

## Code

```
#include <iostream>
using namespace std;
#define V 9
    int distance[V];
    bool shortest path[V];
    int parent[V];
    int minDistance(int distance[], bool shortest path[]);
    void printShortestPath(int distance[]);
    void findSPT(int graph[V][V], int source);
int Dijkstra ::minDistance(int distance[], bool shortest path[]){
    for(int v=0; v<V; v++) {</pre>
        if (shortest path[v] == false && distance[v] <= min) {</pre>
            min = distance[v];
void Dijkstra ::findSPT(int graph[V][V], int source){
        distance[i] = INT MAX;
        shortest path[i] = false;
    distance[source]=0; //distance of source vertex from itself is zero
        int u = minDistance(distance, shortest_path);
        shortest path[u] = true;
```

```
if ((graph[u][v]>0) && (graph[u][v]+
distance[u]<distance[v]) &&shortest path[v]== false && (distance[u] !=
INT MAX)) {
                distance[v] = distance[u] + graph[u][v];
    printShortestPath(distance);
void Dijkstra :: printShortestPath(int distance[])
        cout << i << " \t\t"<<distance[i]<< endl;</pre>
int main(){
   Dijkstra spt;
    spt.findSPT(graph, 0);
```

## Sample Output