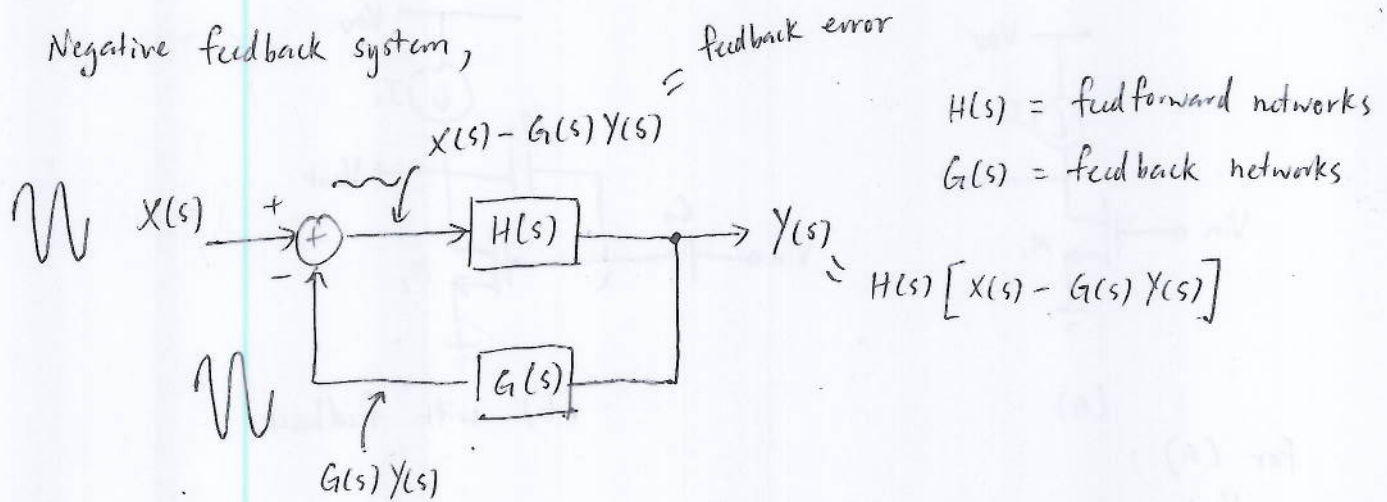


Chapter 7 - Feedback in Amplifiers

General Considerations

Negative feedback system,



$$\therefore \frac{Y(s)}{X(s)} = \frac{H(s)}{1 + G(s)H(s)}$$

$\frac{Y(s)}{X(s)}$ = closed-loop transfer function

$H(s)$ = open-loop transfer function (represents an amplifier)

more precise definition,

~~$H(s)$ represents an amplifier~~

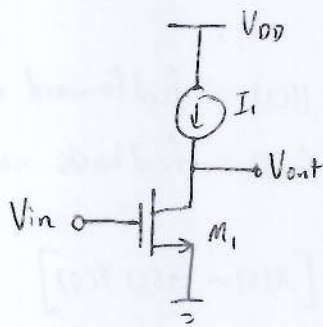
$G(s)$ = frequency-independent quantity. ($B \rightarrow$ feedback factor)

There are four elements in the feedback system:

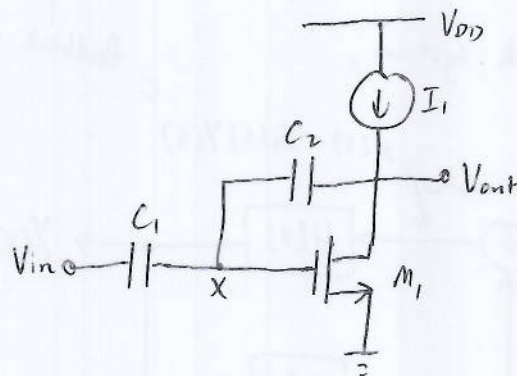
- ① feedforward amplifier
- ② a means of sensing the output
- ③ feedback network
- ④ a means of generating the feedback error.

Properties of Feedback Circuits.

① Gain Desensitization



(a)



(b) with feedback

For (a) :

$$\frac{V_{out}}{V_{in}} = -g_{m1} r_{o1}$$

→ poor definition of the gain. g_{m1} and r_{o1} vary with process and temperature.

For (b) :

$$\frac{V_{out}}{V_x} = -g_{m1} r_{o1}$$

Node analysis at point X :

$$(V_{out} - V_x) C_2 s + (V_{in} - V_x) C_1 s = 0$$

$$\frac{V_{out}}{V_{in}} = - \frac{1}{\left(1 + \frac{1}{g_{m1} r_{o1}}\right) \frac{C_2}{C_1} + \frac{1}{g_{m1} r_{o1}}}$$

If $g_{m1} r_{o1}$ is sufficiently large ,

$$\frac{V_{out}}{V_{in}} = - \frac{C_1}{C_2}$$

→ Gain can be controlled with much higher accuracy

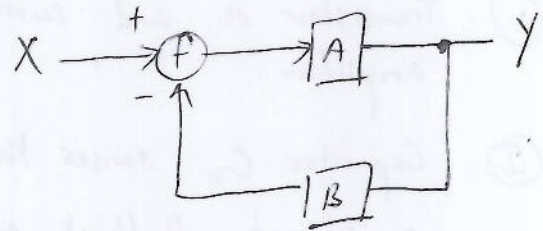
→ If C_1 and C_2 are made of same material, then process and temperature variations do not change C_1/C_2

