

Blatt 3

```
cl c; cl ear;  
format l ong;
```

Aufgabe 1

```
Ni 0=l i nquadref(0, 0)
```

```
Ni 0 = 4×1  
0. 2500000000000000  
0. 2500000000000000  
0. 2500000000000000  
0. 2500000000000000
```

```
Ni 0577=l i nquadref(0. 577, -0. 577)
```

```
Ni 0577 = 4×1  
0. 1667677500000000  
0. 6217322500000000  
0. 1667677500000000  
0. 0447322500000000
```

Aufgabe 2

```
x_node=[ -1, -1; +1, -1; +1, +1; -1, +1];  
y_node=[0; 1; 3; 1];  
val 0=0;  
% f_L=0, 0  
for i =1: 4  
    val 0=val 0+Ni 0(i) . *y_node(i) ;  
end  
val 0
```

```
val 0 =  
1. 2500000000000000
```

```
% f_L=0. 577, -0. 577  
val 0577=0;  
for i =1: 4  
    val 0577=val 0577+Ni 0577(i) . *y_node(i) ;  
end  
val 0577
```

```
val 0577 =  
1. 1667677500000000
```

Aufgabe 3

```
dNi 0=l i nquadderi vref(0, 0)
```

```
dNi 0 = 4×2  
-0. 2500000000000000 -0. 2500000000000000  
0. 2500000000000000 -0. 2500000000000000  
0. 2500000000000000 0. 2500000000000000  
-0. 2500000000000000 0. 2500000000000000
```

```
dNi 0577=l i nquadderi vref(0. 577, -0. 577)
```

```
dNi 0577 = 4x2  
-0. 3942500000000000 -0. 1057500000000000  
0. 3942500000000000 -0. 3942500000000000  
0. 1057500000000000 0. 3942500000000000  
-0. 1057500000000000 0. 1057500000000000
```

Aufgabe 4

```
x_node=[ -1, -1; +1, -1; +1, +1; -1, +1];  
y_node=[0; 1; 3; 1];  
dxi =0; deta=0;  
% f_L=0, 0  
for i =1: 4  
    dxi =dxi +dNi 0(i , 1). *y_node(i );  
    deta=deta+dNi 0(i , 2). *y_node(i );  
end  
dxi
```

```
dxi =  
0. 7500000000000000
```

```
deta
```

```
deta =  
0. 7500000000000000
```

```
% f_L=0. 577, -0. 577  
dxi =0; deta=0;  
for i =1: 4  
    dxi =dxi +dNi 0577(i , 1). *y_node(i );  
    deta=deta+dNi 0577(i , 2). *y_node(i );  
end  
dxi
```

```
dxi =  
0. 6057500000000000
```

```
deta
```

```
deta =  
0. 8942500000000000
```

```
function val = l i nquadref(xi , eta)  
N1 = 0. 25 * (1 - xi ) * (1 - eta);  
N2 = 0. 25 * (1 + xi ) * (1 - eta);  
N3 = 0. 25 * (1 + xi ) * (1 + eta);  
N4 = 0. 25 * (1 - xi ) * (1 + eta);  
val = [N1; N2; N3; N4];  
end
```

```

function deriv = linquadderivref(xi, eta)
a11 = eta/4 - 1/4; % dN1/dxi dN1/deta
a12 = xi/4 - 1/4;
a21 = 1/4 - eta/4;
a22 = - xi/4 - 1/4;
a31 = eta/4 + 1/4;
a32 = xi/4 + 1/4 ;
a41 = - eta/4 - 1/4;
a42 = 1/4 - xi/4;
deriv = [a11 a12;
         a21 a22;
         a31 a32;
         a41 a42];
end

```