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## checkpoint 1:

1	0	0	0
0	cos45	-sin45	0
0	sin45	cos45	0
0	0	0	1

## checkpoint 2:

cos45	0	sin45	0
0	1	0	0
-sin45	0	cos45	0
0	0	0	1

checkpoint 3: t1(1,1,2)