

SEAS 8510 - Analytical MEthods for ML

Homework 2

Due Date: April 6, 2024 (9:00am EST)

Your homework 2 should be submitted as a pdf containing your responses, your code, and your printed results where applicable.

All of the imports

```
In [ ]: import pandas as pd
import numpy as np
import datetime as dt
import matplotlib.pyplot as plt
%matplotlib inline
```

2.4

Compute the following matrix products, if possible. Calculate by hand and verify in Python.

a.

$$\begin{bmatrix} 1 & 2 \\ 4 & 5 \\ 7 & 8 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

This is multiplying a 3x2 matrix with a 3x3 matrix. Since the inner dimensions are different (2 and 3) they cannot be multiplied.

```
In [ ]: m1 = np.array([[1,2],[4,5],[7,8]])
m2 = np.array([[1,1,0],[0,1,1],[1,0,1]])

print("m1")
print(m1.shape)
print(m1)
```

```

print("m2")
print(m2.shape)
print(m2)

print("m1 X m2")
m3 = np.matmul(m1, m2)
print("Did not work as they are not compatible sizes.")

```

```

m1
(3, 2)
[[1 2]
 [4 5]
 [7 8]]
m2
(3, 3)
[[1 1 0]
 [0 1 1]
 [1 0 1]]
m1 X m2

```

ValueError Traceback (most recent call last)

Cell In[2], line 12

```

     9 print(m2)
    11 print("m1 X m2")
---> 12 m3 = np.matmul(m1, m2)
    13 print("Did not work as they are not compatible sizes.")

```

ValueError: matmul: Input operand 1 has a mismatch in its core dimension 0, with gufunc signature (n?,k),(k,m?)->(n?,m?) (size 3 is different from 2)

My results and Numpy agree that these two matrices cannot be multiplied together.

b.

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

Here we have two 3x3 matrices which can be multiplied together. The result is a 3x3 matrix.

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1*1+2*0+3*1 & 1*1+2*1+3*0 & 1*0+2*1+3*1 \\ 4*1+5*0+6*1 & 4*1+5*1+6*0 & 4*0+5*1+6*1 \\ 7*1+8*0+9*1 & 7*1+8*1+9*0 & 7*0+8*1+9*1 \end{bmatrix} =$$

$$\begin{bmatrix} 1+0+3 & 1+2+0 & 0+2+3 \\ 4+0+6 & 4+5+0 & 0+5+6 \\ 7+0+9 & 7+8+0 & 0+8+9 \end{bmatrix} = \begin{bmatrix} 4 & 3 & 5 \\ 10 & 9 & 11 \\ 16 & 15 & 17 \end{bmatrix}$$

```
In [ ]: m1 = np.array([[1,2,3],[4,5,6],[7,8,9]])
m2 = np.array([[1,1,0],[0,1,1],[1,0,1]])

print("m1")
print(m1.shape)
print(m1)
print("m2")
print(m2.shape)
print(m2)
print("m1 x m2")
m3 = np.matmul(m1, m2)
print(m3.shape)
print(m3)
```

```
m1
(3, 3)
[[1 2 3]
 [4 5 6]
 [7 8 9]]
m2
(3, 3)
[[1 1 0]
 [0 1 1]
 [1 0 1]]
m1 x m2
(3, 3)
[[ 4  3  5]
 [10  9 11]
 [16 15 17]]
```

C.

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

Here we have two 3x3 matrices which can be multiplied together. The result is a 3x3 matrix.

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} 1*1+1*4+0*7 & 1*2+1*5+0*8 & 1*3+1*6+0*9 \\ 0*1+1*4+1*7 & 0*2+1*5+1*8 & 0*3+1*6+1*9 \\ 1*1+0*4+1*7 & 1*2+0*5+1*8 & 1*3+0*6+1*9 \end{bmatrix} =$$

$$\begin{bmatrix} 1+4+0 & 2+5+0 & 3+6+0 \\ 0+4+7 & 0+5+8 & 0+6+9 \\ 1+0+7 & 2+0+8 & 3+0+9 \end{bmatrix} = \begin{bmatrix} 5 & 7 & 9 \\ 11 & 13 & 15 \\ 8 & 10 & 12 \end{bmatrix}$$

```
In [ ]: m1 = np.array([[1,1,0],[0,1,1],[1,0,1]])
m2 = np.array([[1,2,3],[4,5,6],[7,8,9]])

print("m1")
print(m1.shape)
print(m1)
print("m2")
print(m2.shape)
print(m2)
print("m1 x m2")
m3 = np.matmul(m1, m2)
print(m3.shape)
print(m3)
```

```

m1
(3, 3)
[[1 1 0]
 [0 1 1]
 [1 0 1]]
m2
(3, 3)
[[1 2 3]
 [4 5 6]
 [7 8 9]]
m1 x m2
(3, 3)
[[ 5  7  9]
 [11 13 15]
 [ 8 10 12]]