For more general case,

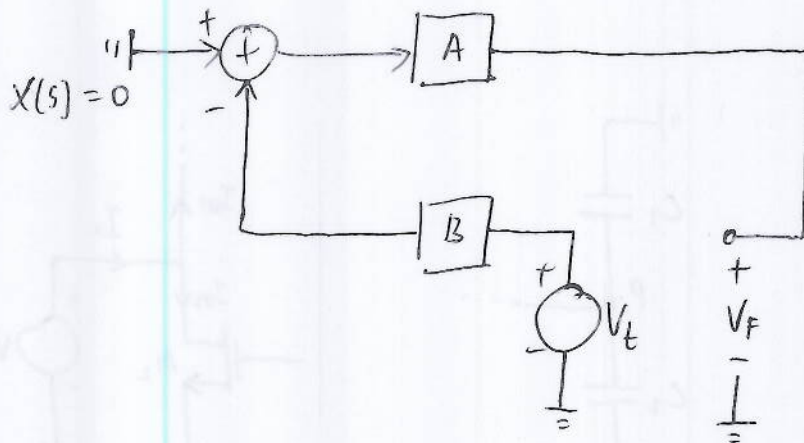
$$\frac{Y}{X} = \frac{A}{1 + BA}$$

$$\approx \frac{1}{B} \left(1 \right) \left(\frac{1}{BA} \right)$$

If $BA \gg 1 \rightarrow \frac{Y}{X} \approx \frac{1}{B}$
 ↑
 loop gain



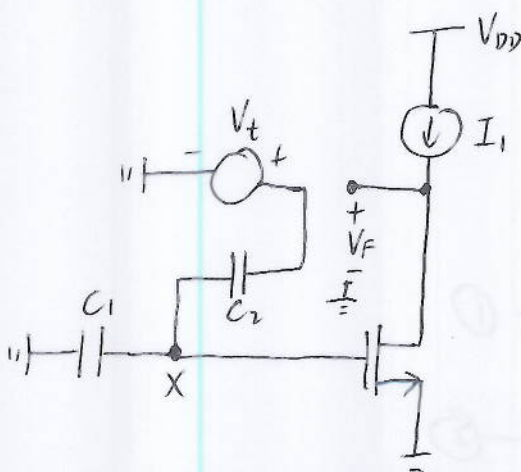
To compute loop gain,



$$V_t \beta (-1) A = V_F$$

$$\therefore \frac{V_F}{V_t} = -\beta A$$

For simple feedback circuit,



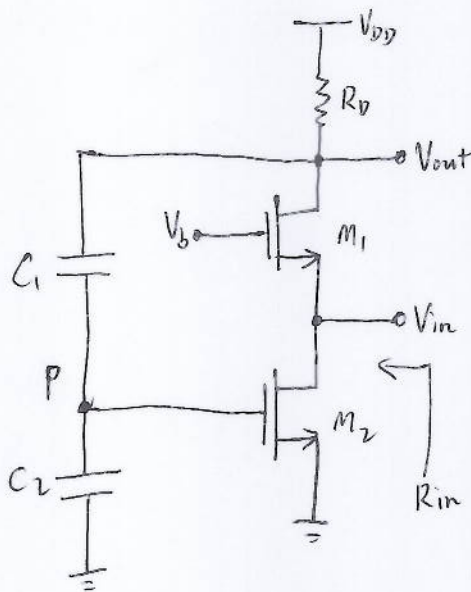
$$V_t \frac{C_2}{C_1 + C_2} (-g_{m1} r_{o1}) = V_F$$

$$\frac{V_F}{V_t} = - \frac{C_2}{C_1 + C_2} g_{m1} r_{o1}$$

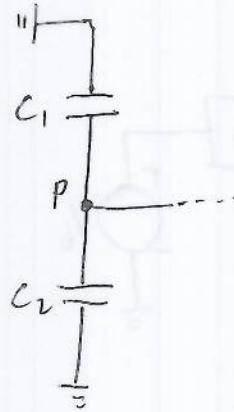
Four elements of feedback in this circuit ?

- ① Transistor M_1 and current source I_1 constitute the feedforward amplifier.
- ② Capacitor C_2 senses the output voltage and converts it to a current feedback signal, which is then added to the current produced by V_{in} through C_1 .

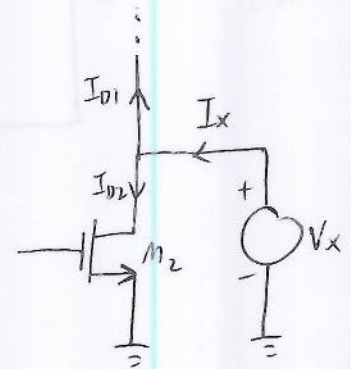
② Terminal Impedance Modification



common-gate
with feedback



open-loop



calculation of
input resistance.

a) Consider ~~the~~ open-loop and $\lambda = 0$,

$$R_{in, open} = \frac{1}{g_{m1} + g_{mb1}}$$

b) For closed-loop circuit,

$$V_{out} = (g_{m1} + g_{mb1}) V_x R_D \quad \text{--- ①}$$

$$V_p = \frac{C_1}{C_1 + C_2} V_{out} \quad \text{--- ②}$$

$$\therefore V_p = (g_{m1} + g_{mb1}) V_x R_D \frac{C_1}{C_1 + C_2}$$

Thus, small-signal drain current of M_2

$$I_{D2} = g_{m2} (g_{m1} + g_{mb1}) V_x R_D \frac{C_1}{C_1 + C_2}$$

Adding this current to the drain current of M_1 :

$$\begin{aligned} I_x &= I_{D1} + I_{D2} \\ &= (g_{m1} + g_{mb1}) V_x + g_{m2} (g_{m1} + g_{mb1}) \frac{C_1}{C_1 + C_2} R_D V_x \\ &= (g_{m1} + g_{mb1}) \left(1 + g_{m2} R_D \frac{C_1}{C_1 + C_2} \right) V_x \end{aligned}$$

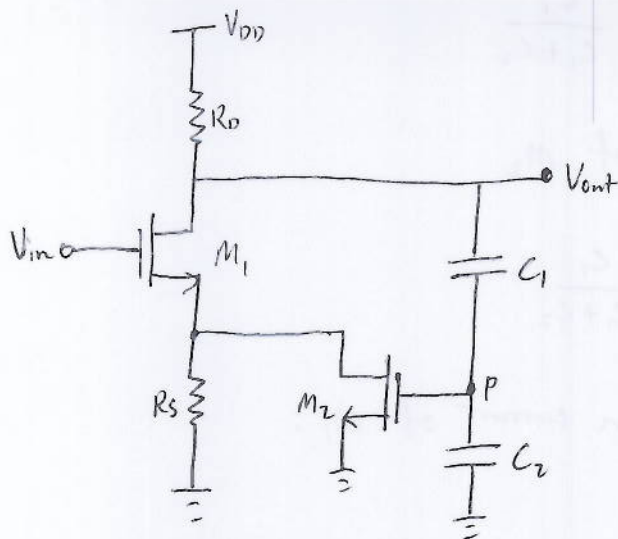
Therefore,

$$\begin{aligned} R_{in, closed} &= \frac{V_x}{I_x} \\ &= \frac{1}{g_{m1} + g_{mb1}} \cdot \frac{1}{1 + g_{m2} R_D \frac{C_1}{C_1 + C_2}} \end{aligned}$$

\uparrow loop gain.

