

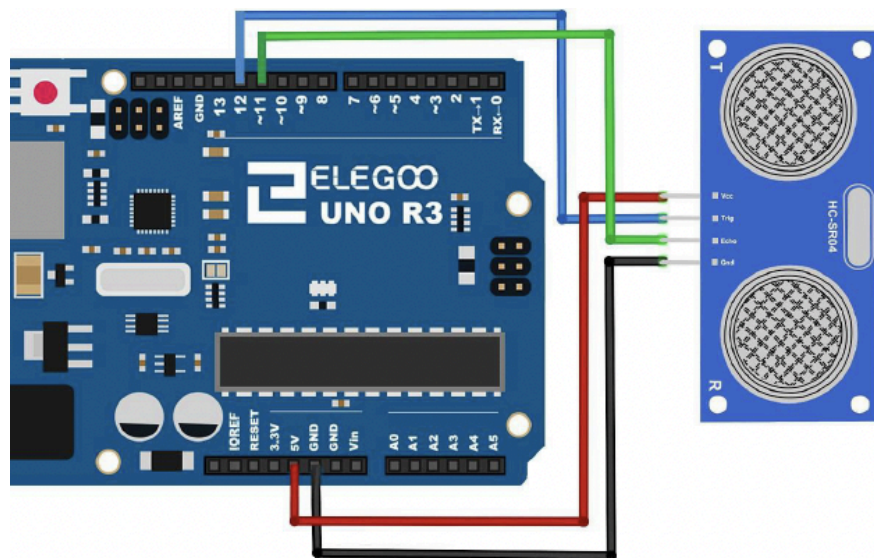
Wiring Documentation for HC-SR04 Sensor

The HC-SR04 sensor has four pins: **VCC**, **GND**, **TRIG**, and **ECHO**. Here's how to connect them to your Arduino:

HC-SR04 Pin	Arduino Pin	Description
VCC	5V	Power supply to the sensor. Connect to the 5V pin of the Arduino.
GND	GND	Ground. Connect to the ground pin on the Arduino.
TRIG	12	Trigger pin. Sends a short burst of ultrasonic sound. Connect to digital pin 12 on Arduino.
ECHO	11	Echo pin. Receives the reflected ultrasonic sound. Connect to digital pin 11 on Arduino.

Wiring Steps

1. Connect the **VCC** pin of the HC-SR04 sensor to the **5V** pin on your Arduino.
2. Connect the **GND** pin of the HC-SR04 sensor to a **GND** pin on your Arduino.
3. Connect the **TRIG** pin of the HC-SR04 sensor to **digital pin 12** on the Arduino.
4. Connect the **ECHO** pin of the HC-SR04 sensor to **digital pin 11** on the Arduino.



Servo Motor Wiring

Components Needed

- Servo motor (e.g., SG90 or MG996R)
 - Arduino board (UNO, Mega, etc.)
 - Power supply (if required for larger servo motors)
 - Jumper wires
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Servo Motor Pins

Most servo motors have three pins:

Servo Pin	Arduino Connection	Description
GND	GND	Connect the GND pin of the servo motor to the Arduino GND pin.
VCC	5V (or external)	Connect the power pin of the servo motor to the Arduino 5V pin (or external 5V source if needed).
Signal (PWM)	Digital Pin (e.g., 9)	Connect the signal pin of the servo motor to an Arduino digital PWM pin (e.g., pin 9).

Wiring Steps

1. **GND (Ground)**: Connect the servo motor's GND pin to the **GND** pin on the Arduino.
 2. **VCC (Power)**: Connect the servo motor's VCC pin to the **5V** pin on the Arduino.
 - For high-torque servos, use an **external power supply** to avoid overloading the Arduino.
 3. **Signal (Control)**: Connect the signal pin of the servo motor to **digital pin 9** (or any other PWM-enabled pin) on the Arduino.
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