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HOMEWORK 2: MONOPOLES

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1 Dirac

- (a) We are interested in the relation between the global properties of a manifold M and the structure of differential forms taking values on its cotangent bundle T^*M at each point of M .

Poincaré's lemma on $M = \mathbb{R}$: Let ω be a p -form ($p \in \{0, 1\}$) constructed from the cotangent space T^*M of M . Then $d\omega = 0$ (ω is closed) implies $\omega = d\lambda$ (ω is closed) where λ is a $(p-1)$ -form (0-form).

Proof: On \mathbb{R} , we can use the identity map as a global coordinate chart. The induced basis on 1-forms is $\{dx\}$ (a smooth frame field) and any 1-forms can be written as $\omega = gdx$ with $g \in C^\infty(\mathbb{R})$. Suppose now that ω is closed: we have $0 = d\omega = \partial_x g dx \wedge dx = 0, \forall g \in C^\infty(\mathbb{R})$ (ω being a 1-form is not restrictive, but would be for \mathbb{R}^n with $n > 1$). Then we take the 0-form $\lambda = G$ where G is any primitive of g ($G(x)$ exists because g is smooth) and apply an exterior derivative to get $d\lambda = gdx$. Because there are no $(0-1)$ -forms there is no need to check the lemma for 0-forms.

Counterexample: Consider the circle smooth manifold $\mathbb{S}^1 \subset \mathbb{R}^2$ (embedded as $\{x^2 + y^2 = 1 | (x, y) \in \mathbb{R}^2\}$ for simplicity). It takes at least two charts to cover this manifold and, although on individual charts all closed 1-forms are exact (charts make the manifold look like \mathbb{R} locally), this property is lost globally. Choose the chart map $\theta = \arctan_2$ sending points (x, y) on the circle to their angle with the x axis excluding the point $(1, 0)$ so that the domain is open. With this chart we have the coordinate induced one form frame field $d\theta$ which we use to construct the closed form $\omega = d\theta$. On $(0, 2\pi)$, this form is exact since we have a 0-form $\lambda = F \in C^\infty((0, 2\pi))$ such that $\omega = d\lambda = \partial_\theta F d\theta = d\theta$ forcing $F = \theta + c, c \in \mathbb{R}$ since F has to be a primitive of 1 in the variable θ . The function F is smooth on the chart, but can never be extended to a smooth function over \mathbb{S}^1 globally. Indeed, 0 and 2π being identified, a continuous function on \mathbb{S}^1 should be constant at the excluded point $(0, 1)$ and this would require $\lim_{\theta \rightarrow 0^+} (\theta + c) = \lim_{\theta \rightarrow 2\pi^-} (\theta + c)$ which is impossible. Therefore there is a closed form on \mathbb{S}^1 that is not exact.

- (b) Let $F^{(2)}$ be a 2-form on the 2-sphere \mathbb{S}^2 . Suppose $F^{(2)}$ is globally exact implying there is a 1-form ω such that $F^{(2)} = d\omega$. Then we can use Stokes theorem in combination with the fact \mathbb{S}^2 has no boundary to write $g = \frac{1}{4\pi} \int_{\mathbb{S}^2} F^{(2)} = \frac{1}{4\pi} \int_{\partial \mathbb{S}^2} d\omega = 0$.
- (c) Now working in Minkowski space $\{\eta, \mathbb{R}^{1,3}\}$ with mostly + signature in the coordinate chart (t, r, θ, ϕ) (this order for the variables provides the notion of positive orientation of a basis) built from spherical coordinates on \mathbb{R}^3 , we have the 2-form $F^{(4)} = Q \sin(\theta) d\theta \wedge d\phi$ with $Q \in \mathbb{R}$. We want to determine if $F^{(4)}$ satisfies Maxwell's equations $dF^{(4)} = 0, \quad d \star F^{(4)} = 0$. We have $dF^{(4)} = Q \cos(\theta) d\theta \wedge d\theta \wedge d\phi = 0$. To evaluate the Hodge dual of $F^{(4)}$, we first calculate

$$\begin{aligned} \star d\theta \wedge d\phi &= \sqrt{|r^4 \sin^2 \theta|} \left| \frac{1}{2!} \frac{1}{2!} \epsilon^{\theta\phi} r_t dr \wedge dt + \frac{1}{2!} \frac{1}{2!} \epsilon^{\theta\phi} r_r dt \wedge dr - \frac{1}{2!} \frac{1}{2!} \epsilon^{\phi\theta} r_t dr \wedge dt - \frac{1}{2!} \frac{1}{2!} \epsilon^{\phi\theta} r_r dt \wedge dr \right. \\ &= r^2 |\sin \theta| \eta^{\theta\theta} \eta^{\phi\phi} \left(\frac{1}{2!} \frac{1}{2!} \epsilon_{\theta\phi r t} dr \wedge dt + \frac{1}{2!} \frac{1}{2!} \epsilon_{\theta\phi t r} dt \wedge dr - \frac{1}{2!} \frac{1}{2!} \epsilon_{\phi\theta r t} dr \wedge dt - \frac{1}{2!} \frac{1}{2!} \epsilon_{\phi\theta t r} dt \wedge dr \right) \\ &= r^2 |\sin \theta| \frac{1}{r^4 \sin^2 \theta} \frac{1}{2!} \frac{1}{2!} ((-1) dr \wedge dt + (+1) dt \wedge dr - (+1) dr \wedge dt - (-1) dt \wedge dr) = dt \wedge dr \end{aligned}$$

