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Problem 3

As usual, import necessary modules, and variables.

```
In [ ]: import torch
                            import torch.nn as nn
                            import torch.nn.functional as F
                            import torchvision
                             from torchvision import datasets, transforms
                            from torchvision.utils import save_image, make_grid
                            import numpy as np
                            import matplotlib.pyplot as plt
                            import warnings
                            warnings.filterwarnings('ignore')
                            batch\_size = 128
                            (full\_dim, mid\_dim, hidden) = (1 * 28 * 28, 1000, 5)
                            Ir = 1e-3
                            epochs = 100
                            device = torch.device("cpu")
       In [ ]: class Logistic(torch.distributions.Distribution):
                                     def __init__(self):
                                               super(Logistic, self).__init__()
                                      def log_prob(self, x):
                                               return -(F.softplus(x) + F.softplus(-x))
                                      def sample(self, size):
                                               z = torch.distributions.Uniform(0., 1.).sample(size).to(device)
                                               return torch. log(z) - torch. log(1. - z)
                            class Coupling(nn.Module):
                                      def __init__(self, in_out_dim, mid_dim, hidden, mask_config):
                                               super(Coupling, self).__init__()
                                               self.mask_config = mask_config
                                               self.in_block = nn.Sequential(nn.Linear(in_out_dim//2, mid_dim), nn.ReLU())
                                               self.mid_block = nn.ModuleList([nn.Sequential(nn.Linear(mid_dim, mid_dim), national content in the self.mid_dim in the self.
                                                                                                                                                                                      for _ in range(hide
                                               self.out_block = nn.Linear(mid_dim, in_out_dim//2)
                                      def forward(self, x, reverse=False):
                                               [B, W] = list(x.size())
                                               x = x.reshape((B, W//2, 2))
                                               if self.mask_config:
                                                        on, off = x[:, :, 0], x[:, :, 1]
                                               else:
                                                        off, on = x[:, :, 0], x[:, :, 1]
                                               off_ = self.in_block(off)
                                               for i in range(len(self.mid_block)):
                                                        off_ = self.mid_block[i](off_)
                                               shift = self.out_block(off_)
                                               if reverse:
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```

```
on = on + shift
        if self.mask_config:
           x = torch.stack((on, off), dim=2)
       else:
           x = torch.stack((off, on), dim=2)
       return x.reshape((B, W))
class Scaling(nn.Module):
   def __init__(self, dim):
       super(Scaling, self).__init__()
       self.scale = nn.Parameter(torch.zeros((1, dim)), requires_grad=True)
   def forward(self, x, reverse=False):
        log_det_J = torch.sum(self.scale)
        if reverse:
           x = x * torch.exp(-self.scale)
           x = x * torch.exp(self.scale)
       return x, log_det_J
class NICE(nn.Module):
   def __init__(self,in_out_dim, mid_dim, hidden, mask_config=1.0, coupling=4):
       super(NICE, self).__init__()
       self.prior = Logistic()
       self.in_out_dim = in_out_dim
       self.coupling = nn.ModuleList([
           Coupling(in_out_dim=in_out_dim,
                    mid_dim=mid_dim,
                    hidden=hidden.
                    mask_config=(mask_config+i)%2) ₩
           for i in range(coupling)])
       self.scaling = Scaling(in_out_dim)
   def g(self, z):
       x, _ = self.scaling(z, reverse=True)
        for i in reversed(range(len(self.coupling))):
           x = self.coupling[i](x, reverse=True)
       return x
   def f(self, x):
        for i in range(len(self.coupling)):
           x = self.coupling[i](x)
       z, log_det_J = self.scaling(x)
       return z, log_det_J
    def log_prob(self, x):
       z, log_det_J = self.f(x)
        log_ll = torch.sum(self.prior.log_prob(z), dim=1)
       return log_II + log_det_J
   def sample(self, size):
       z = self.prior.sample((size, self.in_out_dim)).to(device)
       return self.g(z)
   def forward(self, x):
       return self.log_prob(x)
```

```
Tn []: model = NICE(in out dim=784. mid dim=1000, hidden=5).to(device)

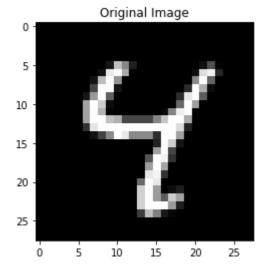
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```

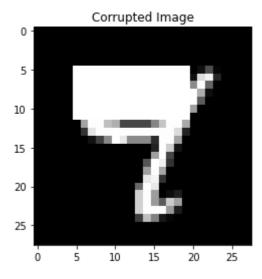
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```
model.requires_grad_(False)
```

Load dataset and define mask.

```
testset = torchvision.datasets.MNIST(root='./', train=False, download=True, transf
In [ ]:
        test_loader = torch.utils.data.DataLoader(testset, batch_size=1, shuffle=False)
        pass\_count = 6
        itr = iter(test_loader)
        for _ in range(pass_count+1):
            image,_ = itr.next()
        plt.figure(figsize = (4,4))
        plt.title('Original Image')
        plt.imshow(make_grid(image.squeeze().detach()).permute(1,2,0))
        plt.show()
        # plt.savefig('plt1.png')
        # Create mask
        mask = torch.ones_like(image,dtype=torch.bool)
        mask[:,:,5:12,5:20] = 0
        # Partially corrupt the image
        image[mask.logical_not()] = torch.ones_like(image[mask.logical_not()])
        plt.figure(figsize = (4,4))
        plt.title('Corrupted Image')
        plt.imshow(make_grid(image.squeeze()).permute(1,2,0))
        plt.show()
        # plt.savefig('plt2.png')
```





Now, we define custom inpainting of single image.

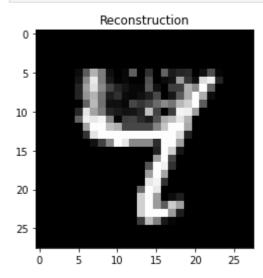
We start from corrupted image, and modifying corrupted part only (by constraints) to maximize likelihood (from NICE).

To do this, we define new module "inpaint", and set its parameter as image pixels. Since we are using projective gradient, which includes projection part after usual gradient descent, we add projecting part in our module.

```
In [ ]: class inpaint(nn.Module):
            def __init__(self, raw_image : torch.Tensor, mask : torch.Tensor):
                image: fix size (1,1,28,28) due to the mask
                1.1.1
                super().__init__()
                self.mask = mask
                self.image = raw_image.clone().requires_grad_(False)
                self.corrupted_part = nn.Parameter(raw_image.clone(), requires_grad=True)
            def forward(self, x): # x always be a mask
                image = x*self.image + x.logical_not()*self.corrupted_part
                image = image.reshape((1,28*28))
                return model(image)
            def project_gradient(self):
                weight = self.corrupted_part.data
                weight = torch.clamp(self.mask*self.image + self.mask.logical_not()*weight,
                self.corrupted_part.data = weight
        inpaint_model = inpaint(image, mask)
        inpaint_optimizer = torch.optim.SGD(params = inpaint_model.parameters(), Ir = Ir)
        for i in range(300):
            inpaint_optimizer.zero_grad()
            loss = -inpaint_model(mask)
            loss.backward()
            inpaint_optimizer.step()
            inpaint_model.project_gradient()
```

The result looks like following.

plt.show()
plt.savefig('plt3.png')



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