```

d.

$$\begin{bmatrix} 1 & 2 & 1 & 2 \\ 4 & 1 & -1 & 4 \end{bmatrix} \begin{bmatrix} 0 & 3 \\ 1 & -1 \\ 2 & 1 \\ 5 & 2 \end{bmatrix}$$

Here we have a 2x4 matrix multiplied by a 4x2 matrix which can be multiplied together. The result is a 2x2 matrix.

$$\begin{bmatrix} 1 & 2 & 1 & 2 \\ 4 & 1 & -1 & 4 \end{bmatrix} \begin{bmatrix} 0 & 3 \\ 1 & -1 \\ 2 & 1 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} 1*0 + 2*1 + 1*2 + 2*5 & 1*3 + 2*(-1) + 1*1 + 2*2 \\ 4*0 + 1*1 + (-1)*2 + 4*5 & 4*3 + 1*(-1) + (-1)*1 + 4*2 \end{bmatrix} =$$

$$\begin{bmatrix} 0 + 2 + 2 + 10 & 3 + -2 + 1 + 4 \\ 0 + 1 + -2 + 20 & 12 + -1 + -1 + 8 \end{bmatrix} = \begin{bmatrix} 14 & 6 \\ 19 & 18 \end{bmatrix}$$

```

In [ ]: m1 = np.array([[1,2,1,2],[4,1,-1,4]])
        m2 = np.array([[0,3],[1,-1],[2,1],[5,2]])

        print("m1")
        print(m1.shape)

```

```

print(m1)
print("m2")
print(m2.shape)
print(m2)
print("m1 x m2")
m3 = np.matmul(m1, m2)
print(m3.shape)
print(m3)

```

```

m1
(2, 4)
[[ 1  2  1  2]
 [ 4  1 -1  4]]
m2
(4, 2)
[[ 0  3]
 [ 1 -1]
 [ 2  1]
 [ 5  2]]
m1 x m2
(2, 2)
[[14  6]
 [19 18]]

```

e.

$$\begin{bmatrix} 0 & 3 \\ 1 & -1 \\ 2 & 1 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 & 2 \\ 4 & 1 & -1 & 4 \end{bmatrix}$$

Here we have a 4x2 matrix multiplied by a 2x4 matrix which can be multiplied together. The result is a 4x4 matrix.

$$\begin{bmatrix} 0 & 3 \\ 1 & -1 \\ 2 & 1 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 & 2 \\ 4 & 1 & -1 & 4 \end{bmatrix} = \begin{bmatrix} 0*1+3*4 & 0*2+3*1 & 0*1+3*-1 & 0*2+3*4 \\ 1*1+(-1)*4 & 1*2+(-1)*1 & 1*1+(-1)*-1 & 1*2+(-1)*4 \\ 2*1+1*4 & 2*2+1*1 & 2*1+1*-1 & 2*2+1*4 \\ 5*1+2*4 & 5*2+2*1 & 5*1+2*-1 & 5*2+2*4 \end{bmatrix} = \\
 \begin{bmatrix} 0+12 & 0+3 & 0+-3 & 0+12 \\ 1+-4 & 2+-1 & 1+1 & 2+-4 \\ 2+4 & 4+1 & 2+-1 & 4+4 \\ 5+8 & 10+2 & 5+-2 & 10+8 \end{bmatrix} = \begin{bmatrix} 12 & 3 & -3 & 12 \\ -3 & 1 & 2 & -2 \\ 6 & 5 & 1 & 8 \\ 13 & 12 & 3 & 18 \end{bmatrix}$$

```

In [ ]: m1 = np.array([[0,3],[1,-1],[2,1],[5,2]])
        m2 = np.array([[1,2,1,2],[4,1,-1,4]])

        print("m1")
        print(m1.shape)
        print(m1)
        print("m2")
        print(m2.shape)
        print(m2)
        print("m1 x m2")
        m3 = np.matmul(m1, m2)
        print(m3.shape)
        print(m3)

