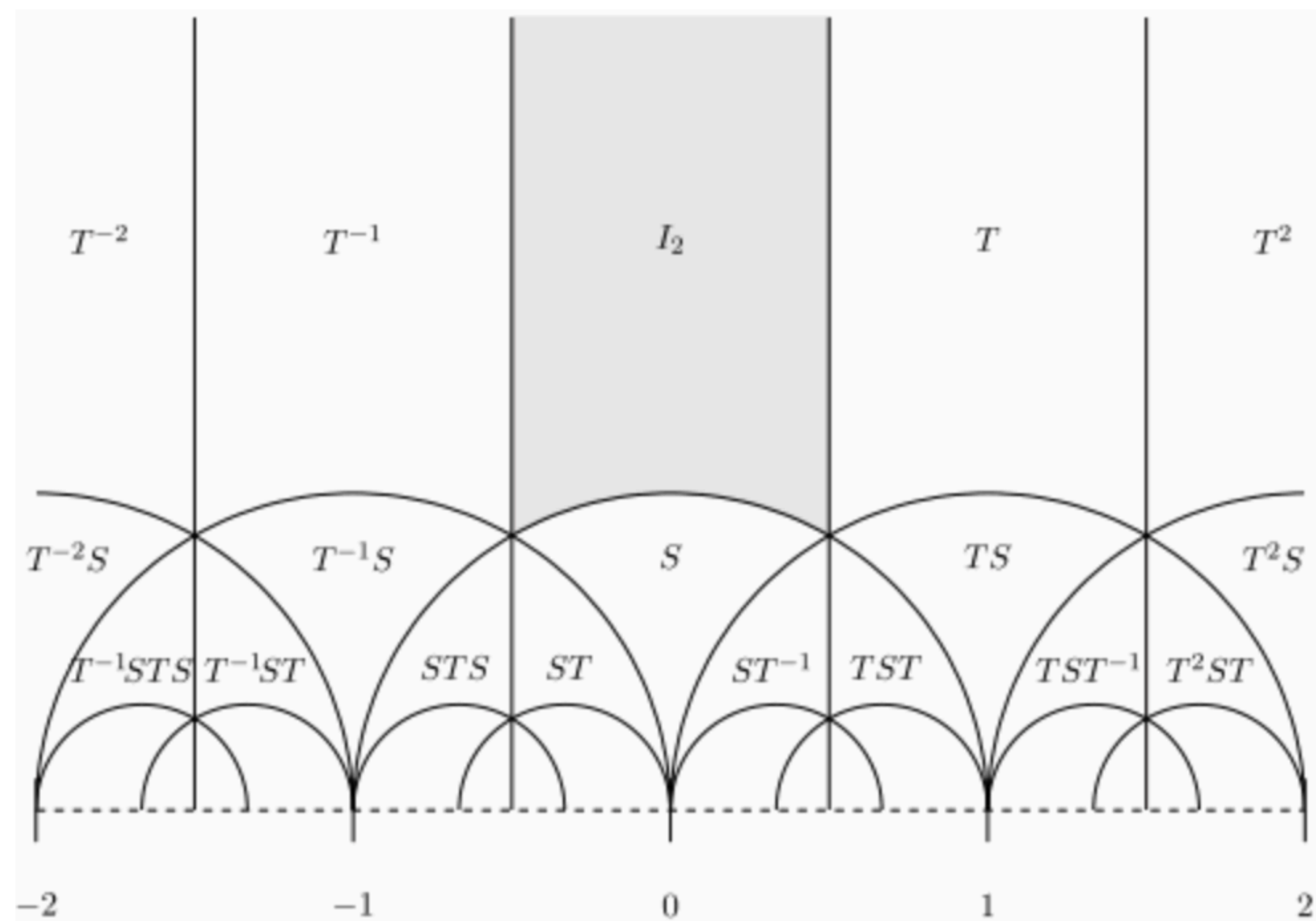
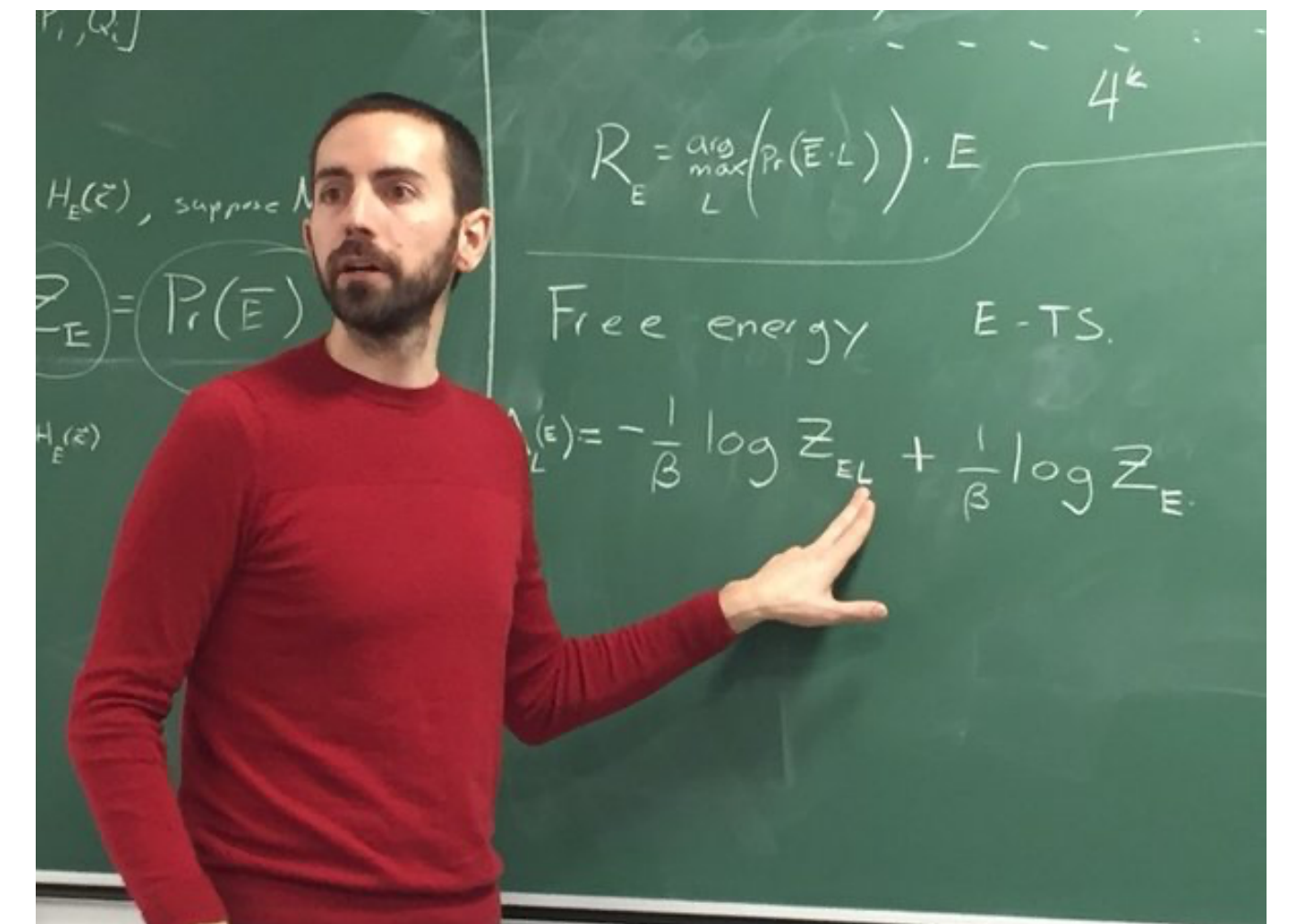


Logical GKP Shadows

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Overview

1. GKP and GKP Cliffords
2. Twirling and Shadows
3. Logical GKP Shadows

GKP codes

[GKP (2001)]
[Harrington & Preskill (2001)]
[Harrington Thesis (2004)]
[JC, Eisert, Arzani (2022)]

Stabilizer Group:

$$\mathcal{S} = \langle D(\xi_1), D(\xi_2), \dots, D(\xi_{2n}) \rangle = \left\{ e^{i\phi(\xi)} D(\xi), \xi \in \mathcal{L} \right\}$$

Lattice:

$$\mathcal{L} = \text{span}_{\mathbb{Z}} \{ \xi_1, \xi_2, \dots, \xi_{2n} \} \subset \mathbb{R}^{2n}$$

Centralizer:

$$\mathcal{C}(\mathcal{S})$$

Symplectic Dual Lattice:

$$\mathcal{L}^\perp = \{ \xi^\perp \in \mathbb{R}^{2n} : (\xi^\perp)^T J \xi \in \mathbb{Z} \forall \xi \in \mathcal{L} \} \subset \mathbb{R}^{2n}$$

Lattice basis

$$M = \begin{pmatrix} \xi_1^T \\ \vdots \\ \xi_{2n}^T \end{pmatrix}$$

Symplectic Gram matrix

$$A = M J M^T$$

$$M = \textcolor{red}{A} M^\perp$$

Quantifies **symp. dual quotient**

$$\mathcal{L} \subseteq \mathcal{L}^\perp$$

$$\#\{\text{logical Pauli operators}\} = d^2 = |\det A|$$

Commutation:

$$D(\xi) D(\eta) = e^{-i2\pi \xi^T J \eta} D(\eta) D(\xi)$$

Closure:

