

Machine-Level Programming IV: Data

CS2011: Introduction to Computer Systems
Lecture 9 (3.8, 3.9, 3.11)

Machine-Level Programming IV: Data

■ Partial recap: Integers

- Word size
- Addresses

■ One-Dimensional Arrays

■ Structs

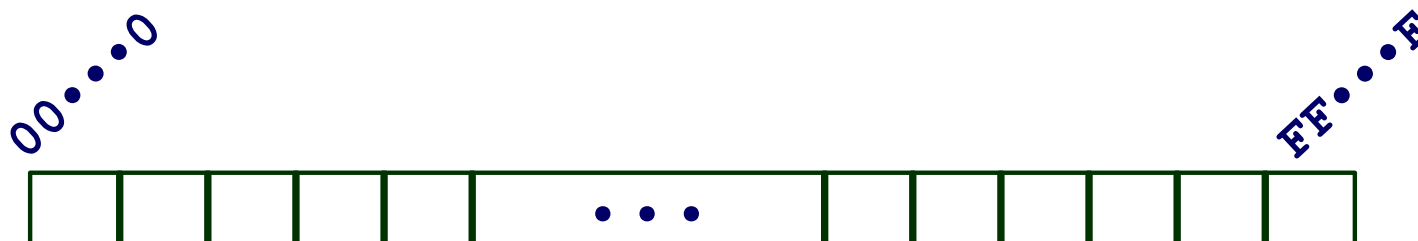
- Alignment
- Arrays of Structs

■ Multi-Dimensional Arrays

- Nested (Arrays of Arrays)
- (Arrays of) Pointers to Arrays

■ Floating Point Machine Code

Byte-Oriented Memory Organization



■ Programs refer to data by address

- Imagine all of RAM as an enormous array of bytes
- An address is an index into that array
 - A pointer variable stores an address

■ System provides a private *address space* to each “process”

- A process is an instance of a program, being executed
- An address space is one of those enormous arrays of bytes
- Each program can see only its own code and data within its enormous array
- We’ll come back to this later (“virtual memory”)

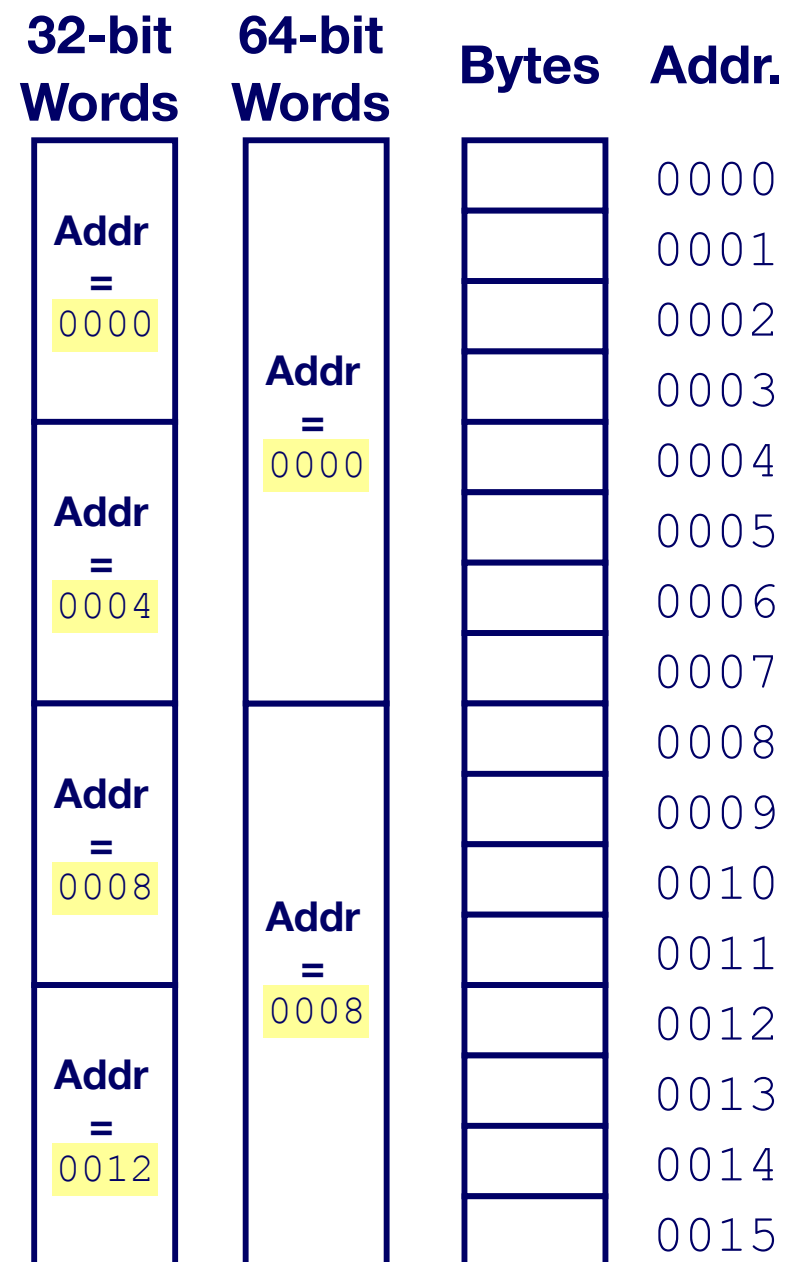
Machine Words

■ Any given computer has a “Word Size”

- Nominal size of integer-valued data
 - and of addresses
- Until recently, most machines used 32 bits (4 bytes) as word size
 - Limits addresses to 4GB (2^{32} bytes)
- Increasingly, machines have 64-bit word size
 - Potentially, could have 16 EB (exabytes) of addressable memory
 - That's 18.4×10^{18} bytes
- Machines still support multiple data formats
 - Fractions or multiples of word size
 - Always integral number of bytes

Addresses *Always* Specify Byte Locations

- Address of a word is address of the first byte in the word
- Addresses of successive words differ by 4 (32-bit) or 8 (64-bit)



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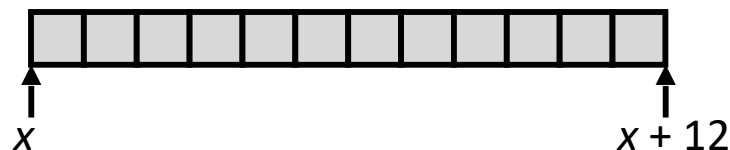
Array Allocation

Basic Principle

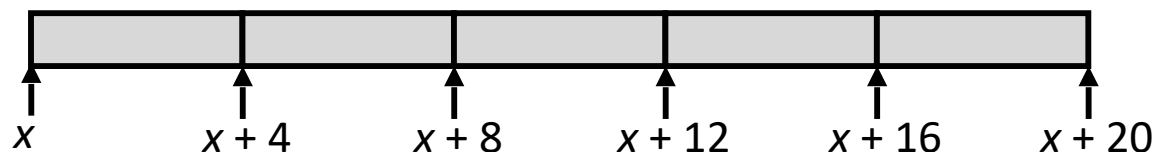
$T \ A[L];$

- Array of data type T and length L
- Contiguously allocated region of $L * \text{sizeof}(T)$ bytes in memory

`char string[12];`



`int val[5];`



`double a[3];`



`char *p[3];`

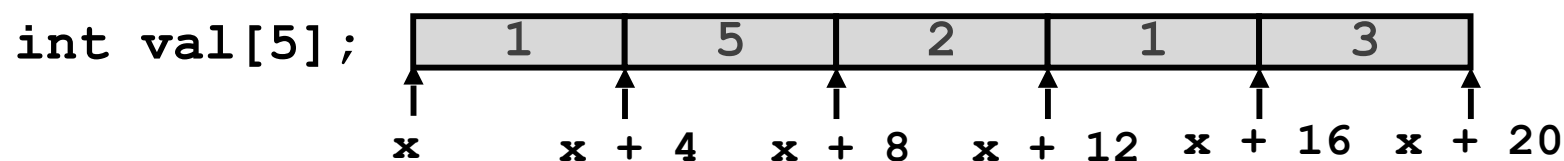


Array Access

Basic Principle

$T \ A[L];$

- Array of data type T and length L
- Identifier A can be used as a pointer to array element 0: Type T^*

