Robot Inspection Checklist (VEXnet or Crystal)



		PETITION YRISE)
Size Inspection		
	Robot fits within starting size restrictions (18" x 18" x 18") does not touch walls or ceiling of the sizing box! Robot should be measured WITH Team ID # Plates installed.	R4
Overall Inspection		
	Team is only competing with ONE robot - they have no spare or replacement robots.	R1
	Robot displays colored VEX Team Identification Number on at least (2) opposing sides.	R19
	Robot does NOT contain any components which will be intentionally detached on the playing-field.	G10
	Robot does NOT contain any components that could entangle or damage the playing-field or other robots.	R3
	Robot does NOT contain any sharp edges or corners.	R3
	Robot on/off switch is accessible & Microcontroller lights are visible without moving or lifting the robot.	R16
	If required by event, Robot Flag Holder is present and adequately holds the flag during normal robot operation.	R20
	When installed the Robot Flag is non-functional and does not extend outside the sizing box.	R20
VEX Parts Inspection		
	ALL Robot components are (or are IDENTICAL to) OFFICIAL VEX Products as sold on VEXrobotics.com	R5 R6 R7
	Robot does not use VEX products not intended for use as a robot component or any VEX packaging.	R5b
	ALL Components on the Robot NOT meeting VRC Inspection Criteria are NON-FUNCTIONAL decorations	R7d
	Any grease is used only in moderation on components that do not contact the field, objects, or other robots.	R7e
	Any non shattering plastic on the robot was cut from a single sheet of 0.070" material not larger than 12"x24".	R7f
	Robot has only (1) VEX EDR Microcontroller (Cortex or PIC)	R9
	Robot utilizes the VEXnet wireless communication system, or VEX 75 MHz Crystals when allowed	R10
	None of the <i>electronics</i> are from the VEXplorer, VEXpro, VEX-RCR, VEX IQ, or VEX Robotics by Hexbug.	R10b
	Total number of Servos and Motors is not more than ten (10).	R11
	Each 2-wire motor is plugged into its own 2-wire port or into a Model 29 motor controller	R11a
	A motor may only be controlled by a single controller port	R11b
	Robot uses a maximum of (1) Y-Cable per each 3-wire Motor Port (cannot "Y" off a 2-wire Motor Port)	R12
	Robot uses (1) VEX 7.2V (Robot) Power Pack as the primary power source.	R13
	If the Robot has a Power Expander, it has a 2nd 7.2V (Robot) Power Pack	R13
	Robot uses a maximum of (1) VEX Power Expander	R13b
	If Using VEXnet, Robot has a charged 9V Backup Battery connected	R13c
	Robot is not controlled by more than (2) VEX hand-held transmitters.	R14
	NO VEX electrical components have been modified from their original state.	R15a
	NO Method of attachment NOT provided by the VEX Design System is used. (Welding, Gluing, etc.)	R15b
	Total number of VEX pneumatic air reservoirs is two (2).	R18
Field Control Check		
	Robot successfully completes the "Field Control Check" Procedure - See Inspection Guidelines	R21
	Robot enters Autonomous mode when prompted - with no driver control for duration of Autonomous	R21
The Hand-held Controller(s) ONLY control the robot when robot is in Driver mode		R21
Р	TC Verification Testing	R15
	illure to pass this test will result in Pass / Fail: Tested By: mediate Event Disqualification	
	Team Initials:	