Data Structures

Arrays []

- V = V-table
 - o Simple array to store all the vertex IDs, and vertices for 1 triangle are consecutive
 - o Ex: [1, 2, 3, 4, 5, 6]
 - Vertex IDs 1, 2, 3 belong to first triangle, and 4, 5, 6 belong to 2nd triangle
- G = Geometry-table
 - Multi-dimensional array to store the actual 3D coordinates of a vertex
 - Ex: [[x1, y1, z1], [x2, y2, z2]]
 - G[0] = the actual coordinates corresponding to vertex 0 [x1, y1, z1]
 - So, if you want the actual coordinates corresponding to a specific corner, use:
 - □ G[V[c]]

Dictionary { }

- O = Opposite-table
 - o For each index, c, in O
 - Key: V[c]
 - Value: the computed value (use helper function to compute O table)

Variables

- currentCorner (integer)
- Flags (boolean)
 - o currentCornerVisible
 - showRandomColors

Helper Functions

• See slide 6 in Rossignac's slides

def nextCorner(cornerNum)

- triangleNum = cornerNum // 3
 - o Find triangle number based on cornerNum
 - Note: the // is floor division in python
- Return 3 * triangleNum + ((cornerNum + 1) % 3)

def previousCorner(cornerNum)

- Use same idea as nextCorner function
- But, instead of adding 1 to cornerNum in the return statement, you should subtract
- Return 3 * triangleNum + ((cornerNum 1) % 3)

def oppositeCorner(cornerNum)

- Use the opposite-table dictionary
- Return O[cornerNum]

def swingCorner(cornerNum)

Return nextCorner(oppositeCorner (nextCorner(cornerNum)))

Note: in the keyPressed section, update currentCorner with the new corner value for each of the 4 corresponding key presses (n, p, o, s) using the above 4 functions

def computeOTable(G, V)

- Temporary variable to store triplets
- For loop: iterate from 0 to len(V)
 - Append (min(V[nextCorner(i)], V[previousCorner(i)]), max(...), i) to triplets
 - See slide 8
- Sort the triplets (see slide 8)
- For loop: iterate from 0 to len(sortedTriplets), add 2 to iterator each time
 - o cornerA = sortedTriplets[i][2]
 - o cornerB = sortedTriplets[i+1][2]
 - Assign O[cornerA] = cornerB and vice versa

def inflate()

- Normalize each array in G and return this new normalized version
 - Then, in keyPressed section, when the inflate key is pressed, update G table by calling this function

Modifying the read mesh function

- In for loop iterating from 0 to num_vertices,
 - Update G table by appending (x, y, z)
- In for loop iterating from 0 to num faces,
 - Update V table by extending it by (index1, index2, index3)
- Outside of these loops, instantiate the O table by calling the helper function you wrote

Modifying the Draw Function

- Use for loop. Iterate starting from 0 to len(V-table), adding 3 to the iterator each time (eg 0, 3, 6, ...)
 - Let iterator variable be c
- beginShape()
- Use if/else block to fill with random colors if showRandomColors flag is turned on
 - o fill(random(255), ..., ...)
 - Otherwise, normal fill is fill(255, 255, 255)
- Use vertex function to draw 3 vertices
 - vertex(G[V[c]].x, G[V[c]].y, G[V[c]].z)
 - vertex(G[V[c + 1]].x, G[V[c + 1]].y, G[V[c + 1]].z)
 - o 3rd is similar
- endShape()
- Logic to make the current corner visible if currentCornerVisible is turned on
 - pushMatrix()
 - currentVertex = G[V[currentCorner]]
 - translate(currentVertex.x, ..., ...)
 - o sphere(0.1)
 - popMatrix()

Create a function for subdivision

Variable for numEdges, which is len(V) // 2

- Make a temporary data structure for the newGTable and newVTable
- Initialize empty dictionary for midpoints
- For loop: going through the O table. Need to have a and b as iterators
 - Endpoint1 = G[V[previousCorner(a)]]
 - Endpoint2 = similar but use nextCorner function
 - Calculate midpoint which is endpoint1 + endpoint2 * 1/2
 - Use Pvector mult
 - Find midpointIndex which is len(newGTable)
 - Append the midpoint to the newGTable
 - o Update the midpoints dictionary with the midpointIndex
 - Midpoints[a] = midpointIndex
 - Do the same for midpoints[b]
- For loop: go from 0 to len(V) and add 3 each time to the iterator x
 - Make 2 new index variables to make your life easier
 - y = x + 1
 - z = x + 2
 - Note that newVTable is a list in Python. So you can use the extend function to attach more items to this list
 - We need to add 4 sets of items to newVTable
 - (V[x], midpoints[z], midpoints[y])
 - (midpoints[z], V[y], midpoints[x])
 - (midpoints[y], midpoints[x], V[z])
 - (midpoints[x], midpoints[z], midpoints[y])
- Return newGTable, newVTable, computeOTable(newGTable, newVTable)
 - In the handleKeyPressed section, for key 'd', you can update the global variables you made for G, V, and O by calling this subdivide helper function