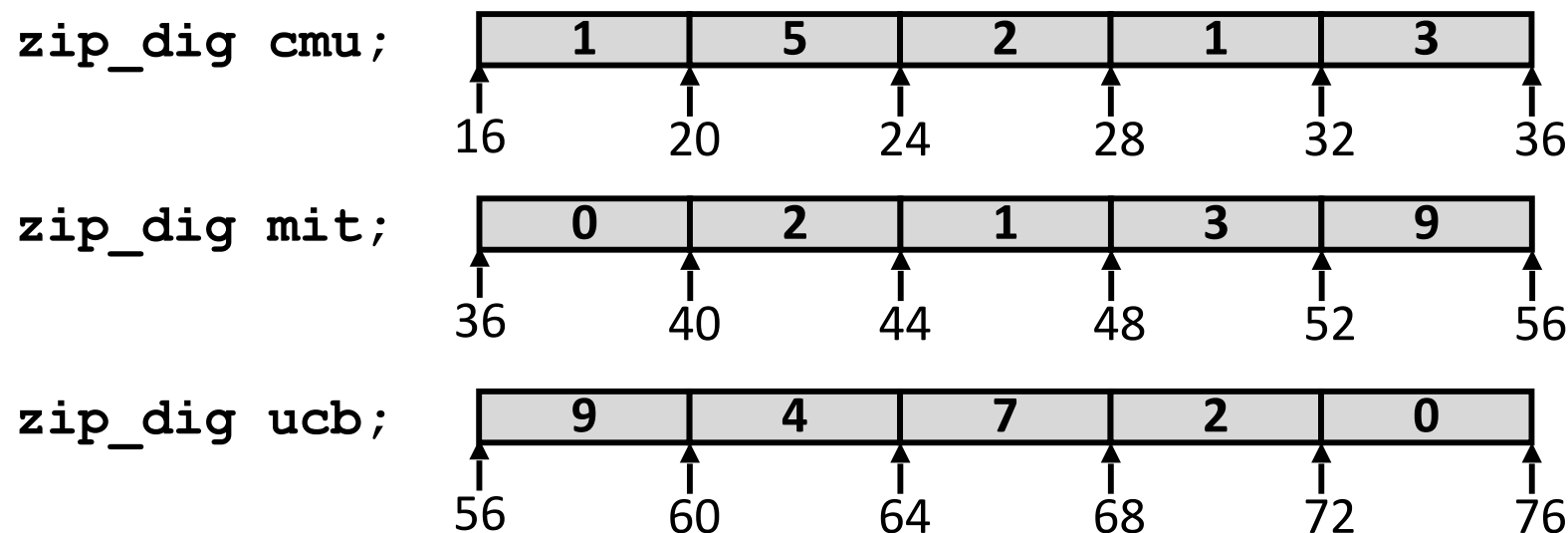


Reference	Type	Value
<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	<code>x</code>
<code>val+1</code>	<code>int *</code>	<code>x + 4</code>
<code>&val[2]</code>	<code>int *</code>	<code>x + 8</code>
<code>val[5]</code>	<code>int</code>	??
<code>*(val+1)</code>	<code>int</code>	5 <code>//val[1]</code>
<code>val + i</code>	<code>int *</code>	<code>x + 4 * i</code> <code>//&val[i]</code>

Array Example

```
#define ZLEN 5
typedef int zip_dig[ZLEN];

zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

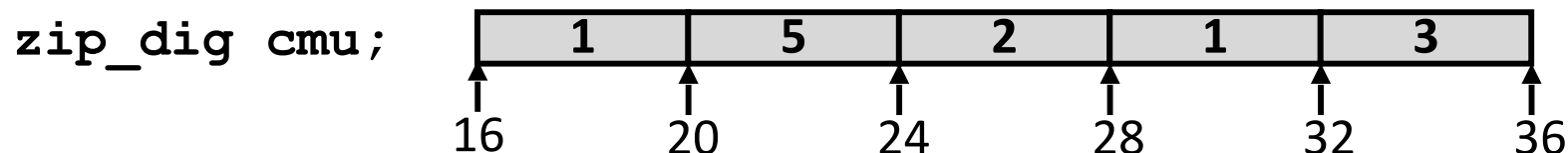


■ Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”

■ Example arrays were allocated in successive 20 byte blocks

- Not guaranteed to happen in general

Array Accessing Example



```
int get_digit
    (zip_dig z, int digit)
{
    return z[digit];
}
```

x86-64

```
# %rdi = z
# %rsi = digit
movl (%rdi,%rsi,4), %eax # z[digit]
```

- Register **%rdi** contains **starting address of array**
- Register **%rsi** contains **array index**
- Desired digit at $\text{\%rdi} + 4 * \text{\%rsi}$
- Use memory reference $(\text{\%rdi}, \text{\%rsi}, 4)$

Array Loop Example

```
# %rdi = z
movl    $0, %eax
jmp     .L3
.L4:
    addl    $1, (%rdi,%rax,4)
    addq    $1, %rax
.L3:
    cmpq    $4, %rax
    jbe     .L4
rep; ret
```

Array Loop Example

```
void zincr(zip_dig z) {
    size_t i;
    for (i = 0; i < ZLEN; i++)
        z[i]++;
}
```

