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HOMework 1

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1 Cartan in a FLRW universe

- (a) The Friedmann-Lemaitre-Robinson-Walker (FLRW) metric two-form describes a spacetime with spacelike foliation in homogeneous and isotropic hypersurfaces. In a coordinate chart with coordinates $x^\mu = \{t, \theta, \phi, r\}$ making the isotropy and foliation manifest, this metric reads

$$g_{\mu\nu} \underline{dx}^\mu \otimes \underline{dx}^\nu \equiv \underline{dt} \otimes \underline{dt} - a^2(t) \left(\frac{dr \otimes dr}{1 - kr^2} + r^2 (\underline{d\theta} \otimes \underline{d\theta} + \sin^2 \theta \underline{d\phi} \otimes \underline{d\phi}) \right)$$

where $\{\underline{dx}^\mu\}_{\mu=0}^3 = \{\underline{dt}, \underline{d\theta}, \underline{d\phi}, \underline{dr}\}$ are the coordinate on-forms dual to the vector basis $\underline{e}_a = \{\partial_t, \partial_\theta, \partial_\phi, \partial_r\}$, $a(t) > 0$ is the scale factor and $k = 0, -1, 1$ gives the sign of the curvature of the spacelike hypersurfaces (respectively flat, Anti-de Sitter, de Sitter). In what follows, the tensor products are implicit. At every point in our chart, we define an orthonormal basis of one-forms $\underline{\omega}^a = c_\mu^a \underline{dx}^\mu$ such that $g_{\mu\nu} \underline{dx}^\mu \underline{dx}^\nu = \eta_{ab} \underline{\omega}^a \underline{\omega}^b$ where η_{ab} is the Minkowski metric components with signature $(+, -, -, -)$. We can write

$$\begin{aligned} g_{\mu\nu} \underline{dx}^\mu \underline{dx}^\nu &= \underline{dt} \underline{dt} - \left(\frac{a(t) dr}{\sqrt{1 - kr^2}} \right) \left(\frac{a(t) dr}{\sqrt{1 - kr^2}} \right) - (a(t) r \underline{d\theta}) (a(t) r \underline{d\theta}) - (a(t) r \sin \theta \underline{d\phi}) (a(t) r \sin \theta \underline{d\phi}) \\ &= \underline{\omega}^0 \underline{\omega}^0 - \underline{\omega}^1 \underline{\omega}^1 - \underline{\omega}^2 \underline{\omega}^2 - \underline{\omega}^3 \underline{\omega}^3 \end{aligned}$$

where $\{\underline{\omega}^a\}_{a=0}^3 = \{\underline{dt}, a(t) r \underline{d\theta}, a(t) r \sin \theta \underline{d\phi}, \frac{a(t)}{\sqrt{1 - kr^2}} \underline{dr}\}$ is shown to satisfy the orthonormality condition. We note that the resulting choice of basis is unique up to a local Lorentz transformation (which preserves orthonormality).

- (b) To calculate the connection one-forms $\underline{\theta}^a_b$, we use the orthonormal basis found in (a) and Cartan's first structure equation for vanishing torsion to get

