

2.32 Consider the following second-order digital filter.

$$H(z) = \frac{3(z+1)}{z^2 - 0.81}$$

- (a) Find the frequency response $H(f)$.
- (b) Find and sketch the magnitude response $A(f)$.
- (c) Find and sketch the phase response $\phi(f)$.
- (d) Find the steady state response to the following periodic input.

$$x(k) = 10 \cos(0.6\pi k)$$

Solution

- (a) Let $\theta = 2\pi fT$. Then applying Definition 2.9.1 and using Euler's identity, the frequency response is

$$\begin{aligned} H(f) &= H(z)|_{z=\exp(j\theta)} \\ &= \frac{3[\exp(j\theta) + 1]}{\exp(2j\theta) - 0.81} \\ &= \frac{3[\cos(\theta) + j \sin(\theta) + 1]}{[\cos(2\theta) + j \sin(2\theta) - 0.81]} \\ &= \frac{3[\cos(\theta) + 1 + j \sin(\theta)]}{[\cos(2\theta) - 0.81 + j \sin(2\theta)]} \quad , \quad \theta = 2\pi fT \end{aligned}$$

- (b) The magnitude response is

$$\begin{aligned} A(f) &= |H(f)| \\ &= \frac{3|\cos(\theta) + 1 + j \sin(\theta)|}{|\cos(2\theta) - 0.81 + j \sin(2\theta)|} \\ &= \frac{3\sqrt{[\cos(\theta) + 1]^2 + \sin^2(\theta)}}{\sqrt{[\cos(2\theta) - 0.81]^2 + \sin^2(2\theta)}} \\ &= \frac{3\sqrt{2[1 + \cos(\theta)]}}{\sqrt{[\cos(2\theta) - 0.81]^2 + \sin^2(2\theta)}} \\ &= \frac{3\sqrt{2[1 + \cos(2\pi fT)]}}{\sqrt{[\cos(4\pi fT) - 0.81]^2 + \sin^2(4\pi fT)}} \end{aligned}$$

(c) The phase response is

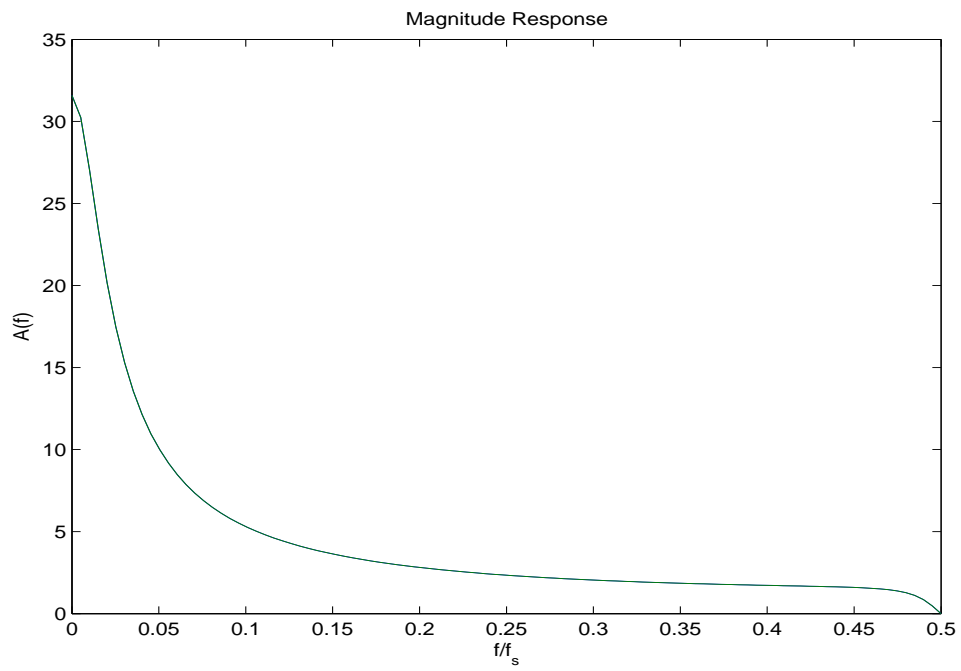
$$\begin{aligned}
\phi(f) &= \angle H(f) \\
&= \angle\{3[\cos(\theta) + 1 + j \sin(\theta)]\} - \angle\{\cos(2\theta) - 0.81 + j \sin(2\theta)\} \\
&= \tan^{-1} \left[\frac{\sin(\theta)}{\cos(\theta) + 1} \right] - \tan^{-1} \left[\frac{\sin(2\theta)}{\cos(2\theta) - 0.81} \right] \\
&= \tan^{-1} \left[\frac{\sin(2\pi fT)}{\cos(2\pi fT) + 1} \right] - \tan^{-1} \left[\frac{\sin(4\pi fT)}{\cos(4\pi fT) - 0.81} \right]
\end{aligned}$$

(d) Since $f_s T = 1$, the input can be rewritten as

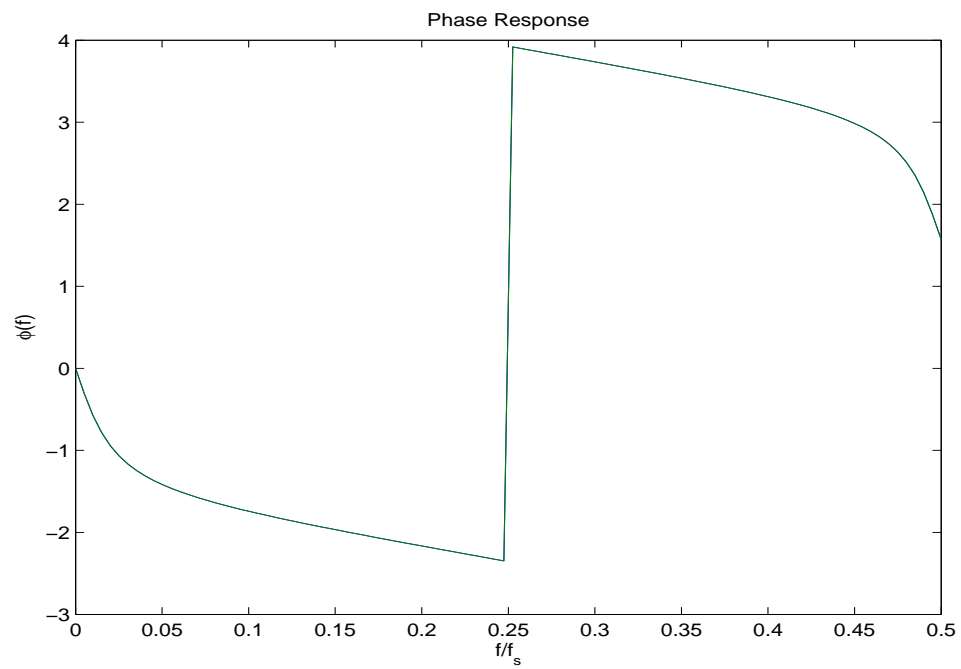
$$\begin{aligned}
x(k) &= 10 \cos(0.6\pi k) \\
&= 10 \cos[2\pi(0.3)k f_s T] \\
&= 10 \cos(2\pi F_1 k T)
\end{aligned}$$

Thus the frequency of $x(k)$, expressed as a fraction of f_s , is $F_1 = 0.3f_s$. Since $H(z)$ is BIBO stable, it follows that the steady-state output is

$$y_{ss}(k) = 2A(0.6\pi) \cos[0.6\pi k + \phi(0.6\pi)]$$



Magnitude Response



Phase Response