```
# %rdi = z
movl    $0, %eax           # i = 0
jmp     .L3                # goto middle
.L4:                          # loop:
    addl    $1, (%rdi,%rax,4) # z[i]++
    addq    $1, %rax        # i++
.L3:                          # middle
    cmpq    $4, %rax        # i:4
    jbe     .L4             # if <=, goto loop
rep; ret
```

Understanding Pointers & Arrays #1

Decl	<i>A_n</i>			<i>*A_n</i>		
	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>						
<code>int *A2</code>						

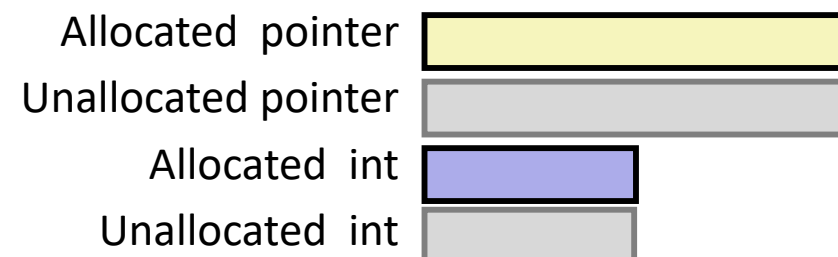
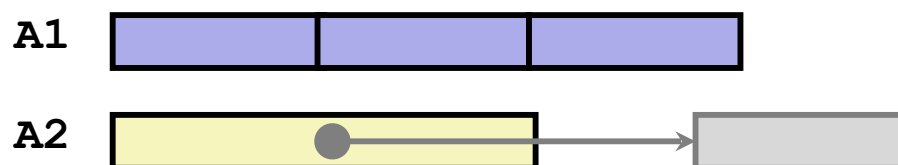
■ Cmp: Compiles (Y/N)

■ Bad: Possible bad pointer reference (Y/N)

■ Size: Value returned by `sizeof`

Understanding Pointers & Arrays #1

Decl	<i>A_n</i>			<i>*A_n</i>		
	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>	Y	N	12	Y	N	4
<code>int *A2</code>	Y	N	8	Y	Y	4



■ Cmp: Compiles (Y/N)

■ Bad: Possible bad pointer reference (Y/N)

■ Size: Value returned by `sizeof`

Understanding Pointers & Arrays #2

Decl	<i>A_n</i>			<i>*A_n</i>			<i>**A_n</i>		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>									
<code>int *A2[3]</code>									
<code>int (*A3)[3]</code>									
<code>int (*A4[3])</code>									

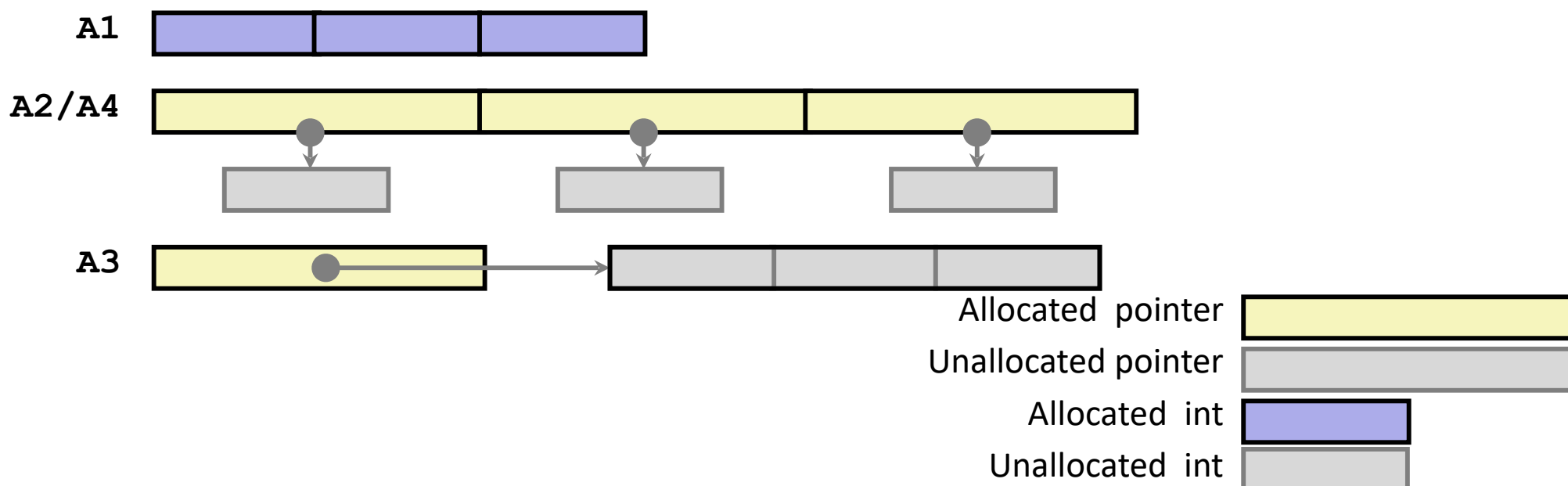
■ Cmp: Compiles (Y/N)

■ Bad: Possible bad pointer reference (Y/N)

■ Size: Value returned by `sizeof`

Understanding Pointers & Arrays #2

Decl	An			$*An$			$**An$		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>	Y	N	12	Y	N	4	N	–	–
<code>int *A2[3]</code>	Y	N	24	Y	N	8	Y	Y	4
<code>int (*A3)[3]</code>	Y	N	8	Y	Y	12	Y	Y	4
<code>int (*A4[3])</code>	Y	N	24	Y	N	8	Y	Y	4



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- Alignment
- Arrays of Structs

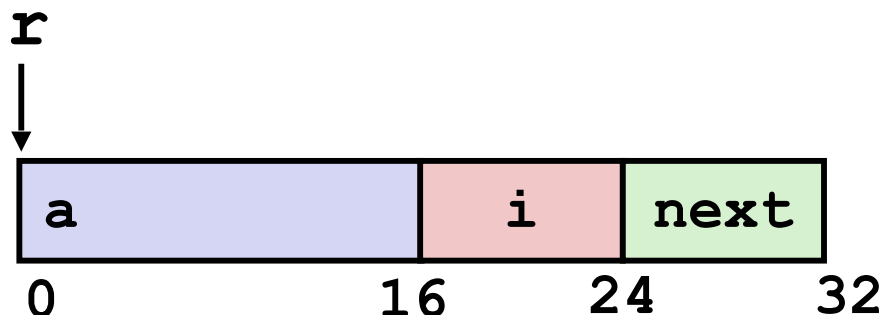
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Structure Representation

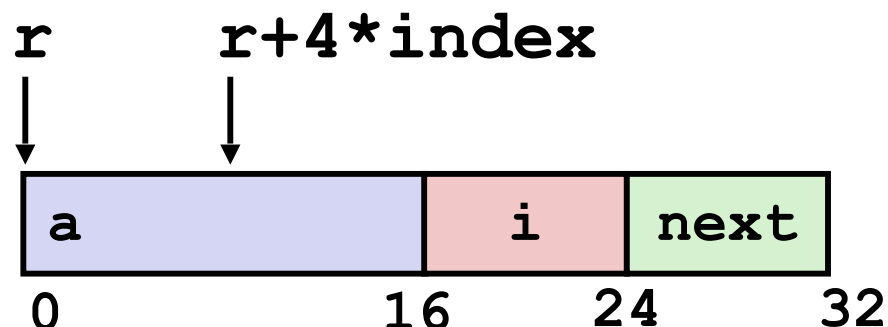
```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



- Structure represented as block of memory
 - Big enough to hold all of the fields
- Fields **ordered** according to declaration (*always in order*)
 - Even if another ordering could yield a more compact representation
- Compiler determines overall size + positions of fields
 - Machine-level program has no understanding of the structures in the source code

Generating Pointer to Structure Member

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



Generating Pointer to Array Element

- **Offset** of each structure member **determined at compile time**
- Compute as $r + 4 * \text{index}$

```
int *get_ap
(struct rec *r, size_t index)
{
    return &r->a[index];
}
```

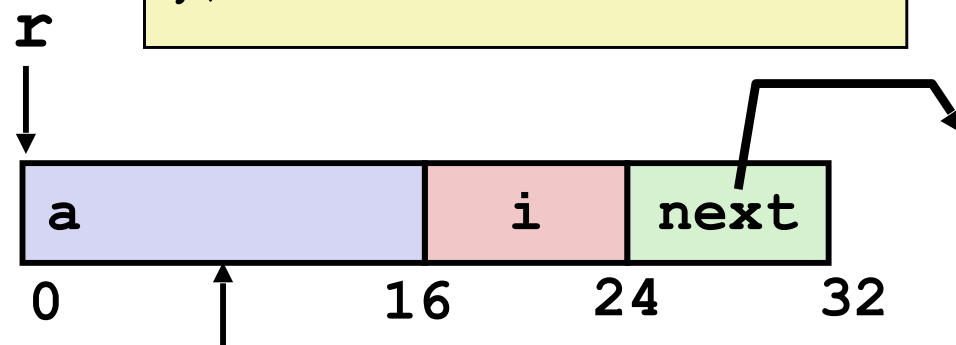
```
# r in %rdi, index in %rsi
leaq  (%rdi,%rsi,4), %rax
ret
```

Following Linked List

■ C Code

```
void set_val
(struct rec *r, int val)
{
    while (r) {
        int i = r->i;
        r->a[i] = val;
        r = r->next;
    }
}
```

```
struct rec {
    int a[4];
    int i;
    struct rec *next;
};
```



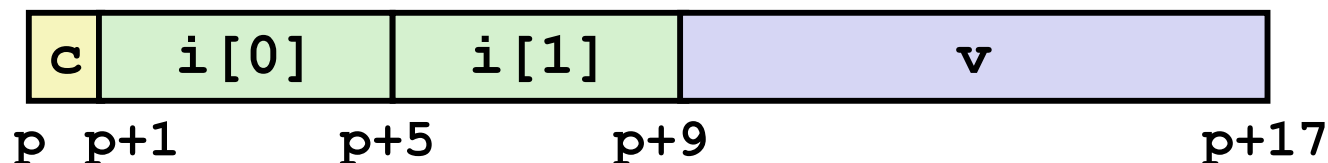
Element i

Register	Value
<code>%rdi</code>	<code>r</code>
<code>%rsi</code>	<code>val</code>

```
.L11:                                # loop:
    movslq    16(%rdi), %rax          # i = M[r+16]
    movl      %esi, (%rdi,%rax,4)     # M[r+4*i] = val
    movq      24(%rdi), %rdi         # r = M[r+24]
    testq     %rdi, %rdi             # Test r
    jne       .L11                   # if !=0 goto loop
```

