

# **ang\_mom.py**

## Angular Momentum Matrices

### Cartesian Components $J_x, J_y, J_z$

ElecSus Library Documentation

### **Abstract**

This document provides comprehensive documentation for `ang_mom.py`, which constructs the matrix representations of angular momentum operators in Cartesian coordinates. These matrices are essential for computing fine structure, hyperfine structure, and Zeeman interactions in atomic physics calculations.

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# 1 Theoretical Foundation

## 1.1 Angular Momentum in Quantum Mechanics

**Axiom 1** (Hermiticity of Observables). *Physical observables correspond to Hermitian operators. The angular momentum components  $J_x$ ,  $J_y$ ,  $J_z$  satisfy:*

$$J_i^\dagger = J_i \quad (1)$$

**Theorem 1** (Ladder Operator Decomposition). *The Cartesian angular momentum components can be expressed in terms of ladder operators:*

$$J_x = \frac{1}{2}(J_+ + J_-) \quad (2)$$

$$J_y = \frac{1}{2i}(J_+ - J_-) = -\frac{i}{2}(J_+ - J_-) \quad (3)$$

$$J_z = \frac{1}{2}[J_+, J_-]_- = \frac{1}{2}(J_+ J_- - J_- J_+) \quad (4)$$

where  $J_\pm = J_x \pm iJ_y$ .

*Proof.* From  $J_+ = J_x + iJ_y$  and  $J_- = J_x - iJ_y$ :

$$J_+ + J_- = 2J_x \implies J_x = \frac{1}{2}(J_+ + J_-) \quad (5)$$

$$J_+ - J_- = 2iJ_y \implies J_y = \frac{1}{2i}(J_+ - J_-) \quad (6)$$

For  $J_z$ , use  $[J_+, J_-] = 2\hbar J_z$  (in units  $\hbar = 1$ ). □

**Definition 1** (Adjoint Relationship). *The lowering operator is the Hermitian adjoint of the raising operator:*

$$J_- = J_+^\dagger \quad (7)$$

For real matrix representations, this reduces to the transpose:  $J_- = J_+^T$ .

**Corollary 1** (Hermiticity Verification). *Using  $J_- = J_+^\dagger$ :*

$$J_x^\dagger = \frac{1}{2}(J_+^\dagger + J_-^\dagger) = \frac{1}{2}(J_- + J_+) = J_x \quad (8)$$

$$J_y^\dagger = \frac{i}{2}(J_+^\dagger - J_-^\dagger) = \frac{i}{2}(J_- - J_+) = J_y \quad (9)$$

confirming  $J_x$  and  $J_y$  are Hermitian.

## 2 Line-by-Line Code Analysis

### 2.1 Module Imports

```
1 from numpy import transpose, dot
2 import ang_mom_p
```

*Import NumPy's transpose and dot product, plus the ladder operator module.*

## 2.2 The $J_x$ Function

```

1 def jx(jj):
2     jp=ang_mom_p.jp(jj)
3     jm=transpose(jp)
4     jx=0.5*(jp+jm)
5     return jx

```

$$J_x = \frac{1}{2}(J_+ + J_-) \quad (10)$$

Construct  $J_x$  from the symmetric combination of ladder operators. The transpose gives  $J_- = J_+^T$  since  $J_+$  is real.

## 2.3 The $J_y$ Function

```

1 def jy(jj):
2     jp=ang_mom_p.jp(jj)
3     jm=transpose(jp)
4     jy=0.5j*(jm-jp)
5     return jy

```

$$J_y = \frac{i}{2}(J_- - J_+) = -\frac{i}{2}(J_+ - J_-) \quad (11)$$

The antisymmetric combination with factor  $i/2$  yields a Hermitian matrix. Note the sign convention:  $J_y = 0.5j \cdot (J_- - J_+)$ .

## 2.4 The $J_z$ Function

```

1 def jz(jj):
2     jp=ang_mom_p.jp(jj)
3     jm=transpose(jp)
4     jz=0.5*(dot(jp,jm)-dot(jm,jp))
5     return jz

```

$$J_z = \frac{1}{2}(J_+J_- - J_-J_+) = \frac{1}{2}[J_+, J_-] \quad (12)$$

The commutator of ladder operators gives the  $z$ -component. This yields a diagonal matrix with eigenvalues  $m = j, j-1, \dots, -j$ .

## 3 Mathematical Properties

### 3.1 Matrix Structure

**Theorem 2** (Matrix Forms). For angular momentum  $j$ :

- $J_z$ : Diagonal with entries  $\{j, j-1, \dots, -j\}$
- $J_x$ : Real symmetric, tri-diagonal
- $J_y$ : Purely imaginary antisymmetric (Hermitian), tri-diagonal

### 3.2 Spin-1/2 Example

For  $j = 1/2$ , the Pauli matrix representation (in units  $\hbar = 1$ ):

$$J_x = \frac{1}{2}\sigma_x = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad (13)$$

$$J_y = \frac{1}{2}\sigma_y = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad (14)$$

$$J_z = \frac{1}{2}\sigma_z = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad (15)$$

### 3.3 Verification of Commutation Relations

The constructed matrices satisfy:

$$[J_x, J_y] = iJ_z, \quad [J_y, J_z] = iJ_x, \quad [J_z, J_x] = iJ_y \quad (16)$$

(in units where  $\hbar = 1$ ).

## 4 Applications in ElecSus

### 4.1 Fine Structure Interaction

The spin-orbit coupling uses:

$$H_{FS} = A_{FS}\vec{L} \cdot \vec{S} = A_{FS}(L_xS_x + L_yS_y + L_zS_z) \quad (17)$$

### 4.2 Hyperfine Structure

The magnetic dipole hyperfine interaction:

$$H_{HFS} = A_{HFS}\vec{I} \cdot \vec{J} = A_{HFS}(I_xJ_x + I_yJ_y + I_zJ_z) \quad (18)$$

### 4.3 Zeeman Interaction

The magnetic field coupling:

$$H_Z = \mu_B B_z(g_L L_z + g_S S_z + g_I I_z) \quad (19)$$

uses the  $z$ -components directly for fields along  $\hat{z}$ .

## 5 Numerical Verification

### 5.1 Total Angular Momentum Squared

The identity  $J^2 = j(j+1)\mathbb{1}$  can verify correctness:

$$J^2 = J_x^2 + J_y^2 + J_z^2 = j(j+1)\mathbb{1}_{(2j+1) \times (2j+1)} \quad (20)$$

### 5.2 Eigenvalue Check

$J_z$  should have eigenvalues  $\{j, j-1, \dots, -j\}$  appearing on the diagonal in descending order.

## 6 Summary

The `ang_mom.py` module provides:

1. `jx(j)`: Returns  $(2j + 1) \times (2j + 1)$  matrix for  $J_x$
2. `jy(j)`: Returns  $(2j + 1) \times (2j + 1)$  matrix for  $J_y$
3. `jz(j)`: Returns  $(2j + 1) \times (2j + 1)$  matrix for  $J_z$

Key features:

- Uses ladder operator construction for numerical stability
- Works for any half-integer or integer  $j$
- Matrices satisfy SU(2) algebra
- Called by `fs_hfs.py` and `sz_lsi.py` for building atomic Hamiltonians