```

```

m1
(4, 2)
[[ 0  3]
 [ 1 -1]
 [ 2  1]
 [ 5  2]]
m2
(2, 4)
[[ 1  2  1  2]
 [ 4  1 -1  4]]
m1 x m2
(4, 4)
[[12  3 -3 12]
 [-3  1  2 -2]
 [ 6  5  1  8]
 [13 12  3 18]]

```

For 2.5 – 2.7, calculate by hand and then show how the results of using `numpy.linalg.solve`

2.5

Find the set S of all solutions in x of the following inhomogeneous linear systems $Ax = b$, where A and b are defined as follows:

a.

$$A = \begin{bmatrix} 1 & 1 & -1 & -1 \\ 2 & 5 & -7 & -5 \\ 2 & -1 & 1 & 3 \\ 5 & 2 & -4 & 2 \end{bmatrix}, \quad b = \begin{bmatrix} 1 \\ -2 \\ 4 \\ 6 \end{bmatrix}$$

Using Gauss-Jordan to solve the equations. Create the augmented matrix $\begin{bmatrix} 1 & 1 & -1 & -1 & 1 \\ 2 & 5 & -7 & -5 & -2 \\ 2 & -1 & 1 & 3 & 4 \\ 5 & 2 & -4 & 2 & 6 \end{bmatrix}$ Multiply row one by 2

$$\begin{bmatrix} 2 & 2 & -2 & -2 & 2 \\ 2 & 5 & -7 & -5 & -2 \\ 2 & -1 & 1 & 3 & 4 \\ 5 & 2 & -4 & 2 & 6 \end{bmatrix} \quad \text{Subtract row one from row two} \quad \begin{bmatrix} 2 & 2 & -2 & -2 & 2 \\ 0 & 3 & -5 & -3 & -4 \\ 2 & -1 & 1 & 3 & 4 \\ 5 & 2 & -4 & 2 & 6 \end{bmatrix} \quad \text{Subtract row one from row three}$$

$$\begin{bmatrix} 2 & 2 & -2 & -2 & 2 \\ 0 & 3 & -5 & -3 & -4 \\ 0 & -3 & 3 & 5 & 2 \\ 5 & 2 & -4 & 2 & 6 \end{bmatrix} \quad \text{Multiply row one by } \frac{1}{2} \quad \begin{bmatrix} 1 & 1 & -1 & -1 & 1 \\ 0 & 3 & -5 & -3 & -4 \\ 0 & -3 & 3 & 5 & 2 \\ 5 & 2 & -4 & 2 & 6 \end{bmatrix} \quad \text{Multiply row one by 5}$$

$$\begin{bmatrix} 5 & 5 & -5 & -5 & 5 \\ 0 & 3 & -5 & -3 & -4 \\ 0 & -3 & 3 & 5 & 2 \\ 5 & 2 & -4 & 2 & 6 \end{bmatrix} \quad \text{Subtract row one from row four} \quad \begin{bmatrix} 5 & 5 & -5 & -5 & 5 \\ 0 & 3 & -5 & -3 & -4 \\ 0 & -3 & 3 & 5 & 2 \\ 0 & -3 & 1 & 7 & 1 \end{bmatrix} \quad \text{Multiply row one by } \frac{1}{5}$$

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$$\begin{bmatrix} 1 & 0 & 0 & \frac{2}{3} & \frac{5}{3} \\ 0 & 1 & 0 & -\frac{8}{3} & \frac{1}{3} \\ 0 & 0 & -4 & 4 & -4 \\ 0 & 0 & -4 & 4 & -3 \end{bmatrix}$$

Subtract row three from row four

$$\begin{bmatrix} 1 & 0 & 0 & \frac{2}{3} & \frac{5}{3} \\ 0 & 1 & 0 & -\frac{8}{3} & \frac{1}{3} \\ 0 & 0 & -4 & 4 & -4 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

