

4月7日作业

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1. Compute a few low degree Padé approximants of $f(x) = (1+x)^{-1/2}$ and visualize the approximation errors over $[0, 2]$.

解: 首先计算三种 Padé 逼近

$$(1) \quad \frac{a+bx}{1+dx} \approx (1+x)^{-1/2}$$

$$\Rightarrow (a+bx)(1+x)^{1/2} \approx 1+dx$$

$$\text{其中 } (1+x)^{1/2} = 1 + \frac{1}{2}x - \frac{1}{8}x^2 + o(x^2)$$

$$\Rightarrow (a+bx)(1 + \frac{1}{2}x - \frac{1}{8}x^2 + o(x^2)) \approx 1+dx$$

$$\Rightarrow a + (\frac{1}{2}a+b)x + (\frac{1}{2}b - \frac{1}{8}a)x^2 + o(x^2) \approx 1+dx$$

$$\Rightarrow \begin{cases} a=1 \\ \frac{1}{2}a+b=d \\ \frac{1}{2}b - \frac{1}{8}a=0 \end{cases} \Rightarrow \begin{cases} a=1 \\ b=\frac{1}{2} \\ d=1 \end{cases}$$

$$\text{则 Padé 逼近为 } \underline{R_{1/1}(x) = \frac{1+\frac{1}{2}x}{1+x}}$$

$$(2) \quad \frac{a+bx}{1+dx+ex^2} \approx (1+x)^{-1/2}$$

$$\Rightarrow (a+bx)(1+x)^{1/2} \approx 1+dx+ex^2$$

$$\Rightarrow (a+bx)(1 + \frac{1}{2}x - \frac{1}{8}x^2 + \frac{3}{8}x^3 + o(x^3)) \approx 1+dx+ex^2$$

$$a + \left(\frac{1}{2}a + b\right)x + \left(\frac{1}{2}b - \frac{1}{4}a\right)x^2 + \left(\frac{3}{8}a - \frac{1}{4}b\right)x^3 + o(x^3) \approx 1 + dx + ex^2$$

$$\Rightarrow \begin{cases} a=1 \\ \frac{1}{2}a + b = d \\ \frac{1}{2}b - \frac{1}{4}a = e \\ \frac{3}{8}a - \frac{1}{4}b = 0 \end{cases} \Rightarrow \begin{cases} a=1 \\ b=\frac{3}{2} \\ d=2 \\ e=\frac{1}{2} \end{cases}$$

则 Padé 逼近为 $R_{1/2} = \frac{1 + \frac{3}{2}x}{1 + 2x + \frac{1}{2}x^2}$

$$3) \frac{a + bx + cx^2}{1 + dx} \approx (1+x)^{-1/2}$$

$$\Rightarrow (a + bx + cx^2) \left(1 + \frac{1}{2}x - \frac{1}{4}x^2 + \frac{3}{8}x^3 + o(x^3)\right) \approx 1 + dx$$

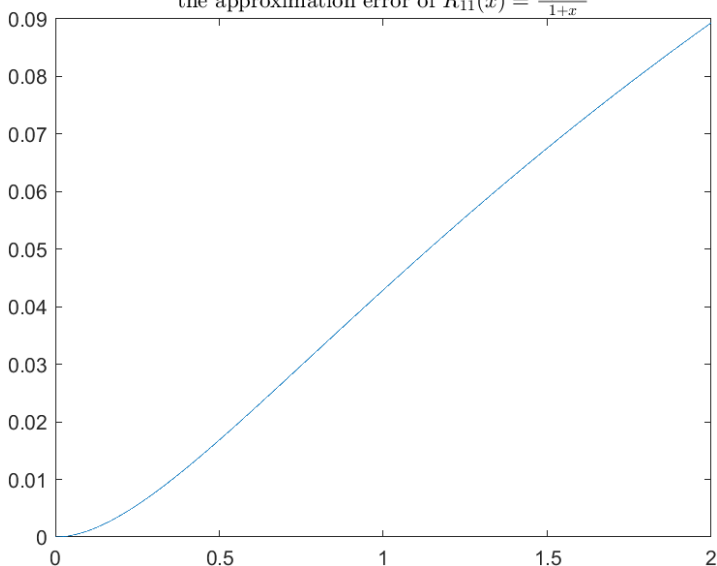
$$\Rightarrow a + \left(\frac{1}{2}a + b\right)x + \left(-\frac{1}{4}a + \frac{1}{2}b\right)x^2 + \left(\frac{3}{8}a - \frac{1}{4}b + \frac{1}{2}c\right)x^3 + o(x^3) \approx 1 + dx$$