Four elements of feedback?

- ① M_1 and $R_D \rightarrow$ feedforward amplifier
- ② C_1 and $C_2 \rightarrow$ sense output
- ③ C_1, C_2 and $M_2 \rightarrow$ feedback network
- ④ the subtraction occurs in the current domain at the input terminal.



CS stage with feedback

calculation of output resistance

$$I_{D1} = V_x \underbrace{\frac{C_1}{C_1 + C_2} g_{m2}}_{I_{D2}} \underbrace{\frac{R_s}{R_s + \frac{1}{g_{m1} + g_{mb1}}}}_{\text{current divider rule}}$$

Since $I_x = V_x / R_D + I_{D1}$

$$\frac{V_x}{I_x} = \frac{R_D}{1 + \frac{g_{m2} R_s (g_{m1} + g_{mb1}) R_D}{(g_{m1} + g_{mb1}) R_s + 1} \frac{C_1}{C_1 + C_2}}$$

- M_1 , R_s and R_D constitute a common-source stage and G
- C_1 , C_2 and M_2 sense the output voltage
- Returning a current equal to $[C_1 / (C_1 + C_2)] V_{out} g_{m2}$ to the source of M_1 .

③ Bandwidth Modification.

Suppose the feedforward amplifier has a one-pole transfer function:

$$A(s) = \frac{A_0}{1 + \frac{s}{\omega_0}}$$

where A_0 = low-frequency gain

ω_0 = 3-dB bandwidth

What is the transfer function of the closed-loop system?

$$\frac{Y(s)}{X(s)} = \frac{\frac{A_0}{1 + \frac{s}{\omega_0}}}{1 + B \frac{A_0}{1 + \frac{s}{\omega_0}}}$$

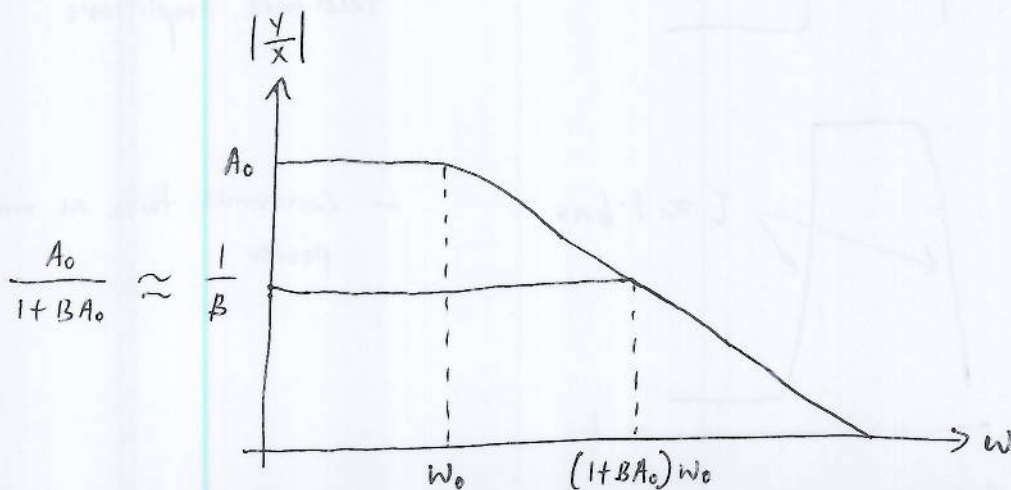
$$= \frac{A_0}{1 + BA_0 + \frac{s}{\omega_0}}$$

$$= \frac{A_0}{1 + BA_0} \cdot \frac{1}{1 + \frac{s}{(1+BA_0)\omega_0}}$$

closed-loop gain at low frequency

pole at $(1+BA_0)\omega_0$

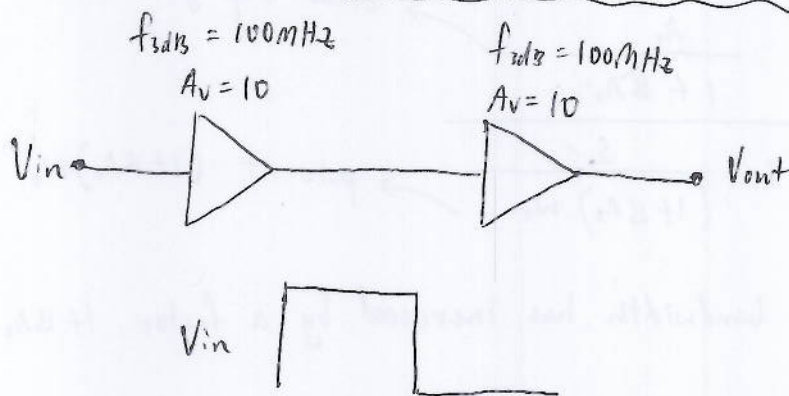
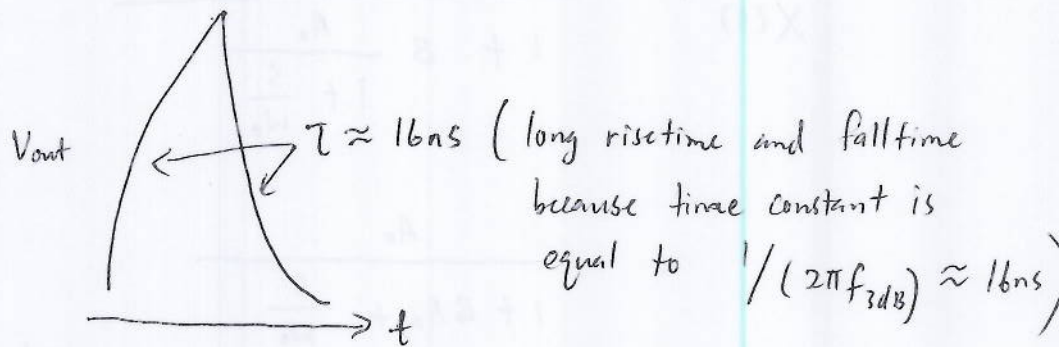
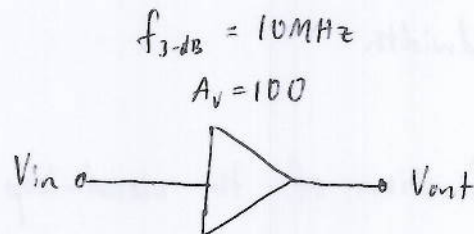
Thus, the 3-dB bandwidth has increased by a factor $1+BA_0$.



