

# Lecture Notes for **Machine Learning in Python**



## Professor Eric Larson **Optimization Techniques for Logistic Regression Continued**

# Class Logistics and Agenda

- Agenda
  - Numerical Optimization Techniques
    - Types of Optimization
    - Programming the Optimization
- **Last Time:**
  - Logistic regression update equations
  - Line Searches
  - Stochastic small batches
  - Hessian-based methods

# Class Overview, by topic

Table Data  
Visualization

Numpy, Pandas, Seaborn  
Overviews with some in-depth discussion

Dimension  
Reduction and  
Image Processing

Scikit-learn, Scikit Image,  
Intuition only, Some mathematics

Linear and  
Logistic  
Regression

Numpy, Recreate API for Scikit-learn  
Detailed mathematics for simple optimization  
***intuition for advanced optimization***

Neural Networks  
and Back Prop.

Numpy  
Detailed mathematics for NN operations

Wide and Deep  
Networks

Convolutional  
Networks

Recurrent  
Networks

Keras, Tensorflow  
Intuition, Detailed implement.

Ethics in  
Language Models

ConceptNet  
Case studies

$$\mathbf{H}_{j,k}(\mathbf{w}) = \frac{\partial}{\partial w_k} \frac{\partial}{\partial w_j} l(\mathbf{w}) \qquad \frac{\partial}{\partial w_j} l(\mathbf{w}) = \sum_i (y^{(i)} - g(\mathbf{w}^T \cdot \mathbf{x}^{(i)})) x_j^{(i)}$$

$$\begin{aligned} \mathbf{H}_{j,k}(\mathbf{w}) &= \frac{\partial}{\partial w_k} \sum_i (y^{(i)} - g(\mathbf{w}^T \cdot \mathbf{x}^{(i)})) x_j^{(i)} \\ &= \sum_i \frac{\partial}{\partial w_k} y^{(i)} x_j^{(i)} - \sum_i \frac{\partial}{\partial w_k} g(\mathbf{w}^T \cdot \mathbf{x}^{(i)}) x_j^{(i)} \end{aligned}$$

no dependence on  $w_k$ , zero

$$= - \sum_i x_j^{(i)} \frac{\partial}{\partial w_k} g(\mathbf{w}^T \cdot \mathbf{x}^{(i)})$$

already know this as  $g(1-g)x_k$

$$\mathbf{H}_{j,k}(\mathbf{w}) = - \sum_{i=1}^M [g(\mathbf{w}^T \mathbf{x}^{(i)}) [1 - g(\mathbf{w}^T \mathbf{x}^{(i)})]] \cdot x_k^{(i)} x_j^{(i)}$$

for each  $j, k$   
pair



$$L_2 = C \sum_j w_j^2$$

penalty = 'l2'

$$L_1 = C \sum_j |w_j|$$

penalty = 'l1'