$$D(\xi) D(\eta) = e^{-i\pi \xi^T J \eta} D(\xi + \eta)$$

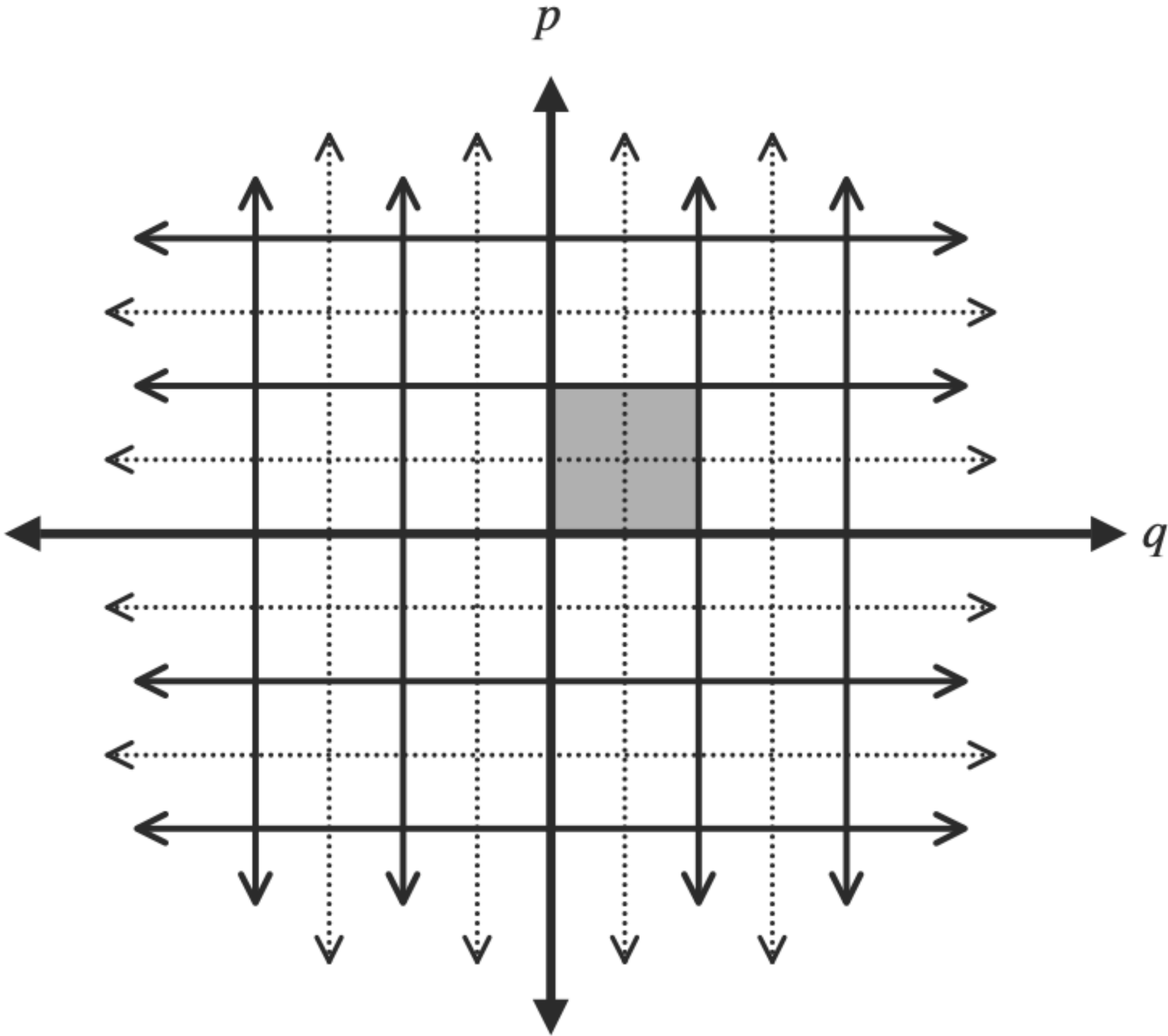
Scaled GKP Codes

- Scaled GKP codes: rescale symplectic lattice

$$M_0 \in \mathbb{R}^{2n \times 2n} : M_0 J M_0^T = J \Rightarrow M = \sqrt{\lambda} M_0, \lambda \in \mathbb{N}$$

$$D = \lambda^n;$$

n	$\dim(\mathcal{L}_0) \ (\mathcal{L})$	\mathcal{L}_0	$(\lambda_1(\mathcal{L}))^2$	Symp. self-dual	Eucl. self-dual
1	2	\mathbb{Z}^2	1	✓	✓
1	2	A_2	$\frac{2}{\sqrt{3}}$	✓	✓
2	4	D_4	$\sqrt{2}$	✓ [10]	✓
4	8	E_8	2	✓	✓
6	12	K_{12}	$\frac{4}{\sqrt{3}}$ [10]	✓ [10]	✓
12	24	Λ_{24}	4 [32]	✓ [28]	✓
n	$2n$	$\sqrt{\lambda/q} L_{\text{cs}}$	$\Delta \sim O\left(\sqrt{n/q\lambda}\right)$	✓	✓
N	$2N$	$\Lambda_{\square}(\mathcal{Q})$	$\Delta \geq \sqrt{d/2}$	x	x
N	$2N$	$\Lambda_{\circ}(\mathcal{Q})$	$\Delta = \sqrt{d/\sqrt{3}}$	x	x



GKP Cliffords = $\text{Aut}(\mathcal{L}^\perp)$

- Logical Paulis = Trivial Automorphisms $\text{Aut}_0(\mathcal{L}^\perp) =$ translations by vectors in \mathcal{L}^\perp
- Logical non-trivial Cliffords = non-trivial symp. Automorphisms
 $\text{Aut}^S(\mathcal{L}^\perp) = \text{Aut}(\mathcal{L}^\perp) \cap \text{Sp}_{2n}(\mathbb{R})$
- Scaled GKP codes: $\mathcal{L}^\perp \propto \mathcal{L} \Rightarrow \text{Aut}^S(\mathcal{L}^\perp) = \text{Aut}^S(\mathcal{L})$

GKP Cliffords

- $S \in \text{Aut}(\mathcal{L})$:

$$MS^T = UM$$

GKP Cliffords

- $S \in \text{Aut}(\mathcal{L})$:

$$MS^T = UM$$

GKP Cliffords

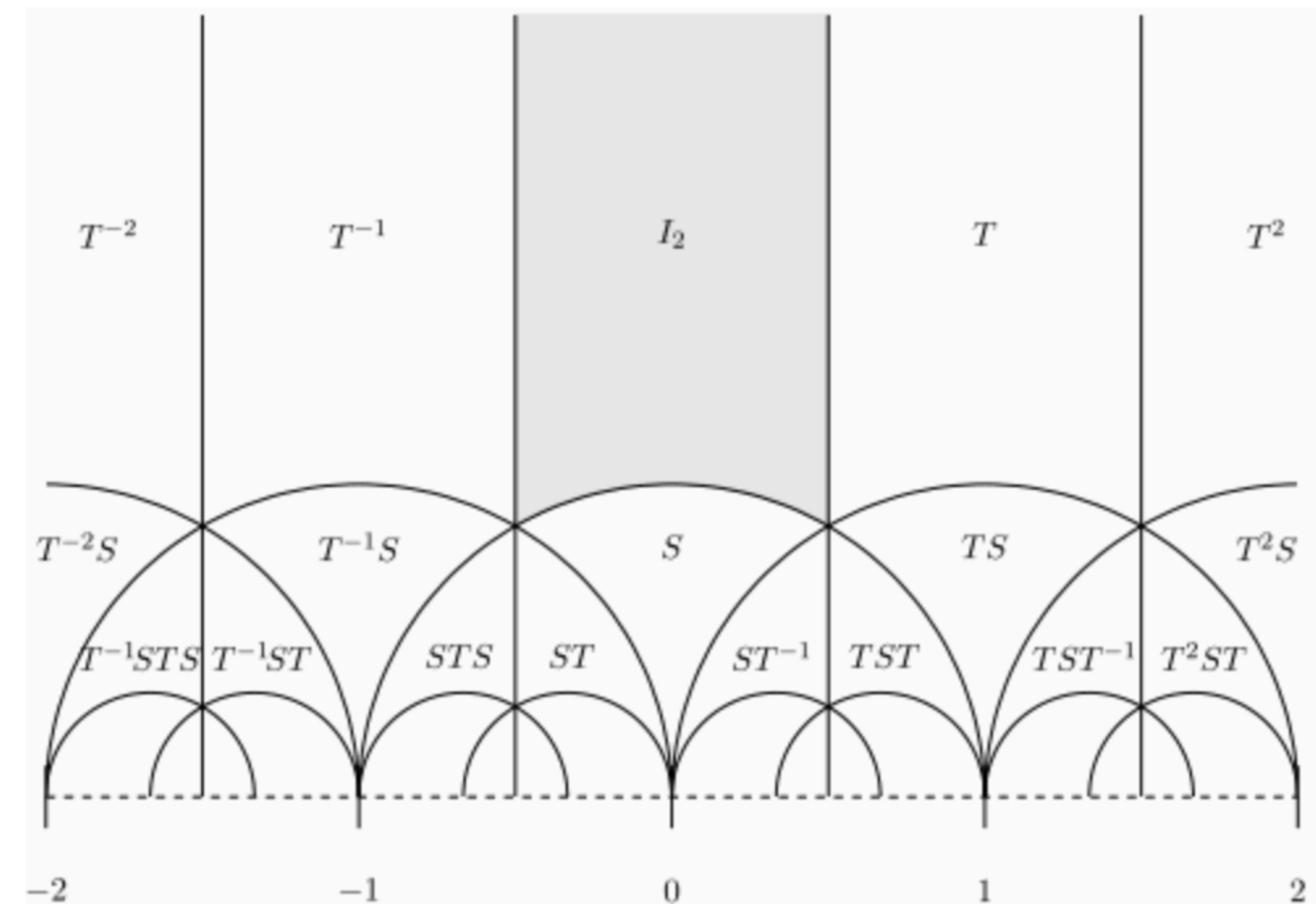
$$\begin{array}{ccc} \mathrm{Aut}^S(\mathcal{L}^\perp) & \longleftarrow & \mathrm{SL}_{2n}(\mathbb{Z}) \supseteq \mathrm{Sp}_{2n}(\mathbb{Z}) \\ \downarrow \text{mod } \mathcal{L} & & \downarrow \text{mod } d \\ \mathrm{Aut}^S(\mathcal{L}^\perp / \mathcal{L}) & \longleftrightarrow & \mathrm{Sp}_{2n}(\mathbb{Z}/d\mathbb{Z}) \end{array}$$

GKP Cliffords in a single mode

- $\Gamma = \text{Sp}_2(\mathbb{Z}) = \text{SL}_2(\mathbb{Z}) = \langle S, T \mid S^4 = 1, (ST)^3 = 1 \rangle$
- Mapping Class group of Torus $T = \mathbb{R}^2 / \mathcal{L}^\perp$
- Action can be represented in $\mathfrak{h} = \mathbb{R} \oplus i\mathbb{R}_{>0}$ as $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}_2(\mathbb{Z}) : \gamma z = \frac{az + b}{cz + d}$

$$S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, T = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$$