$$\Rightarrow \begin{cases} a=1 \\ \frac{1}{2}a + b = d \\ -\frac{1}{4}a + \frac{1}{2}b = 0 \\ \frac{3}{8}a - \frac{1}{4}b + \frac{1}{2}c = 0 \end{cases} \Rightarrow \begin{cases} a=1 \\ b=0 \\ c=-\frac{3}{8} \\ d=\frac{1}{2} \end{cases}$$

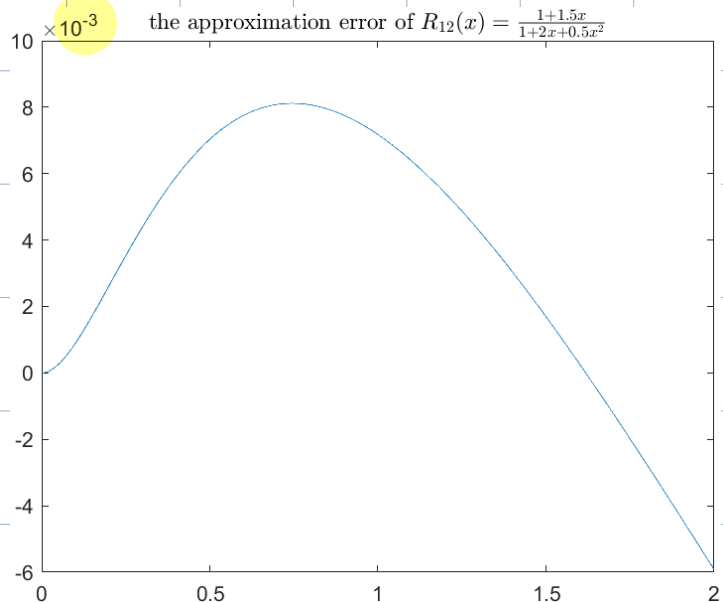
则 Padé 逼近为 $R_{2/1} = \frac{1 - \frac{3}{8}x^2}{1 + \frac{1}{2}x}$

三种 Padé 逼近的误差如下:

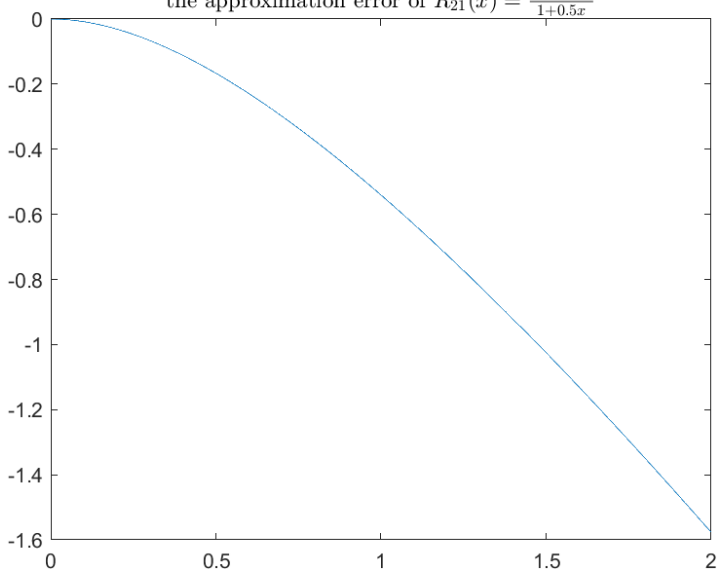
the approximation error of $R_{11}(x) = \frac{1+0.5x}{1+x}$



the approximation error of $R_{12}(x) = \frac{1+1.5x}{1+2x+0.5x^2}$



the approximation error of $R_{21}(x) = \frac{1-0.75x^2}{1+0.5x}$



对比可知, $R_{12}(x)$ 的逼近效果最好。

□

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2. Construct a concrete example to show that Padé approximation is not always a well-posed problem.

