

# **Nanorobotics Based Thrombolysis : Dissolving blood clot using nanorobots**

**Presented by : Mohammed Shaheer V K**

**S7G**

**CHN19AE015**

**Guide**

**:Mrs. Anupama A**

**Department of Electronics Engineering**  
College of Engineering Chengannur



# Content

- **Problem Statement**
- **Introduction**
  - ▣ **Nanotechnology**
  - ▣ **Nanorobotics**
  - ▣ **Nanorobot**
  - ▣ **Thrombolysis**
- **Nanorobotics for Thrombolysis**
  - ▣ **Medications for thrombolysis**
- **Procedure**
  - ▣ **Stages of action**
- **Conclusion and future scope**
- **Pros and cons**
- **References**
- **Thank you**
- **Questions**

# Problem Statement

---

Inaccessible blood clots at deeper part of body, increasing fatality rates in patients.

**"Nanotechnology in medicine is going to have a major impact on the survival of the human race."**

**-Bernard Marcus**

# **INTRODUCTION**

## **NANO TECHNOLOGY**

**-Norio Taniguchi-1974**

# Introduction

---

What is nano technology?



# Nanorobot

---

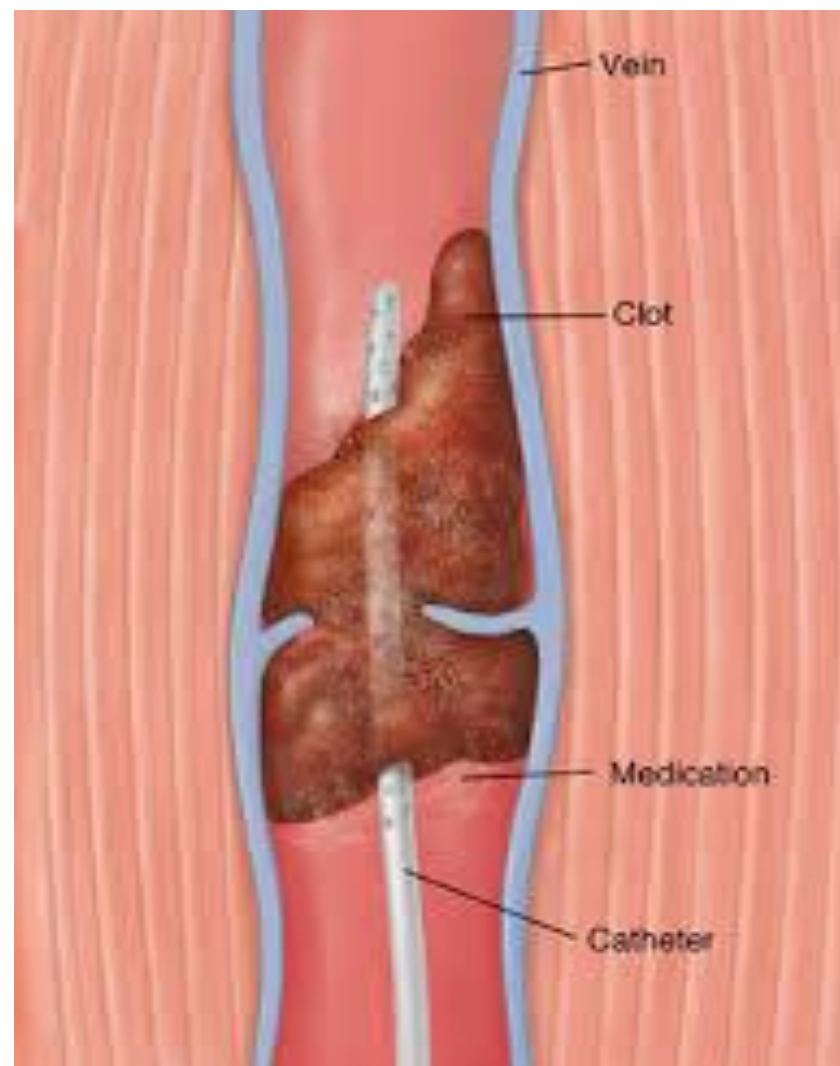
- A nanorobot is 50-100nm sized small robot developed to carry out specific functions

# Thrombolysis

---

What is blood clot?