Structures & Alignment

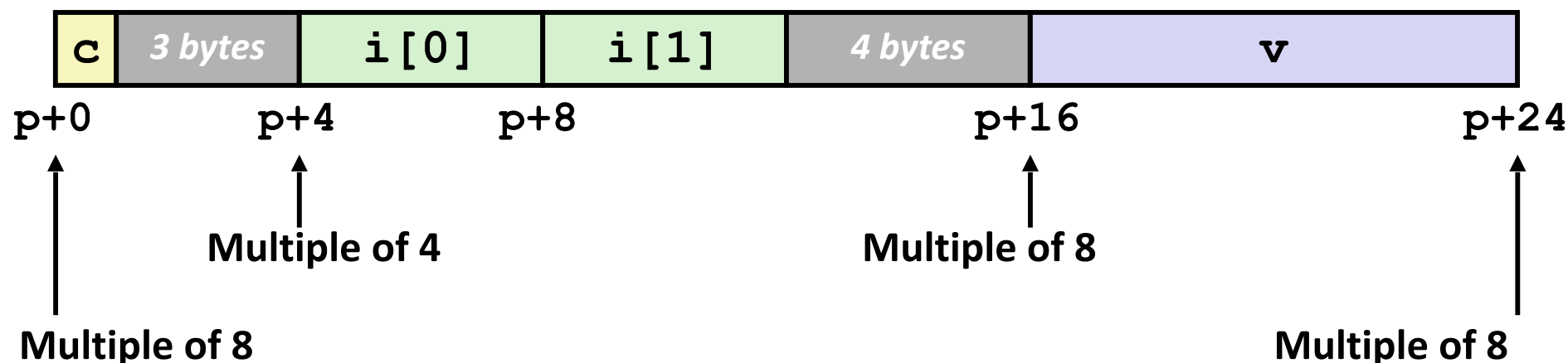
Unaligned Data



```
struct S1 {
    char c;
    int i[2];
    double v;
} *p;
```

Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K



Alignment Principles

■ Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K
- Required on some machines; **advised on x86-64**

■ Motivation for Aligning Data

- Memory accessed by (aligned) chunks of 4 or 8 bytes (system dependent)
 - Inefficient to load or store datum that spans quad word boundaries
 - E.g., a *double* value that is *saved at an address that is not a multiple of 8* will *require 2 memory accesses* to be read instead of a single read if it was saved at an address that is a multiple of 8.
 - *Virtual memory trickier* when datum *spans 2 pages*
 - Alignment *simplifies the design of the hardware*

■ Compiler

- *Inserts gaps* in structure to ensure correct alignment of fields

Specific Cases of Alignment (x86-64)

■ 1 byte: `char`, ...

- $K = 1 \rightarrow$ Address must be a multiple of 1
- no restrictions on address

■ 2 bytes: `short`, ...

- $K = 2 \rightarrow$ Address must be a multiple of 2
- lowest 1 bit of address must be 0_2

■ 4 bytes: `int`, `float`, ...

- $K = 4 \rightarrow$ Address must be a multiple of 4
- lowest 2 bits of address must be 00_2

■ 8 bytes: `double`, `long`, `char *`, ...

- $K = 8 \rightarrow$ Address must be a multiple of 8
- lowest 3 bits of address must be 000_2

Satisfying Alignment with Structures

■ Within structure:

- Must satisfy each element's alignment requirement

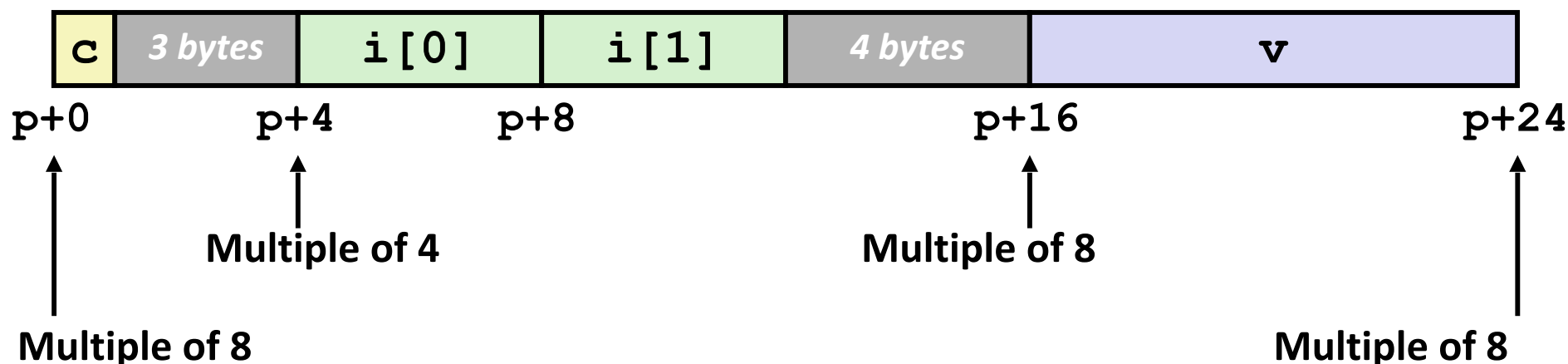
■ Overall **structure** placement

- Each structure has alignment requirement K
 - $K =$ **Largest alignment** of any element
- **Initial address** & structure length **must be multiples of K**

```
struct S1 {
    char c;
    int i[2];
    double v;
} *p;
```

■ Example:

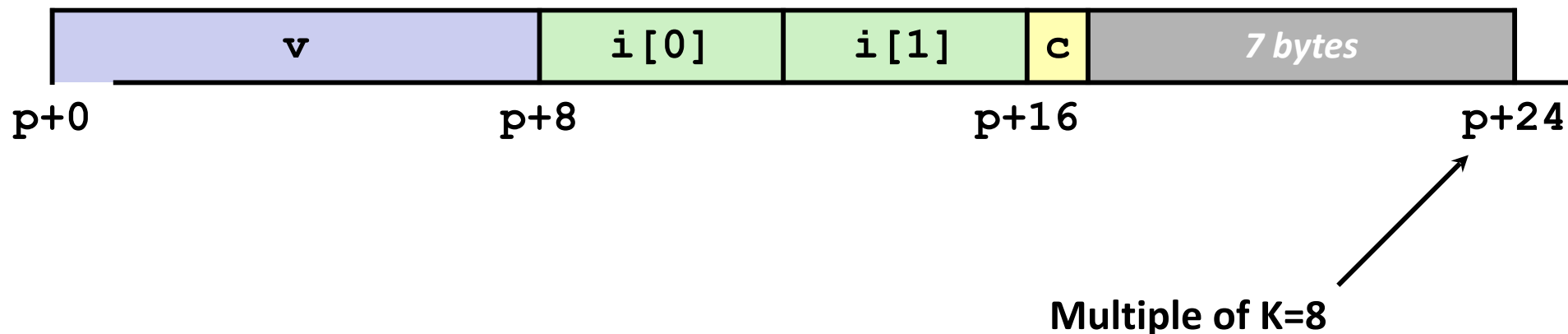
- $K = 8$, due to **double** element



Meeting Overall Alignment Requirement

- For largest alignment requirement K
- Overall structure must be multiple of K
- Add **padding** at the **end** if needed

```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} *p;
```



Saving Space

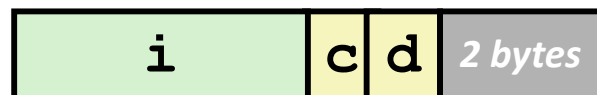
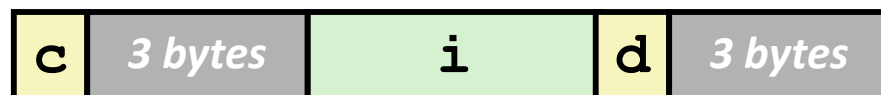
■ Put large data types first

```
struct S4 {  
    char c;  
    int i;  
    char d;  
} *p;
```



```
struct S5 {  
    int i;  
    char c;  
    char d;  
} *p;
```