$$L_{12} = C_1 \sum_j |w_j| + C_2 \sum_j w_j^2$$

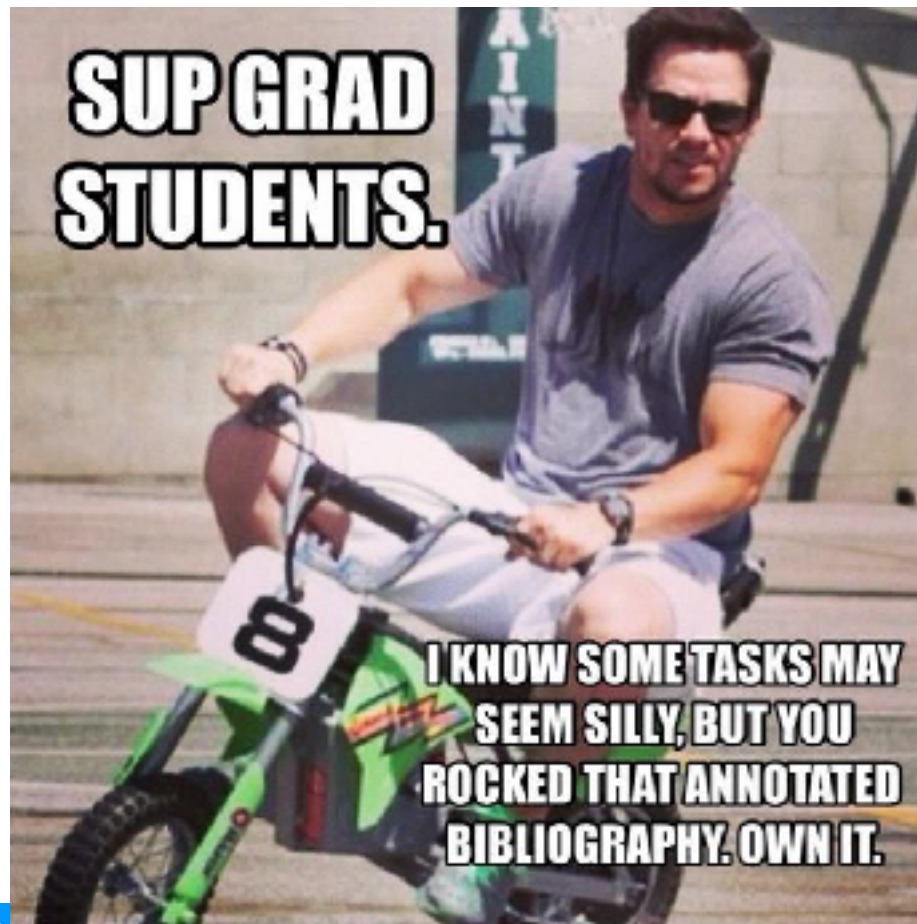
penalty = 'elasticnet'

**Warning:** The choice of the algorithm depends on the penalty chosen. Supported penalties by solver:

- 'lbfgs' - ['l2', None]
- 'liblinear' - ['l1', 'l2']
- 'newton-cg' - ['l2', None]
- 'newton-cholesky' - ['l2', None]
- 'sag' - ['l2', None]
- 'saga' - ['elasticnet', 'l1', 'l2', None]

# Scratch Paper

# Back Up Slides



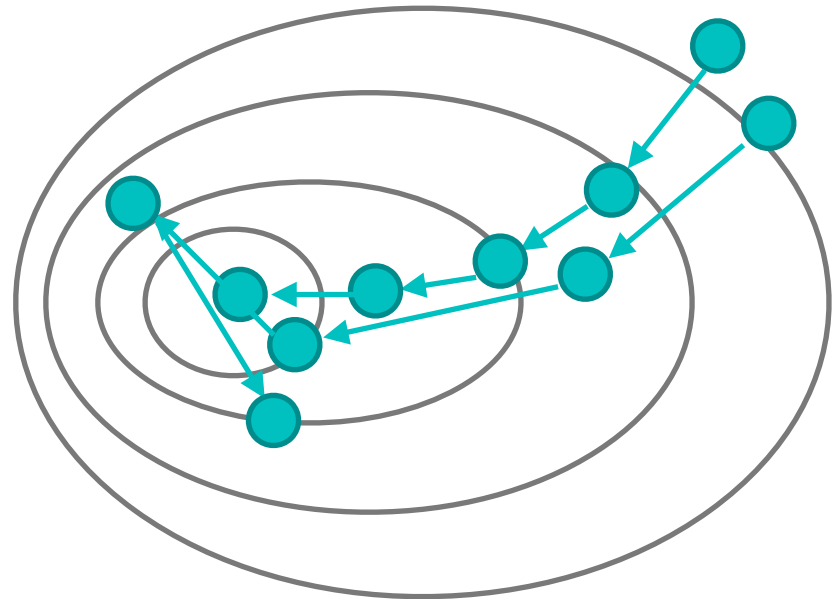


# Optimization: gradient descent

- What we know thus far:

$$\underbrace{w_j}_{\text{new value}} \leftarrow \underbrace{w_j}_{\text{old value}} + \eta \underbrace{\left[ \left( \sum_{i=1}^M (y^{(i)} - g(x^{(i)})) x_j^{(i)} \right) - C \cdot 2w_j \right]}_{\nabla l(w)}$$

