

# CHATER OUMAIMA

+33 7 78 63 30 60

oumaima.chaterconnect@gmail.com

oumaima-chater

Ouma487

## EDUCATION

### Centrale Supélec

Engineer in Artificial Intelligence

August 2021 – December 2024

Gif-sur-Yvette, France

- Key studies: Probability, Statistics, Optimization, Programming, Big Data, Data Science, Machine Learning, Deep Learning, NLP, Computer Vision, Game Theory, Reinforcement Learning.

### Preparatory Classes for French Grandes Écoles (CPGE)

MPSI & MP\* – Advanced Mathematics, Physics, and Engineering Sciences

September 2019 – June 2021

Rabat, Morocco

- Intensive program focused on advanced mathematics, physics, chemistry, and problem-solving for competitive engineering school entrance.

## WORK EXPERIENCE

### Libertify

Junior AI Engineer

December 2024 – Present

Paris, France

- Redesigned a scalable Retrieval-Augmented Generation (RAG) architecture for document and video content.
- Built multimodal RAG systems and AI agents for automating analysis and media workflows.
- Automated background removal and implemented robust testing for production stability.

### Renault

AI Engineer Intern

May 2024 – November 2024

Guyancourt, France

- Built predictive models for recurring vehicle defects using diagnostic data.
- Applied prompt engineering and LLMs to optimize RFP responses.
- Collaborated with engineering teams to deploy AI tools in production.

## PROJECTS

### Genvia – Predictive Manufacturing | ML, Reliability, VAE, UDA

October 2023 – April 2024

- Digitized manufacturing orders and processes, saving **160+** hours.
- Applied Variational Autoencoders and Domain Adaptation to predict hydrogen electrolyzer failures (**90.8%** accuracy).
- Awarded **Prix de l'Innovation Dzung Tran** for innovation and impact.

### Emotion Recognition | AI, Computer Vision, Audio Processing

February 2024

- Built a deep learning system for facial and audio emotion detection using CNNs and LSTMs.
- Achieved 90.3% image accuracy and 75.8% audio accuracy.

### Multi-Agent Robot Mission Planning | Simulation, Optimization, MAS

March 2024

- Simulated autonomous robots cleaning radioactive waste across 3 zones with constrained mobility and waste conversion rules.
- Developed two strategies: (1) random non-communicating agents, and (2) hierarchical agents with communication and target assignment.
- Achieved **100% task completion** and reduced steps by 3.5× in all 40 runs with communication vs. 60% without.

## TECHNICAL SKILLS

**Programming Languages:** Python, C++

**Data Visualization:** Power BI, Seaborn, Matplotlib, Excel

**Big Data Management:** SQL, Neo4j, PostgreSQL, MongoDB

**Mathematical & Machine Learning Tools:** Matlab, Sage, Scikit-Learn, TensorFlow, PyTorch, Pandas, NumPy, SciPy

## LANGUAGES

**Arabic:** Native

**French:** Bilingual Proficiency

**English:** Full Professional Proficiency