Day 4: Overfitting and Generalization Summer STEM: Machine Learning

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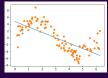
Outline

- 1 Leftovers from Day 3
- 2 Regularization
- 3 Non-linear Optimization





- We have been using straight lines to fit our data. But it doesn't work well every time
- Some data have more complex relation that cannot be fitted well using a straight line



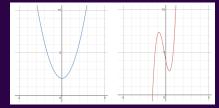
■ Can we use some other model to fit this data?





- Can we use a polynomial to fit our data?
- Polynomial: A sum of different powers of a variable

■ Examples:
$$y = x^2 + 2$$
, $y = 5x^3 - 3x^2 + 4$





- Polynomials of x: $\hat{y} = w_0 + w_1 x + w_2 x^2 + w_3 x^3 + \cdots + w_M x^M$
- lacktriangleq M is called the order of the polynomial.
- The process of fitting a polynomial is similar to linearly fitting multivariate data.





■ Rewrite in matrix-vector form

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} \approx \begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^M \\ 1 & x_2 & x_2^2 & \cdots & x_2^M \\ \vdots & & \ddots & & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^M \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_M \end{bmatrix}$$

■ This can still be written as

$$Y \approx X \mathbf{w}$$

- Loss $J(\mathbf{w}) = \frac{1}{N} \|Y X\mathbf{w}\|^2$
- The i-th row of the design matrix X is simply a transformed feature $\phi(x_i) = (1, x_i, x_i^2, \cdots, x_i^M)$





■ Original design matrix:
$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix}$$
■ Design matrix after feature transform

■ Design matrix after feature transformation:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^M \\ 1 & x_2 & x_2^2 & \cdots & x_2^M \\ \vdots & & \ddots & & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^M \end{bmatrix}$$

■ For the polynomial fitting, we just added columns of features that are powers of the original feature



Linear Regression

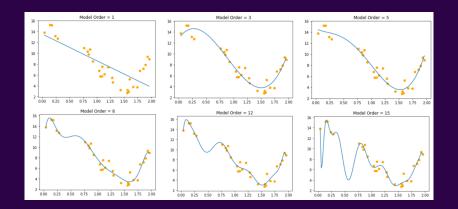
- Model $\hat{y} = \mathbf{w}^T \phi(\mathbf{x})$
- Loss $J(\mathbf{w}) = \frac{1}{N} \|Y X\mathbf{w}\|^2$
- \blacksquare Find \mathbf{w} that minimizes $J(\mathbf{w})$

Review

- We learned how to fit our data using polynomials of different order
- With a higher model order, we can fit the data with increasing accuracy
- As you increase the model order, at certain point it is possible find a model that fits your data perfectly (ie. zero error)
- What could be the problem?







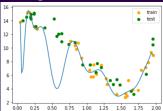
■ Which of these model do you think is the best? Why?





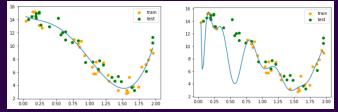
Review

- The problem is that we are only fitting our model using data that is given
- Data usually contains noise
- When a model becomes too complex, it will start to fit the noise in the data
- What happens if we apply our model to predict some data that the model has never seen before? It will not work well.
- This is called over-fitting





- Split the data set into a train set and a test set
- Train set will be used to train the model
- The test set will not be seen by the model during the training process
- Use test set to evaluate the model when a model is trained

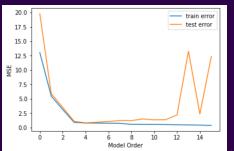


■ With the training and test sets shown, which one do you think is the better model now?

Train and Test Error

- Plot of train error and test error for different model order
- Initially both train and test error go down as model order increase

■ But at a certain point, test error start to increase because of overfitting





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■ Regularization: methods to prevent overfitting





- **Regularization**: methods to prevent overfitting
 - We just covered regularization by model order selection





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 - We just covered regularization by model order selection
- Is there another way? Talk among your classmates.