We now have all zeros in row four so the

system is inconsistent. There is no solution.

```
In [ ]: A = np.array([[1,1,-1,-1],[2,5,-7,-5],[2,-1,1,3],[5,2,-4,2]])
        b = np.array([[1],[-2],[4],[6]])
```

```
print("A")
print(A.shape)
print(A)
print("b")
print(b.shape)
print(b)
print("Solving Ax = b")
sol = np.linalg.solve(A,b)
print(sol.shape)
print(sol)
```

```
A
(4, 4)
[[ 1  1 -1 -1]
 [ 2  5 -7 -5]
 [ 2 -1  1  3]
 [ 5  2 -4  2]]
b
(4, 1)
[[ 1]
 [-2]
 [ 4]
 [ 6]]
Solving Ax = b
(4, 1)
[[ 7.50599938e+14]
 [-3.00239975e+15]
 [-1.12589991e+15]
 [-1.12589991e+15]]
```

Why could Numpy find a solution? It must be using a numerical method that will approximate a solution. The numbers are very small.

b.

$$A = \begin{bmatrix} 1 & -1 & 0 & 0 & 1 \\ 1 & 1 & 0 & -3 & 0 \\ 2 & -1 & 0 & 1 & -1 \\ -1 & 2 & 0 & -2 & -1 \end{bmatrix}, \quad b = \begin{bmatrix} 3 \\ 6 \\ 5 \\ -1 \end{bmatrix}$$

Using Gauss-Jordan to solve the equations. Create the augmented matrix

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 1 & 3 \\ 1 & 1 & 0 & -3 & 0 & 6 \\ 2 & -1 & 0 & 1 & -1 & 5 \\ -1 & 2 & 0 & -2 & -1 & -1 \end{bmatrix}$$

Subtract row one from

row two

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 1 & 3 \\ 0 & 2 & 0 & -3 & -1 & 3 \\ 2 & -1 & 0 & 1 & -1 & 5 \\ -1 & 2 & 0 & -2 & -1 & -1 \end{bmatrix}$$

Subtract 2 times the first row from the third row

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 1 & 3 \\ 0 & 2 & 0 & -3 & -1 & 3 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ -1 & 2 & 0 & -2 & -1 & -1 \end{bmatrix}$$

Subtract -1 times the first row from the fourth row

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 1 & 3 \\ 0 & 2 & 0 & -3 & -1 & 3 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 1 & 0 & -2 & 0 & 2 \end{bmatrix}$$

Swap the second and third rows

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 1 & 3 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 2 & 0 & -3 & -1 & 3 \\ 0 & 1 & 0 & -2 & 0 & 2 \end{bmatrix}$$

Subtract -1 times the second row from the first row

$$\begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 2 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 2 & 0 & -3 & -1 & 3 \\ 0 & 1 & 0 & -2 & 0 & 2 \end{bmatrix}$$

Subtract 2

times the second row from the third row

$$\begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 2 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & -5 & 5 & 5 \\ 0 & 1 & 0 & -2 & 0 & 2 \end{bmatrix}$$

Subtract the second row from the fourth row

$$\begin{array}{l}
 \begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 2 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & -5 & 5 & 5 \\ 0 & 0 & 0 & -3 & 3 & 3 \end{bmatrix} \xrightarrow{\text{Divide the third row by } -5} \begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 2 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & -3 & 3 & 3 \end{bmatrix} \xrightarrow{\text{Subtract the third row from the first row}} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 3 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & -3 & 3 & 3 \end{bmatrix} \\
 \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 3 \\ 0 & 1 & 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & -3 & 3 & 3 \end{bmatrix} \xrightarrow{\text{Subtract the third row from the second row}} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 3 \\ 0 & 1 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & -3 & 3 & 3 \end{bmatrix} \xrightarrow{\text{Subtract } -3 \text{ times the third row from the fourth row}} \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 3 \\ 0 & 1 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}
 \end{array}$$

Reading from the matrix, the solution set is: $x_1 = 3 + x_5$ $x_2 = 2x_5$

x_3 is free $x_4 = -1 + x_5$ x_5 is free

```

In [ ]: A = np.array([[1,-1,0,0,1],[1,1,0,-3,0],[2,-1,0,1,-1],[-1,2,0,-2,-1]])
        b = np.array([[3],[6],[5],[-1]])

print("A")
print(A.shape)
print(A)
print("b")
print(b.shape)
print(b)
print("Solving Ax = b")
sol = np.linalg.solve(A,b)
print(sol.shape)
print(sol)

