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Abstract—This manual is an introduction to control systems based on GATE problems.Links to sample Python codes are available in the text.

Download python codes using

svn co https://github.com/gadepall/school/trunk/control/codes

1 STABILITY

- 1.1 Second order System
- 1.1. Consider the following second order system with the transfer function

$$G(s) = \frac{1}{1 + 2s + s^2} \tag{1.1.1}$$

Is the system stable?

Solution: The poles of

$$G(s) = \frac{1}{1 + 2s + s^2}$$
 (1.1.2)

are at

$$s = -1$$
 (1.1.3)

i.e., the left half of s-plane. Hence the system is stable.

1.2. Find and sketch the step response c(t) of the system.

Solution: For step-response, we take input as unit-step function u(t)

$$C(s) = U(s).G(s) = \left[\frac{1}{s}\right] \left[\frac{1}{1+2s+s^2}\right]$$
(1.2.1)

$$=\frac{1}{s(1+s)^2}$$
 (1.2.2)

$$= \frac{1}{s} - \frac{1}{(1+s)} - \frac{1}{(1+s)^2}$$
 (1.2.3)

Taking the inverse Laplace transform,

$$c(t) = L^{-1} \left[\frac{1}{s} \right] - L^{-1} \left[\frac{1}{1+s} \right] - L^{-1} \left[\frac{1}{(1+s)^2} \right]$$
(1.2.4)

$$= (1 - e^{-t} - te^{-t}) u(t)$$
 (1.2.5)

The following code plots c(t) in Fig. ??

codes/ee18btech11002/plot.py

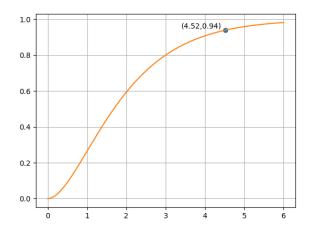


Fig. 1.2

1.3. Find the steady state response of the system using the final value theorem. Verify using ?? **Solution:** To know the steady response value of c(t), Using Final value theorem:

$$\lim_{t \to \infty} c(t) = \lim_{s \to 0} sC(s) \tag{1.3.1}$$

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We get

$$\lim_{s \to 0} s \left(\frac{1}{s}\right) \left(\frac{1}{1+s+s^2}\right) = \frac{1}{1+0+0} = 1$$
(1.3.2)

To verify, calculate

$$\lim_{t \to \infty} c(t) = (1 - 0 - 0) = 1 \tag{1.3.3}$$

1.4. Find the time taken for the system output c(t) to reach 94% of its steady state value.

Solution: Now, 94% of 1 is 0.94, so we should now solve for a positive t such that

$$1 - e^{-t} - te^{-t} = 0.94 (1.4.1)$$

The following code

codes/ee18btech11002/solution.py

provides the necessary solution as

$$t = 4.5228 \tag{1.4.2}$$

- 2 ROUTH HURWITZ CRITERION
 - 3 Compensators
 - 4 NYQUIST PLOT