$$\begin{aligned} \underline{\theta}^a_b \wedge \underline{\omega}^b &= -\underline{d\omega}^a = \begin{cases} -\partial_\mu(1) \underline{dx}^\mu \wedge \underline{dt} \\ -\partial_\mu(a(t)r) \underline{dx}^\mu \wedge \underline{d\theta} \\ -\partial_\mu(a(t)r \sin \theta) \underline{dx}^\mu \wedge \underline{d\phi} \\ -\partial_\mu\left(\frac{a(t)}{\sqrt{1 - kr^2}}\right) \underline{dx}^\mu \wedge \underline{dr} \end{cases} = \begin{cases} 0 \\ -a'(t)r \underline{dt} \wedge \underline{d\theta} - a(t) \underline{dr} \wedge \underline{d\theta} \\ -a'(t)r \sin \theta \underline{dt} \wedge \underline{d\phi} - a(t) \sin \theta \underline{dr} \wedge \underline{d\phi} - a(t)r \cos \theta \underline{d\theta} \wedge \underline{d\phi} \\ -\frac{a'(t)}{\sqrt{1 - kr^2}} \underline{dt} \wedge \underline{dr} - [\dots] \underline{dr} \wedge \underline{dr} \end{cases} \\ &= \begin{cases} 0 \\ \frac{a'(t)}{a(t)} \underline{\omega}^1 \wedge \underline{\omega}^0 + \frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^1 \wedge \underline{\omega}^3 \\ \frac{a'(t)}{a(t)} \underline{\omega}^2 \wedge \underline{\omega}^0 + \frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^2 \wedge \underline{\omega}^3 + \frac{1}{a(t)r} \cot \theta \underline{\omega}^2 \wedge \underline{\omega}^1 \\ \frac{a'(t)}{a(t)} \underline{\omega}^3 \wedge \underline{\omega}^0 \end{cases} = \begin{cases} \underline{\theta}^0_b \wedge \underline{\omega}^b \\ \underline{\theta}^1_b \wedge \underline{\omega}^b \\ \underline{\theta}^2_b \wedge \underline{\omega}^b \\ \underline{\theta}^3_b \wedge \underline{\omega}^b \end{cases} \end{aligned}$$

Since the \wedge product with $\underline{\omega}^b$ maps $\underline{\omega}^{c \neq b}$ to linearly independent two-forms, we can read the coefficients of $\underline{\omega}^{c \neq b}$ preceding the \wedge product in the previous expressions. We have

$$\begin{cases} \underline{\theta}^0_1 = [\dots] \underline{\omega}^1, & \underline{\theta}^0_2 = [\dots] \underline{\omega}^2, & \underline{\theta}^0_3 = [\dots] \underline{\omega}^3 \\ \underline{\theta}^1_0 = \frac{a'(t)}{a(t)} \underline{\omega}^1 + [\dots] \underline{\omega}^0, & \underline{\theta}^1_2 = [\dots] \underline{\omega}^2, & \underline{\theta}^1_3 = \frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^1 + [\dots] \underline{\omega}^3 \\ \underline{\theta}^2_0 = \frac{a'(t)}{a(t)} \underline{\omega}^2 + [\dots] \underline{\omega}^0, & \underline{\theta}^2_3 = \frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^2 + [\dots] \underline{\omega}^3, & \underline{\theta}^2_1 = \frac{1}{a(t)r} \cot \theta \underline{\omega}^2 + [\dots] \underline{\omega}^1 \\ \underline{\theta}^3_0 = \frac{a'(t)}{a(t)} \underline{\omega}^3 + [\dots] \underline{\omega}^0, & \underline{\theta}^3_1 = [\dots] \underline{\omega}^1, & \underline{\theta}^3_2 = [\dots] \underline{\omega}^2 \end{cases}$$

where $[\dots]$ terms represent the terms mapped to 0 by the \wedge product from which information about $\underline{\theta}^a_b$ was read. From the first line we can also read $\underline{\theta}^0_{1,2,3} = [\dots] \underline{\omega}^{1,2,3}$

To fully determine the one-forms components from these relations, we invoke the relation $\underline{\theta}_{ab} + \underline{\theta}_{ba} = \underline{dg}_{ab}$ where $\underline{\theta}_{ba} = g_{bc} \underline{\theta}^c_a$. Recalling that in our orthonormal basis $g_{ab} = \eta_{ab}$, we get the antisymmetry relation $\underline{\theta}_{ab} + \underline{\theta}_{ba} = 0$, $\forall a$ and we can use it to determine $[\dots]$. Making the relation between $\underline{\theta}^b_a$ and $\underline{\theta}^a_b$ more explicit yields