- Gain bandwidth product of one-pole system does not change.
- How feedback improves the speed if a high gain is required?

(Eg.)

Suppose need to amplify a 20MHz square wave by a factor of 100 and maximum bandwidth but we have only a single-pole amplifier with an opm-loop gain of 100 and 3-dB bandwidth of 10MHz.



cascade of two 100MHz feedback amplifiers.

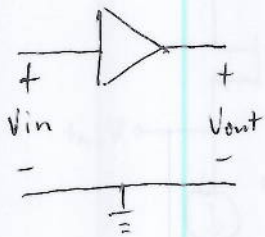


- Consumes twice as much power

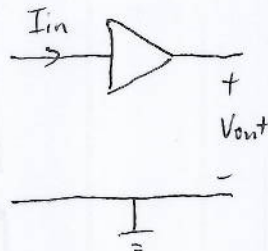
(4) Nonlinearity Reduction

Types of Amplifiers

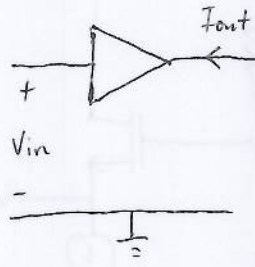
Voltage Amp.



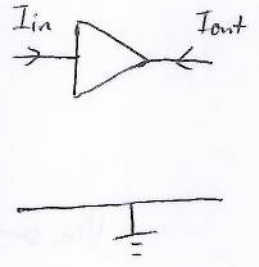
Transimpedance Amp.



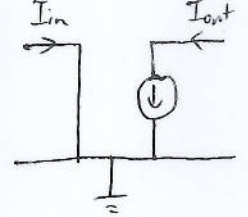
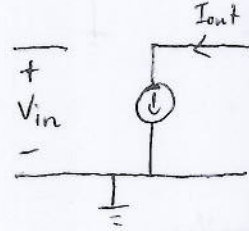
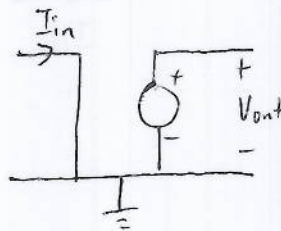
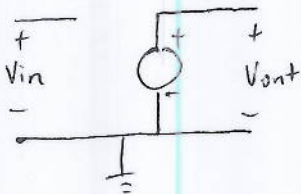
Transconductance Amp.



Current Amp



Ideal models



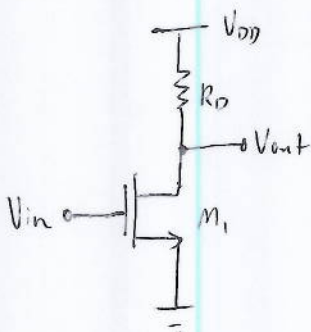
Four configurations have different properties:

- ① Circuits sensing a voltage \rightarrow high input impedance (voltage meter)
- ② " sensing a current \rightarrow low input impedance (current meter)
- ③ " generating a voltage \rightarrow low output impedance (voltage source)
- ④ " generating a current \rightarrow high output impedance (current source)

Note: Gains of transimpedance and transconductance amps have different dimensions

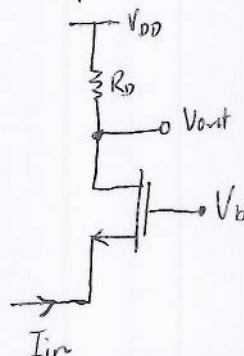
Simple implementation

suffer from high output impedance



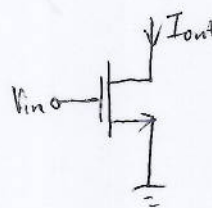
CS

$V \rightarrow V$



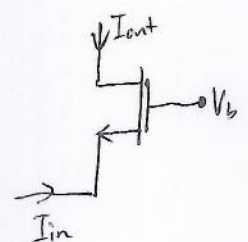
CG

$I \rightarrow V$



CS

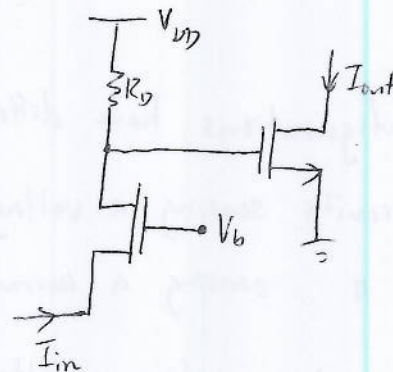
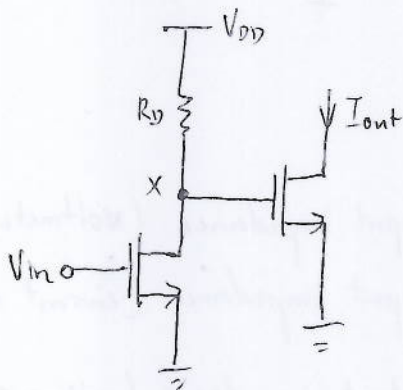
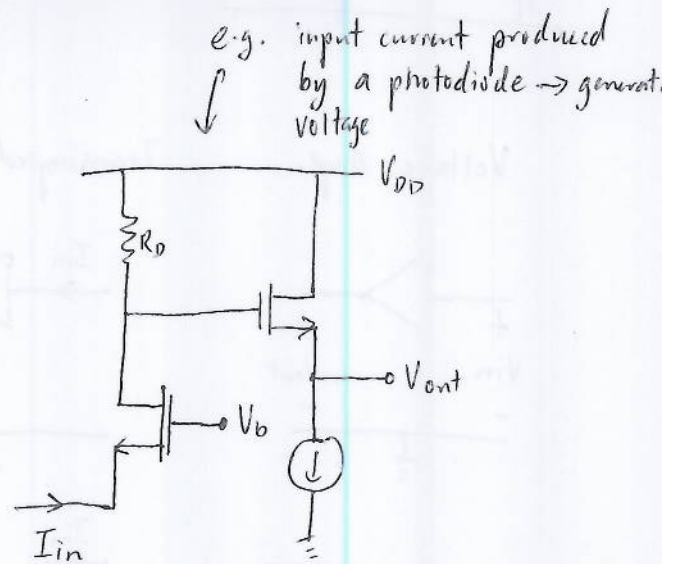
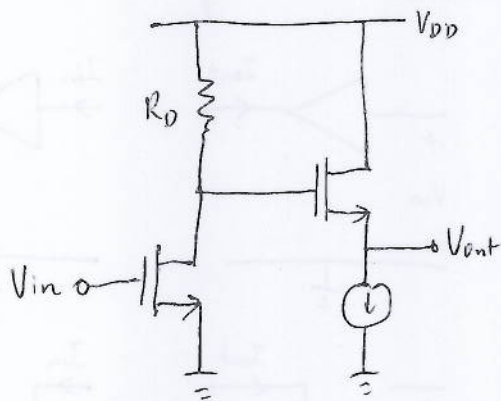
$V \leftrightarrow I$