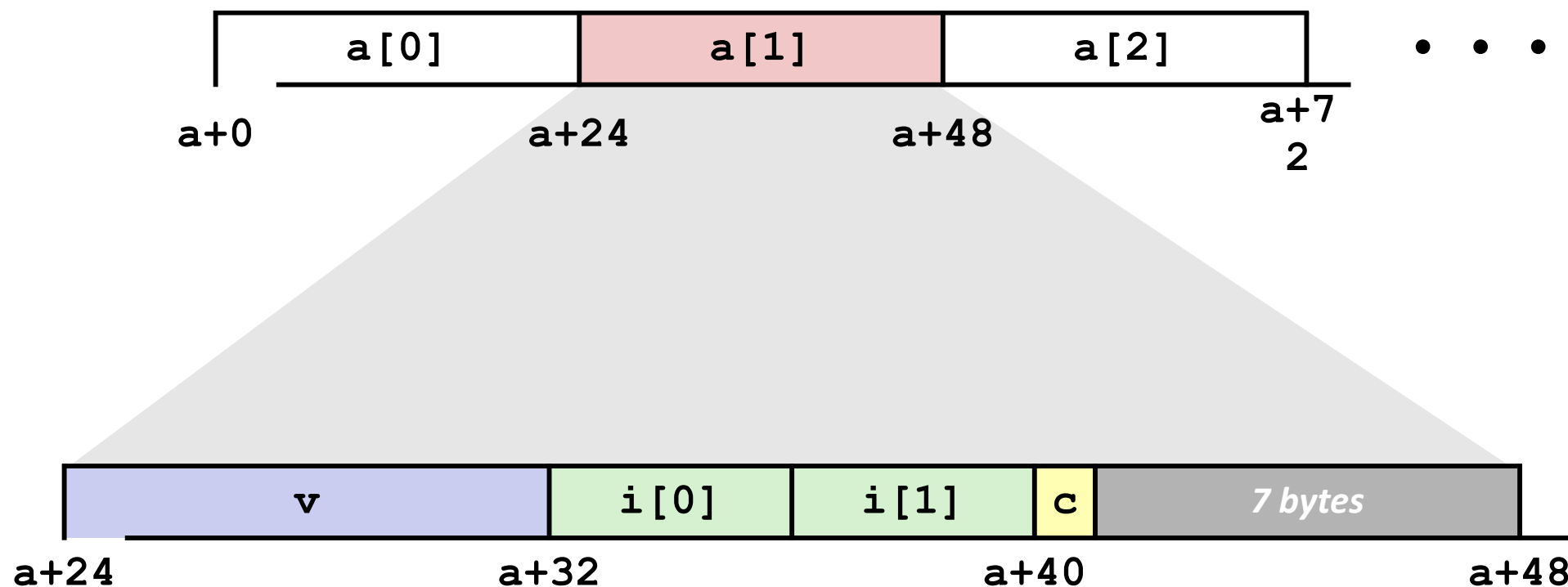
■ Effect (K=4)



Arrays of Structures

- Overall structure length multiple of K
- Satisfy alignment requirement for every element

```
struct S2 {
    double v;
    int i[2];
    char c;
} a[10];
```



Array of Structures (Accessing Elements Example)

■ Compute array offset $12 * \text{idx}$ (i.e., index)

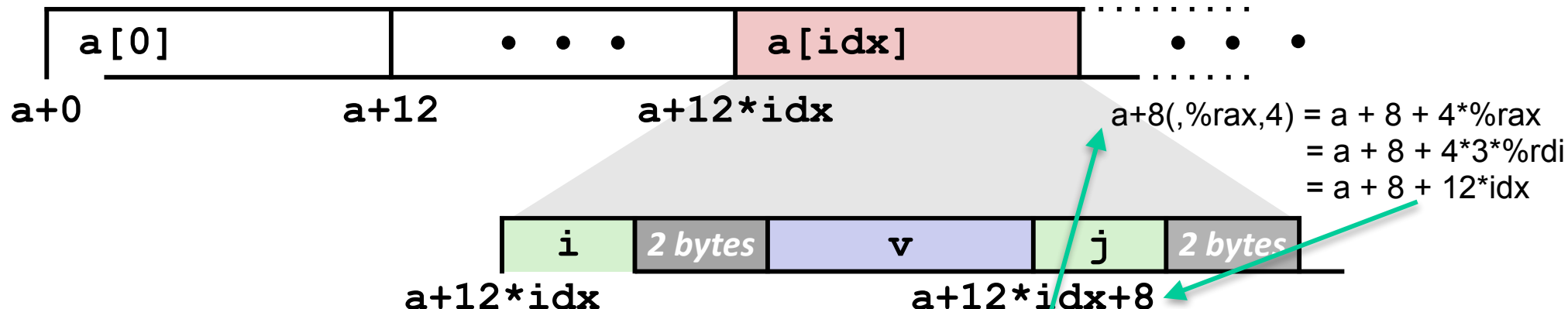
- `sizeof(S3)`, including alignment spacers

■ Element `j` is at offset 8 within structure

■ Assembler gives offset **`a+8`**

- *Resolved during linking*

```
struct S3 {
    short i;
    float v;
    short j;
} a[10];
```



```
short get_j(int idx)
{
    return a[idx].j;
}
```

```
# %rdi = idx
leaq (%rdi,%rdi,2),%rax # 3*idx
movzwl a+8(,%rax,4),%eax
```

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Multidimensional (Nested) Arrays

Declaration

$T \ A[R][C];$

- 2D array of data type T
- R rows, C columns
- Type T element requires K bytes

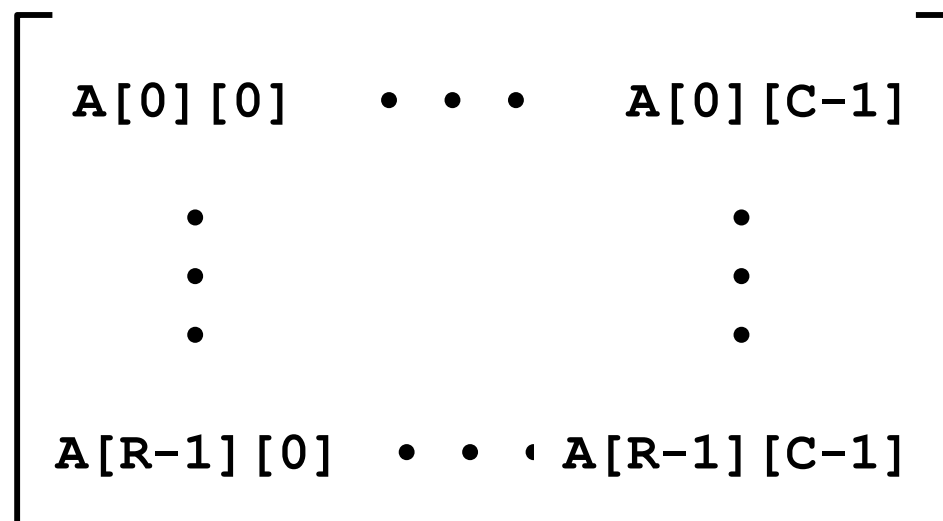
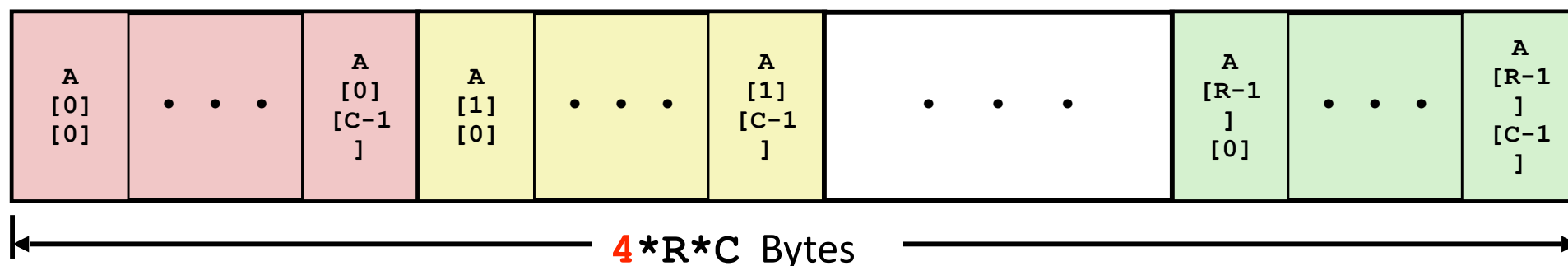
Array Size

- $R * C * K$ bytes

Arrangement

- *Row-Major Ordering: lay out matrix **by row** in the one dimensional memory (common convention)*

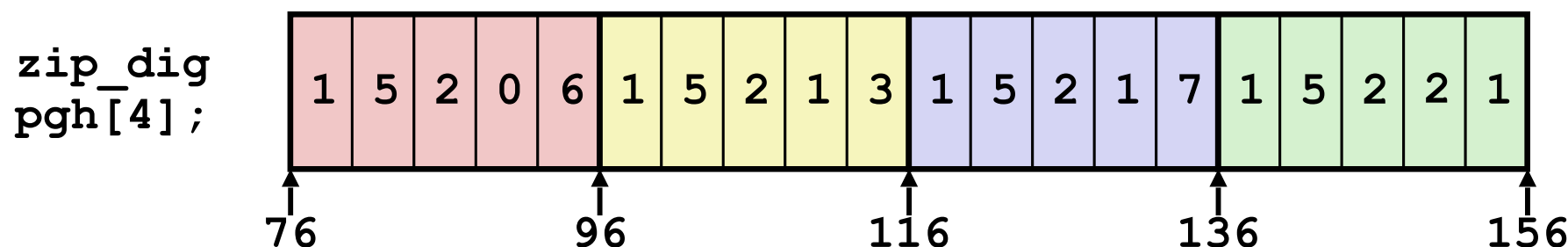
int $A[R][C];$



Nested Array Example

```
#define PCOUNT 4
typedef int zip_dig[5];

zip_dig pgh[PCOUNT] =
    {{1, 5, 2, 0, 6},
     {1, 5, 2, 1, 3 },
     {1, 5, 2, 1, 7 },
     {1, 5, 2, 2, 1 }};
```