```

```
A
(4, 5)
[[ 1 -1  0  0  1]
 [ 1  1  0 -3  0]
 [ 2 -1  0  1 -1]
 [-1  2  0 -2 -1]]
```

```
b
(4, 1)
[[ 3]
 [ 6]
 [ 5]
 [-1]]
```

Solving $Ax = b$

```
-----
LinAlgError                                Traceback (most recent call last)
Cell In[8], line 11
      9 print(b)
     10 print("Solving Ax = b")
--> 11 sol = np.linalg.solve(A,b)
     12 print(sol.shape)
     13 print(sol)

File c:\Users\Micha\AppData\Local\Programs\Python\Python312\Lib\site-packages\numpy.linalg.linalg.py:396, in solve(a, b)
    394 a, _ = _makearray(a)
    395 _assert_stacked_2d(a)
--> 396 _assert_stacked_square(a)
    397 b, wrap = _makearray(b)
    398 t, result_t = _commonType(a, b)

File c:\Users\Micha\AppData\Local\Programs\Python\Python312\Lib\site-packages\numpy.linalg.linalg.py:213, in _assert_stacked_square(*arrays)
    211 m, n = a.shape[-2:]
    212 if m != n:
--> 213     raise LinAlgError('Last 2 dimensions of the array must be square')

LinAlgError: Last 2 dimensions of the array must be square
```

I suppose that Numpy is using a numerical method that can only solve for one value and therefore does not work in this case.

2.6

Use Gaussian Elimination, find all solutions of the inhomogeneous equation system $Ax = b$ with

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{bmatrix}, \quad b = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

Using Gauss-Jordan to solve the equations. Create the augmented matrix $\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}$ Subtract row one from row three

row three $\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & -1 & 1 & -1 \end{bmatrix}$ Multiply row three by -1 $\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & -1 & 1 \end{bmatrix}$ Subtract row three from row two

one $\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & -1 & 1 \end{bmatrix}$ Subtract row three from row two $\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 1 & -1 & 1 \end{bmatrix}$ Reading from the matrix,

the solution set is: x_1 is free $x_2 = 1 - x_6$ x_3 is free $x_4 = -2 - x_6$ $x_5 = 1 + x_6$ x_6 is free

```
In [ ]: A = np.array([[0,1,0,0,1,0],[0,0,0,1,1,0],[0,1,0,0,0,1]])
b = np.array([[2],[-1],[1]])

print("A")
print(A.shape)
print(A)
print("b")
print(b.shape)
print(b)
print("Solving Ax = b")
sol = np.linalg.solve(A,b)
print(sol.shape)
print(sol)
```

```
A
(3, 6)
[[0 1 0 0 1 0]
 [0 0 0 1 1 0]
 [0 1 0 0 0 1]]
```

```
b
(3, 1)
[[ 2]
 [-1]
 [ 1]]
```

Solving $Ax = b$

LinAlgError Traceback (most recent call last)

Cell In[9], line 11

```
9 print(b)
10 print("Solving Ax = b")
--> 11 sol = np.linalg.solve(A,b)
12 print(sol.shape)
13 print(sol)
```

File c:\Users\Micha\AppData\Local\Programs\Python\Python312\Lib\site-packages\numpy\linalg\linalg.py:396, in solve(a, b)

```
394 a, _ = _makearray(a)
395 _assert_stacked_2d(a)
--> 396 _assert_stacked_square(a)
397 b, wrap = _makearray(b)
398 t, result_t = _commonType(a, b)
```

File c:\Users\Micha\AppData\Local\Programs\Python\Python312\Lib\site-packages\numpy\linalg\linalg.py:213, in _assert_stacked_square(*arrays)

```
211 m, n = a.shape[-2:]
212 if m != n:
--> 213     raise LinAlgError('Last 2 dimensions of the array must be square')
```

LinAlgError: Last 2 dimensions of the array must be square

2.7

Find all solutions in $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3$ of the equation system $Ax = 12x$, where

$$A = \begin{bmatrix} 6 & 4 & 3 \\ 6 & 0 & 9 \\ 0 & 8 & 0 \end{bmatrix} \text{ and } \sum_{i=1}^3 x_i = 1$$