CG

$I \leftrightarrow I$

Improved performance



↑
Gain of the transconductance?

$$\begin{aligned}
 G_m &= \frac{I_{out}}{V_{in}} \\
 &= \frac{V_x}{V_{in}} \cdot \frac{I_{out}}{V_x} \\
 &= -g_{m1} (r_{o1} \parallel R_D) \cdot g_{m2}
 \end{aligned}$$

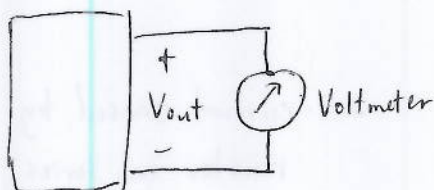
Four types of feedback :

- ① Voltage - voltage
- ② voltage - current
- ③ current - current
- ④ current - voltage

1st term ~~1st~~ quantity sensed at the output

2nd term - type of signal returned to the input

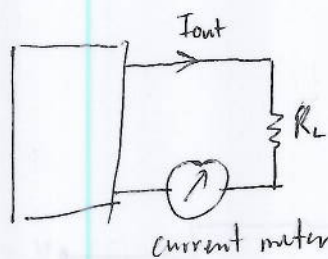
Sense and Return mechanisms



- sense a voltage

- put in parallel

- when used in feedback system \rightarrow shunt feedback



- sense a current

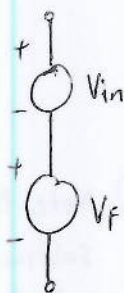
- put in series

- series feedback

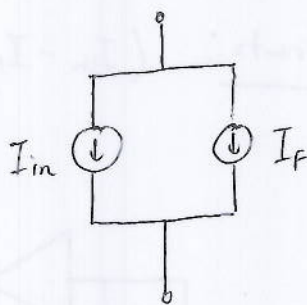
can replace \rightarrow with a resistor

Addition of the feedback signal and the input signal :

For voltage domain

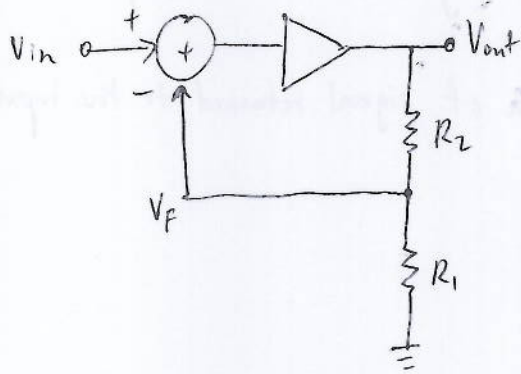


for current domain

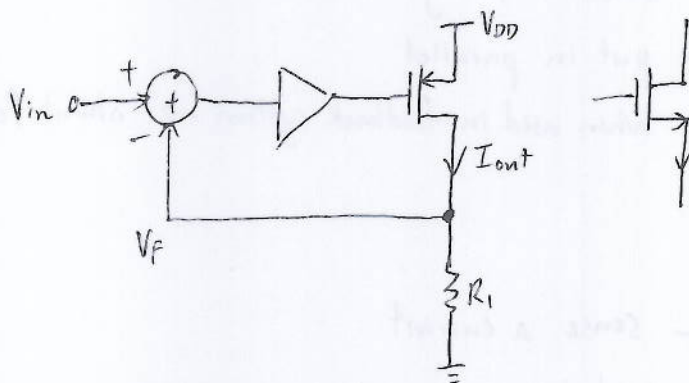


- no influence on the operation of the open-loop amplifier (ideally)
- introduces loading effects that must be taken into account (practically)

Practical implementations

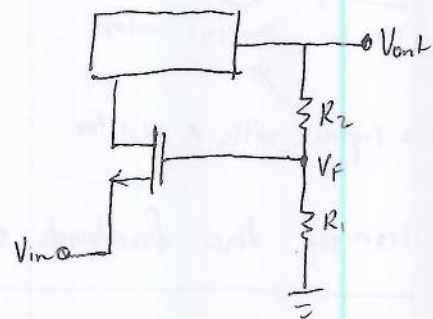
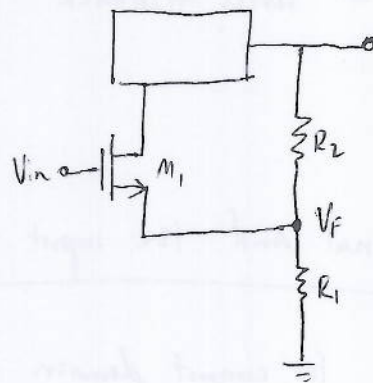
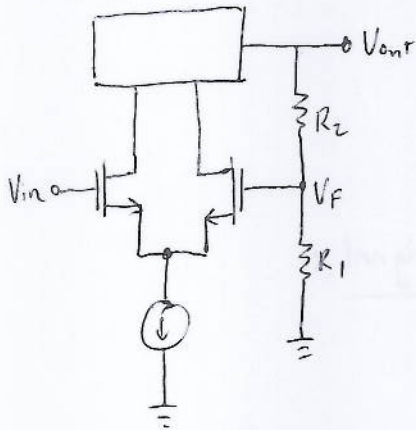


— voltage sensed by a resistive or capacitive divider in parallel with the port.