■ “**zip_dig pgh[4]**” equivalent to “**int pgh[4][5]**”

- Variable **pgh**: array of 4 elements, allocated contiguously
- Each element is an array of 5 **int**’s, allocated contiguously

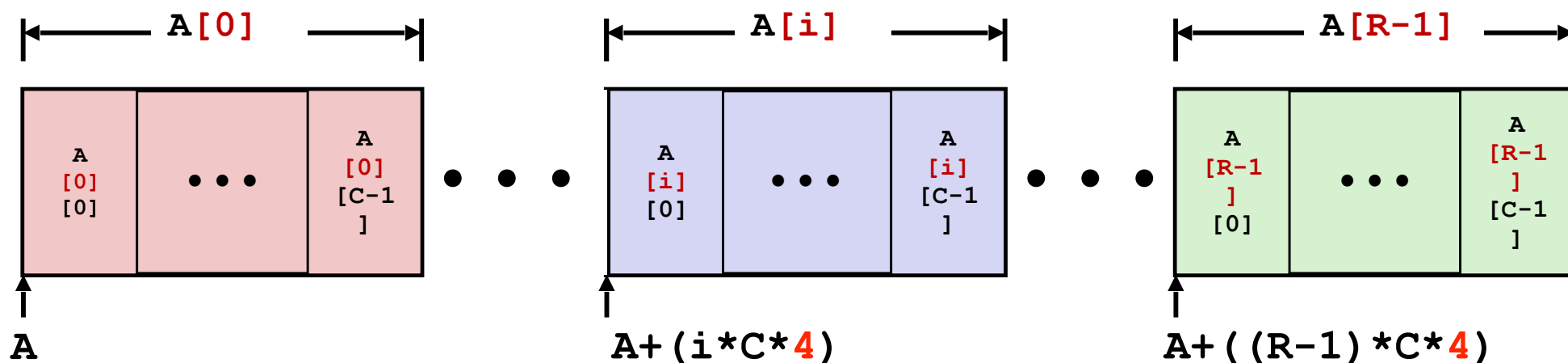
■ “**Row-Major**” ordering of all elements in memory

Nested Array **Row** Access

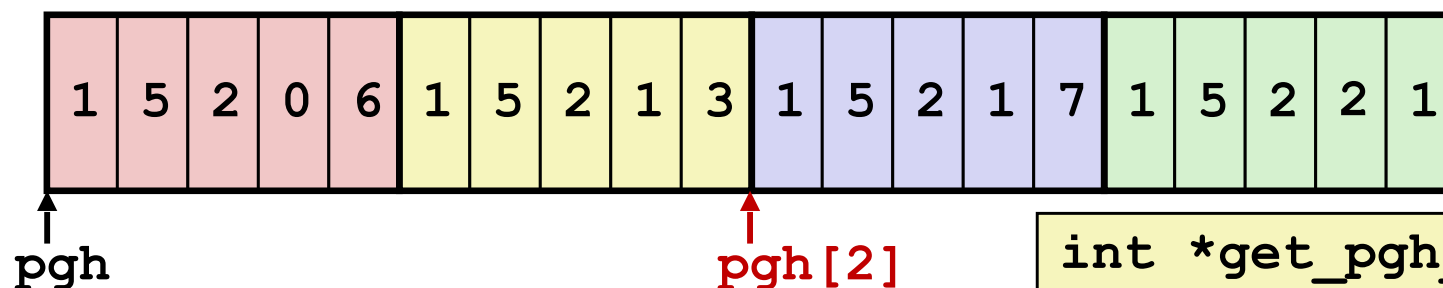
Row Vectors

- $A[i]$ is array of C elements
- Each element of type T requires K bytes
- Starting address $A + i * (C * K)$

```
int A[R][C];
```



Nested Array **Row** Access Code



```
int *get_pgh_zip(int index)
{
    return pgh[index];
}
```

```
# %rdi = index
leaq (%rdi,%rdi,4),%rax      # 5 * index
leaq pgh(,%rax,4),%rax      # pgh + (20 * index)
```

Row Vector

- `pgh[index]` is array of 5 `int`'s
- Starting address `pgh+20*index`

Machine Code

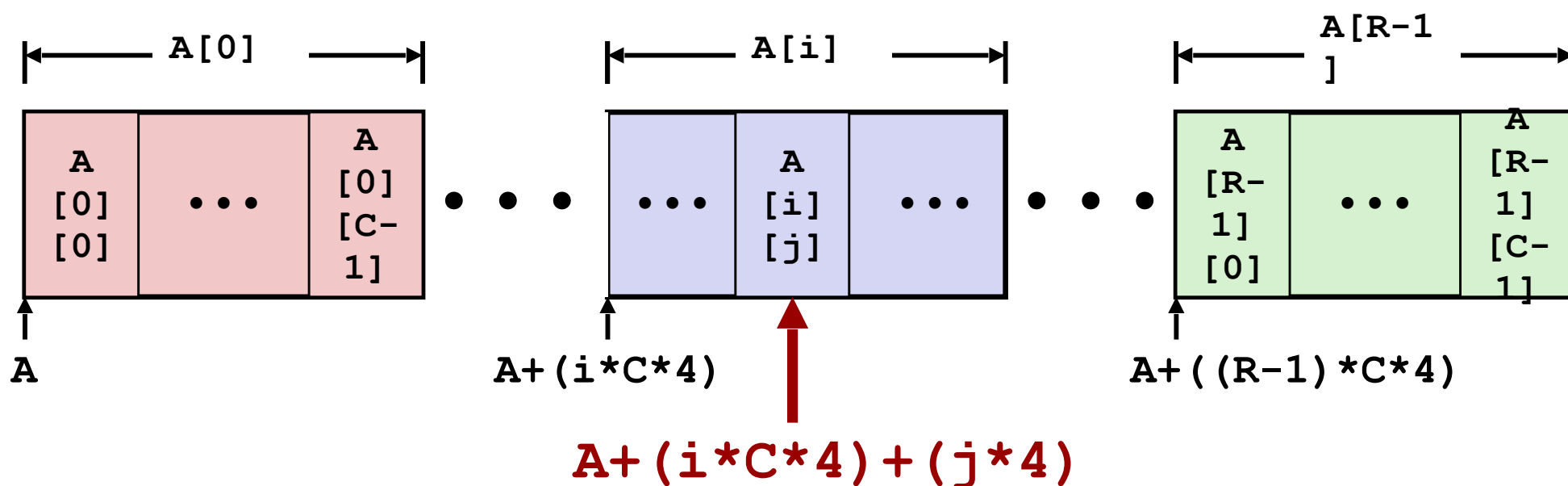
- Computes and returns address
- Compute as `pgh + 4*(index+4*index)`

Nested Array **Element** Access

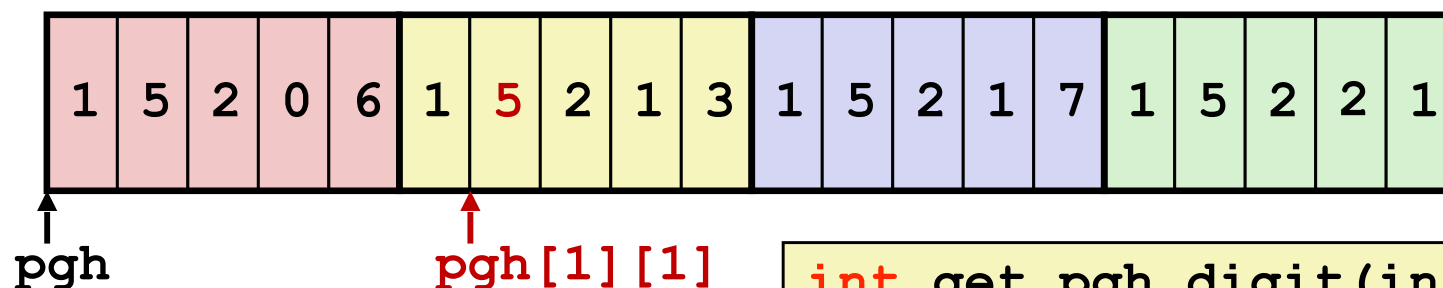
■ Array Elements

- $A[i][j]$ is element of type T , which requires K bytes
- Address $A + i * (C * K) + j * K$
 $= A + (i * C + j) * K$

```
int A[R][C];
```