Given $A = \begin{bmatrix} 6 & 4 & 3 \\ 6 & 0 & 9 \\ 0 & 8 & 0 \end{bmatrix}$ $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ $Ax = 12x$ and $\sum_{i=1}^3 x_i = 1$ then $\frac{1}{12}Ax = x$ $\frac{1}{12} \begin{bmatrix} 6 & 4 & 3 \\ 6 & 0 & 9 \\ 0 & 8 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

$$\begin{bmatrix} \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & 0 & \frac{3}{4} \\ 0 & \frac{2}{3} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

From row three of the matrix $\frac{2}{3}x_2 = x_3$ From row one of the matrix $\frac{1}{2}x_1 + \frac{1}{3}x_2 + \frac{1}{4}x_3 = x_1$

Substituting for x_3 $\frac{1}{2}x_1 + \frac{1}{3}x_2 + \frac{1}{4} \cdot \frac{2}{3}x_2 = x_1$ Calculating $\frac{1}{2}x_1 + \frac{1}{3}x_2 + \frac{2}{12}x_2 = x_1$ Multiply term two by $\frac{4}{4}$
 $\frac{1}{2}x_1 + \frac{4}{12}x_2 + \frac{2}{12}x_2 = x_1$ Combine terms two and three $\frac{1}{2}x_1 + \frac{6}{12}x_2 = x_1$ Simplify $\frac{1}{2}x_1 + \frac{1}{2}x_2 = x_1$ Combine terms one and two $\frac{1}{2}x_2 = \frac{1}{2}x_1$ Multiply both sides by 2 $x_2 = x_1$ We now have $x_1 = x_2$ and $x_3 = \frac{2}{3}x_2$. We also know that $\sum_{i=1}^3 x_i = 1$. Expand the sum $x_1 + x_2 + x_3 = 1$ Substitute for x_1 and x_3 $x_2 + x_2 + \frac{2}{3}x_2 = 1$ Combine terms one, two, and three $2\frac{2}{3}x_2 = 1$ Express as a fraction $\frac{8}{3}x_2 = 1$ Solve for x_2 $x_2 = \frac{3}{8}$ Therefore $x_1 = \frac{3}{8}$ $x_2 = \frac{3}{8}$ $x_3 = \frac{2}{8}$

This seems to be the only solution. I cannot think of a way to present this to Numpy to calculate.

For 2.8, calculate by hand and then show the results of using `numpy.linalg.inv`

2.8

Determine the inverses of the following matrices if possible:

a.

$$A = \begin{bmatrix} 2 & 3 & 4 \\ 3 & 4 & 5 \\ 4 & 5 & 6 \end{bmatrix}$$

Attempting to invert the matrix by augmenting it with an Identity Matrix and then performing gaussian elimination. Append the

identity matrix $\begin{bmatrix} 2 & 3 & 4 & 1 & 0 & 0 \\ 3 & 4 & 5 & 0 & 1 & 0 \\ 4 & 5 & 6 & 0 & 0 & 1 \end{bmatrix}$ Swap rows 2 and 3 $\begin{bmatrix} 2 & 3 & 4 & 1 & 0 & 0 \\ 4 & 5 & 6 & 0 & 0 & 1 \\ 3 & 4 & 5 & 0 & 1 & 0 \end{bmatrix}$ Subtract 2 * Row 1 from Row 2

$\begin{bmatrix} 2 & 3 & 4 & 1 & 0 & 0 \\ 0 & -1 & -2 & -2 & 0 & 1 \\ 3 & 4 & 5 & 0 & 1 & 0 \end{bmatrix}$ Multiply row 3 by 2 $\begin{bmatrix} 2 & 3 & 4 & 1 & 0 & 0 \\ 0 & -1 & -2 & -2 & 0 & 1 \\ 6 & 8 & 10 & 0 & 2 & 0 \end{bmatrix}$ Subtract 3 times row 1 from row 3