and it follows that $d \star F^{(4)} = d(Q/r^2 (dt \wedge dr)) = -Q/r^3 (dr \wedge dt \wedge dr) = 0$ where the absolute value was ignored because $\theta \in (0, 2\pi)$ making $\sin(\theta) > 0$.

- (d) We can convert the form $F^{(4)}$ to cartesian coordinates with the relations

$$\phi = \arctan_2(y, x), \quad \theta = \arctan_2(z, \sqrt{x^2 + y^2}) \implies d\phi = \frac{-ydx + xdy}{x^2 + y^2}, \quad d\theta = \frac{\sqrt{x^2 + y^2} dz - (xdx + ydy) \frac{z}{\sqrt{x^2 + y^2}}}{r^2}$$

leading to

$$\begin{aligned} F^{(4)} &= Q \sin(\theta) d\theta \wedge d\phi = Q \frac{\sqrt{x^2 + y^2}}{r} \left(\frac{\sqrt{x^2 + y^2} dz - (xdx + ydy) \frac{z}{\sqrt{x^2 + y^2}}}{r^2} \right) \wedge \left(\frac{-ydx + xdy}{x^2 + y^2} \right) \\ &= Q \frac{1}{r^3} \left(dz \wedge (-ydx + xdy) - (x^2 dx \wedge dy - y^2 dy \wedge dx) \frac{z}{x^2 + y^2} \right) = Q \frac{1}{r^3} (-ydz \wedge dx - xdy \wedge dz - zdx \wedge dy). \end{aligned}$$

We note the electric field components (associated to $dx^i \wedge dt$) all vanish and we only have a magnetic field (associated to $dx^i \wedge dx^j$). The magnetic field has the same form as an electric monopole (inverse square law multiplies by a unit "vector").

- (e) Since the monopole field is static, we drop the time direction by mapping $F^{(4)}$ to the two-form $F^{(3)}$ in the cotangent bundle over \mathbb{R}^3 on a fixed time slice. Going further we can map $F^{(3)}$ on the cotangent bundle over \mathbb{S}^2 (embedded in \mathbb{R}^3 as a sphere of radius 1) to get the two-form $F^{(2)}$. To characterize the two-form $F^{(2)}$, we evaluate the integral given in (b) as

$$g = \frac{Q}{4\pi} \int_{\mathbb{S}^2} \sin(\theta) d\theta \wedge d\phi = \frac{Q}{4\pi} \int_{\mathbb{S}^2} \sin(\theta) d\theta (e_\theta) \wedge d\phi (e_\phi) = Q$$

with e_ϕ, e_θ the dual vector basis to $d\phi, d\theta$. More formally, this integration on $V \subset \mathbb{S}^2$ is brought to an integral in $U \subset \mathbb{R}^2$ on the pullback of $F^{(2)}$ by a diffeomorphism mapping U to V . A convenient choice of diffeomorphism is the coordinate chart already used to write $F^{(2)}$. Under this diffeomorphism, $d\theta$ and $d\phi$ are mapped to the exterior derivatives of the coordinate functions θ, ϕ over U (the exterior derivative of the projection map on each axis which are also named $d\theta$ and $d\phi$). This allows us to use regular forms of integration where θ and ϕ range from 0 to π and 0 to 2π respectively and use the coordinate representation of the two-form components. Since **exact** \implies **vanishing of g** as shown in (b), we have **non vanishing of $g \implies$ not exact** and $F^{(2)}$ is not exact.

One could say that $g = \frac{1}{4\pi} \int_{S^2=\partial \text{Ball}} F^{(2)} = \frac{1}{4\pi} \int_{\text{Ball}} dF^{(2)} = 0$ forming a contradiction with $F^{(2)}$ not being exact. The solution to this problem can be seen with result (c) where $F^{(2)}$ is shown to be ill-defined at the origin. Therefore we need to puncture \mathbb{R}^3 by removing the origin from the domain of definition of $F^{(3)}$ creating a second boundary restoring the result $0 = \frac{1}{4\pi} \int_{\partial \text{Ball} + \text{puncture}} F^{(2)}$. Normally the set added to the boundary would be of zero measure, but comparing with the usual treatment of electric monopoles, we get that a dirac delta at the puncture point will change the value of g from 0 to Q .

