

# ANNEXURE -A

## SOURCE CODE

```
#include <Wire.h>

#include <OneWire.h>

#include <Wire.h>

#include <LiquidCrystal_I2C.h>

LiquidCrystal_I2C lcd(0x27, 16, 2);

#include <dht.h> // Include library

#define outPin 2 // Defines pin number to which the sensor is connected

dht DHT; // Creates a DHT object

// // Pin Assignments const int voltageSensorPin = A2; //

Voltage sensor input const int currentSensorPin = A3; //

Current sensor input const int relayMotorPin = 4;    //

Relay for motor const int relayFanPin = 3;    // Relay for

fan const int relayBatteryPin = 5; // Relay for battery

charger const int relayChargerPin = 6; // Relay for mobile

charger

// LED Pins const int

ledTemperaturePin = 8; const int

ledBattery50Pin = 9; const int

ledBattery75Pin = 10;

void setup() {

  Serial.begin(9600);
```

```

    pinMode(relayMotorPin, OUTPUT);

    pinMode(relayFanPin, OUTPUT);

    pinMode(relayChargerPin, OUTPUT);

    pinMode(relayBatteryPin, OUTPUT);

    // Define LED pins as outputs

    pinMode(ledBattery50Pin, OUTPUT);

    pinMode(ledBattery75Pin, OUTPUT);

    pinMode(ledTemperaturePin, OUTPUT);

    // Initialize all relays to HIGH (inactive state for active-low relays)

    digitalWrite(relayMotorPin, HIGH); // Motor relay off  digitalWrite(relayFanPin,
HIGH); // Fan relay off  digitalWrite(relayChargerPin, HIGH); // Charger relay
off  digitalWrite(relayBatteryPin, HIGH); // Battery relay off

    // Initialize LED states to LOW (off state)

    digitalWrite(ledBattery50Pin, LOW); digitalWrite(ledBattery75Pin,
LOW); digitalWrite(ledTemperaturePin, LOW);

    lcd.begin(16, 2);

    lcd.backlight(); lcd.setCursor(0,
0); lcd.print("System Ready!");

}

void loop() { float voltageSensorValue = analogRead(voltageSensorPin) *
(5.0 / 1023.0); float voltage = voltageSensorValue * 5.0; float current =
analogRead(currentSensorPin) * (5.0 / 1023.0);

```

```

    int batteryPercentage = 0;  if (voltage >= 10.0)

batteryPercentage = 100;  if (voltage >= 9.0 && voltage <
10.0) batteryPercentage = 75;  if (voltage >= 8.0 && voltage <
9.0) batteryPercentage = 50;  if (voltage >= 7.0 && voltage <
8.0) batteryPercentage = 25;  if (voltage < 7.0)

batteryPercentage = 0;

    int readData = DHT.read11(outPin);
    float t = DHT.temperature; // Read temperature  float

h = DHT.humidity;  // Read humidity

    String data = "a" + String(voltage, 2) + "b" + String(current, 2) + "c" + String(t, 2)+ "d"+
String(batteryPercentage)+"e";

    Serial.println(data);

    lcd.setCursor(0, 0);

    lcd.print("V: ");

    lcd.print(voltage, 2);

    lcd.print(" T:");  lcd.print(t,

1);

    lcd.setCursor(0, 1);

    lcd.print("C: ");

    lcd.print(current, 2);  lcd.print("

B:");

    lcd.print(batteryPercentage);

    lcd.print("%");

    // Motor Control

    if (t >= 29) {

```

```

digitalWrite(relay
MotorPin, HIGH);

// Turn off motor

} if (t < 29) { if (voltage >= 7) {
digitalWrite(relayMotorPin, LOW); // Turn on motor

}

}

// Fan Control if (t > 29) {
digitalWrite(relayFanPin, LOW); // Turn on fan

} if (t <= 29) { digitalWrite(relayFanPin,
HIGH); // Turn off fan

}

// Charger Control if (voltage < 7) {
digitalWrite(relayChargerPin, HIGH); // Turn off charger
digitalWrite(relayBatteryPin, LOW); // Turn on battery charge
digitalWrite(relayMotorPin, HIGH); // Turn on motor

} if (voltage >=
7) { if (t < 29) {
digitalWrite(relayC
hargerPin, LOW);

// Ensure charger
stays on

digitalWrite(relay
MotorPin, LOW);

```

```

// Turn on motor

digitalWrite(relayB
atteryPin, HIGH);

// Turn on battery
charge

    } } if (t > 29) {    digitalWrite(relayChargerPin, HIGH); //
Turn off charger    digitalWrite(relayBatteryPin, HIGH); // Turn
off battery charge

    }

// LED Indicators and Buzzer  if
(voltage < 7) {
digitalWrite(ledBattery50Pin, LOW);
digitalWrite(ledBattery75Pin, LOW);
delay(500);
digitalWrite(ledBattery50Pin, HIGH);
digitalWrite(ledBattery75Pin, HIGH);
delay(500);

    } if (voltage > 7) {    if (voltage < 9) {
digitalWrite(ledBattery50Pin, LOW);
digitalWrite(ledBattery75Pin, HIGH);

        }    if (voltage >= 9) {
digitalWrite(ledBattery50Pin, HIGH);
digitalWrite(ledBattery75Pin, HIGH);

        }
    }
}

```

## Temperature LED Indicator

```
if (t > 29) {      digitalWrite(ledTemperaturePin, HIGH); // High
temperature indicator
} if (t <= 29) {    digitalWrite(ledTemperaturePin, LOW); // Low
temperature indicator
}

delay(1000); // 1-second interval
}
```

# ANNEXURE -B



## PROJECT BUDGET DETAILS

S.NO	COMPONENT NAME	COST (₹)
1	Arduino with Motor driver	2000
2	12V Battery	300
3	DC motors	400
4	LCD display	300
5	Mobile charger	300
6	Adapter and USB cable	300
7	CPU Fan	200
8	Temperature sensor	100
9	Current Sensor	100
10	Voltage sensor	100
11	Node MCU	90
12	Relays	160
13	Buzzer	50
14	Other Components	1000
	<b>Total</b>	<b>₹ 5400</b>

# ANNEXURE -C