$\begin{bmatrix} 2 & 3 & 4 & 1 & 0 & 0 \\ 0 & -1 & -2 & -2 & 0 & 1 \\ 0 & -1 & -2 & -3 & 2 & 0 \end{bmatrix}$ Subtract row 2 from row 3 $\begin{bmatrix} 2 & 3 & 4 & 1 & 0 & 0 \\ 0 & -1 & -2 & -2 & 0 & 1 \\ 0 & 0 & 0 & -1 & 2 & -1 \end{bmatrix}$ The inverse is There is no inverse since the two rows had the same values, the matrix is singular.

```
In [ ]: # In code
A = np.array([[2,3,4],[3,4,5],[4,5,6]])

print("A")
print(A.shape)
print(A)
print("Calculating the inverse of A")
sol = np.linalg.inv(A)
print(sol.shape)
print(sol)
```

```
A
(3, 3)
[[2 3 4]
 [3 4 5]
 [4 5 6]]
Calculating the inverse of A
```

```

-----
LinAlgError                                Traceback (most recent call last)
Cell In[10], line 8
      6 print(A)
      7 print("Calculating the inverse of A")
----> 8 sol = np.linalg.inv(A)
      9 print(sol.shape)
     10 print(sol)

File c:\Users\Micha\AppData\Local\Programs\Python\Python312\Lib\site-packages\numpy.linalg.linalg.py:561, in inv(a)
     559 signature = 'D->D' if isComplexType(t) else 'd->d'
     560 extobj = get_linalg_error_extobj(_raise_linalgerror_singular)
--> 561 ainv = umath_linalg.inv(a, signature=signature, extobj=extobj)
     562 return wrap(ainv.astype(result_t, copy=False))

File c:\Users\Micha\AppData\Local\Programs\Python\Python312\Lib\site-packages\numpy.linalg.linalg.py:112, in _raise_linalgerror_singular(err, flag)
     111 def _raise_linalgerror_singular(err, flag):
--> 112     raise LinAlgError("Singular matrix")

LinAlgError: Singular matrix

```

My results and Numpy agree that this matrix has no inverse.

b.

$$A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

Attempting to invert the matrix by augmenting it with an Identity Matrix and then performing gaussian elimination. Append the

$$\text{identity matrix} \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{array}{l} \text{Subtract row 1 from row 3} \\ \text{Subtract row 1 from row 4} \end{array}$$

$$\begin{array}{l}
 \text{from row 4} \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 1 & -1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 \end{bmatrix} \quad \text{Subtract row 2 from row 3} \quad \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & -2 & 1 & -1 & -1 & 1 & 0 \\ 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 \end{bmatrix} \quad \text{Subtract row} \\
 \\
 2 \text{ from row 4} \quad \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & -2 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & -1 & 0 & -1 & -1 & 0 & 1 \end{bmatrix} \quad \text{Swap rows 3 and 4} \quad \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 & -1 & -1 & 0 & 1 \\ 0 & 0 & -2 & 1 & -1 & -1 & 1 & 0 \end{bmatrix} \quad \text{Multiply row 3 by} \\
 \\
 -1 \quad \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & -2 & 1 & -1 & -1 & 1 & 0 \end{bmatrix} \quad \text{Subtract row 3 from row 1} \quad \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & -2 & 1 & -1 & -1 & 1 & 0 \end{bmatrix} \quad \text{Subtract row 3} \\
 \\
 \text{from row 2} \quad \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & -2 & 1 & -1 & -1 & 1 & 0 \end{bmatrix} \quad \text{Multiply row 3 by } -2 \quad \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & -2 & 0 & -2 & -2 & 0 & 2 \\ 0 & 0 & -2 & 1 & -1 & -1 & 1 & 0 \end{bmatrix} \quad \text{Subtract row 3} \\
 \\
 \text{from row 4} \quad \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & -2 & 0 & -2 & -2 & 0 & 2 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & -2 \end{bmatrix} \quad \text{Multiply row 3 by } -\frac{1}{2} \quad \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & -2 \end{bmatrix} \quad \text{The inverse is} \\
 \\
 \begin{bmatrix} 0 & -1 & 0 & 1 \\ -1 & 0 & 0 & 1 \\ 1 & 1 & 0 & -1 \\ 1 & 1 & 1 & -2 \end{bmatrix}
 \end{array}$$

```

In [ ]: # In code
A = np.array([[1,0,1,0],[0,1,1,0],[1,1,0,1],[1,1,1,0]])

print("A")
print(A.shape)
print(A)
print("Calculating the inverse of A")
sol = np.linalg.inv(A)
print(sol.shape)
print(sol)

```

A

(4, 4)

[[1 0 1 0]

[0 1 1 0]

[1 1 0 1]

[1 1 1 0]]

Calculating the inverse of A

(4, 4)

[[0. -1. 0. 1.]

[-1. 0. 0. 1.]

[1. 1. -0. -1.]

[1. 1. 1. -2.]]

The results match. It actually took me multiple tries to get to a solution.