$$w \leftarrow w + \eta \nabla l(w)$$

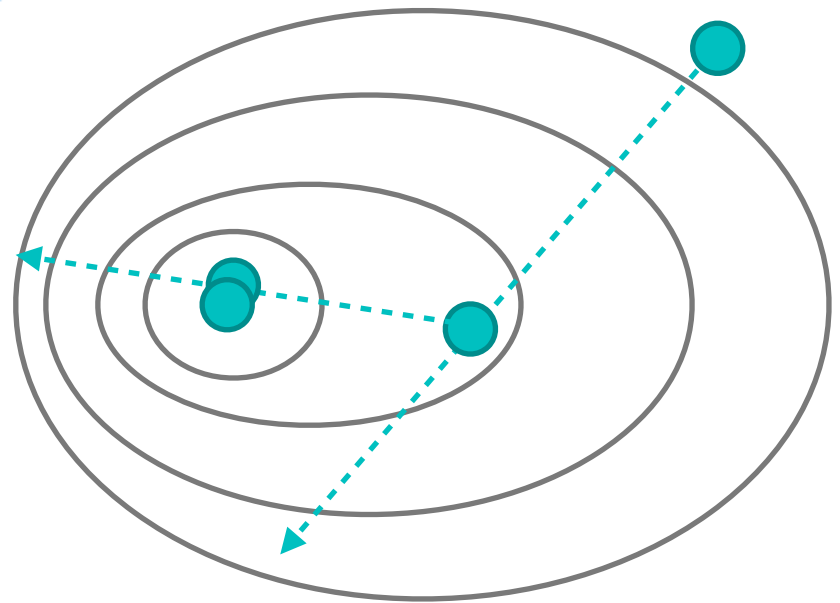


# Line Search: a better method

- Line search in direction of gradient:

$$w \leftarrow w + \eta \nabla l(w)$$

$$w \leftarrow w + \underbrace{\eta}_{\text{best step?}} \nabla l(w)$$



# Revisiting the Gradient

- How much computation is required (for gradient)?

$$\sum_{i=1}^M (y^{(i)} - \hat{y}^{(i)})x^{(i)} - 2C \cdot w$$

M = number of instances

N = number of features

**Self Test: How many multiplies  
per gradient calculation?**

- A.  $M \cdot N + 1$  multiplications
- B.  $(M + 1) \cdot N$  multiplications
- C.  $2N$  multiplications
- D.  $2N - M$  multiplications

# Stochastic Methods

- How much computation is required (for gradient)?

$$\sum_{i=1}^M (y^{(i)} - \hat{y}^{(i)})x^{(i)} - 2C \cdot w$$

**Per iteration:**

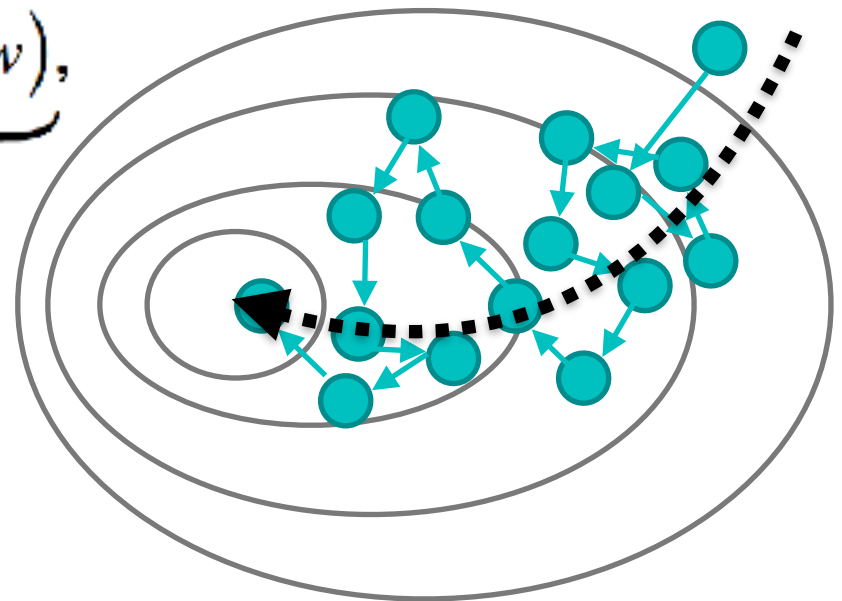
(M+1)\*N multiplications  
2M add/subtract

$$w \leftarrow w + \underbrace{\eta \left( (y^{(i)} - \hat{y}^{(i)})x^{(i)} - 2C \cdot w \right)}_{\text{approx. gradient}},$$