Nested Array **Element** Access Code



```
int get_pgh_digit(int index, int dig)
{
    return pgh[index][dig];
}
```

```
leaq    (%rdi,%rdi,4), %rax    # 5 * index
addl    %rax, %rsi             # 5 * index + dig
movl    pgh(,%rsi,4), %eax     # M[pgh + 4 * (5 * index + dig)]
```

■ Array Elements

- `pgh[index][dig]` is **int**
- Address: $\text{pgh} + 20 \cdot \text{index} + 4 \cdot \text{dig}$
 $= \text{pgh} + 4 \cdot (5 \cdot \text{index} + \text{dig})$

Multi-Level Array Example

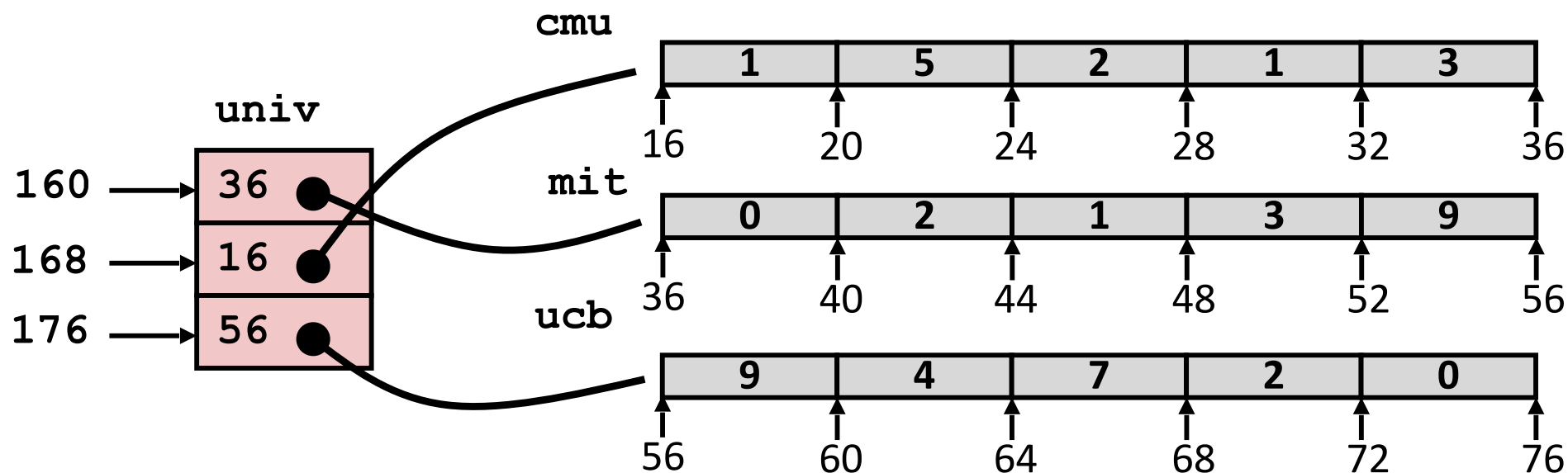
```
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

```
#define UCOUNT 3
int *univ[UCOUNT] = {mit, cmu, ucb};
```

Variable `univ` denotes array of 3 elements

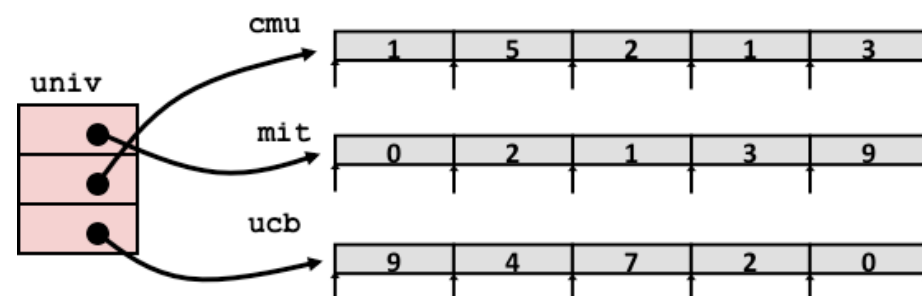
Each element is a **pointer**
 ■ 8 bytes

Each pointer points to array of `int`'s



Element Access in Multi-Level Array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



```
salq    $2, %rsi          # 4*digit
addq    univ(,%rdi,8), %rsi # p = univ[8*index] + 4*digit
movl    (%rsi), %eax       # return *p
ret
```

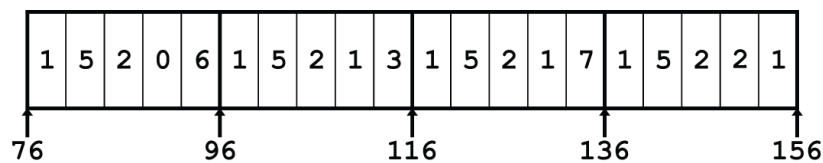
Computation

- Element access `Mem[Mem[univ+8*index]+4*digit]`
- Requires two memory reads (less efficient)
 - First get pointer to row array
 - Then access element within array

Array Element Accesses (Comparison)

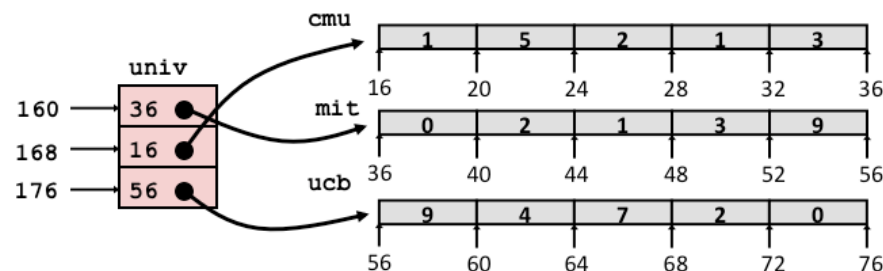
Nested array

```
int get_pgh_digit
(size_t index, size_t
digit)
{
    return pgh[index][digit];
}
```



Multi-level array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



Accesses looks similar in C, but address computations very different:

One memory read:

$\text{Mem}[\text{pgh} + 20 * \text{index} + 4 * \text{digit}]$

Two memory reads:

$\text{Mem}[\text{Mem}[\text{univ} + 8 * \text{index}] + 4 * \text{digit}]$

N X N Matrix

Code

Fixed dimensions

- Know value of N (# of Columns) at **compile time**

```
#define N 16
typedef int fix_matrix[N][N];
/* Get element A[i][j] */
int fix_ele(fix_matrix A,
            size_t i, size_t j)
{
    return A[i][j];
}
```

Variable dimensions, explicit indexing

- Traditional** way to implement dynamic arrays
- Programmer** needs to explicitly define indexing

```
#define IDX(n, i, j) ((i)*(n)+(j))
/* Get element A[i][j] */
int vec_ele(size_t n, int *A,
            size_t i, size_t j)
{
    return A[IDX(n, i, j)];
}
```

Variable dimensions, implicit indexing

- “New” feature in C99
- gcc compiler does the work for you, allowing you to simply use **same** accessing format **as** in arrays with **fixed dimensions**

