

# CECS 229 Programming Assignment #4

## Due Date:

Sunday, 3/24 @ 11:59 PM

## Submission Instructions:

Complete the programming problems in the file named `pa4.py`. You may test your implementation on your Repl.it workspace by running `main.py`. When you are satisfied with your implementation,

1. Submit your Repl.it workspace
2. Download the file `pa4.py` and submit it to the appropriate CodePost auto-grader folder.

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## Objectives:

1. Apply vector operations to translate, scale, and rotate a set of points representing an image.
2. Perform various operations with or on vectors: addition, subtraction, dot product, norm.

## NOTES:

1. Unless otherwise stated in the FIXME comment, you may not change the outline of the algorithm provided by introducing new loops or conditionals, or by calling any built-in functions that perform the entire algorithm or replaces a part of the algorithm.
2. You may import and use the Python `math` module to obtain the value for  $e$  and to calculate sine, cosine, and tangent functions, if needed.

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## Problem 1:

Create a function `translate(S, z0)` that translates the points in the input set  $S$  by  $z_0 = a_0 + b_0i$ . The function should satisfy the following:

1. INPUT:
  - `S` - set  $S$
  - `z0` - complex number
2. OUT:
  - `T` - set  $T$  consisting of points in  $S$  translated by  $z_0$

```
In [ ]: def translate(S, z0):  
        """  
        translates the complex numbers of set S by z0  
        :param S: set type; a set of complex numbers  
        :param z0: complex type; a complex number
```

```

:return: set type; a set consisting of points in S translated by z0
"""

# FIXME: Implement this function
# FIXME: Return correct output
return None

```

## Problem 2:

Create a function `scale(S, k)` that scales the points in the input set  $S$  by a factor of  $k$ :

### 1. INPUT:

- `S` - set  $S$
- `k` - positive float, raises `ValueError` if  $k \leq 0$ .

### 2. OUTPUT:

- a set consisting of points in  $S$  scaled by  $k$ .

```

In [ ]: def scale(S, k):
        """
        scales the complex numbers of set S by k.
        :param S: set type; a set of complex numbers
        :param k: float type; positive real number
        :return: set type; a set consisting of points in S scaled by k
        :raise: raises ValueError if k <= 0
        """

        # FIXME: Implement this function.
        # FIXME: Return correct output
        return None

```

## Problem 3:

Create a function `rotate(S, tau)` that rotates the points in the input set  $S$  by  $\tau$  radians:

### 1. INPUT:

- `S` - set  $S$
- `tau` - float. If negative, the rotation is clockwise. If positive the rotation is counterclockwise. If zero, no rotation.

### 2. OUT:

- a set consisting of points in  $S$  rotated by  $\tau$

```

In [ ]: def rotate(S, tau):
        """
        rotates the complex numbers of set S by tau radians.
        :param S: set type; - set of complex numbers
        :param tau: float type; radian measure of the rotation value. If negative, the rot
                    If positive the rotation is counterclockwise. If zero, no rotation.
        :returns: set type; a set consisting of points in S rotated by tau radians
        """

        # FIXME: Implement this function.
        # FIXME: Return correct output
        return None

```

## Problem 4:

Finish the implementation of class `Vec` which instantiates row-vector objects with defined operations of addition, subtraction, scalar multiplication, and dot product. In addition, `Vec` class overloads the Python built-in function `abs()` so that when it is called on a `Vec` object, it returns the Euclidean norm of the vector.

```
In [ ]: class Vec:
    def __init__(self, contents = []):
        """
        Constructor defaults to empty vector
        INPUT: list of elements to initialize a vector object, defaults to empty list
        """
        self.elements = contents
        return

    def __abs__(self):
        """
        Overloads the built-in function abs(v)
        :returns: float type; the Euclidean norm of vector v
        """
        # FIXME: Implement this method
        # FIXME: Return correct output
        return None

    def __add__(self, other):
        """
        overloads the + operator to support Vec + Vec
        :raises: ValueError if vectors are not same length
        :returns: Vec type; a Vec object that is the sum vector of this Vec and 'other'
        """
        # FIXME: Finish the implementation
        # FIXME: Return correct output
        return None

    def __sub__(self, other):
        """
        overloads the - operator to support Vec - Vec
        :raises: ValueError if vectors are not same length
        :returns: Vec type; a Vec object that is the difference vector of this Vec and
        """
        # FIXME: Finish the implementation
        # FIXME: Return correct output
        return None

    def __mul__(self, other):
        """
        Overloads the * operator to support
        - Vec * Vec (dot product) raises ValueError if vectors are not
          same length in the case of dot product; returns scalar
        - Vec * float (component-wise product); returns Vec object
        - Vec * int (component-wise product); returns Vec object
        """
```

```
if type(other) == Vec: #define dot product
    # FIXME: Complete the implementation
    # FIXME: Return the correct output
    return None

elif type(other) == float or type(other) == int: #scalar-vector multiplication
    # FIXME: Complete the implementation
    # FIXME: Return the correct output
    return None

def __rmul__(self, other):
    """Overloads the * operation to support
    - float * Vec; returns Vec object
    - int * Vec; returns Vec object
    """
    # FIXME: Complete the implementation
    # FIXME: Return the correct output
    return None

def __str__(self):
    """returns string representation of this Vec object"""
    return str(self.elements) # does NOT need further implementation
```