Thrombolysis treatment for blood clot







10000000

10 million cases of VTE occur annually across the globe

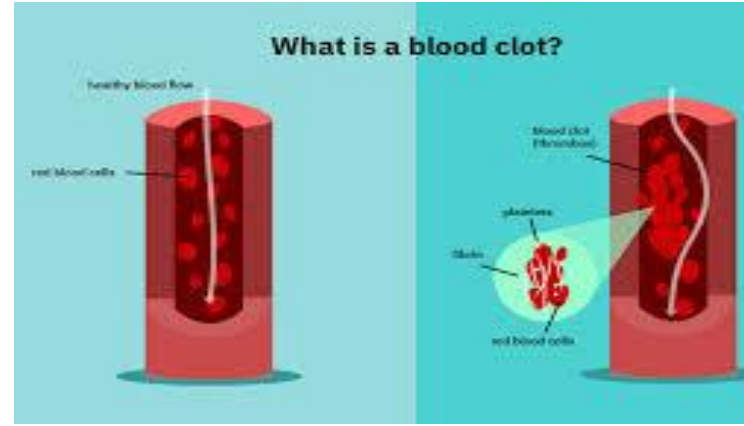
# Nano Robotics For Thrombolysis

---

- Blood clots in deep arteries or veins, narrow internal sections of brain are accessed for treatment using nanorobots

# Medications for Removing blood Clot

- Streptokinase.
- Alteplase.
- Reteplase.
- Tenecteplase.
- Urokinase.
- Prourokinase.
- Anistreplase(APSAC)