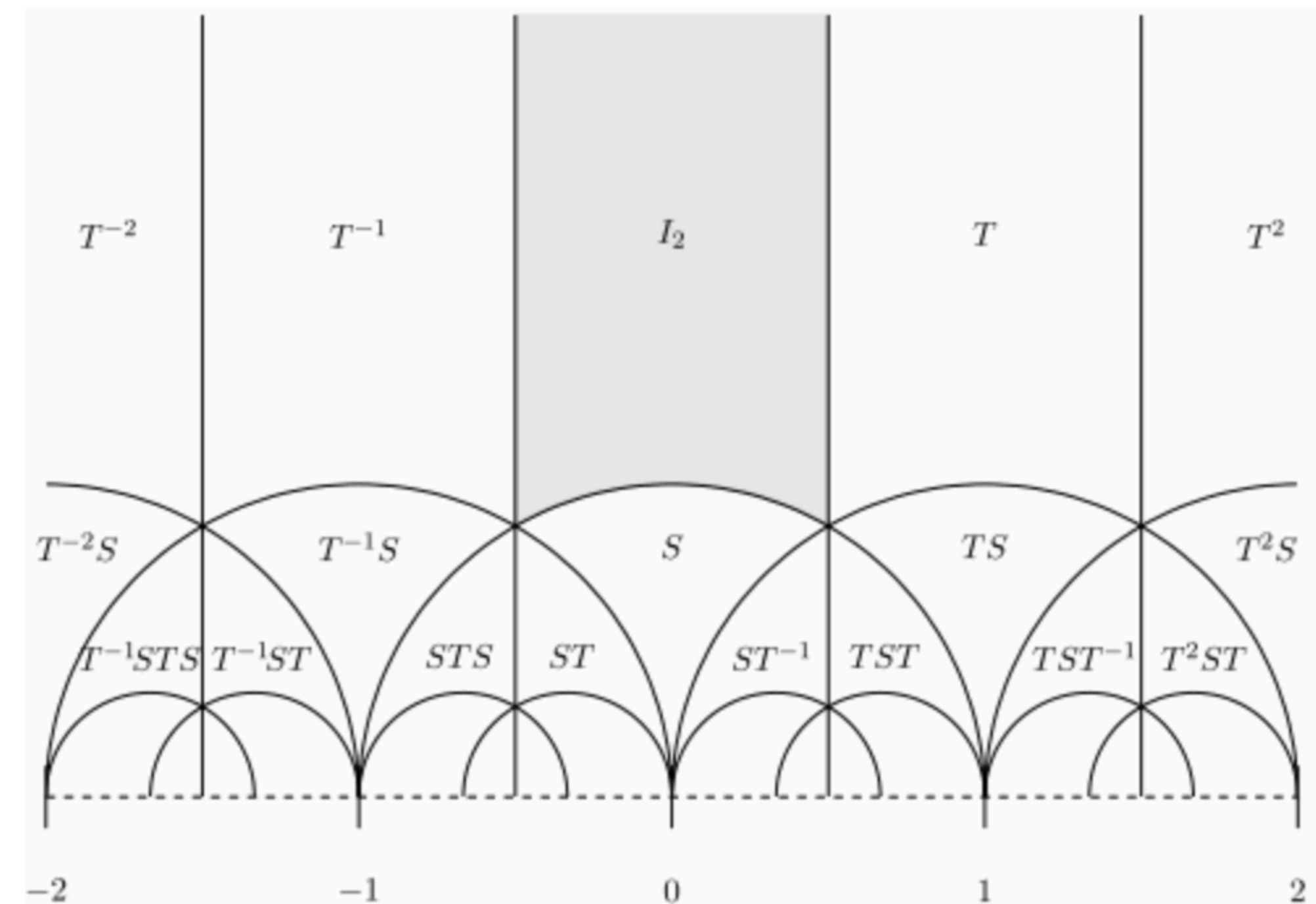
$$Sz = \frac{-1}{z}, Tz = z + 1$$



GKP Cliffords in a single mode

- $\Gamma := \text{Sp}_2(\mathbb{Z}) = \text{SL}_2(\mathbb{Z}) = \langle S, T \mid S^4 = 1, (ST)^3 = 1 \rangle$
- Principal Congruence subgroup $\Gamma(2) = \{\gamma \in \Gamma : \gamma \bmod 2 = I\}$

$$\begin{array}{ccc}
 \text{Aut}^S(\mathcal{L}^\perp) & \longleftarrow & \text{SL}_2(\mathbb{Z}) \\
 \downarrow \text{mod } \mathcal{L} & & \downarrow \text{mod } \Gamma(2) \\
 \text{Aut}^S(\mathcal{L}^\perp / \mathcal{L}) & \longleftrightarrow & \text{SL}_2(\mathbb{Z}) / \Gamma(2) = \text{SL}_2(\mathbb{Z}_2)
 \end{array}$$



Twirling Theory

Flavours of Twirling

State twirl [Bennet et al (1996)]

$$\rho \mapsto \Pi(\rho)$$

- $\mathcal{G} = \{R \otimes R, R \in \text{SU}(2)\}$
- $\mathcal{G} = \text{SU}(2) \leftarrow$ depolarizing channel

Channel Twirl

$$\mathcal{C} = \sum_i K_i \otimes \bar{K}_i \mapsto \Pi_{\mathcal{G}}(\mathcal{C})$$

- standard twirl : $\mathcal{G} = \{U \otimes \bar{U}, U \in \mathcal{G}_0\}$
- $\mathcal{G}_0 = \mathcal{P} \leftarrow$ Pauli twirl, $\Pi(\mathcal{C})$ is diagonal in Paulis

Group Projector

$$\Pi_{\mathcal{G}}(\cdot) = \sum_{g \in \mathcal{G}} g \cdot g^{-1} \in \mathcal{C}(\mathcal{G})$$

Hamiltonian Twirl = Dynamical Decoupling

$$H \mapsto \Pi_{\mathcal{G}}(H) = \langle H \rangle_T$$

- $\mathcal{G} = \langle X \rangle \leftarrow$ Spin Echo

POVM Twirl = Shadow Tomography

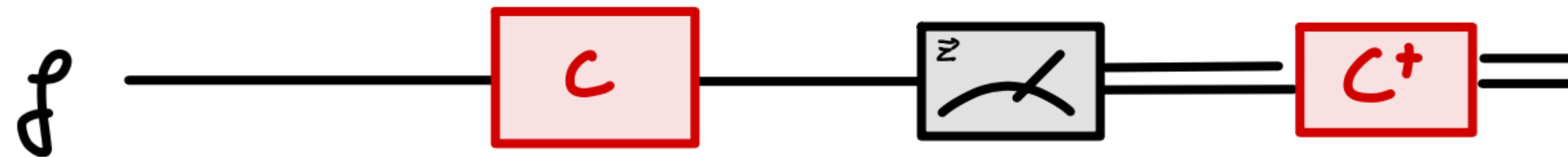
$$\mathcal{M}_0 \mapsto \Pi_{\mathcal{G}}(\mathcal{M}_0)$$

- Standard setup [Huang et al (2022)]:

$$\mathcal{M}_0 = \sum_{\vec{z}} |\vec{z}\rangle\rangle\langle\langle\vec{z}|$$

- $\mathcal{G} = \{C \otimes \bar{C}, C \in \text{Cl}_n\}$

Shadow Tomography



$$|S\rangle\rangle = \underbrace{\mathcal{U}^\dagger \left[\overbrace{|\vec{z}\rangle\rangle \langle\langle \vec{z}|}^{\mathcal{M}} \right] \mathcal{U}}_{\mathcal{M}} |\rho\rangle\rangle \quad \mathcal{U} = U \otimes \bar{U}, U \in \text{Cl}_n$$

- $\mathcal{M} = |I\rangle\rangle\langle\langle I| + f(I \otimes \bar{I} - |I\rangle\rangle\langle\langle I|)$ is the depolarizing channel, invertible as matrix.
- Shadow is set of states $\mathcal{U}^\dagger |\vec{z}\rangle\rangle$. Clifford + Z-measurements \rightarrow Stabilizer States
- Channel Twirl **projects** onto depol. channel. Robust to imperfections in POVM [Chen et al (2021)].

Displacement twirling

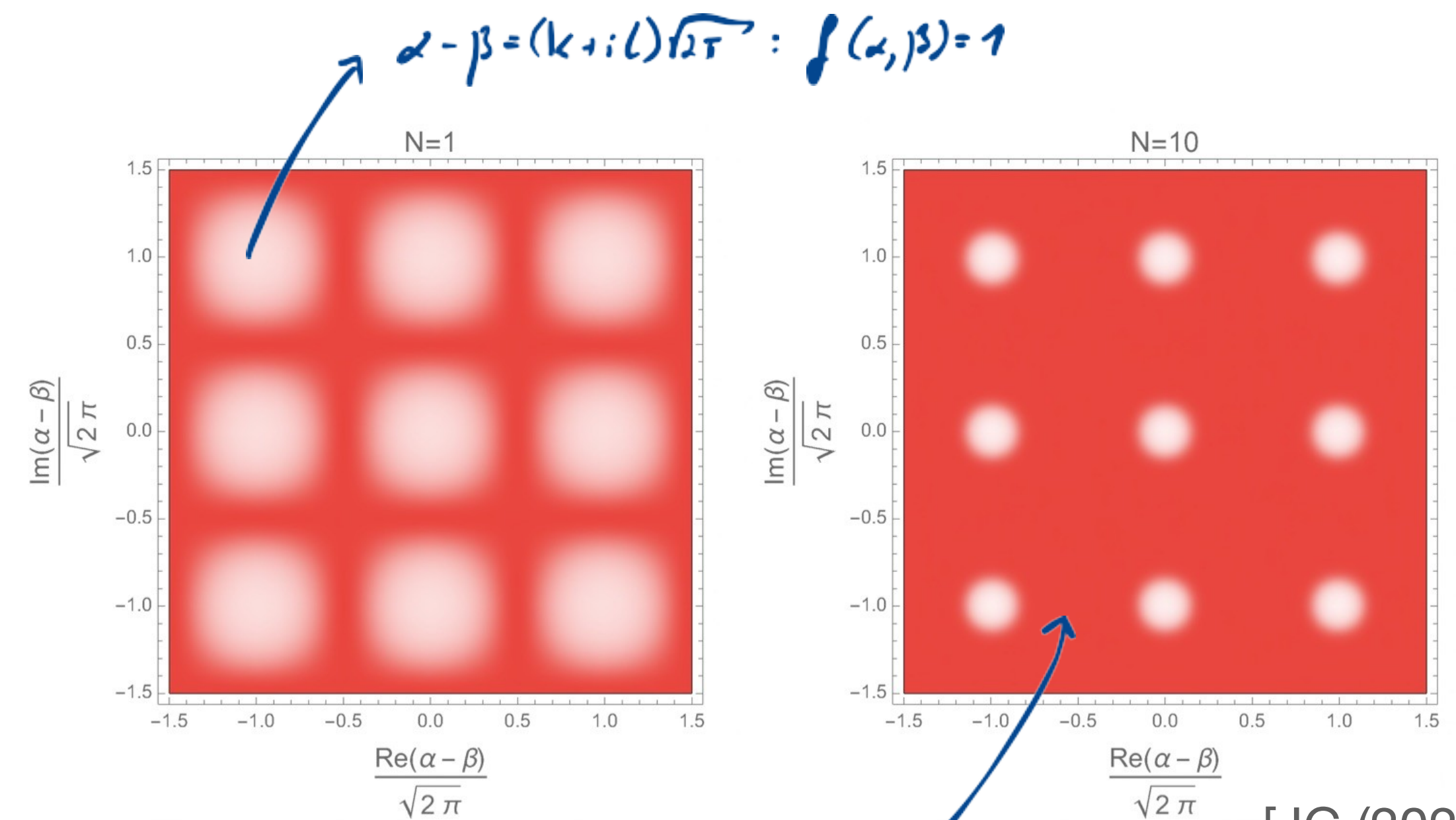
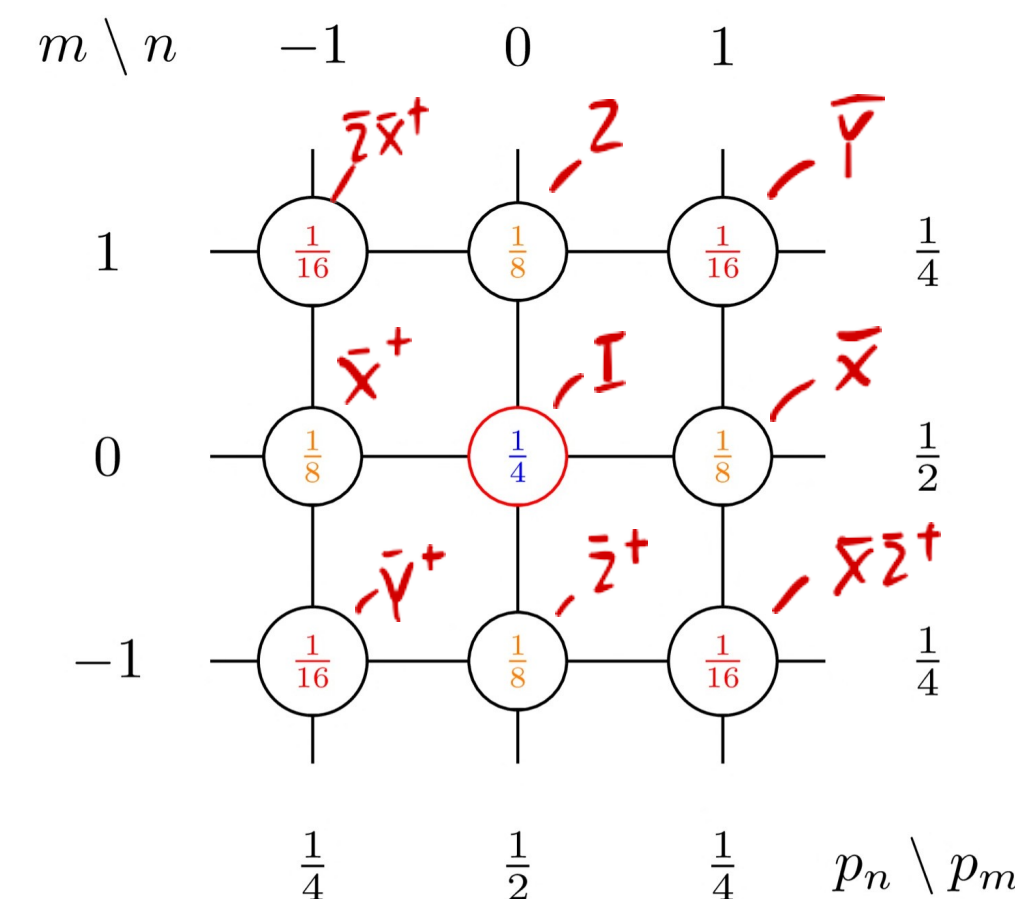
[JC (2020)]:

