Problem 4

```
In [ ]: import torch
        from torch import Tensor, tensor
        import torch.optim as optim
        import torch.nn as nn
        from torch.utils.data import Dataset, TensorDataset, DataLoader
        import numpy as np
        import seaborn as sns
         import matplotlib.pyplot as plt
In [ ]: batch_size = 64
        learning_rate = 5e-4
        num_epochs = 2000
        reg\_coeff = 500
        device = "cuda:0" if torch.cuda.is_available() else "cpu"
In [ ]: def make_swiss_roll(n_samples=2000, noise = 1.0, dimension = 2, a = 20, b = 5):
            Generate 2D swiss roll dataset
            t = 2 * np.pi * np.sqrt(np.random.uniform(0.25,4,n_samples))
            X = 0.1 * t * np.cos(t)
            Y = 0.1 * t * np.sin(t)
            errors = 0.025 * np.random.multivariate_normal(np.zeros(2), np.eye(dimension),
            X += errors[:, 0]
            Y += errors[:, 1]
            return np.stack((X, Y)).T
        def show_data(data, title):
            Plot the data distribution
            sns.set(rc={'axes.facecolor': 'honeydew', 'figure.figsize': (5.0, 5.0)})
            plt.figure(figsize = (5, 5))
            plt.rc('text', usetex = False)
            plt.rc('font', family = 'serif')
            plt.rc('font', size = 10)
            g = sns.kdeplot(x=data[:, 0], y=data[:, 1], fill=True, thresh=0.1, levels=1000
            g.grid(False)
            plt.margins(0, 0)
            plt.xlim(-1.5, 1.5)
            plt.ylim(-1.5, 1.5)
            plt.title(title)
            plt.show()
In [ ]: class SwissRollDataset(Dataset) :
            def __init__(self, data) :
                super().__init__()
                self.data = torch.from_numpy(data)
                self.data = self.data.to(dtype=torch.float)
            def __len__(self) :
                return len(self.data)
```

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def __getitem__(self, idx) :
    return self.data[idx]

data = make_swiss_roll()
dataset = SwissRollDataset(data)
loader = DataLoader(dataset, batch_size = batch_size, shuffle = True)
```

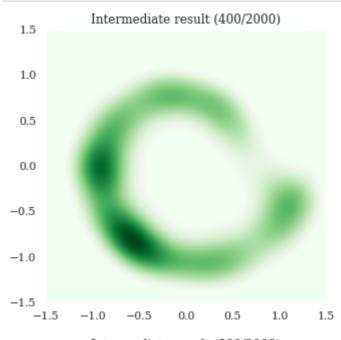
Similar to problem 3, define generator, discriminator, and variables.

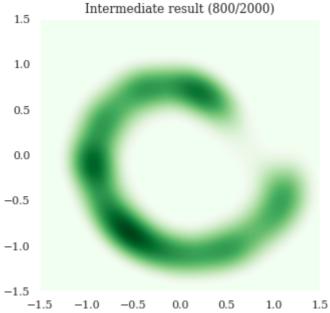
```
In [ ]: z_{dim} = 100
        class Generator(nn.Module):
            def __init__(self, input_dim = z_dim, output_dim = 2):
                super().__init__()
                self.network = nn.Sequential(nn.Linear(input_dim, 32),
                                              nn.Tanh(),
                                              nn.Linear(32,output_dim))
            def forward(self, x):
                return self.network(x)
        class Discriminator(nn.Module):
            def __init__(self, input_dim = 2):
                super().__init__()
                self.network = nn.Sequential(nn.Linear(input_dim, 128),
                                              nn.Tanh(),
                                              nn.Linear(128,128),
                                              nn. Tanh(),
                                              nn.Linear(128,1),
                                              nn.Sigmoid())
            def forward(self.x):
                return self.network(x)
        gen = Generator().to(device)
        dis = Discriminator().to(device)
        gen_optimizer = optim.Adam(gen.parameters(), Ir=learning_rate)
        dis_optimizer = optim.Adam(dis.parameters(), Ir=learning_rate)
```

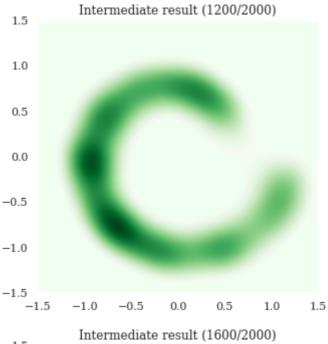
Next we train models.

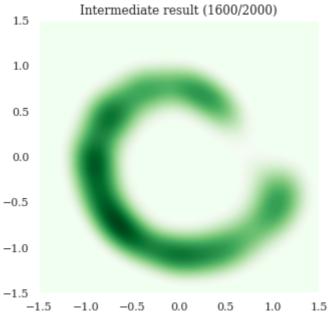
```
In [ ]: |
        for epoch in range(1,num_epochs):
             for batch_idx, x in enumerate(loader):
                x = x.detach().to(device)
                D_{real\_loss} = torch.mean(torch.log(dis(x)))
                z = torch.randn(batch_size, z_dim).to(device)
                D_fake_loss = torch.mean(torch.log(1-dis(gen(z))))
                D_loss = - D_real_loss - D_fake_loss
                dis.zero_grad()
                D_loss.backward()
                dis_optimizer.step()
                 z = torch.randn(batch_size, z_dim).to(device)
                G_{loss} = -torch.mean(torch.log(dis(gen(z))))
                 gen.zero_grad()
                 G_loss.backward()
                gen_optimizer.step()
```

```
if epoch % (num_epochs // 5) == 0:
    z = torch.randn(2000, z_dim).to(device)
    image = gen(z).detach().cpu().numpy()
    show_data(image, f"Intermediate result ({epoch}/{num_epochs})")
```









Unlike we expected, not entire roll shape is constructed. This may becomes input dimension of generator $z_{\rm dim}$ is not enoughly large.

Below is final result.

```
In [ ]: z = torch.randn(2000, z_dim).to(device)
  image = gen(z).detach().cpu().numpy()
  show_data(image, f"Final result")
```