```
/* Get element a[i][j] */
int var_ele(size_t n, int A[n][n],
            size_t i, size_t j) {
    return A[i][j];
}
```

Machine-Level Programming IV: Data

■ Partial recap: Integers

- Word size
- Addresses

■ One-Dimensional Arrays

■ Structs

- Alignment
- Arrays of Structs

■ Multi-Dimensional Arrays

- Nested (Arrays of Arrays)
- (Arrays of) Pointers to Arrays

■ Floating Point Machine Code

Floating Point Machine Code - Background

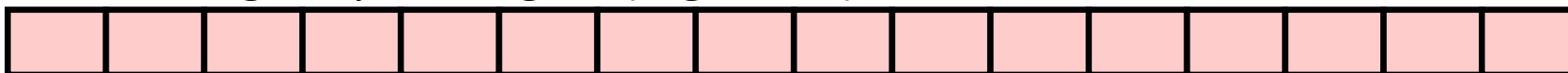
History

- x87 FP
 - Legacy, very ugly
- **SSE** (**S**treaming **S**IMD **E**xtensions) FP
 - Special case use of vector instructions
 - Instructions that allow multiple operations to be performed in a **parallel** mode known as **SIMD** 'sim-dee' (**S**ingle **I**nstruction, **M**ultiple **D**ata)
 - **SSE2**, version 2 of SSE, is supported by all processors capable of executing x86-64 code
 - Will briefly cover **SSE3** here
- **AVX** (**A**dvanced **V**ector **E**xtensions) FP
 - Newest version
 - AVX2, version 2 of AVX, introduced in **iCore 7 Haswell**
 - Similar to SSE (but registers are 32 bytes instead of 16)
 - Not covered here, but documented in book

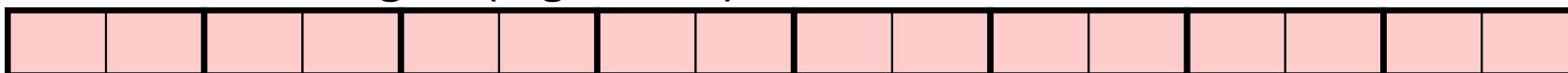
Programming with SSE3

XMM Registers

- 16 total, each 16 bytes (128 bits)
- 16 single-byte integers (e.g., char)



- 8 16-bit integers (e.g., short)



- 4 32-bit integers (e.g., int)



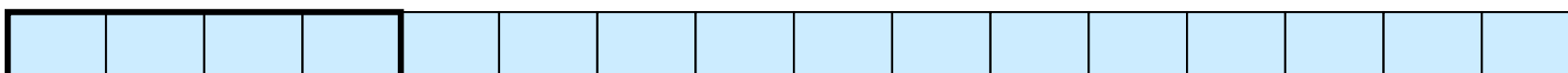
- 4 single-precision floats (i.e., float)



- 2 double-precision floats (i.e., double)



- 1 single-precision float (no parallelism)



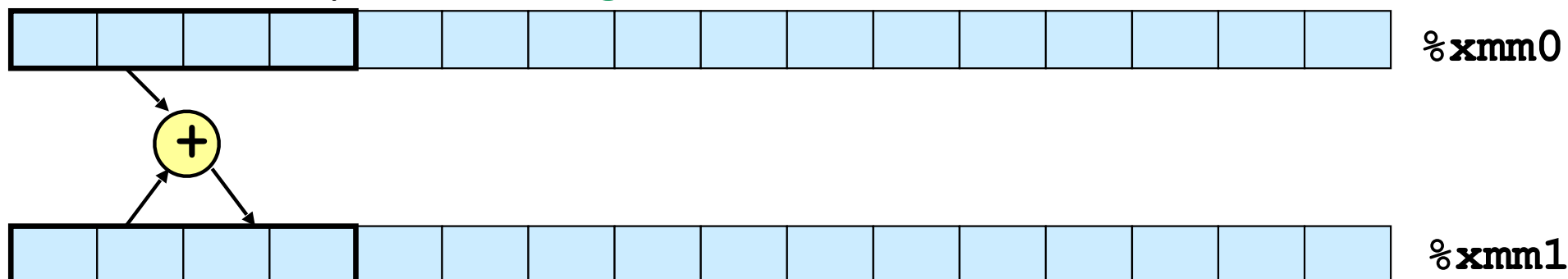
- 1 double-precision float (no parallelism)



Scalar & SIMD Operations

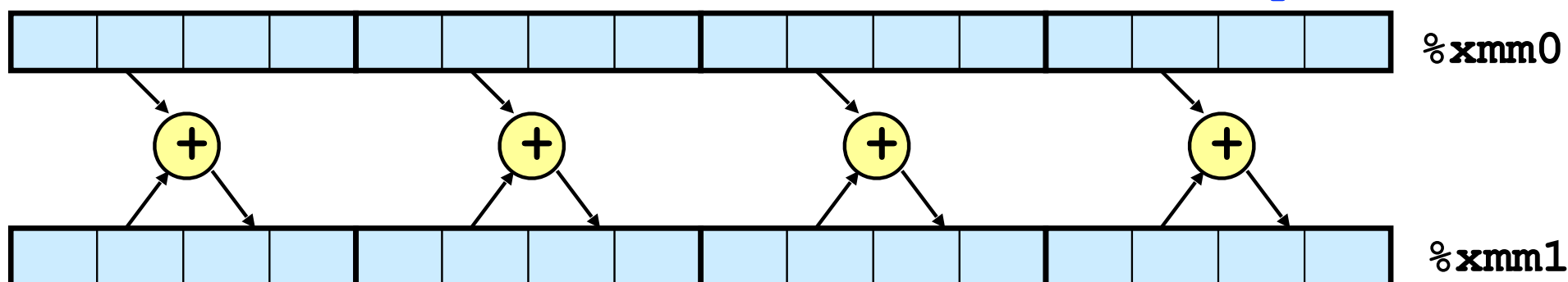
■ Scalar Operations: Single Precision

`addss %xmm0, %xmm1`



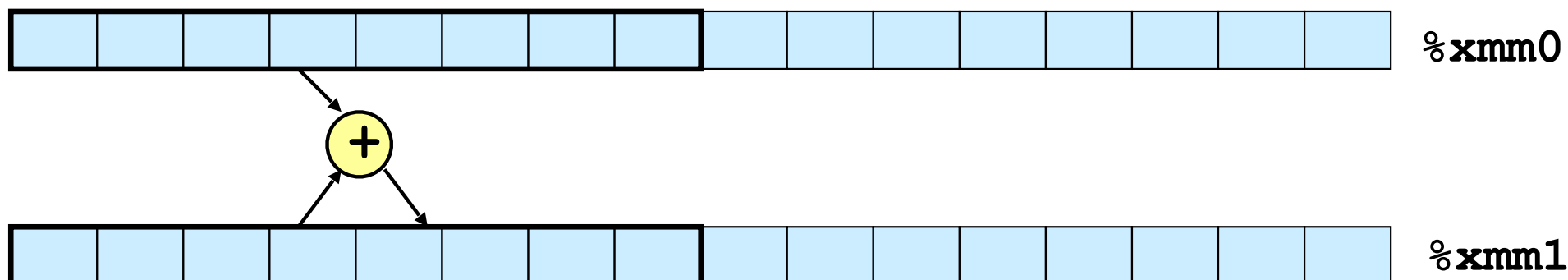
■ SIMD Operations: Single Precision

`addps %xmm0, %xmm1`



■ Scalar Operations: Double Precision

`addsd %xmm0, %xmm1`



FP Basics

■ Arguments passed in `%xmm0`, `%xmm1`, ...

■ Result returned in `%xmm0`

■ All XMM registers caller-saved

```
float fadd(float x, float y)
{
    return x + y;
}
```

```
double dadd(double x, double y)
{
    return x + y;
}
```

```
# x in %xmm0, y in %xmm1
addss    %xmm1, %xmm0
ret
```

```
# x in %xmm0, y in %xmm1
addsd    %xmm1, %xmm0
ret
```

FP Memory Referencing

- Integer (and pointer) **arguments passed in** regular **registers**
- FP values passed in XMM registers
- Different mov instructions to move between XMM registers, and between memory and XMM registers

```
double dincr(double *p, double v)
{
    double x = *p;
    *p = x + v;
    return x;
}
```

```
# p in %rdi, v in %xmm0
movapd    %xmm0, %xmm1    # Copy v
movsd     (%rdi), %xmm0    # x = *p
addsd     %xmm0, %xmm1    # t = x + v
movsd     %xmm1, (%rdi)    # *p = t
ret
```

Summary

■ Arrays

- Elements packed into contiguous region of memory
- Use index arithmetic to locate individual elements

■ Structures

- Elements packed into single region of memory
- Access using offsets determined by compiler
- Possible require internal and external padding to ensure alignment

■ Combinations

- Can nest structure and array code arbitrarily

■ Floating Point Machine Code