- Approximate displacement twirl by random walk over \mathcal{L}^\perp .
- Suppresses non-stabilizer coherences.

$$N(\cdot) = \int d^2\alpha d^2\beta c(\alpha, \beta) D(\alpha) \cdot D^\dagger(\beta)$$

$$N(\cdot) \mapsto \int d\mu(\gamma) D^\dagger(\gamma) N(D(\gamma) \cdot D^\dagger(\gamma)) D(\gamma)$$

$$c(\alpha, \beta) \mapsto c(\alpha, \beta) \left[\int d\mu(\gamma) e^{i2\pi\gamma^T J(\alpha-\beta)} \right]^N$$



[JC (2020)]

Gaussian twirling

- Approximate Gaussian Unitary twirling as random walk over $\text{Aut}^S(\mathcal{L}^\perp)$.
- If $\mu_{SL_2(\mathbb{Z})}(S) = \mu_{SL_2(\mathbb{Z}_2)}^{\text{Haar}}(S)$ this realizes logical Clifford twirl.

$$N(\cdot) = \int d^2\alpha d^2\beta c(\alpha, \beta) D(\alpha) \cdot D^\dagger(\beta)$$

$$N(\cdot) \mapsto \int d\mu_{SL_2(\mathbb{Z})}(S) U_S^\dagger N(U_S \cdot U_S^\dagger) U_S$$

$$c(\alpha, \beta) \mapsto \int d\mu_{SL_2(\mathbb{Z})}(S) c(S\alpha, S\beta)$$

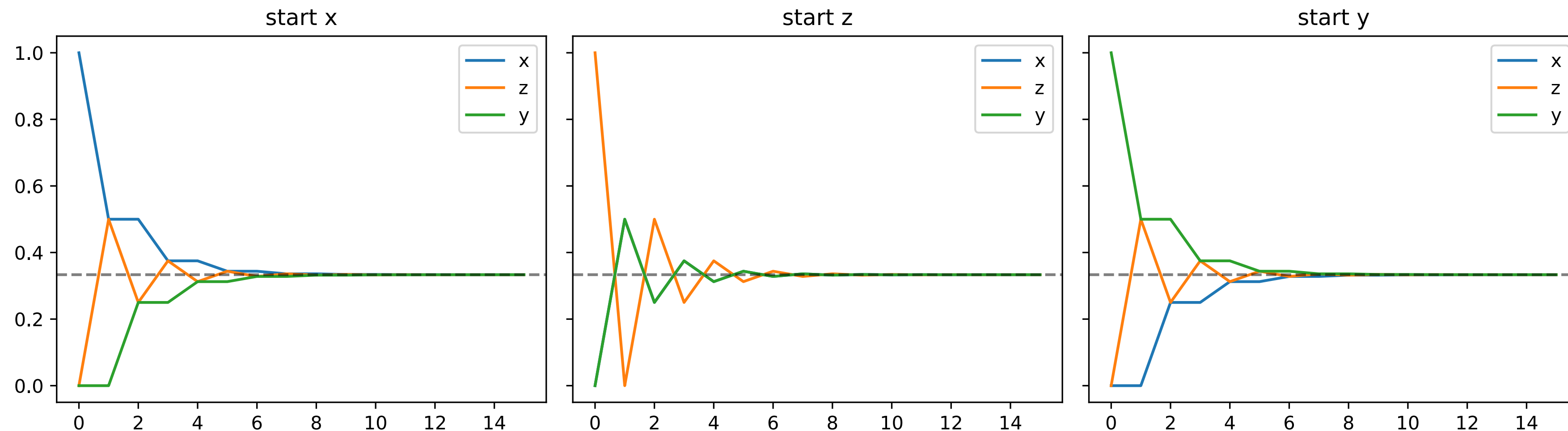
Representation of POVMs:

- Homodyne: $c(\alpha, \beta) \propto \delta(\Re(\alpha))\delta(\Re(\beta))\delta(\Im(\alpha - \beta))e^{i\Re(\alpha - \beta)\Im(\alpha)}$
- Heterodyne: $c(\alpha, \beta) \propto e^{-|\alpha|^2}\delta(\alpha - \beta)$
- Photon Counting: $c(\alpha, \beta) \propto e^{-|\alpha|^2/2 - |\beta|^2/2} \sum_n L_n(|\alpha|^2) L_n(|\beta|^2)$

Logical GKP Clifford twirl from Random Walks

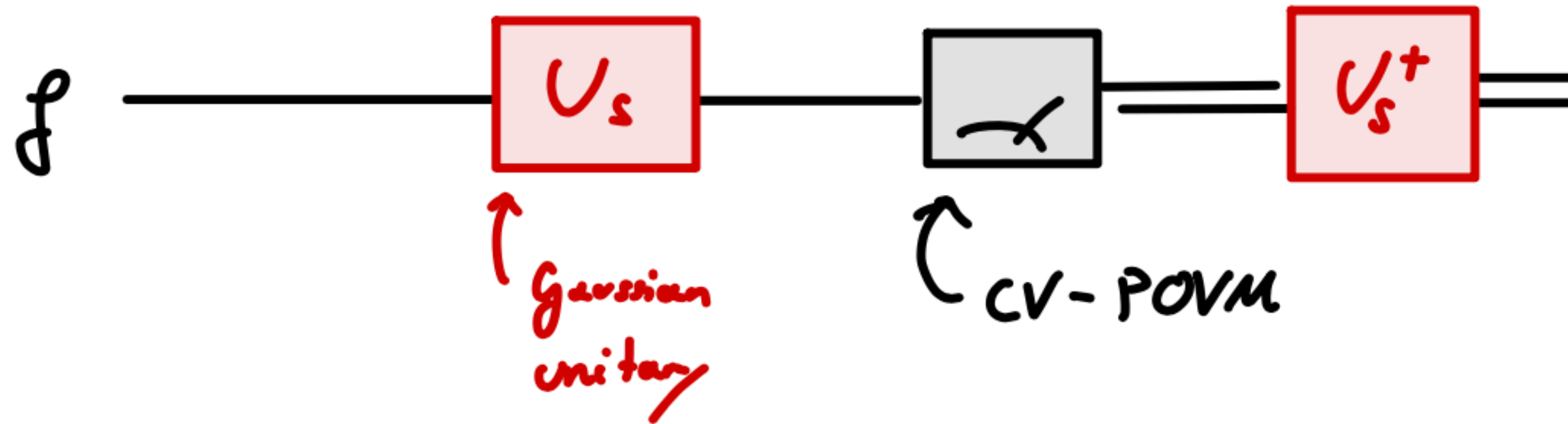
Compute effective marginal distribution of Logical Paulis in random walk:

Independent of P , random walk yields $\text{prob}(P \mapsto P' = X, Y, Z) \rightarrow \frac{1}{3}$



Together with displacement twirling, this yields full twirl over $\text{Aut}(\mathcal{L}^\perp)$ and projects any POVM onto logical depolarizing channel with $p = 2/3$.