- (f) Stereographic projections provide maps from $U_+ = S^2 - \text{North pole}$ (projecting from the north pole) and $U_- = S^2 - \text{South pole}$ (projecting to the south pole) to all of \mathbb{R}^2 . Expressed in the cartesian coordinates of the embedding space of S^2 in \mathbb{R}^3 , the associated coordinate maps φ_{\pm} are

$$\varphi_{\pm} : (x, y, z) \mapsto (u_{\pm}, v_{\pm}) = \left(\frac{x}{1 \mp z}, \frac{y}{1 \mp z} \right).$$

This form can be obtained by looking at a cut of the sphere in a zw -plane containing the z axis. In this plane, we look for the intersection u_{\pm}, v_{\pm} of a line passing through the relevant pole and the point x, y, z with the xy -plane. In the section plane, the line is given by points of coordinates w_l, z_l such that $z_l = 1 - \frac{1+z}{w} w_l$ (North pole) or $z_l = -1 + \frac{1-z}{w} w_l$ (South pole). The intersection with the xy -plane is given by $u_{\pm} = \frac{w}{1 \mp z} \frac{x}{w}$ and $v_{\pm} = \frac{w}{1 \mp z} \frac{y}{w}$ (w coordinate projected on the x and y axis respectively).

To express $F^{(2)}$ in these new coordinates, we notice that $x = u_{\pm}(1 \mp z)$ and $y = v_{\pm}(1 \mp z)$. Since our sphere has radius 1, we have

$$u_{\pm}^2 + v_{\pm}^2 = (1 - z^2)/(1 \mp z)^2 = (1 \pm z)/(1 \mp z) \implies u_{\pm}^2 + v_{\pm}^2 \mp z(u_{\pm}^2 + v_{\pm}^2) = 1 \pm z \implies z = \pm \frac{1 - u_{\pm}^2 - v_{\pm}^2}{1 + u_{\pm}^2 + v_{\pm}^2}$$

leading to $dx = (1 \mp z)du_{\pm} \mp u_{\pm}dz$, $dy = (1 \mp z)dv_{\pm} \mp v_{\pm}dz$ and $dz = Adu_{\pm} + Bdv_{\pm}$ where

$$A = -\pm \frac{2u_{\pm}(1 + u_{\pm}^2 + v_{\pm}^2)}{(1 + u_{\pm}^2 + v_{\pm}^2)^2} - \pm \frac{2u_{\pm}(1 - u_{\pm}^2 - v_{\pm}^2)}{(1 + u_{\pm}^2 + v_{\pm}^2)^2} = \mp \frac{4u_{\pm}}{(1 + u_{\pm}^2 + v_{\pm}^2)^2}, \quad B = \mp \frac{4v_{\pm}}{(1 + u_{\pm}^2 + v_{\pm}^2)^2}.$$

We can also relate the two-form frame fields in cartesian coordinates to the $du \wedge dv$ frame field as (omitting \pm on u, v symbols from now on)

$$\begin{aligned} dx \wedge dy &= ((1 \mp z)du \mp u dz) \wedge ((1 \mp z)dv \mp v dz) \\ &= (1 \mp z)^2 du \wedge dv \mp (1 \mp z)(Bv + Au) du \wedge dv \\ &= (1 \mp z)^2 du \wedge dv + 4(1 \mp z) \frac{v^2 + u^2}{(1 + u^2 + v^2)^2} du \wedge dv \\ dy \wedge dz &= (1 \mp z)A dv \wedge du = \pm(1 \mp z) \frac{4u}{(1 + u^2 + v^2)^2} du \wedge dv \\ dz \wedge dx &= (1 \mp z)B dv \wedge du = \pm(1 \mp z) \frac{4v}{(1 + u^2 + v^2)^2} du \wedge dv \end{aligned}$$

With these expressions we are ready to express $F^{(3)}$ in the du and dv frame field (we omit the \pm on u, v in what follows) as

$$\begin{aligned} F^{(3)} &= Q \frac{1}{r^3} (-y dz \wedge dx - x dy \wedge dz - z dx \wedge dy) \\ &= -Q \left(z(1 \mp z)^2 + 4z(1 \mp z) \frac{v^2 + u^2}{(1 + u^2 + v^2)^2} \pm (1 \mp z)^2 \frac{4u^2 + 4v^2}{(1 + u^2 + v^2)^2} \right) \\ &= -Q \left(z(1 \mp z)^2 + 4(1 \pm z)(1 \mp z) \frac{v^2 + u^2}{(1 + u^2 + v^2)^2} \right) \\ &= -Q(1 \mp z)^2 \left(\pm \frac{1 - (u^2 + v^2)^2}{(1 + u^2 + v^2)^2} + 4 \frac{(u^2 + v^2)^2}{(1 + u^2 + v^2)^2} \right). \end{aligned}$$

- (g)
(h)
(i)

2 Taub-NUT, or the gravitomagnetic monopole

- (a)
(b)
(c)
(d)