$i$  chosen at random

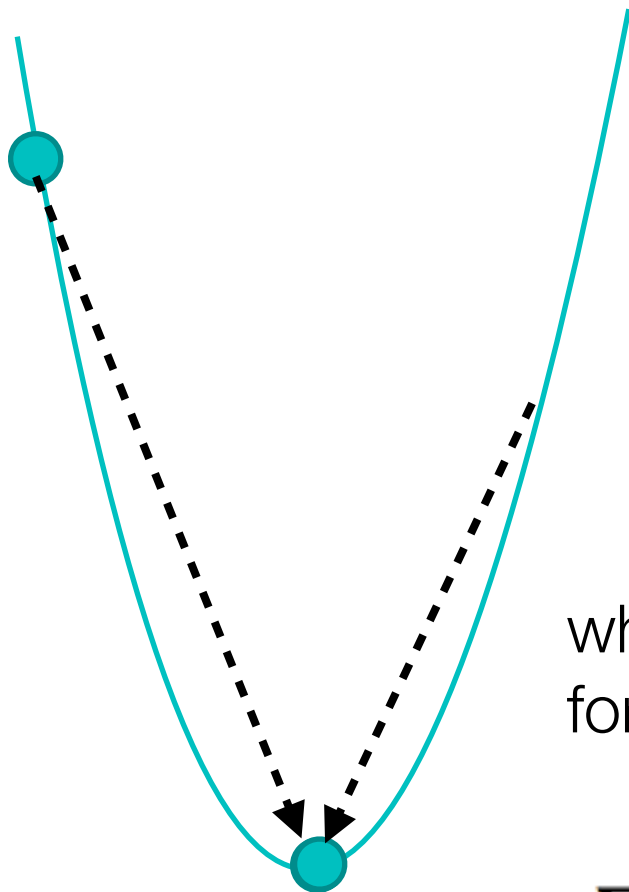
**Per iteration:**

N+1 multiplications  
1 add/subtract



# Can we do better than the gradient?

- Assume function is quadratic:



function of one variable:

$$w \leftarrow w - \underbrace{\left[ \frac{\partial^2}{\partial w} l(w) \right]^{-1}}_{\text{inverse 2nd deriv}} \underbrace{\frac{\partial}{\partial w} l(w)}_{\text{derivative}}$$

will solve in one step!

what is the second order derivative  
for a multivariate function?

$$\nabla^2 l(w) = \mathbf{H}[l(w)]$$

# The Hessian

- Assume function is quadratic:

function of one variable:

$$\mathbf{H}[l(w)] = \begin{bmatrix} \frac{\partial^2}{\partial w_1} l(w) & \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_2} l(w) & \dots & \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_N} l(w) \\ \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_1} l(w) & \frac{\partial^2}{\partial w_2} l(w) & \dots & \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_N} l(w) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial}{\partial w_N} \frac{\partial}{\partial w_1} l(w) & \frac{\partial}{\partial w_N} \frac{\partial}{\partial w_2} l(w) & \dots & \frac{\partial^2}{\partial w_N} l(w) \end{bmatrix}$$



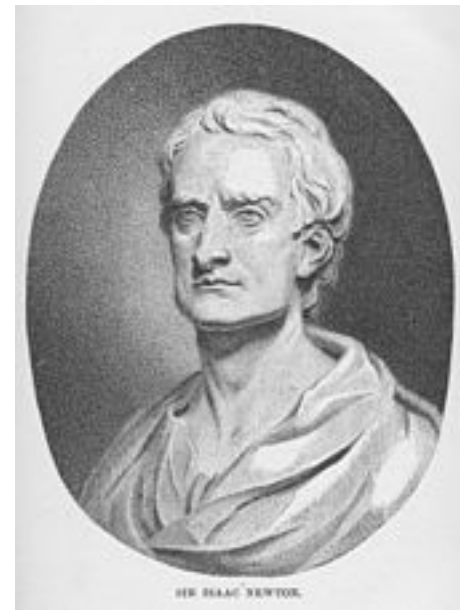
$$\nabla^2 l(w) = \mathbf{H}[l(w)]$$

# The Newton Update Method

- Assume function is quadratic (in high dimensions):