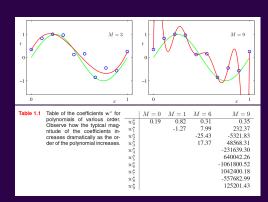
- **Regularization**: methods to prevent overfitting
 - We just covered regularization by model order selection
- Is there another way? Talk among your classmates.
 - Solution: We can change our cost function.





Weight Based Regularization

- Looking back at the polynomial overfitting
- Notice that weight-size increases with overfitting







New Cost Function

$$J(\mathbf{w}) = \frac{1}{N} \|Y - X\mathbf{w}\|^2 + \lambda \|\mathbf{w}\|^2$$

- Penalize complexity by simultaneously minimizing weight values.
- We call λ a **hyper-parameter**
 - \blacksquare λ determines relative importance

Table 1.2	Table of the coefficients \mathbf{w}^* for $M=9$ polynomials with various values for the regularization parameter λ . Note that $\ln \lambda = -\infty$ corresponds to a model with no regularization, i.e., to the graph at the bottom right in Figure 1.4. We see that, as the value of λ increases, the typical magnitude of the coefficients gets smaller.	$\begin{array}{c} w_0^{\star} \\ w_1^{\star} \\ w_2^{\star} \\ w_3^{\star} \\ w_5^{\star} \\ w_6^{\star} \\ w_7^{\star} \\ w_8^{\star} \\ w_9^{\star} \end{array}$	$\begin{array}{c} \ln \lambda = -\infty \\ 0.35 \\ 232.37 \\ -5321.83 \\ 48568.31 \\ -231639.30 \\ 640042.26 \\ -1061800.26 \\ 1042400.18 \\ -557682.99 \\ 125201.43 \end{array}$	$\begin{array}{c} \ln \lambda = -18 \\ \hline 0.35 \\ 4.74 \\ -0.77 \\ -31.97 \\ -3.89 \\ 55.28 \\ 41.32 \\ -45.95 \\ -91.53 \\ 72.68 \end{array}$	$\begin{array}{c} \ln \lambda = 0 \\ \hline 0.13 \\ -0.05 \\ -0.06 \\ -0.05 \\ -0.03 \\ -0.02 \\ -0.01 \\ -0.00 \\ 0.00 \\ 0.01 \end{array}$	
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Tuning Hyper-parameters

- Motivation: never determine a hyper-parameter based on training data
- **Hyper-Parameter**: a parameter of the algorithm that is not a model-parameter solved for in optimization.
 - **E**x: λ weight regularization value vs. model weights (**w**)
- Solution: split dataset into three
 - Training set: to compute the model-parameters (w)
 - Validation set: to tune hyper-parameters (λ)
 - **Test set**: to compute the performance of the algorithm (MSE)





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Motivation

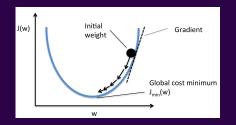
- Cannot rely on closed form solutions
 - Computation efficiency: operations like inverting a matrix is not efficient
 - For more complex problems such as neural networks, a closed-form solution is not always available
- Need an optimization technique to find an optimal solution
 - Machine learning practitioners use **gradient**-based methods





Gradient Descent Algorithm

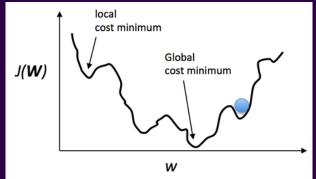
■ Update Rule $Repeat\{ \\ \mathbf{w}_{new} = \mathbf{w} - \alpha \nabla J(\mathbf{w}) \\ \} \\ \alpha \text{ is the learning rate}$





General Loss Function Contours

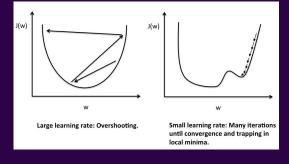
- Most loss function contours are not perfectly parabolic
- Our goal is to find a solution that is very close to global minimum by the right choice of hyper-parameters

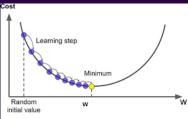






Understanding Learning Rate





Correct learning rate





Some Animations

■ Demonstrate gradient descent animation

Importance of Feature Normalization (Optional)

■ Helps improve the performance of gradient based optimization