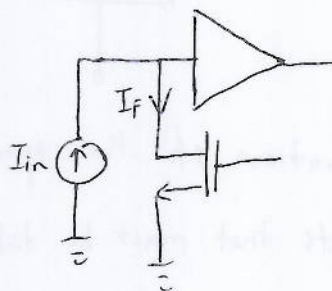
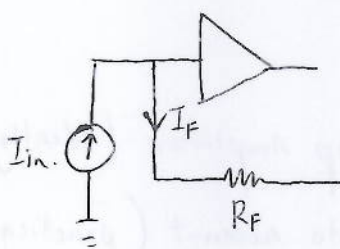


— current sensed by placing a resistor in series with the wire and sensing voltage across it.

To subtract two voltages: ($V_{in} - V_F$)



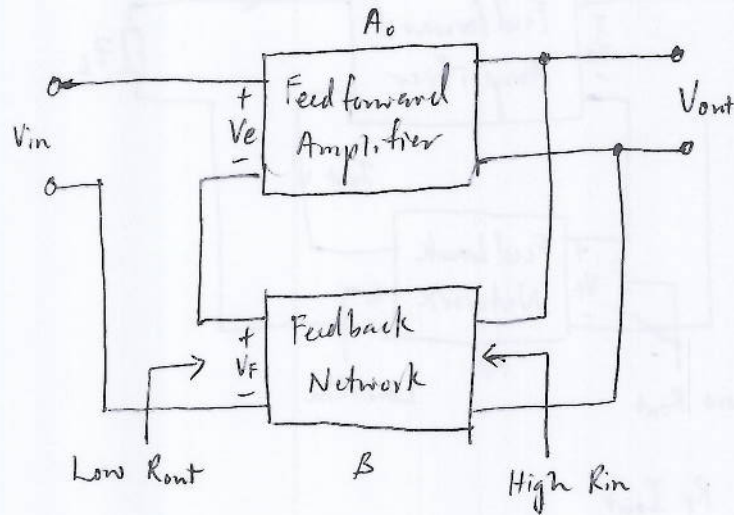
To subtract two currents: ($I_{in} - I_F$)



⚡ Note that voltage subtraction the input and output signals are applied to two distinct nodes whereas current subtraction they are applied to a single node.

Feedback Topologies

① Voltage - voltage Feedback (series-shunt)



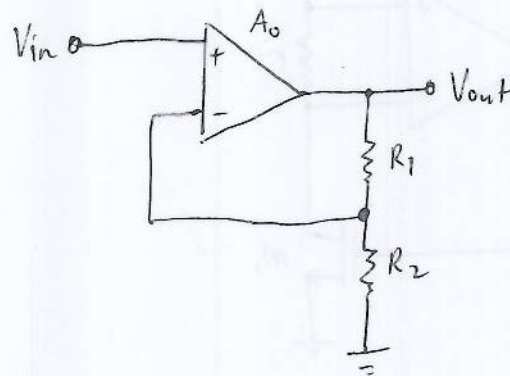
$$\therefore V_F = \beta V_{out}$$

$$V_e = V_{in} - V_F$$

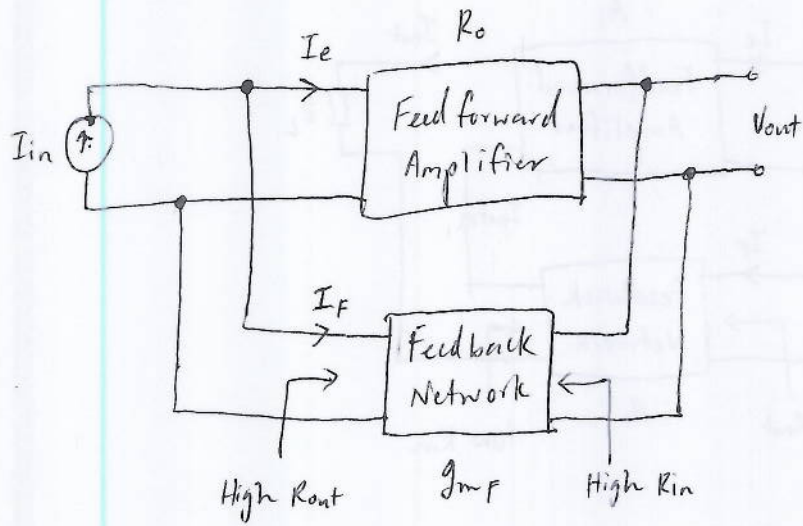
$$V_{out} = A_o (V_{in} - \beta V_{out})$$

$$\therefore \frac{V_{out}}{V_{in}} = \frac{A_o}{1 + \beta A_o}$$

Simple example :



(3) Voltage-Current Feedback (shunt-shunt)



