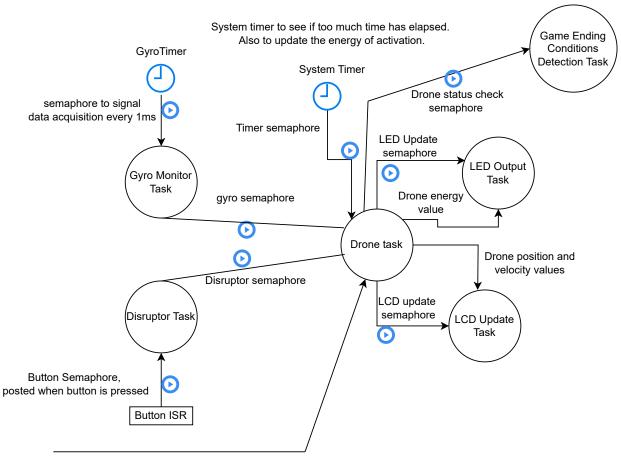
## Owen Hushka: Week 4 refined task diagram

Drone task is in charge of implementing physics and modeling where the drone is and whether it is running into walls, etc.



Pass the 2d array representing the maze as an argument to the drone task