorems for stationary increments Lévy driven moving averages. *Annals of Probability*.
- [2] S. Mazur, D. Otryakhin and M. Podolskij (2018): Parameter estimation of the linear fractional stable motion. Submitted.
- [3] S. Mazur, D. Otryakhin (2018): Linear fractional stable motion: The rlfsm package. Working paper.

PERFORMANCE OF $(\tilde{\sigma}_{\text{low}}, \tilde{\alpha}_{\text{low}}, \tilde{H}_{\text{low}})$

n	$\tilde{\sigma}_{\text{low}}$	$\tilde{\alpha}_{\text{low}}$	\tilde{H}_{low}
100	-0.05/0.09	-0.031/0.18	-0.12/0.23
1000	-4e-3/0.04	0.01/0.068	-0.018/0.12
10000	3e-4/0.015	1e-3/0.022	-3e-3/0.05

Bias/standard deviation of the estimator $(\tilde{\sigma}_{\text{low}}, \tilde{\alpha}_{\text{low}}, \tilde{H}_{\text{low}})$. $p = -0.4, (\sigma, \alpha, H) = (0.3, 1.8, 0.8)$.



Empirical distributions of estimates $(\tilde{\sigma}_{\text{low}}, \tilde{\alpha}_{\text{low}}, \tilde{H}_{\text{low}})$. $p = 0.4, (\sigma, \alpha, H) = (0.3, 1.8, 0.8)$.

n	$\tilde{\sigma}_{\text{low}}$	$\tilde{\alpha}_{\text{low}}$	\tilde{H}_{low}
100	-0.06/0.31	-0.003/0.41	-0.15/0.24
1000	-0.05/0.27	-0.08/0.31	0.003/0.13
10000	0.03/0.26	0.008/0.27	0.04/0.05

Bias/standard deviation of the estimator $(\tilde{\sigma}_{\text{low}}, \tilde{\alpha}_{\text{low}}, \tilde{H}_{\text{low}})$. $p = -0.4, (\sigma, \alpha, H) = (0.3, 0.8, 0.8)$.

SUPPLEMENTARY MATERIALS