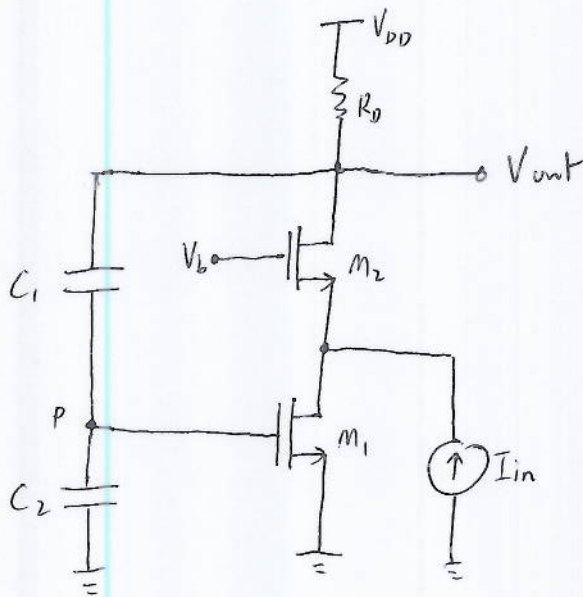
$$\therefore I_F = g_{mF} V_{out}$$

$$I_e = I_{in} - I_F$$

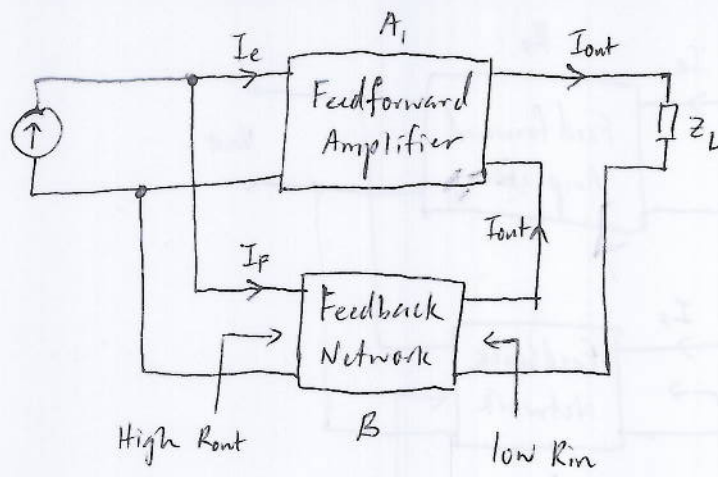
$$V_{out} = R_o I_e = R_o (I_{in} - g_{mF} V_{out})$$

$$\therefore \frac{V_{out}}{I_{in}} = \frac{R_o}{1 + g_{mF} R_o}$$

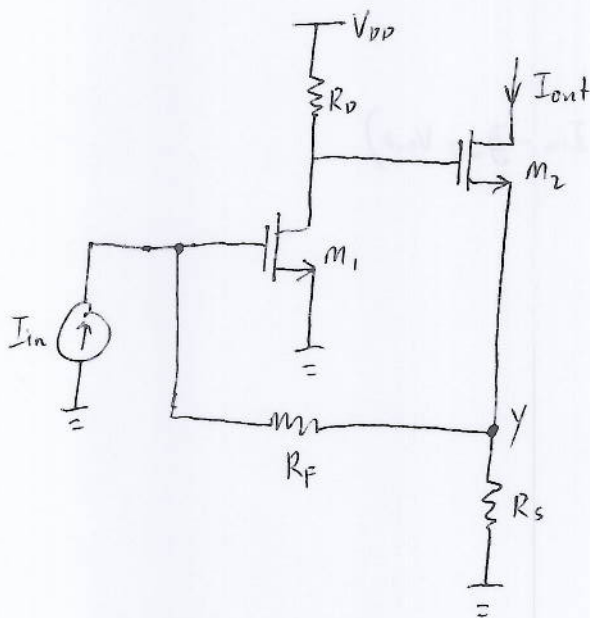
Example



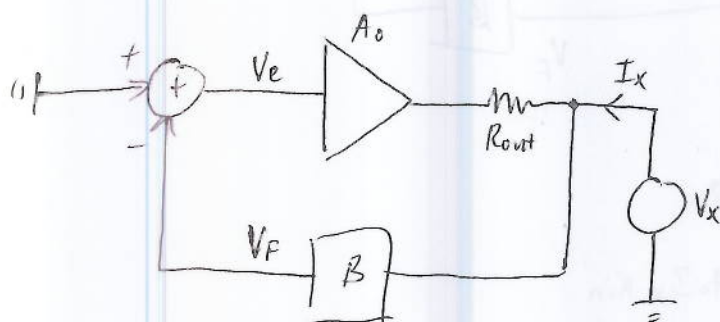
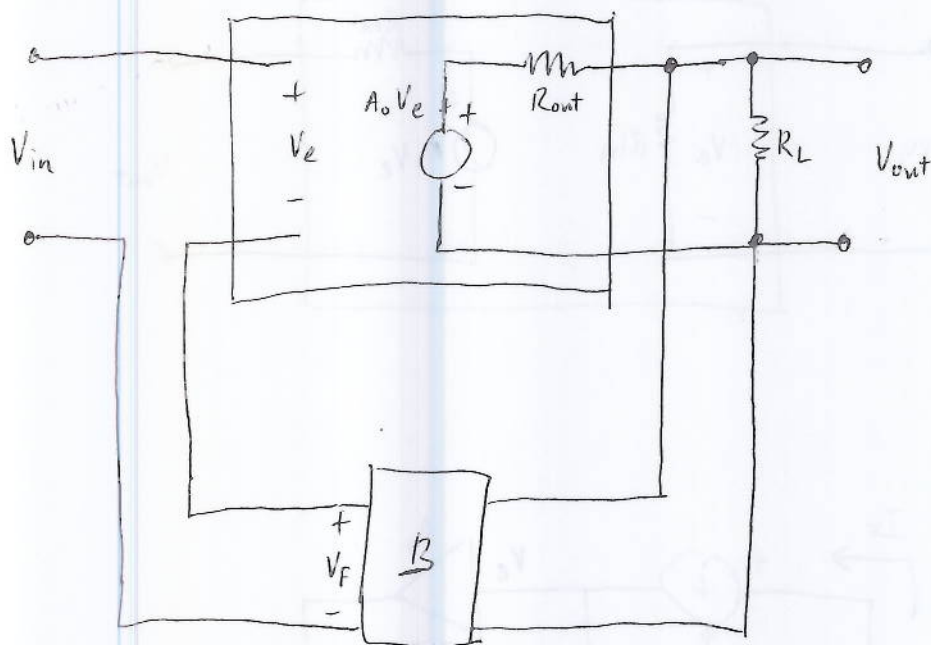
④ Current-current Feedback (shunt-series)