$$\begin{cases} b \text{ spacelike} \implies \underline{\theta}^b_a = \eta^{bc} \underline{\theta}_{ca} = (-1) \underline{\theta}_{ba} = \underline{\theta}_{ab} \implies \begin{cases} a \text{ spacelike} \implies \underline{\theta}^b_a = -\underline{\theta}^a_b \\ a \text{ timelike} \implies \underline{\theta}^b_a = \underline{\theta}^a_b \end{cases} \\ b \text{ timelike} \implies \underline{\theta}^b_a = \eta^{bc} \underline{\theta}_{ca} = \underline{\theta}_{ba} = -\underline{\theta}_{ab} \implies \begin{cases} a \text{ spacelike} \implies \underline{\theta}^b_a = \underline{\theta}^a_b \\ a \text{ timelike} \implies \underline{\theta}^b_a = -\underline{\theta}^a_b \end{cases} \text{ never happens } (a \neq b) \end{cases}$$

Comparing $\underline{\theta}^a_b$ with $\underline{\theta}^b_a$, we finally see

$$\begin{aligned} [\dots] \underline{\omega}^1 &= \underline{\theta}^0_1 = \underline{\theta}^1_0 = \frac{a'(t)}{a(t)} \underline{\omega}^1 + [\dots] \underline{\omega}^0 \iff \underline{\theta}^1_0 = \frac{a'(t)}{a(t)} \underline{\omega}^1, & \underline{\theta}^0_1 &= \frac{a'(t)}{a(t)} \underline{\omega}^1 \\ [\dots] \underline{\omega}^2 &= \underline{\theta}^0_2 = \underline{\theta}^2_0 = \frac{a'(t)}{a(t)} \underline{\omega}^2 + [\dots] \underline{\omega}^0 \iff \underline{\theta}^2_0 = \frac{a'(t)}{a(t)} \underline{\omega}^2, & \underline{\theta}^0_2 &= \frac{a'(t)}{a(t)} \underline{\omega}^2 \\ [\dots] \underline{\omega}^3 &= \underline{\theta}^0_3 = \underline{\theta}^3_0 = \frac{a'(t)}{a(t)} \underline{\omega}^3 + [\dots] \underline{\omega}^0 \iff \underline{\theta}^3_0 = \frac{a'(t)}{a(t)} \underline{\omega}^3, & \underline{\theta}^0_3 &= \frac{a'(t)}{a(t)} \underline{\omega}^3 \\ [\dots] \underline{\omega}^2 &= \underline{\theta}^1_2 = -\underline{\theta}^2_1 = -\frac{1}{a(t)r} \cot \theta \underline{\omega}^2 - [\dots] \underline{\omega}^1 \iff \underline{\theta}^1_2 = -\frac{1}{a(t)r} \cot \theta \underline{\omega}^2, & \underline{\theta}^2_1 &= \frac{1}{a(t)r} \cot \theta \underline{\omega}^2 \\ [\dots] \underline{\omega}^2 &= \underline{\theta}^3_2 = -\underline{\theta}^2_3 = -\frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^2 - [\dots] \underline{\omega}^3 \iff \underline{\theta}^3_2 = -\frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^2, & \underline{\theta}^2_3 &= \frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^2 \\ [\dots] \underline{\omega}^1 &= \underline{\theta}^3_1 = -\underline{\theta}^1_3 = -\frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^1 - [\dots] \underline{\omega}^3 \iff \underline{\theta}^3_1 = -\frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^1, & \underline{\theta}^1_3 &= \frac{1}{a(t)r} \sqrt{1 - kr^2} \underline{\omega}^1 \end{aligned}$$