Logical GKP Clifford twirl from Random Walks

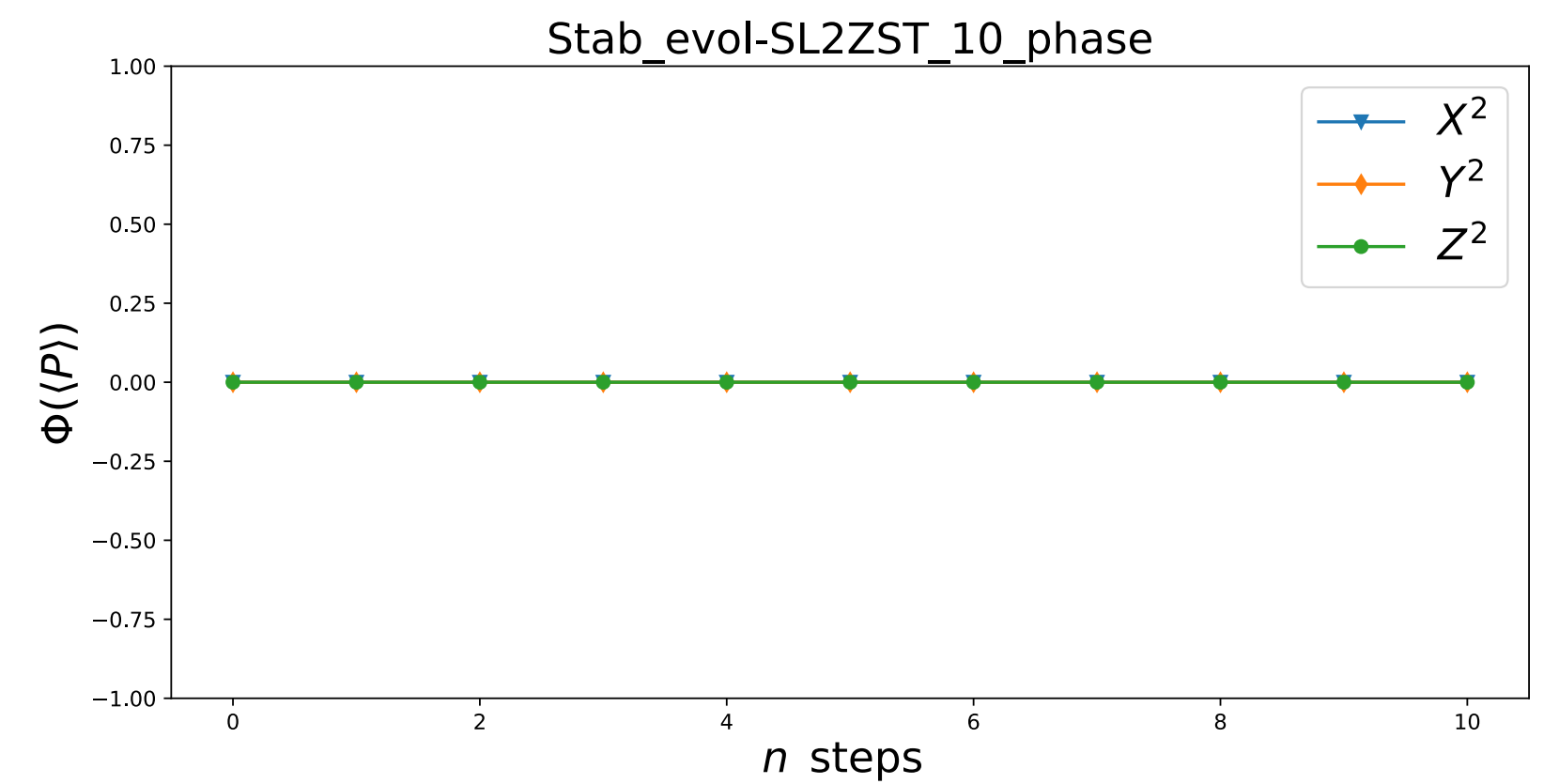
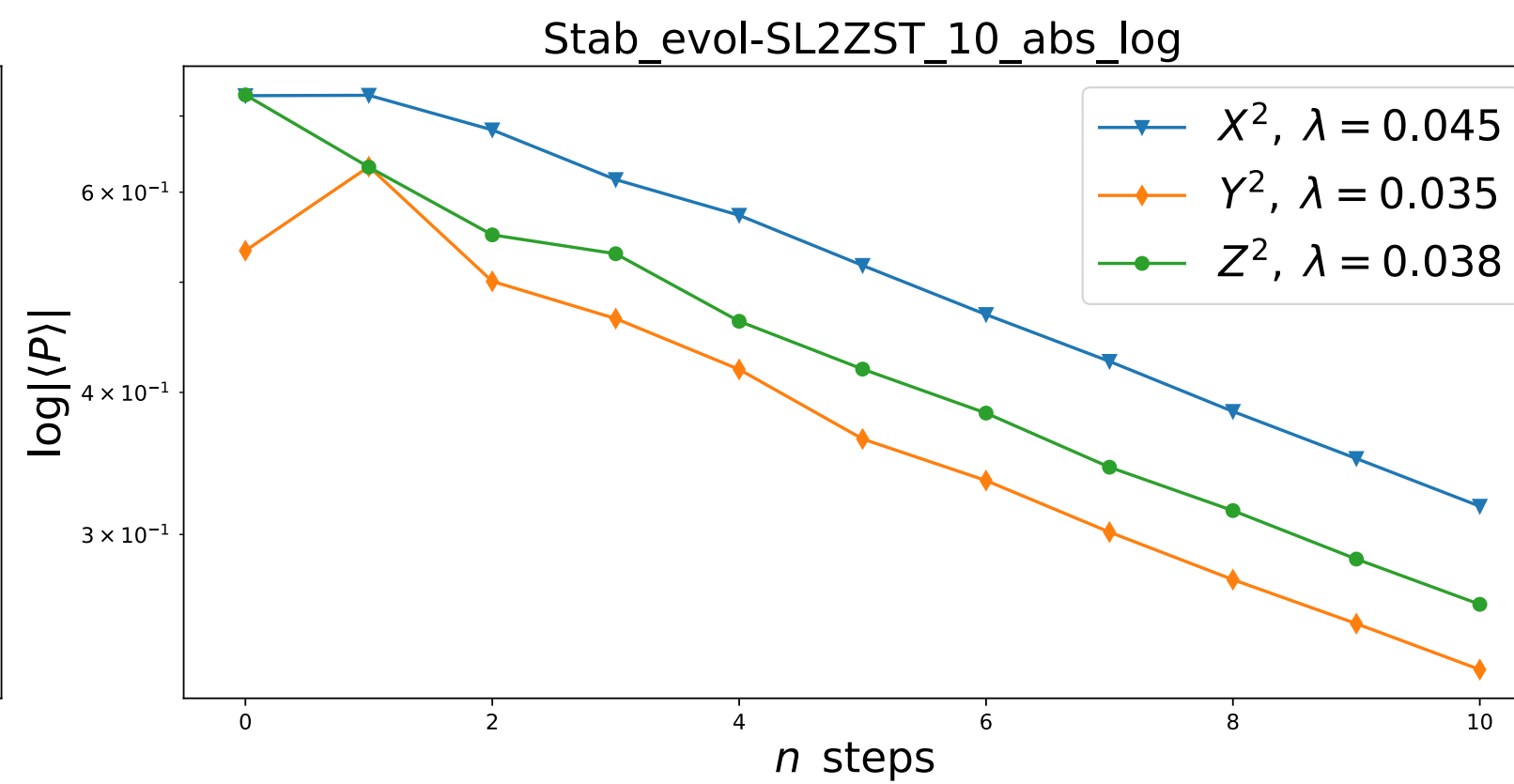
