```
task r_i. Julin (\mathcal{N})
     wait for [S_i] \leftarrow \mathcal{R}
      for wait for \mathcal{P}_k \in [\mathcal{T}_i] \leftarrow \mathcal{S}_i do
            [\mathtt{hello}] 	o \mathcal{P}_k
            RTT_k = timeit wait for [hello] \leftarrow \mathcal{P}_k with timeou
      N(\mathcal{P}_i) = \{\mathcal{P}_k \mid \text{RTT}_k < \text{timeout}\}
      N^*(\mathcal{P}_i) = \{ \text{first } K \ \mathcal{P}_k \in N(\mathcal{P}_i) \mid \text{RTT}_k < \text{RTT}_{k+1} \}
task \mathcal{P}_o.Leave(\mathcal{S}_i)
      [\mathtt{goodbye}] 	o \mathcal{S}_i
      for \mathcal{P}_k \in N(\mathcal{P}_o \text{ do [goodbye]} \to \mathcal{P}_k
      relay pending chunks
      wait for [goodbye] \leftarrow S_i with timeout
     while timeout do
            [\mathtt{goodbye}] 	o \mathcal{S}_i
            wait for [goodbye] \leftarrow S_i with timeout
task \mathcal{P}_k. EchoHello()
      while True do
            wait for [hello] \leftarrow \mathcal{P}_i
            [\mathtt{hello}] 	o \mathcal{P}_i
            N(\mathcal{P}_k) = (N\mathcal{P}_k) \cup \mathcal{P}_i
task \mathcal{P}_k.ProcessGoodbye()
      while True do
            wait for [goodbye] \leftarrow \mathcal{P}_o
            N(\mathcal{P}_k) = N(\mathcal{P}_k) \setminus \mathcal{P}_o
task \mathcal{P}_k. ShortestPathRouting()
      for all \mathcal{P}_i \in N(\mathcal{P}_k) do
            D[\mathcal{P}_i] = \infty
      D[\mathcal{P}_k] = 0
      for all \mathcal{P}_i \in N^*(\mathcal{P}_k) do
            G[\mathcal{P}_i] = \mathcal{P}_i
      for all \mathcal{P}_i \in N^*(\mathcal{P}_k) do
            [G[\cdot]] \to \mathcal{P}_i
      while True do
            found\_shorter\_route = false
            [D_{\mathcal{P}_n}^*[\cdot], G_{\mathcal{P}_n}^*[\cdot]] \leftarrow \text{from any } \mathcal{P}_n \in N^*(\mathcal{P}_k)
            for all D_{\mathcal{P}_n}^*[\mathcal{P}_i] \in D_{\mathcal{P}_k}^*[\cdot] do
                  alternative_distance_\mathcal{P}_i = D_{\mathcal{P}_n}^*[\mathcal{P}_i] + D[\mathcal{P}_n]
                  if alternative_distance_\mathcal{P}_i < D[\mathcal{P}_i] then
                        found\_shorter\_route = true
                        D[\mathcal{P}_i] = \text{alternative\_distance}
                        G[\mathcal{P}_i] = \mathcal{P}_n
            if found_shorter_route then
                  for all \mathcal{P}_i \in N^*(\mathcal{P}_k) do
```

```
|D| \cdot |\cdot G| \cdot |\cdot| \rightarrow r_i
task \mathcal{P}_k. ChunkFlooding()
      while True do
             wait for [x, \text{chunk}] \leftarrow \mathcal{S}_i or [x, \mathcal{P}_i, \text{chunk}] \leftarrow \mathcal{P}
             if sender = S_i then
                    for all \mathcal{P}_n \in N^*(\mathcal{P}_k) do
                          [x, \mathcal{P}_k, \text{chunk}] \to \mathcal{P}_n
             _{
m else}
                   for all \mathcal{P}_n \in N^*(\mathcal{P}_k) \setminus \mathcal{P}_m do
                          if \mathcal{P}_k \in G_{\mathcal{D}}^* [\mathcal{P}_i] then
                                 [x, \mathcal{P}_i, \text{chunk}] \to \mathcal{P}_n
task \mathcal{P}_k.FreeRidingControl()
      while True do
             for all \mathcal{P}_o \in N(\mathcal{P}_k) do
                   & wait for [x, \mathcal{P}_i, \text{chunk}] \leftarrow \mathcal{P}_o
                        with timeout of L rounds
                       on timeout N(\mathcal{P}_k) = N(\mathcal{P}_k) \setminus \mathcal{P}_o
```