- (c) The curvature two-forms are obtained from the connection one-forms calculated above with the relation $\underline{R}^a_b = d\underline{\theta}^a_b + \underline{\theta}^a_c \wedge \underline{\theta}^c_b$. Using $H = a'(t)/a(t)$, $A = \frac{1}{a(t)r} \sqrt{1 - kr^2}$ and $B = \frac{1}{a(t)r} \cot \theta$ the connection one form can be organised as

$$[\underline{\theta}^a_b] = \begin{pmatrix} 0 & H\underline{\omega}^1 & H\underline{\omega}^2 & H\underline{\omega}^3 \\ H\underline{\omega}^1 & 0 & B\underline{\omega}^2 & A\underline{\omega}^1 \\ H\underline{\omega}^2 & -B\underline{\omega}^2 & 0 & A\underline{\omega}^2 \\ H\underline{\omega}^3 & -A\underline{\omega}^1 & -A\underline{\omega}^2 & 0 \end{pmatrix}$$

and the second term in the curvature two-forms can be expressed as a matrix multiplication where the elementwise multiplication is a \wedge . We have

$$\begin{aligned} & [\underline{\theta}^a_c \wedge \underline{\theta}^c_b] \\ &= \begin{pmatrix} 0 & H\underline{\omega}^1 & H\underline{\omega}^2 & H\underline{\omega}^3 \\ H\underline{\omega}^1 & 0 & B\underline{\omega}^2 & A\underline{\omega}^1 \\ H\underline{\omega}^2 & -B\underline{\omega}^2 & 0 & A\underline{\omega}^2 \\ H\underline{\omega}^3 & -A\underline{\omega}^1 & -A\underline{\omega}^2 & 0 \end{pmatrix} \wedge \begin{pmatrix} 0 & H\underline{\omega}^1 & H\underline{\omega}^2 & H\underline{\omega}^3 \\ H\underline{\omega}^1 & 0 & B\underline{\omega}^2 & A\underline{\omega}^1 \\ H\underline{\omega}^2 & -B\underline{\omega}^2 & 0 & A\underline{\omega}^2 \\ H\underline{\omega}^3 & -A\underline{\omega}^1 & -A\underline{\omega}^2 & 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 & H\underline{\omega}^2 \wedge (-B\underline{\omega}^2) + H\underline{\omega}^3 \wedge (-A\underline{\omega}^1) & H\underline{\omega}^1 \wedge (B\underline{\omega}^2) + H\underline{\omega}^3 \wedge (-A\underline{\omega}^2) & 0 \\ A\underline{\omega}^1 \wedge (H\underline{\omega}^3) & 0 & H\underline{\omega}^1 \wedge (H\underline{\omega}^2) + A\underline{\omega}^1 \wedge (-A\underline{\omega}^2) & H\underline{\omega}^1 \wedge (H\underline{\omega}^3) \\ -B\underline{\omega}^2 \wedge (H\underline{\omega}^1) + A\underline{\omega}^2 \wedge (H\underline{\omega}^3) & H\underline{\omega}^2 \wedge (H\underline{\omega}^1) + A\underline{\omega}^2 \wedge (-A\underline{\omega}^1) & 0 & H\underline{\omega}^2 \wedge (H\underline{\omega}^3) - B\underline{\omega}^2 \wedge (A\underline{\omega}^1) \\ 0 & H\underline{\omega}^3 \wedge (H\underline{\omega}^1) & H\underline{\omega}^3 \wedge (H\underline{\omega}^2) - A\underline{\omega}^1 \wedge (B\underline{\omega}^2) & 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 & (HA)\underline{\omega}^1 \wedge \underline{\omega}^3 & (HB)\underline{\omega}^1 \wedge \underline{\omega}^2 - (HA)\underline{\omega}^3 \wedge \underline{\omega}^2 & 0 \\ (HA)\underline{\omega}^1 \wedge \underline{\omega}^3 & 0 & (H^2 - A^2)\underline{\omega}^1 \wedge \underline{\omega}^2 & (H^2)\underline{\omega}^1 \wedge \underline{\omega}^3 \\ (HB)\underline{\omega}^1 \wedge \underline{\omega}^2 - (HA)\underline{\omega}^3 \wedge \underline{\omega}^2 & -(H^2 - A^2)\underline{\omega}^1 \wedge \underline{\omega}^2 & 0 & (H^2)\underline{\omega}^2 \wedge \underline{\omega}^3 - (AB)\underline{\omega}^2 \wedge \underline{\omega}^1 \\ 0 & -(H^2)\underline{\omega}^1 \wedge \underline{\omega}^3 & -((H^2)\underline{\omega}^2 \wedge \underline{\omega}^3 - (AB)\underline{\omega}^2 \wedge \underline{\omega}^1) & 0 \end{pmatrix} \end{aligned}$$