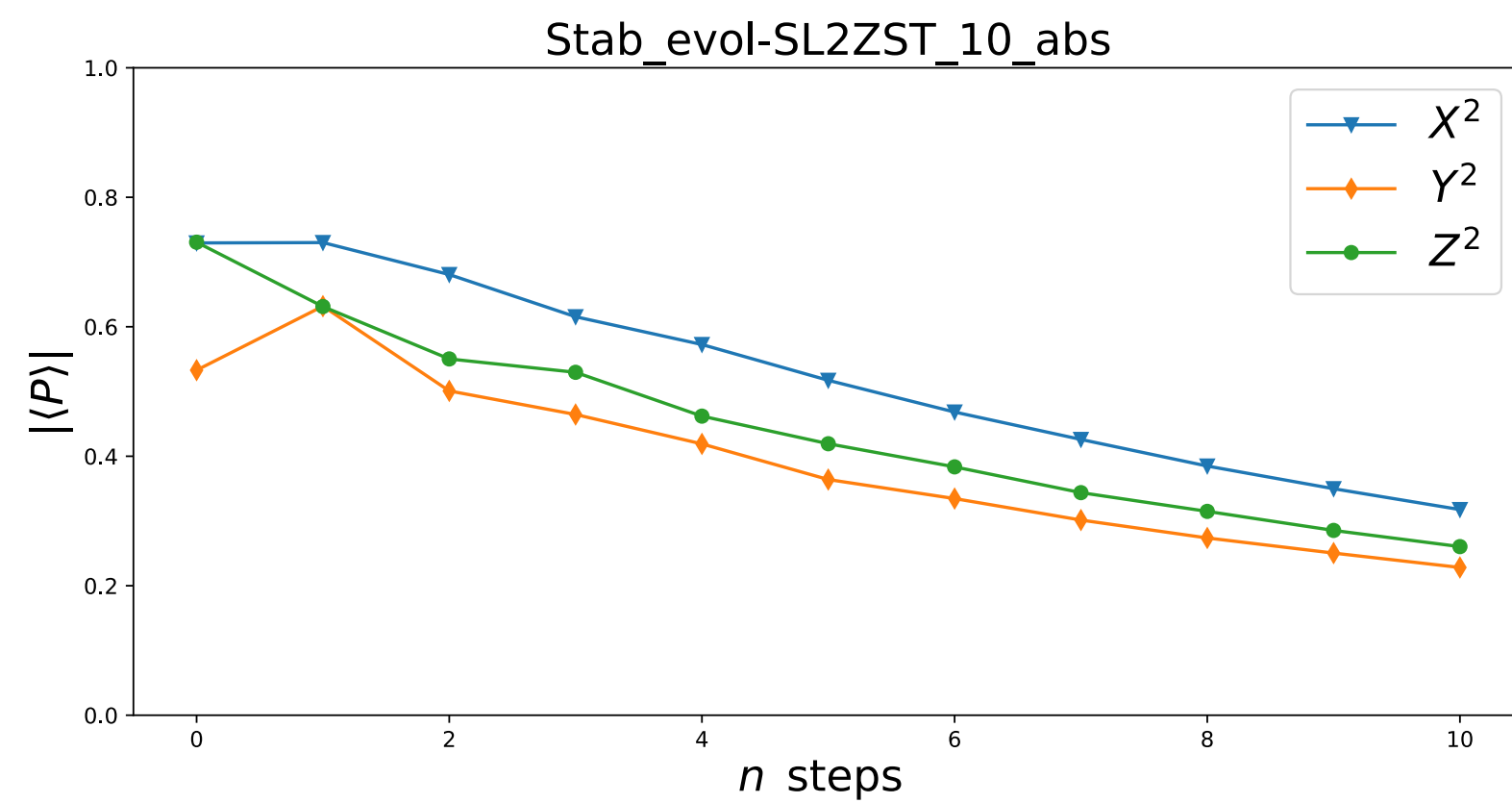
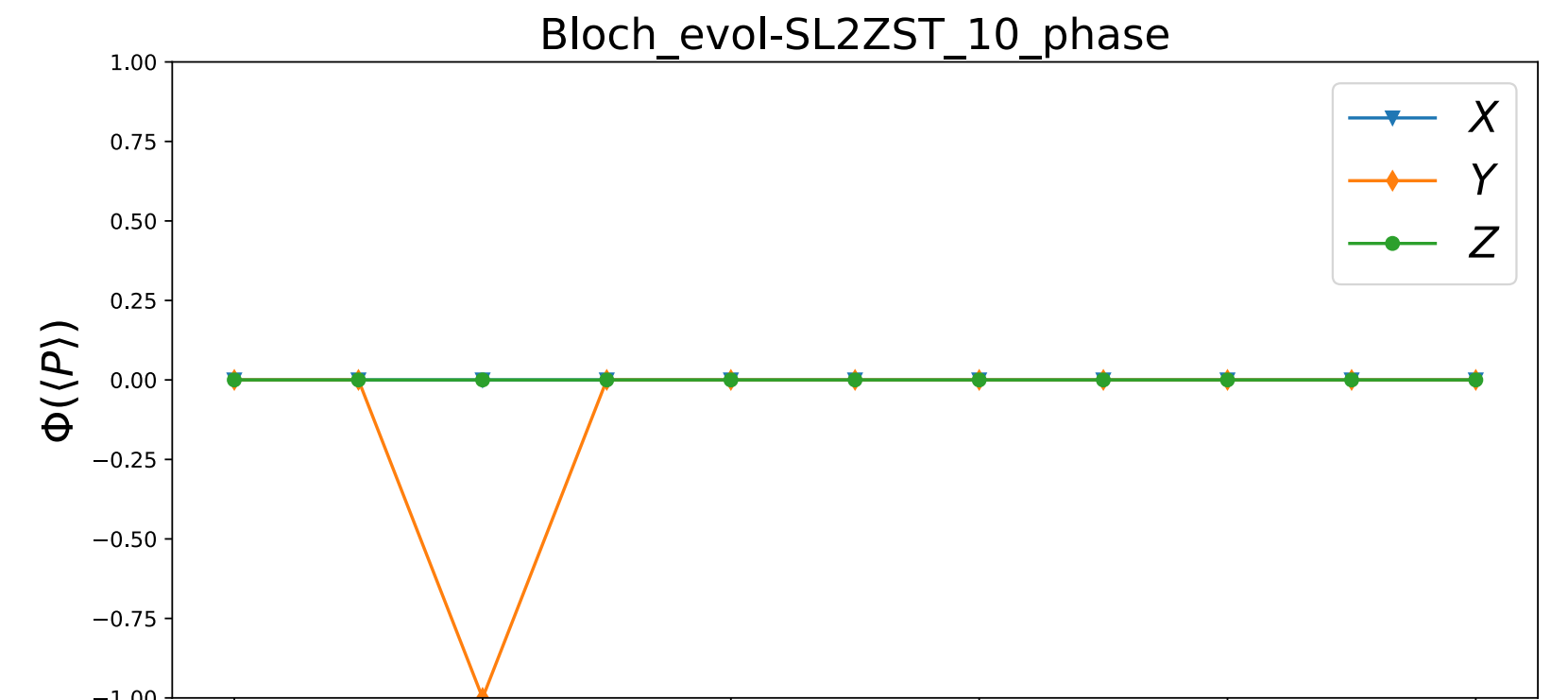
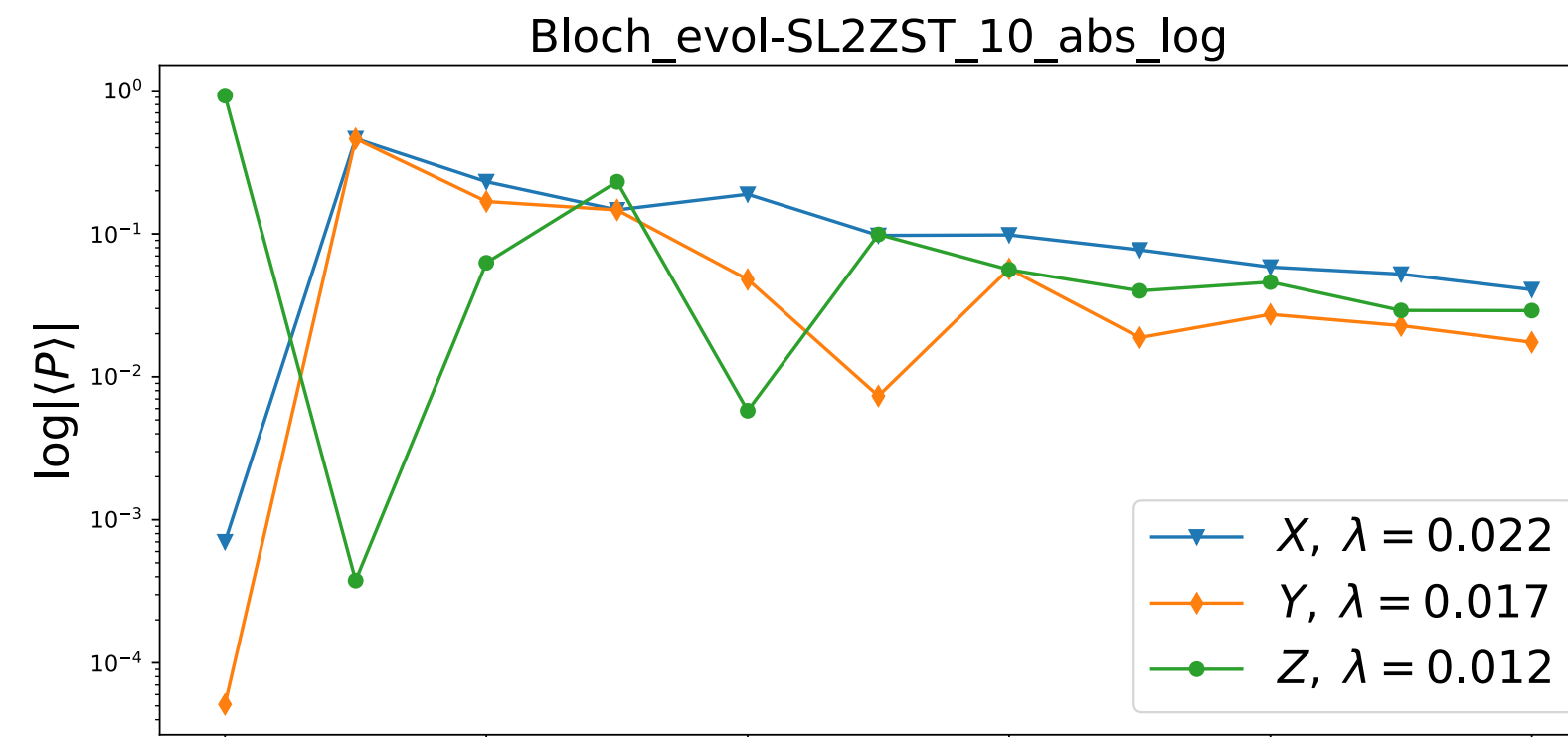
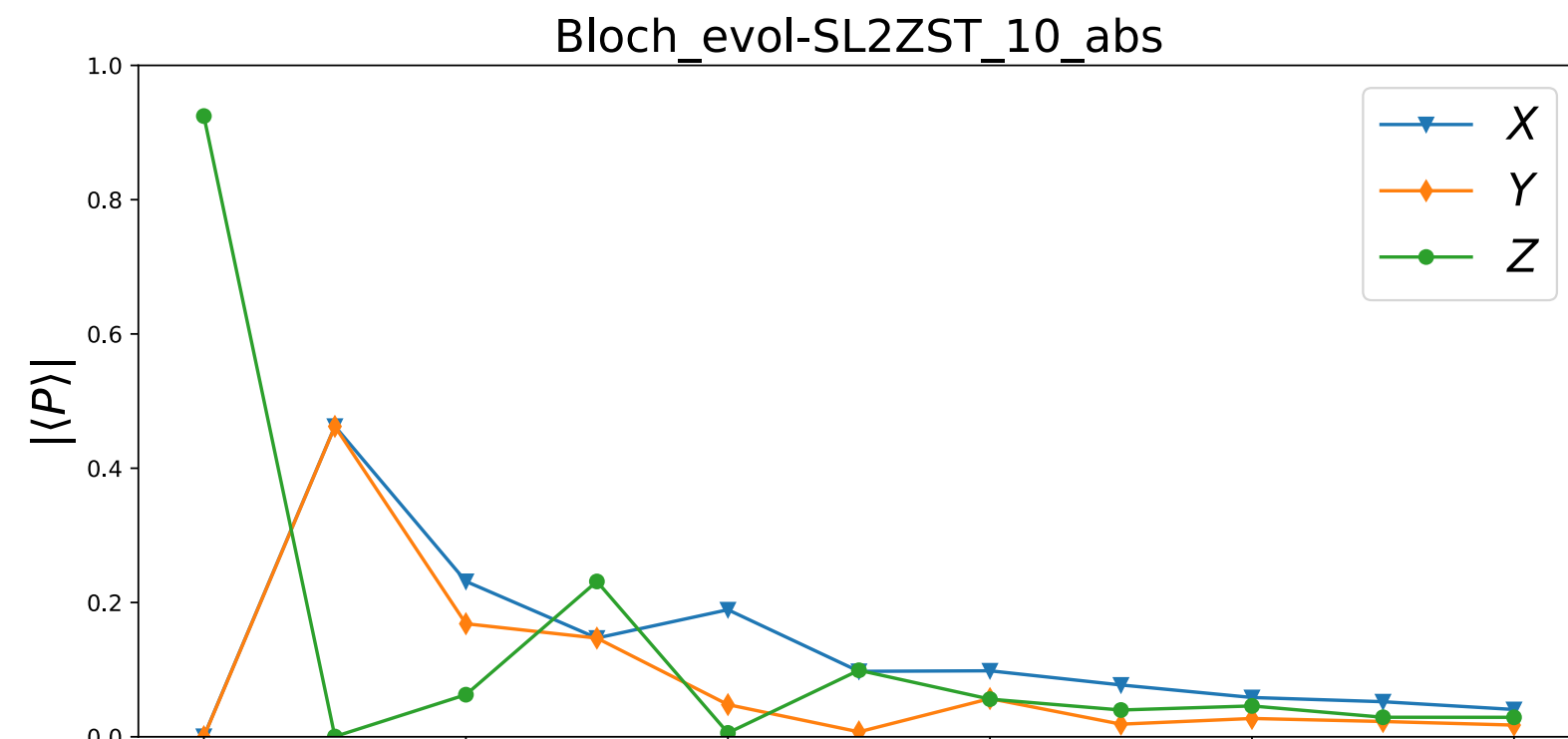