解: 用 $R_{1/1} = \frac{a+bx}{1+dx}$ 去逼近 $(1+x^2)$

$$\frac{a+bx}{1+dx} \approx 1+x^2$$

$$a+bx \approx (1+dx)(1+x^2)$$

$$\Rightarrow a+bx \approx 1+dx+x^2+dx^3$$

$$\Rightarrow \begin{cases} a=1 \\ b=d \end{cases}$$

这个方程组是亚定的, 而非适定的。

□

3. Show that a quadratic Bézier curve is part of a parabola.

解: 2次 Bézier 曲线需要三个控制点, 分别设为:

$$P_0 = (x_0, y_0), P_1 = (x_1, y_1), P_2 = (x_2, y_2)$$

抛物线的形状在平移后保持不变, 可以把 P_0 移到原点处, 因此可设 $P_0 = (0, 0)$

类似的, 围绕原点进行旋转也不改变抛物线的形状

$$\text{设: } \tilde{P}_1 = \begin{pmatrix} c & s \\ -s & c \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} cx_1 + sy_1 \\ -sx_1 + cy_1 \end{pmatrix}$$

$$\tilde{P}_2 = \begin{pmatrix} c & s \\ -s & c \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} cx_2 + sy_2 \\ -sx_2 + cy_2 \end{pmatrix}$$

这里对 c 和 s 提两个约束:

$$\begin{cases} c^2 + s^2 = 1 \\ 2(cx_1 + sy_1) - cx_2 + sy_2 = 0 \end{cases}$$

$$\text{那: } \begin{cases} c^2 + s^2 = 1 \\ (2x_1 + x_2) \cdot c - (2y_1 + y_2) \cdot s = 0 \end{cases} \quad (*)$$

方程因 (*) 在 (1) $2x_1 + x_2 = 0, 2y_1 + y_2 = 0$; (2) $2x_1 + x_2 = 0, 2y_1 + y_2 \neq 0$; (3) $2x_1 + x_2 \neq 0, 2y_1 + y_2 = 0$; (4) $2x_1 + x_2 \neq 0, 2y_1 + y_2 \neq 0$ 情况下都有解, 则 (*) 总是有解

记旋转后的点为 $\tilde{P}_1 = (\tilde{x}_1, \tilde{y}_1), \tilde{P}_2 = (\tilde{x}_2, \tilde{y}_2)$

且满足 $2\tilde{x}_1 - \tilde{x}_2 = 0$

$$\begin{aligned} x(t) &= 0 \cdot (1-t)^2 + 2 \cdot \tilde{x}_1 t \cdot (1-t) + \tilde{x}_2 t^2 \\ &= 2\tilde{x}_1 t - 2\tilde{x}_1 t^2 + \tilde{x}_2 t^2 \\ &= 2\tilde{x}_1 t \end{aligned}$$

$$\begin{aligned} y(t) &= 0 \cdot (1-t)^2 + 2\tilde{y}_1 t \cdot (1-t) + \tilde{y}_2 t^2 \\ &= (\tilde{y}_2 - 2\tilde{y}_1) t + 2\tilde{y}_1 t \end{aligned}$$

当 $\tilde{x}_1 \neq 0, \tilde{y}_2 - 2\tilde{y}_1 \neq 0$ 时, $(x(t), y(t))$ 是抛物线一部分

当 $\tilde{x}_1 \neq 0, \tilde{y}_2 - 2\tilde{y}_1 = 0$ 时, $(x(t), y(t))$ 退化为线段

当 $\tilde{x}_1 = 0$ 时, 可知 $\tilde{x}_2 = 0$, 此时 $(x(t), y(t))$ 退化为线段

Q: 似乎题目中忽略了可能退化为线段的情况?