Then, the first term in the curvature two-forms reads

$$\begin{aligned} & [d\underline{\theta}^a_b] = \begin{pmatrix} 0 & H'\underline{dt} \wedge \underline{\omega}^1 + H\underline{d}\underline{\omega}^1 & H'\underline{dt} \wedge \underline{\omega}^2 + H\underline{d}\underline{\omega}^2 & H'\underline{dt} \wedge \underline{\omega}^3 + H\underline{d}\underline{\omega}^3 \\ +[\dots] & 0 & (\partial_r B \underline{dr} + \partial_\theta B \underline{d}\theta + \partial_t B \underline{dt}) \wedge \underline{\omega}^2 + B \underline{d}\underline{\omega}^2 & (\partial_r A \underline{dr} + \partial_t A \underline{dt}) \wedge \underline{\omega}^1 + A \underline{d}\underline{\omega}^1 \\ +[\dots] & -[\dots] & 0 & (\partial_r A \underline{dr} + \partial_t A \underline{dt}) \wedge \underline{\omega}^2 + A \underline{d}\underline{\omega}^2 \\ +[\dots] & -[\dots] & -[\dots] & 0 \end{pmatrix} \\ & \begin{cases} H'\underline{dt} \wedge \underline{\omega}^1 + H\underline{d}\underline{\omega}^1 = H'\underline{\omega}^0 \wedge \underline{\omega}^1 + H^2 \underline{\omega}^0 \wedge \underline{\omega}^1 + (HA)\underline{\omega}^3 \wedge \underline{\omega}^1 \\ H'\underline{dt} \wedge \underline{\omega}^2 + H\underline{d}\underline{\omega}^2 = H'\underline{\omega}^0 \wedge \underline{\omega}^2 + H^2 \underline{\omega}^0 \wedge \underline{\omega}^2 + (HA)\underline{\omega}^3 \wedge \underline{\omega}^2 + (HB)\underline{\omega}^1 \wedge \underline{\omega}^2 \\ H'\underline{dt} \wedge \underline{\omega}^3 + H\underline{d}\underline{\omega}^3 = H'\underline{\omega}^0 \wedge \underline{\omega}^3 + H^2 \underline{\omega}^0 \wedge \underline{\omega}^3 \\ (\partial_r B \underline{dr} + \partial_\theta B \underline{d}\theta + \partial_t B \underline{dt}) \wedge \underline{\omega}^2 + B \underline{d}\underline{\omega}^2 = -(AB)\underline{\omega}^3 \wedge \underline{\omega}^2 - \frac{\csc^2(\theta)}{r^2 a(t)^2} \underline{\omega}^1 \wedge \underline{\omega}^2 - (BH)\underline{\omega}^0 \wedge \underline{\omega}^2 + (BH)\underline{\omega}^0 \wedge \underline{\omega}^2 + (AB)\underline{\omega}^3 \wedge \underline{\omega}^2 + B^2 \underline{\omega}^2 \wedge \underline{\omega}^1 \\ (\partial_r A \underline{dr} + \partial_t A \underline{dt}) \wedge \underline{\omega}^1 + A \underline{d}\underline{\omega}^1 = (-A^2 + \frac{k}{a(t)^2}) \underline{\omega}^3 \wedge \underline{\omega}^1 - (HA)\underline{\omega}^0 \wedge \underline{\omega}^1 + (HA)\underline{\omega}^0 \wedge \underline{\omega}^1 + A^2 \underline{\omega}^3 \wedge \underline{\omega}^1 \\ (\partial_r A \underline{dr} + \partial_t A \underline{dt}) \wedge \underline{\omega}^2 + A \underline{d}\underline{\omega}^2 = (-A^2 + \frac{k}{a(t)^2}) \underline{\omega}^3 \wedge \underline{\omega}^2 - (HA)\underline{\omega}^0 \wedge \underline{\omega}^2 + (HA)\underline{\omega}^0 \wedge \underline{\omega}^2 + A^2 \underline{\omega}^3 \wedge \underline{\omega}^2 + (AB)\underline{\omega}^1 \wedge \underline{\omega}^2 \end{cases} \\ &= \begin{cases} (H' + H^2)\underline{\omega}^0 \wedge \underline{\omega}^1 + (HA)\underline{\omega}^3 \wedge \underline{\omega}^1 \\ (H' + H^2)\underline{\omega}^0 \wedge \underline{\omega}^2 + (HA)\underline{\omega}^3 \wedge \underline{\omega}^2 + (HB)\underline{\omega}^1 \wedge \underline{\omega}^2 \\ (H' + H^2)\underline{\omega}^0 \wedge \underline{\omega}^3 \\ -\left(\frac{\csc^2(\theta)}{r^2 a(t)^2} + B^2\right) \underline{\omega}^1 \wedge \underline{\omega}^2 \\ \frac{k}{a(t)^2} \underline{\omega}^3 \wedge \underline{\omega}^1 \\ \frac{k}{a(t)^2} \underline{\omega}^3 \wedge \underline{\omega}^2 + (AB)\underline{\omega}^1 \wedge \underline{\omega}^2 \end{cases} \end{aligned}$$