Example



Effect of voltage-voltage feedback on output resistance



$$V_F = \beta V_x$$

$$V_e = -\beta V_x$$

$$V_M = -\beta A_0 V_x$$

$$I_x = [V_x - (-\beta A_0 V_x)] / R_{out}$$

$$\therefore \frac{V_x}{I_x} = \frac{R_{out}}{1 + \beta A_0}$$

Current - voltage

$$\frac{V_x}{I_x} = R_{out} (1 + G_m R_F)$$

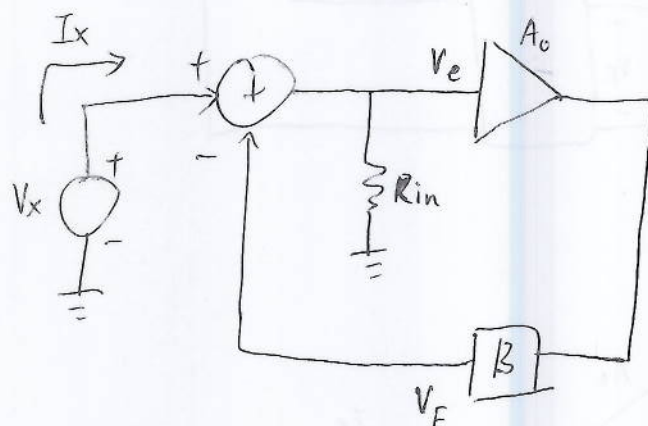
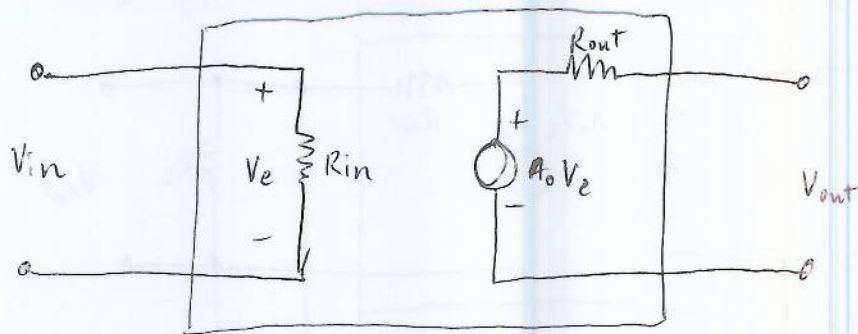
Voltage - current

$$\frac{V_x}{I_x} = \frac{R_{out}}{1 + g_m R_F R_o}$$

Current - current

$$\frac{V_x}{I_x} = R_{out} (1 + \beta A_0)$$

Effect of voltage-voltage feedback on input impedance



$$V_e = I_x R_{in}$$

$$V_F = B A_0 I_x R_{in}$$

$$V_e = V_x - V_F = V_x - B A_0 I_x R_{in}$$

$$I_x R_{in} = V_x - B A_0 I_x R_{in}$$

$$\frac{V_x}{I_x} = R_{in} (1 + B A_0)$$

current-voltage

$$\frac{V_x}{I_x} = R_{in} (1 + G_m R_F)$$

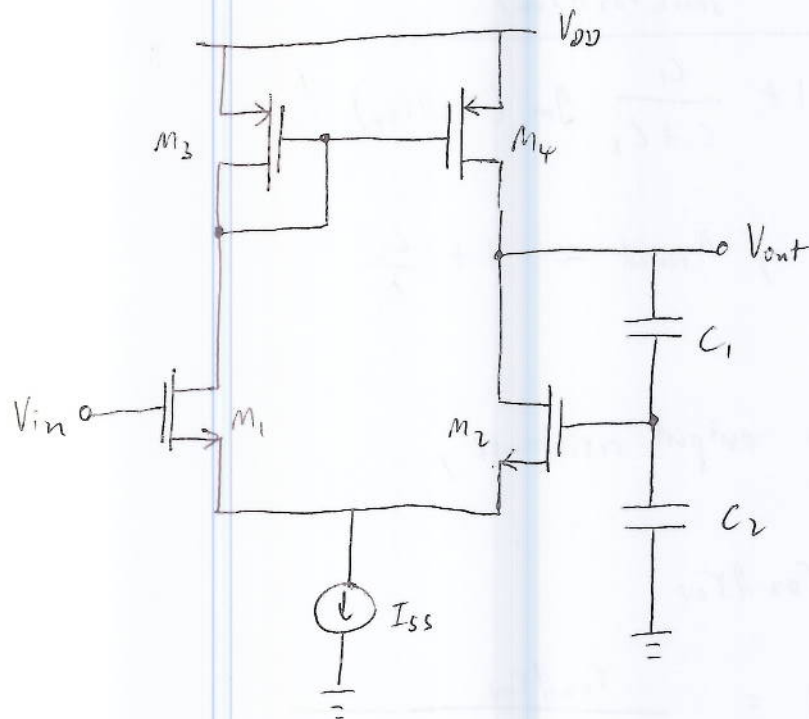
voltage-current

$$\frac{V_x}{I_x} = \frac{R_{in}}{1 + g_{mf} R_o}$$

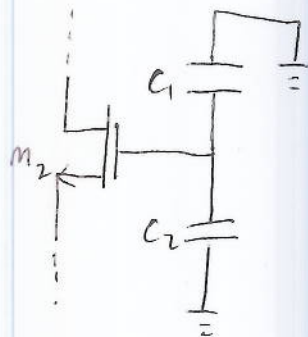
current-current

$$\frac{V_x}{I_x} = \frac{R_{in}}{1 + B A_0}$$

(E.g.) Calculate the closed-loop gain and output resistance of the amplifier.



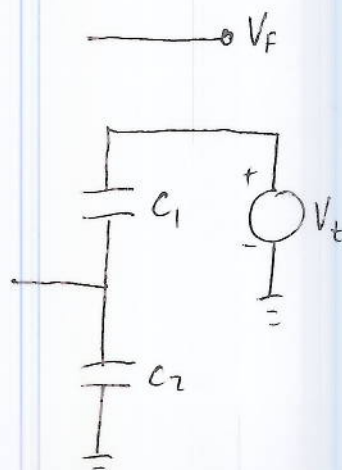
To find open-loop voltage gain, break the feedback loop



The open-loop gain,

$$A_{open} = g_{m1} (r_{o2} \parallel r_{o4})$$

To find loop gain,



$$V_F = -V_t \frac{C_1}{C_1 + C_2} g_{m1} (r_{o2} \parallel r_{o4})$$

$$BA_o = \frac{C_1}{C_1 + C_2} g_{m1} (r_{o2} \parallel r_{o4})$$

To find closed-loop gain,

$$A_{\text{closed}} = \frac{g_{m1}(r_{o2} \parallel r_{o4})}{1 + \frac{C_1}{C_1 + C_2} g_{m1}(r_{o2} \parallel r_{o4})}$$

(*) if $\beta A_o \gg 1$, $A_{\text{closed}} \approx 1 + \frac{C_2}{C_1}$

To find closed-loop output resistance,

$$R_{\text{open}} = r_{o2} \parallel r_{o4}$$

$$\therefore R_{\text{out, closed}} = \frac{r_{o2} \parallel r_{o4}}{1 + \frac{C_1}{C_1 + C_2} g_{m1}(r_{o2} \parallel r_{o4})}$$