## PATH-DEPENDENT VOLATILITY

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## 1. THE 2-FACTOR MARKOVIAN PDV MODEL

For  $t \in [0, T]$ , the 2-f PDV reads :

$$dS_{t} = S_{t}\sigma(R_{1,t}, R_{2,t}) dW_{t}$$

$$dR_{1,t} = -\lambda_{1}R_{1,t} dt + \lambda_{1}\sigma(R_{1,t}, R_{2,t}) dW_{t}$$

$$dR_{2,t} = \lambda_{2} \left(\sigma(R_{1,t}, R_{2,t})^{2} - R_{2,t}\right) dt$$

s.t  $\sigma: (R_1, R_2) \mapsto \beta_0 + \beta_1 R_1 + \beta_2 \sqrt{R_2}$ .

Let  $X := (S, R_1, R_2)^{\top}$  be our state process. Then, X is a markovian-diffusion with dynamics:

$$dX_{t} = \mu(t, X_{t}) dt + \delta(t, X_{t}) dW_{t}$$

with, for  $(t, x) = (t, (S, R_1, R_2)) \in [0, T] \times \mathbb{R}^3$ :

$$\mu(t,x) := \begin{pmatrix} 0 \\ -\lambda_1 R_1 \\ \lambda_2 \left(\sigma \left(R_1, R_2\right)^2 - R_2\right) \end{pmatrix}, \quad \delta(t,x) = \begin{pmatrix} S\sigma \left(R_1, R_2\right) & 0 & 0 \\ 0 & \lambda_1 \sigma \left(R_1, R_2\right) & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

The infinitesimal generator of X, denoted by  $\mathcal{L}^X$ , is defined for  $u \in \mathcal{C}_c^{1,2}((0,T) \times \mathbb{R}^3)$  by

$$\mathcal{L}^X u := -\left(\lambda_1 R_1 \partial_{R_1} u + \lambda_2 R_2 \partial_{R_2} u\right) + \lambda_2 \sigma^2 \partial_{R_2} u + \frac{\sigma^2}{2} \left(S^2 \partial_{S,S}^2 u + \lambda_1^2 \partial_{R_1,R_1}^2 u\right)$$

The dynamics of the vol reads:

 $=\kappa(t,(S_u)_{u\leq t},(\sigma_u)_{u\leq t})$  jointly path-dependent drift  $\Rightarrow$  strong Zumbach effect

$$d\sigma_{t} = \underbrace{\left(-\beta_{1}\lambda_{1}R_{1,t} + \frac{\beta_{2}\lambda_{2}}{2}\frac{\sigma_{t}^{2} - R_{2,t}}{\sqrt{R_{2,t}}}\right)}_{\text{vol clustering}} dt + \underbrace{\frac{\beta_{1}\lambda_{1}}{\sum_{\text{vol of vol constant}}} \sigma_{t} dW_{t}}_{\text{vol of vol constant}}$$

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