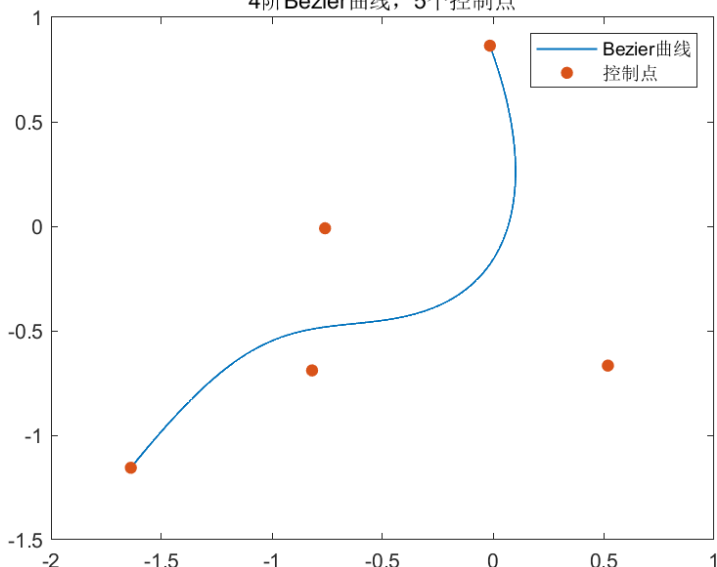
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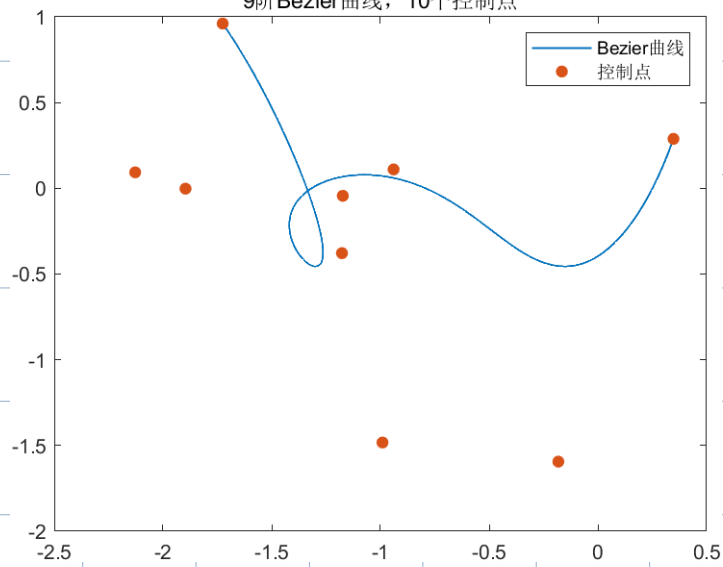
4. Write a program to plot the Bézier curve with arbitrary set of control points. Visualize a few examples.