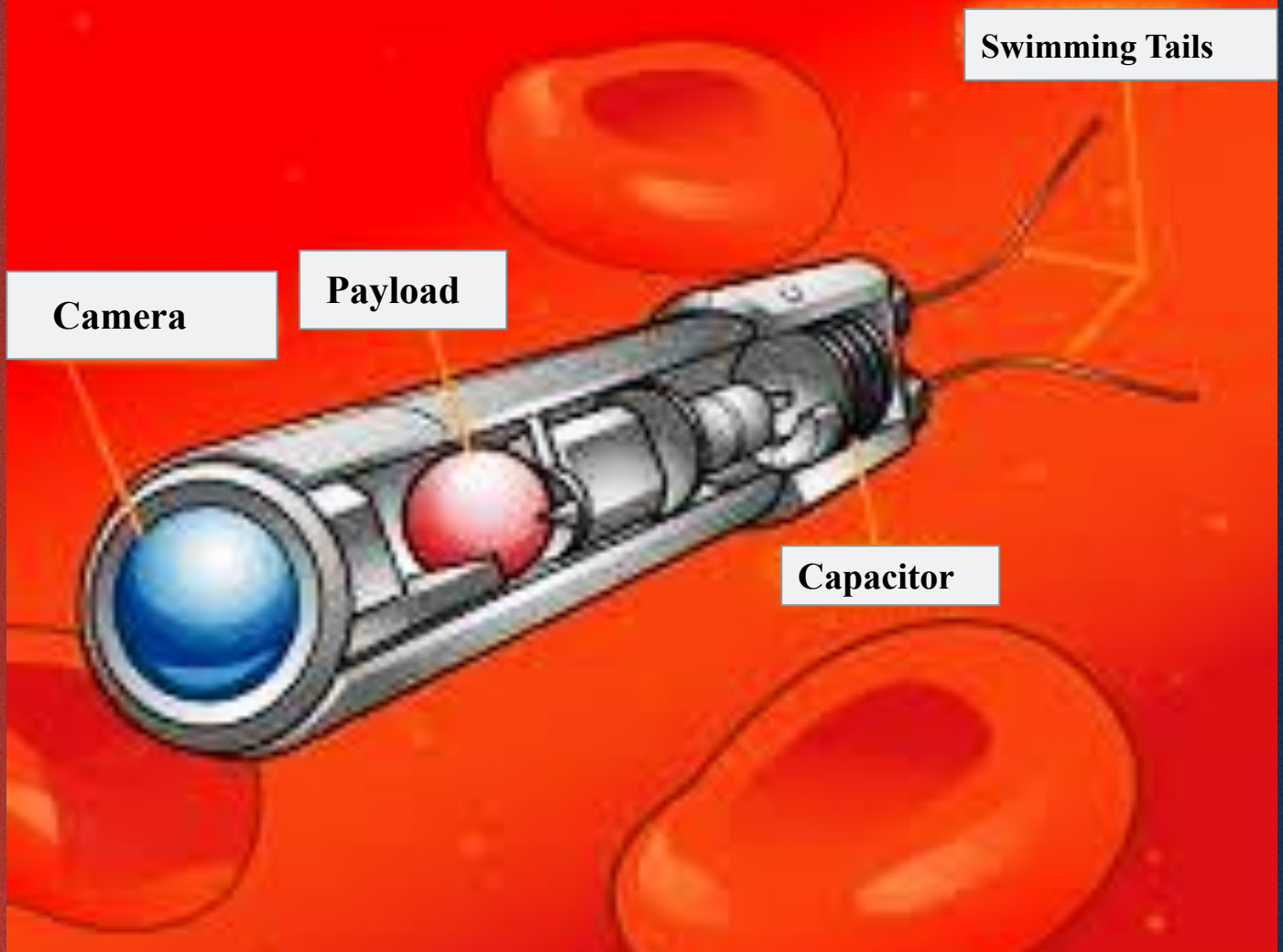


# Medicines used for Thrombolysis

---

- tissue plasminogen activator (tPA)
- TNKase (tenecteplase)
- Urokinase

# Nanorobot

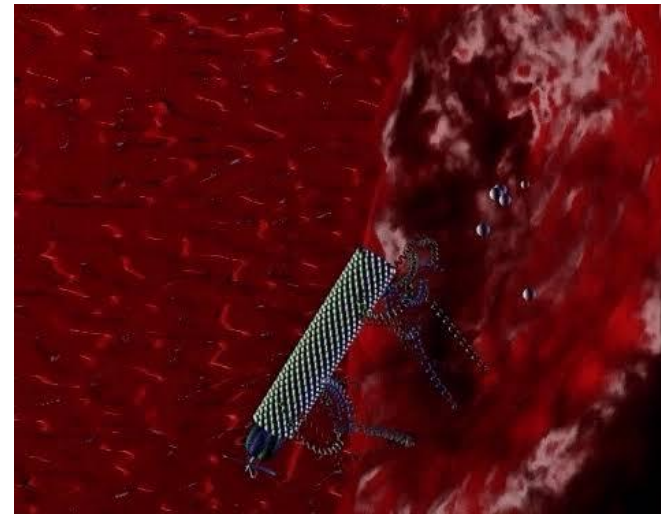
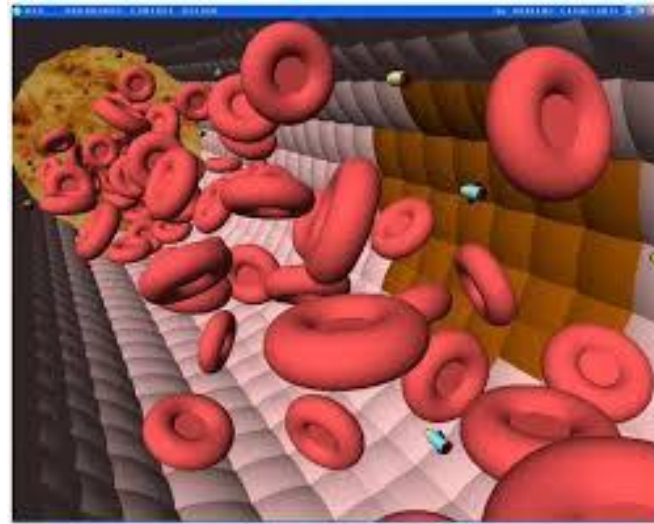


# Procedure

---

Swarms of nanorobots with medications are passed to the destinations area

It consists of 3 stages.



# Procedure



## Stage 1

Injecting nanorobots  
via veins

## Stage 2

Movement of nanorobots via  
bloodstream to area of action

Controlling via  
ultrasonic/electromagnetic field

## Stage 3

Location of treatment area  
via chemical changes

Distribution of medicine

# Pros and Cons

---

## Pros

- Faster healing
- Quick action
- Precise
- Low chance of failure

## Cons

- Chance for misuse
- Security issue
- Malfunction
- Underdevelopment



# Conclusion And Future Scope

---

Advancement of medical science as well as breakthroughs in nanotechnology now is becoming a reality for nanorobotic treatment of different human diseases and conditions.

Introducing nanorobots and image processing to autonomously remove blood clots without any medications.

# Reference

---

P. Malhotra and N. Shahdadpuri, "Nano-robotic based Thrombolysis: Dissolving Blood Clots using Nanobots," 2020 IEEE 17th India Council International Conference (INDICON), 2020, pp. 1-4, doi: 10.1109/INDICON49873.2020.9342510.

Akita, S., Nakayama, Y., 2002, "Manipulation of nanomaterial by carbon nanotube nanotweezers in scanning probe microscope," Japanese Journal of Applied Physics, Vol. 41, Part 1, No. 6B, pp. 4242-4245.

individual carbon nanotubes through nanorobotic manipulations and its applications," Proceedings of the IEEE International Conference on Robotics and Automation, New Orleans, LA, pp. 440-445.

# Thanks!



**Any questions?**



# Reference

---

Akita, S., Nakayama, Y., 2002, "Manipulation of nanomaterial by carbon nanotube nanotweezers in scanning probe microscope," Japanese Journal of Applied Physics, Vol. 41, Part 1, No. 6B, pp. 4242-4245.

individual carbon nanotubes through nanorobotic manipulations and its applications," Proceedings of the IEEE International Conference on Robotics and Automation, New Orleans, LA, pp. 440-445.

.

# Reference



individual carbon nanotubes through nanorobotic manipulations and its applications,” Proceedings of the IEEE International Conference on Robotics and Automation, New Orleans, LA, pp. 440-445.

Arai, F., Nakajima, M., Dong, L., Fukuda, T., 2002, “Force measurement with pico-Newton order resolution using a carbon nanotube probe,” International Symposium on Micromechatronics and Human Science, pp. 105-110.

Arai, F., Nakajima, M., Dong, L., Fukuda, T., 2003a, “Pico-Newton order force measurement using a calibrated carbon nanotube probe by electromechanical resonance,” Proceedings of the 2003 IEEE International Conference on Robotics and Automation, Taipei, Taiwan, pp. 300-305.