- Projects arbitrary CV-POVM onto logical depolarizing channel, can be classically inverted.
- Heterodyne: Shadow = generalized Gaussian decomposition of input states that reproduces logical expectation values

Appendix

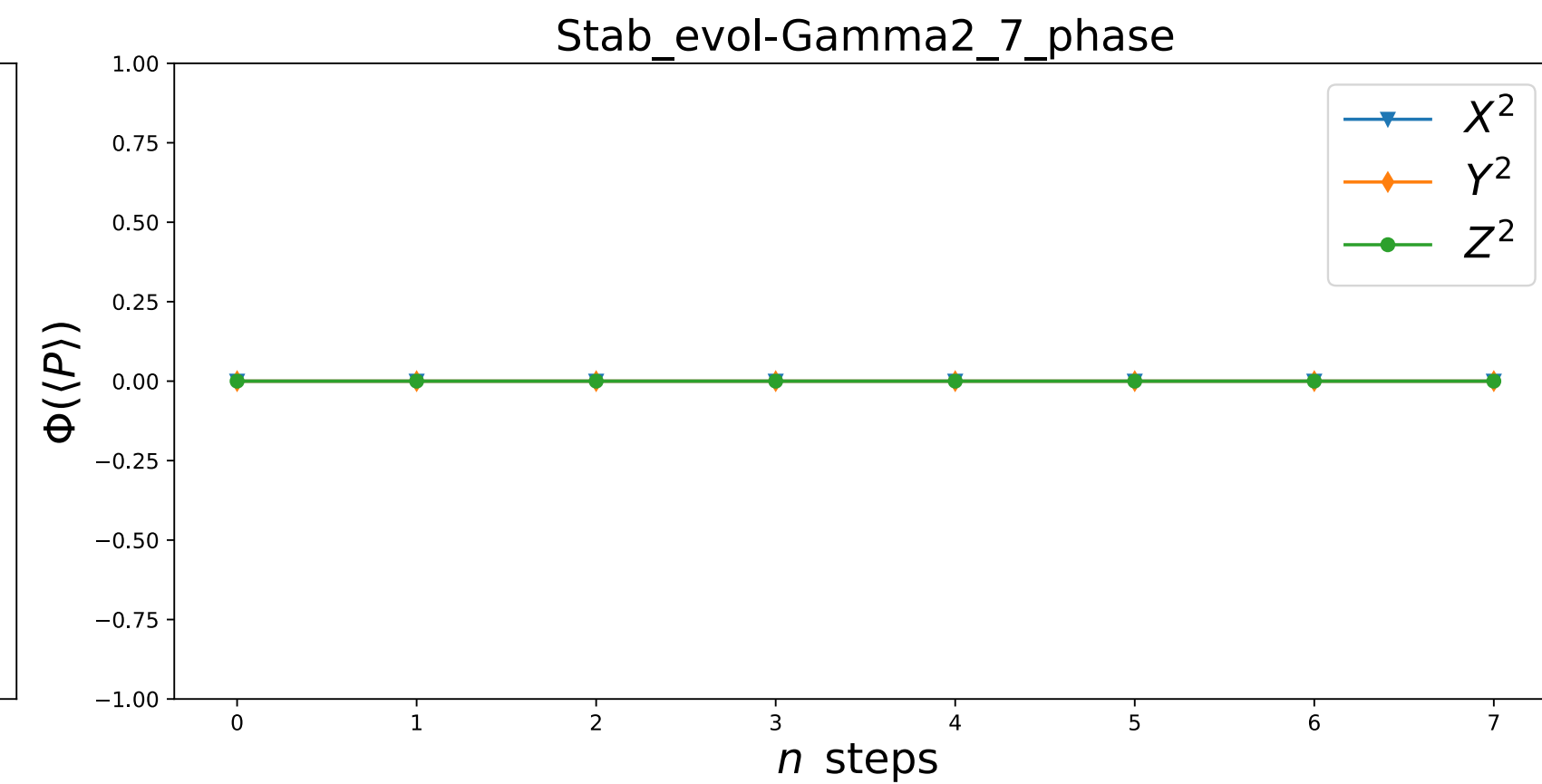
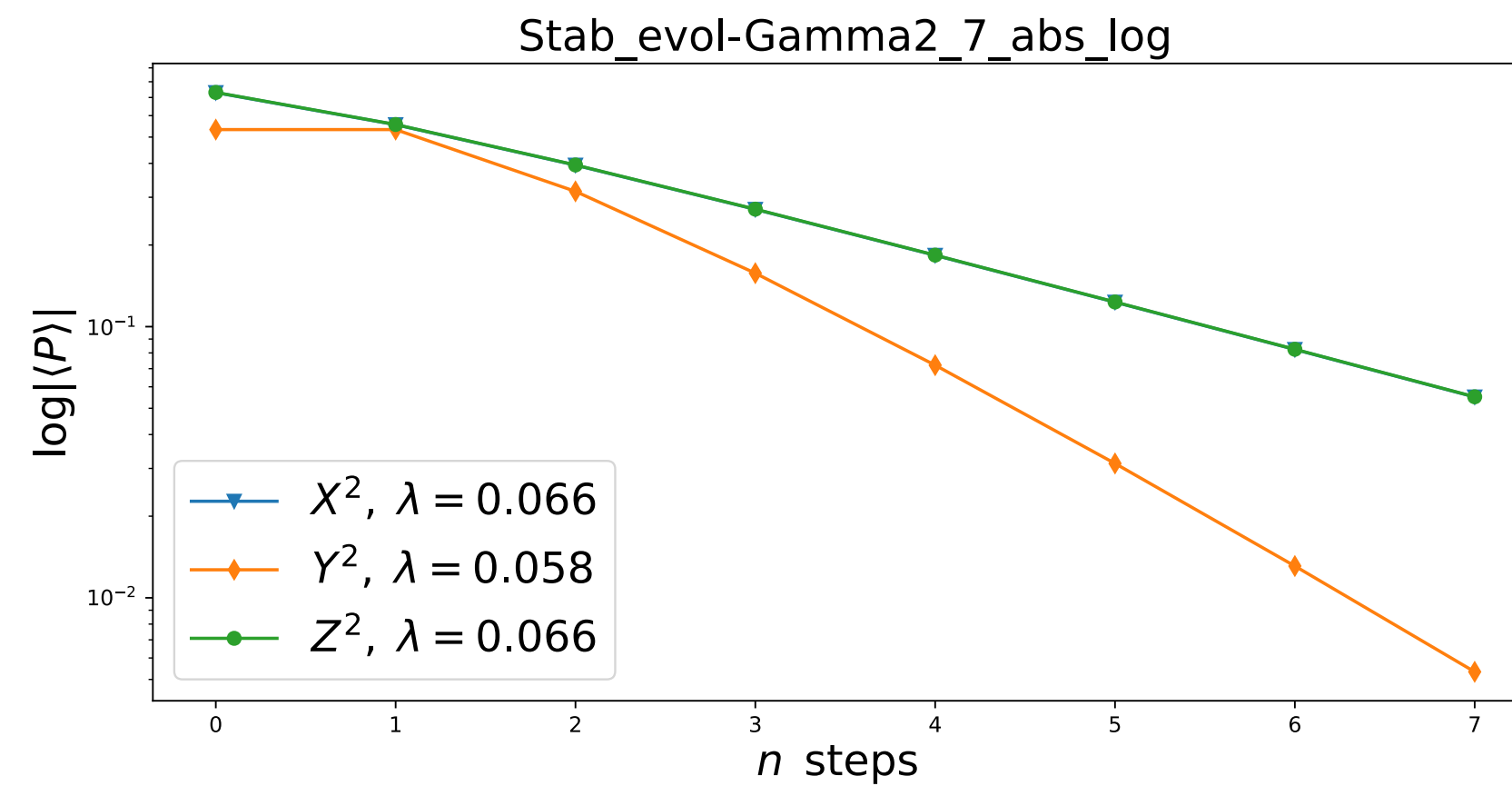
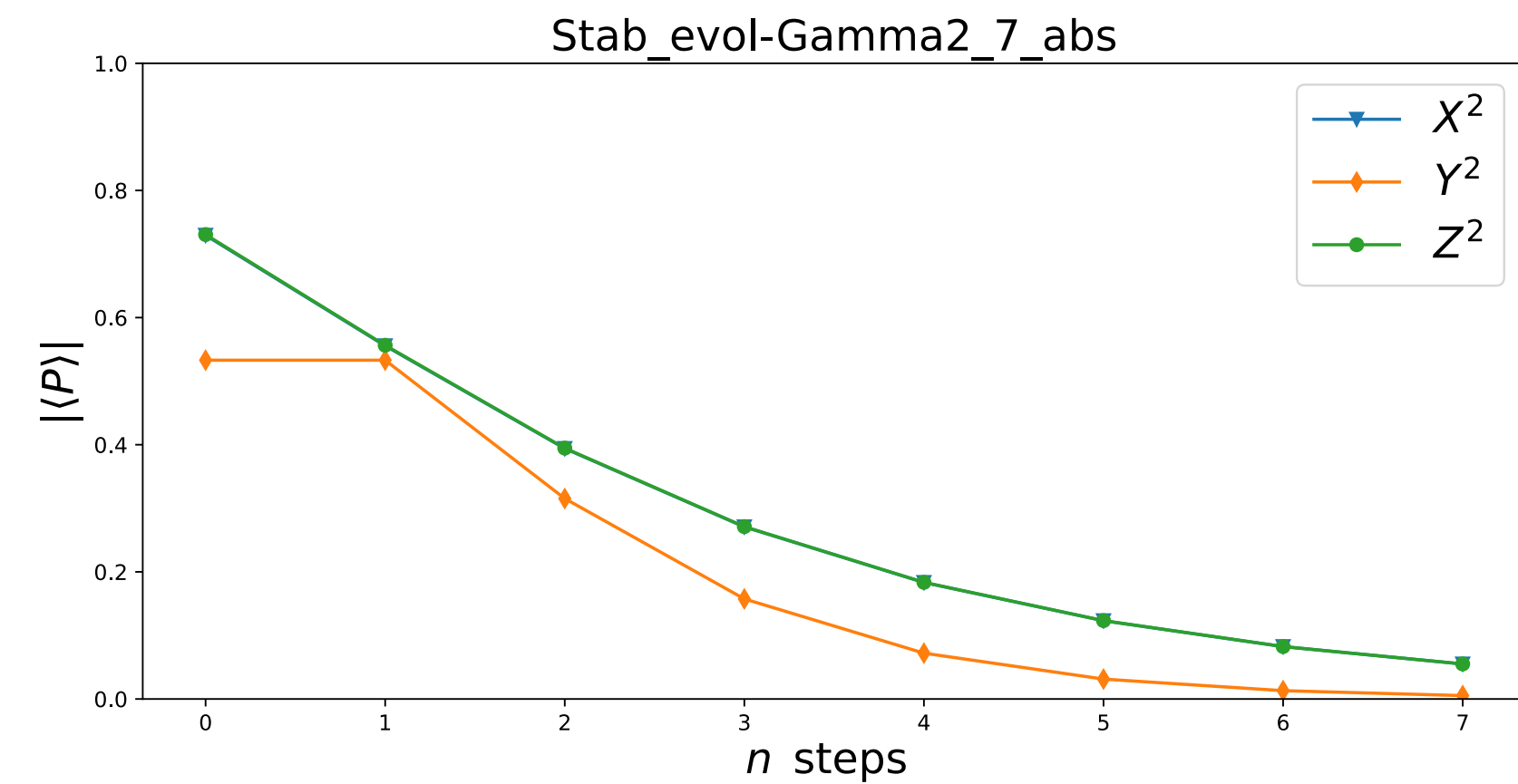
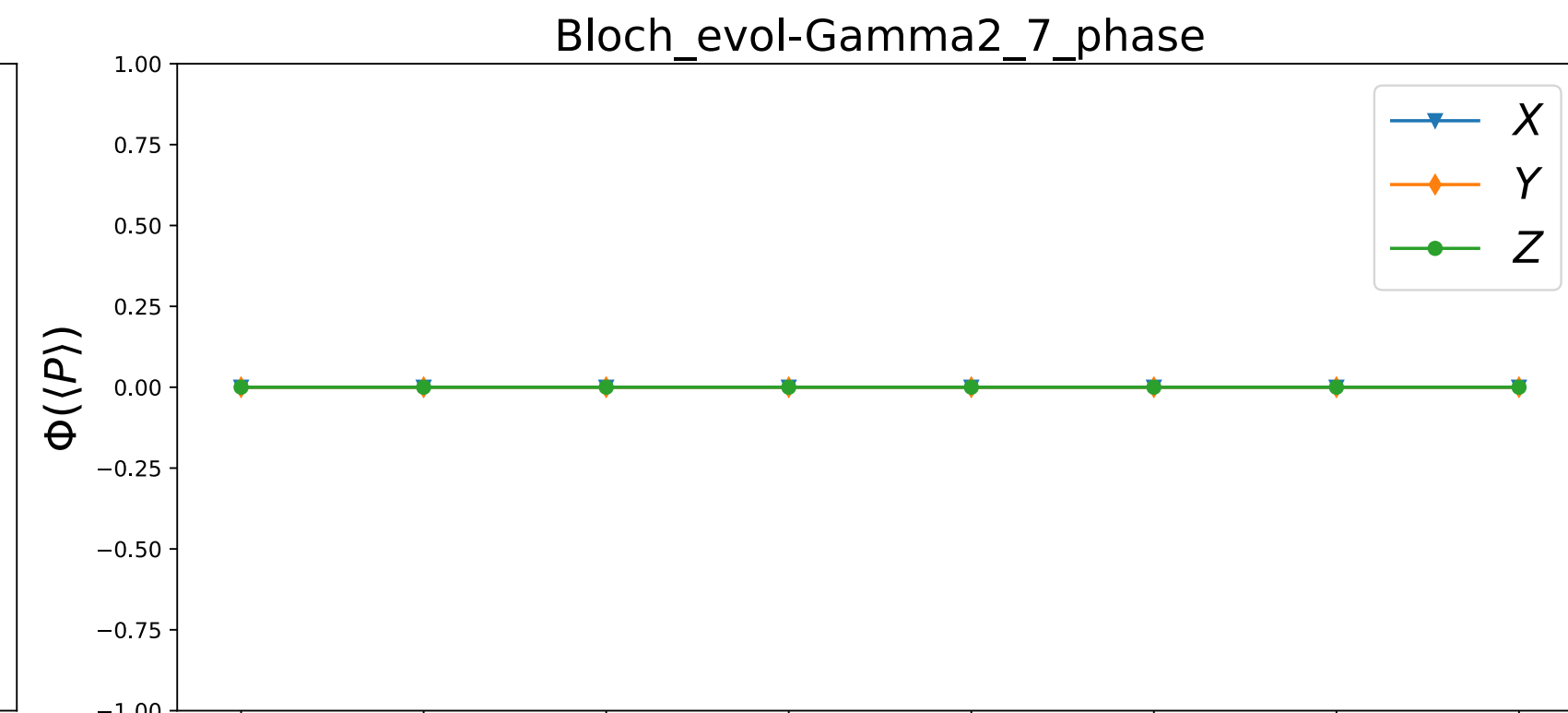
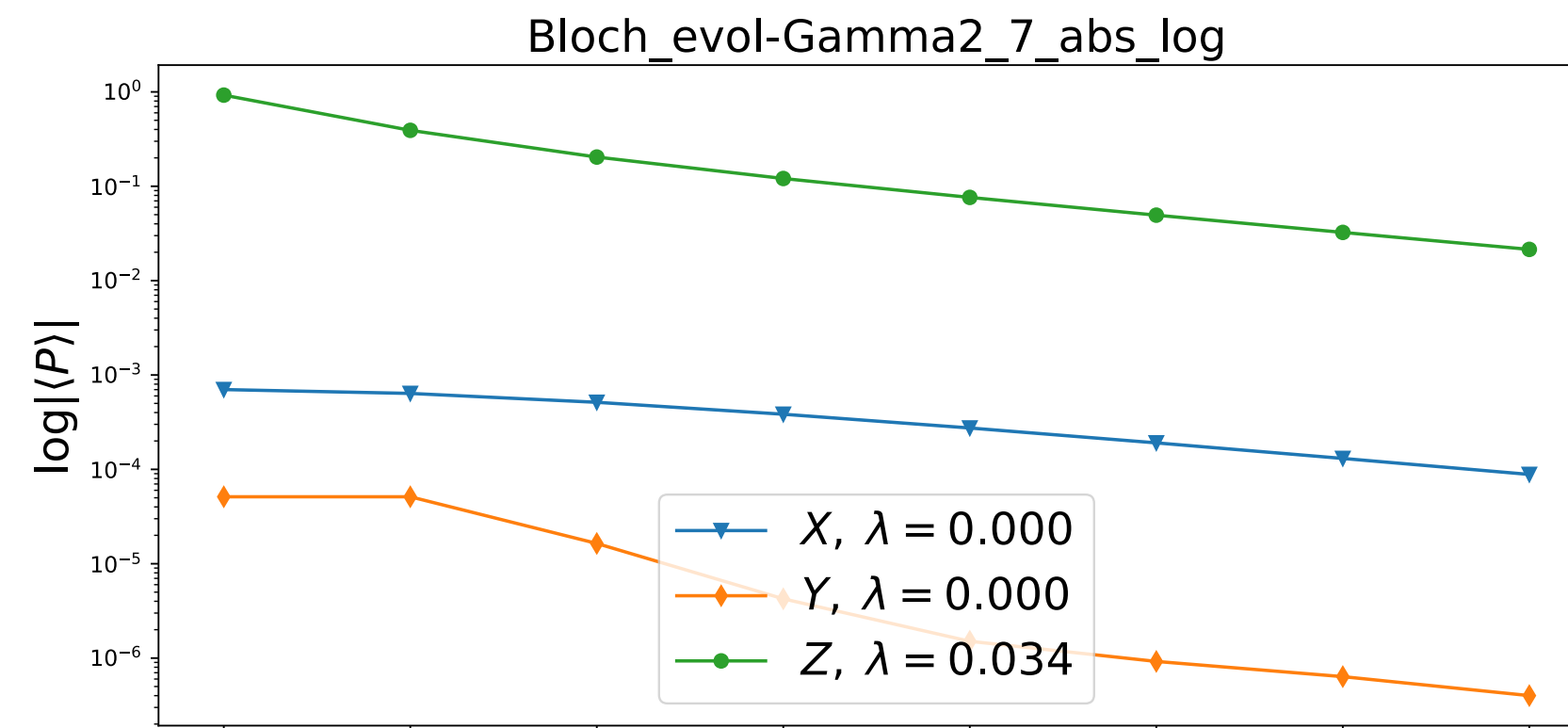
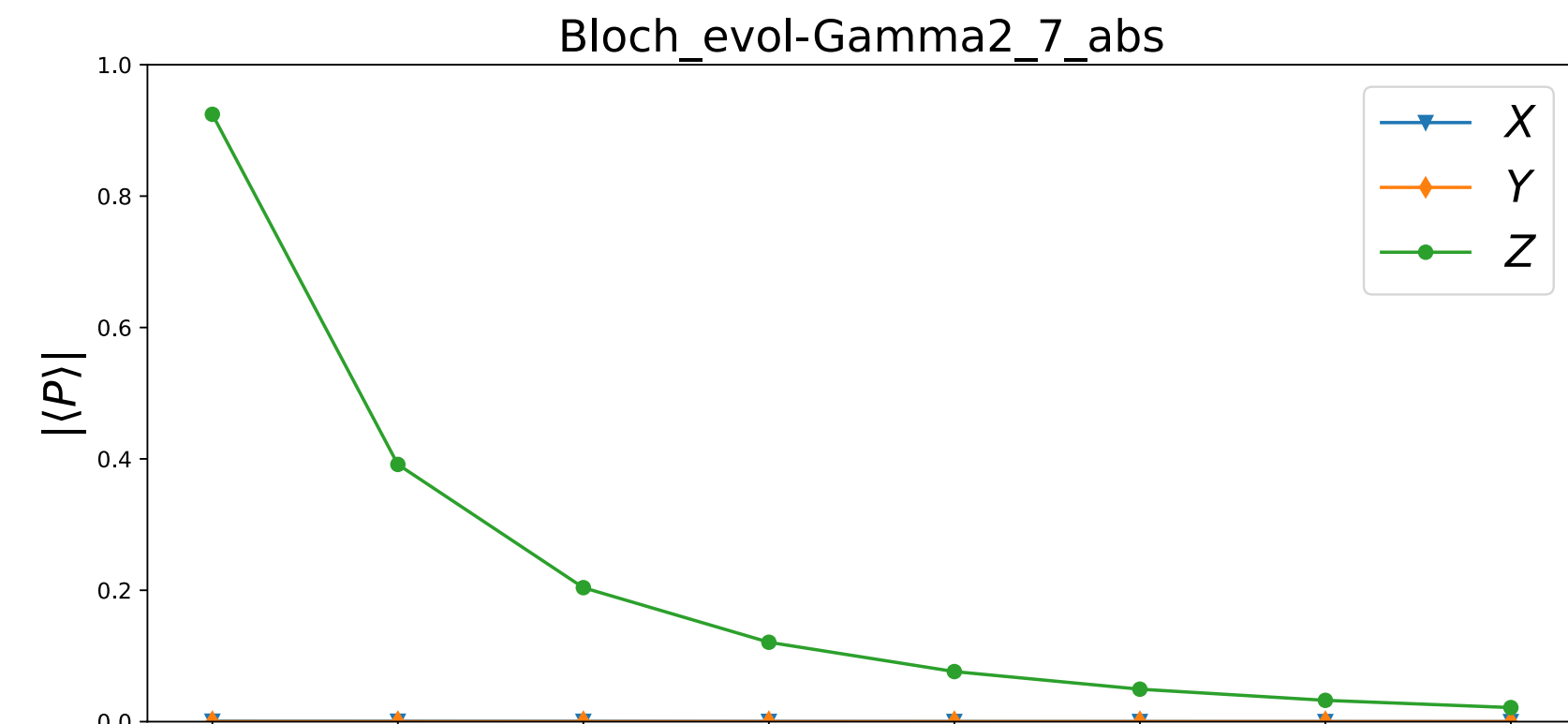
Finite Squeezing?

- For Simplicity, look at Clifford twirling of **States**



Finite Squeezing errors ?

- For Simplicity, look at Clifford twirling of **States**



TODO

- Use Logically decoded metric, sufficient to combat finite squeezing dynamics?

$$P_0 = \langle \text{rect}_{1, \sqrt{\pi}, 2\sqrt{\pi}}(\hat{x}) \rangle,$$
$$P_1 = \langle \text{rect}_{1, \sqrt{\pi}, 2\sqrt{\pi}}(\hat{x} - \sqrt{\pi}) \rangle,$$

$$\text{rect}_{A, \tau, T}(x) = \sum_n c_n(\tau) e^{i \frac{2\pi}{T} x}$$

$$P_0 = \sum_n c_n \langle e^{i \sqrt{\pi} n \hat{x}} \rangle,$$
$$P_1 = \sum_n c_n (-1)^n \langle e^{i \sqrt{\pi} n \hat{x}} \rangle,$$

Can obtain logically-decoded statistics from Displacement- expectations:
Improve phase estimation results in controlled-Displacement implementations