解：以下是四个实验结果：

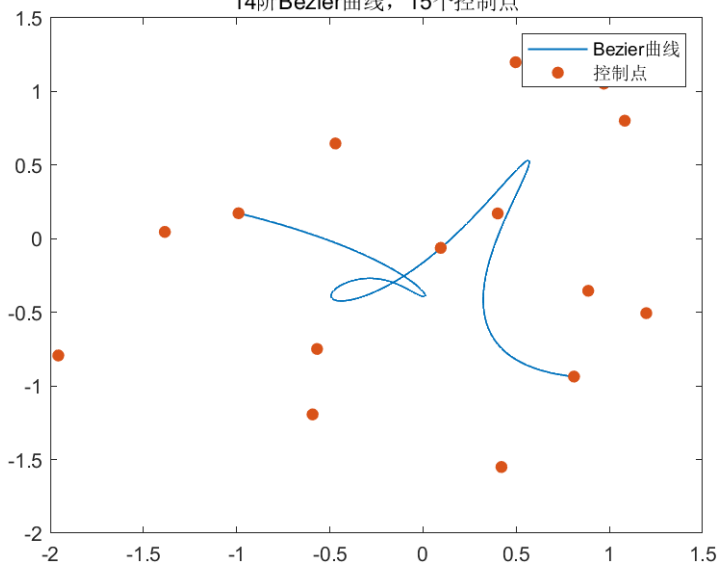
4阶Bezier曲线，5个控制点



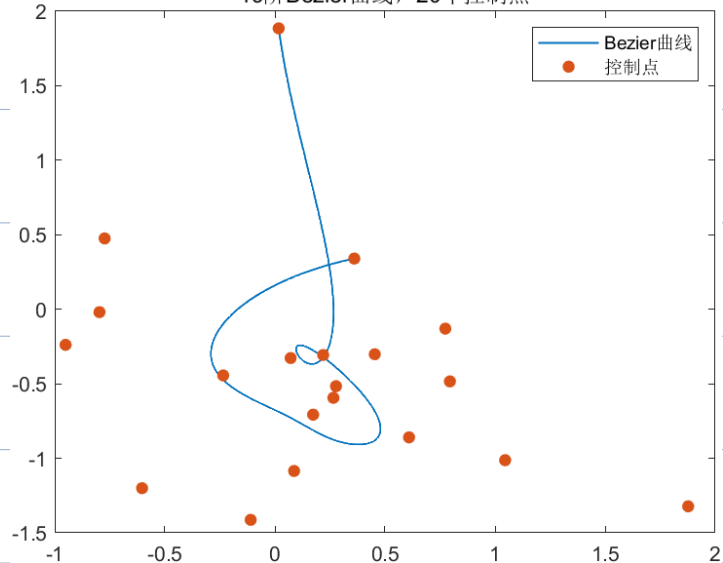
9阶Bezier曲线，10个控制点



14阶Bezier曲线，15个控制点



19阶Bezier曲线，20个控制点



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5. (optional) Linear and quadratic Bézier curves can exactly fit line segments and parabolas, respectively. However, many computer programs only support cubic Bézier curves. Suppose you want to plot a segment of parabola of the form $y = ax^2 + bx + c$ for $x \in [x_1, x_2]$. How to construct four control points for this purpose?

解：为了书写方便，改记 $x \in [\hat{x}_1, \hat{x}_2]$ ，其中 $\hat{x}_1 \neq \hat{x}_2$
并记四个控制点分别为：

$$P_0(x_0, y_0), P_1(x_1, y_1), P_2(x_2, y_2), P_3(x_3, y_3)$$

$$\begin{aligned} x(t) &= x_0(1-t)^3 + 3x_1t(1-t)^2 + 3x_2t^2(1-t) + x_3t^3 \\ &= C_3t^3 + C_2t^2 + C_1t + C_0 \end{aligned}$$

其中 C_j 是 t^j 的系数, 是 x_0, x_1, x_2, x_3 的线性组合
类似的:

$$\begin{aligned} y(t) &= y_0(1-t)^3 + 3y_1t(1-t)^2 + 3y_2t^2(1-t) + y_3t^3 \\ &= D_3t^3 + D_2t^2 + D_1t + D_0 \end{aligned}$$

由于最终希望 $(x(t), y(t))$ 具有 $y = ax^2 + bx + c, x \in [\hat{x}_1, \hat{x}_2]$
的形式, 那么对控制点有如下四个约束:

$$\begin{cases} x_0 = \hat{x}_1, & x_3 = \hat{x}_2 & (\text{首尾控制点}) \\ C_3 = 0, & C_2 = 0 & (x(t) \text{ 关于 } t \text{ 是线性的}) \end{cases}$$

以上四个约束确定了 x_0, x_1, x_2, x_3 , 且易验证方程组适定

并且, 由于 $\hat{x}_1 \neq \hat{x}_2$, 则 $(x(t), y(t))$ 不会退化为平行于 y 轴的
线段, 则 $C_1 \neq 0$

$$x(t) = C_1t + C_0 \Rightarrow t = \frac{x - C_0}{C_1}$$

$$\begin{aligned} \Rightarrow y(t) &= D_3 \left(\frac{x - C_0}{C_1} \right)^3 + D_2 \left(\frac{x - C_0}{C_1} \right)^2 \\ &\quad + D_1 \left(\frac{x - C_0}{C_1} \right) + D_0 \end{aligned}$$

$$= E_3 \cdot x^3 + E_2 \cdot x^2 + E_1 \cdot x + E_0$$

其中 E_j 分别是 D_3, D_2, D_1, D_0 的线性组合

满足下面四个约束:

$$E_3 = 0, \quad E_2 = a, \quad E_1 = b, \quad E_0 = c$$

四个约束确定了 D_3, D_2, D_1, D_0 , 而 D_j 都是 y_3, y_2, y_1, y_0

的线性组合, 则也同时确定了 y_3, y_2, y_1, y_0

这样, 就确定了四个控制点 P_0, P_1, P_2, P_3

□