Summing the two terms leads to

$$[\underline{R}^a_b] = \begin{pmatrix} 0 & (H' + H^2)\underline{\omega}^0 \wedge \underline{\omega}^1 & (H' + H^2)\underline{\omega}^0 \wedge \underline{\omega}^2 + (2HB)\underline{\omega}^1 \wedge \underline{\omega}^2 & (H' + H^2)\underline{\omega}^0 \wedge \underline{\omega}^3 \\ +[\dots] & 0 & (H^2 - A^2 - B^2 - \frac{\csc^2(\theta)}{r^2 a(t)^2}) \underline{\omega}^1 \wedge \underline{\omega}^2 & (H^2 - \frac{k}{a(t)^2}) \underline{\omega}^1 \wedge \underline{\omega}^3 \\ +[\dots] & -[\dots] & 0 & (H^2 - \frac{k}{a(t)^2}) \underline{\omega}^2 \wedge \underline{\omega}^3 \\ +[\dots] & -[\dots] & -[\dots] & 0 \end{pmatrix}$$

- (d) From each curvature two-form found above, we can extract the components of the Riemann tensor with $\underline{R}^a{}_b = \frac{1}{2}R^a{}_{bcd}\omega^c \wedge \omega^d$. To make these components more transparent we use the new notation $0 \rightarrow \hat{t}, 1 \rightarrow \hat{\theta}, 2 \rightarrow \hat{\phi}, 3 \rightarrow \hat{r}$ and the only non-vanishing components of the Riemann tensor (up to symmetry property of indices) are

$$2R^{\hat{t}}_{\hat{\phi}\hat{t}\hat{\phi}} = 2R^{\hat{t}}_{\hat{\theta}\hat{t}\hat{\theta}} = 2R^{\hat{t}}_{\hat{r}\hat{t}\hat{r}} = H' + H^2, \quad R^{\hat{t}}_{\hat{\phi}\hat{\theta}\hat{\phi}} = HB, \quad 2R^{\hat{\theta}}_{\hat{\phi}\hat{\theta}\hat{\phi}} = H^2 - A^2 - B^2 - \frac{\csc^2(\theta)}{r^2 a(t)^2}, \quad 2R^{\hat{\theta}}_{\hat{r}\hat{\theta}\hat{r}} = 2R^{\hat{\phi}}_{\hat{r}\hat{\phi}\hat{r}} = H^2 - \frac{k}{a(t)^2}.$$

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Thanks to Thomas for help verifying my answers for (b)