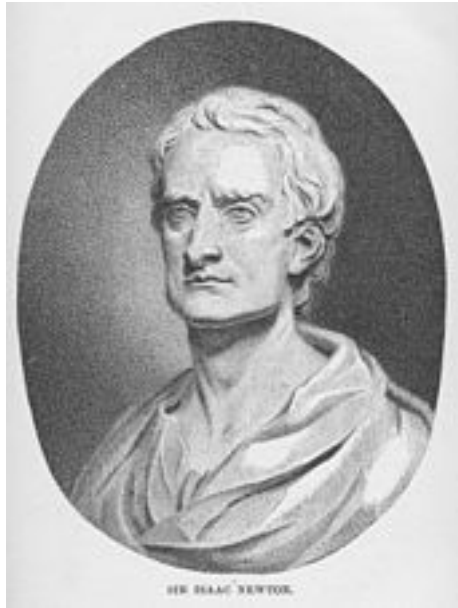
$$w \leftarrow w - \underbrace{\left[ \frac{\partial^2}{\partial w} l(w) \right]^{-1}}_{\text{inverse 2nd deriv}} \underbrace{\frac{\partial}{\partial w} l(w)}_{\text{derivative}}$$

$$w \leftarrow w + \eta \cdot \underbrace{\mathbf{H}[l(w)]^{-1}}_{\text{inverse Hessian}} \cdot \underbrace{\nabla l(w)}_{\text{gradient}}$$



*Is. Newton*

I do not know what I may appear to the world, but to myself I seem to have been only like a boy playing on the sea-shore, and diverting myself in now and then finding a smoother pebble or a prettier shell than ordinary, whilst the great ocean of truth lay all undiscovered before me.



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*Is. Newton*



$$\frac{\partial}{\partial w_j} l(w) = \sum_i (y^{(i)} - g(x^{(i)})) x_j^{(i)}$$

↓ PLUG IN

$$H[k,j] = \frac{\partial}{\partial w_k} \frac{\partial}{\partial w_j} l = \frac{\partial}{\partial w_k} \left( \sum_i (y^{(i)} - g(x^{(i)})) x_j^{(i)} \right)$$

$$= \sum_i \frac{\partial}{\partial w_k} y^{(i)} x_j^{(i)} - \frac{\partial}{\partial w_k} g(x^{(i)}) x_j^{(i)}$$

← LEFT OVER TERM

$$= - \sum_i \frac{\partial}{\partial w_k} g(x^{(i)}) x_j^{(i)}$$

Already know  $\frac{\partial}{\partial w_k} g(w^T x^{(i)})$  side calculation

$$= g(x^{(i)}) (1 - g(x^{(i)})) \frac{\partial}{\partial w_k} (w^T x^{(i)})$$

$$= g(x^{(i)}) (1 - g(x^{(i)})) x_k^{(i)}$$

← PLUG IN

$$\therefore = - \sum_i g(x^{(i)}) (1 - g(x^{(i)})) x_k^{(i)} x_j^{(i)}$$

← THAT'S THE HESSIAN!

$$H(k,j) =$$

This is a valid equation for the Hessian, but we want to represent it using linear algebra

$$= - \sum_i g(x^{(i)}) (1 - g(x^{(i)})) x_k^{(i)} x_j^{(i)}$$

↑ SIGMOID

3D LINEAR ALG

# The Hessian for Logistic Regression

- The hessian is easy to calculate from the gradient for logistic regression

$$w \leftarrow w + \eta \cdot \underbrace{\mathbf{H}[l(w)]^{-1}}_{\text{inverse Hessian}} \cdot \underbrace{\nabla l(w)}_{\text{gradient}}$$

$$\mathbf{H}_{j,k}[l(w)] = - \sum_{i=1}^M g(x^{(i)})(1 - g(x^{(i)})) x_k^{(i)} x_j^{(i)}$$

$$\underbrace{\sum_{i=1}^M (y^{(i)} - \hat{y}^{(i)}) x_j^{(i)}}_{\text{gradient}}$$

$$\mathbf{H}[l(w)] = X^T \cdot \text{diag}[g(x^{(i)})(1 - g(x^{(i)}))] \cdot X$$

$$X * y_{diff}$$

$$w \leftarrow w + \eta [X^T \cdot \text{diag}[g(x^{(i)})(1 - g(x^{(i)}))] \cdot X]^{-1} \cdot X * y_{diff}$$

Newton's method



BFGS (if time)  
parallelization

