

## Session 8

To follow up with the establishment of the base, the size and the first stretch of arm. I ran the pre-modeled forearm print and forearm gripper linkage.

The shape of the gripper is still being modeled.

During this time, I aimed the servomotors at their locations, as well as the plastic rudders.

Then while wanting to test the servomotors one by one in search of a defective servomotor, my laptop broke down.

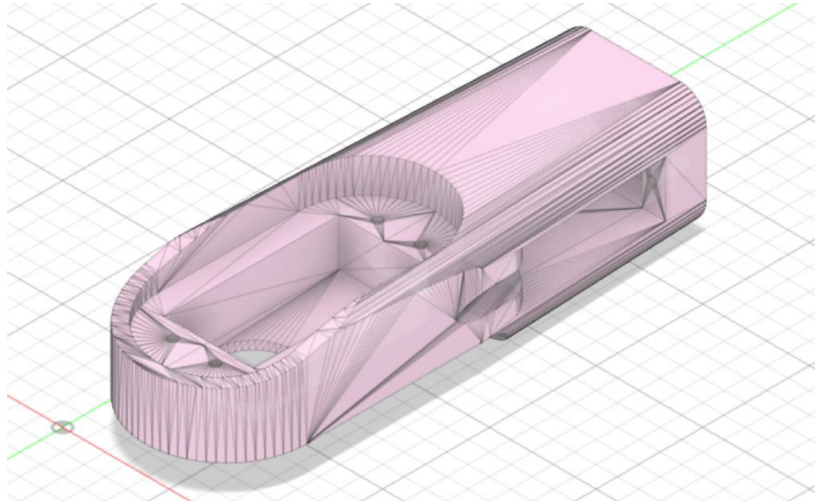


Fig 1 Arm 3

Arm 3: With a space provided for two servomotors, one linked to arm 2 and the other to the gripper.

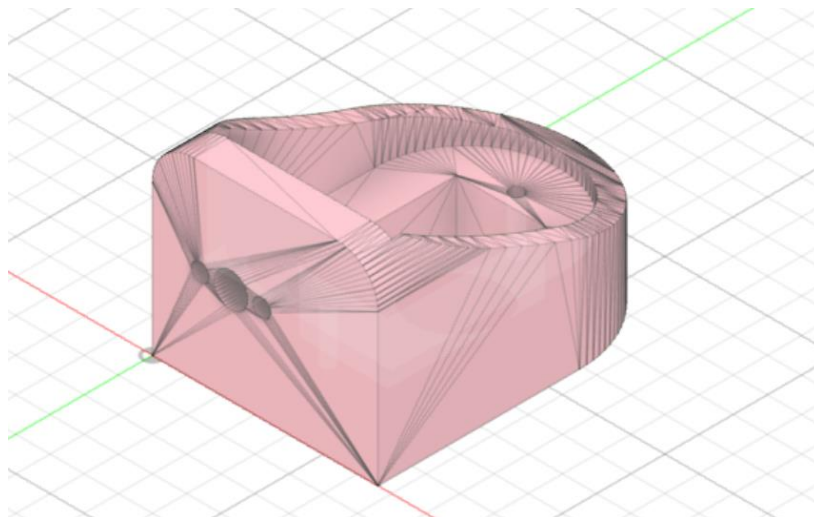


Fig 2 Gripper Arm

Gripper arm : with a space provided for two servomotors, one linked to arm 3 and the second linked with the clamp.