Appendix A List of Distributions

Here we list common statistical distributions used throughout the book. The often used indicator symbol $1_{\{.\}}$ and gamma function $\Gamma(\alpha)$ are defined as follows.

Definition A.1 The indicator symbol is defined as

$$1_{\{.\}} = \begin{cases} 1, & \text{if condition in } \{.\} \text{ is true,} \\ 0, & \text{otherwise.} \end{cases}$$
 (A.1)

Definition A.2 The standard gamma function is defined as

$$\Gamma(\alpha) = \int_0^\infty t^{\alpha - 1} e^{-t} dt, \ \alpha > 0.$$
 (A.2)

A.1 Discrete Distributions

A.1.1 Poisson Distribution, Poisson(λ)

A Poisson distribution function is denoted as $Poisson(\lambda)$. The random variable N has a Poisson distribution, denoted $N \sim Poisson(\lambda)$, if its probability mass function is

$$p(k) = \Pr[N = k] = \frac{\lambda^k}{k!} e^{-\lambda}, \ \lambda > 0$$
 (A.3)

for all $k \in \{0, 1, 2, ...\}$. Expectation, variance and variational coefficient of a random variable $N \sim Poisson(\lambda)$ are

$$E[N] = \lambda, \ Var[N] = \lambda, \ Vco[N] = \frac{1}{\sqrt{\lambda}}.$$
 (A.4)

A.1.2 Binomial Distribution, Bin(n, p)

The binomial distribution function is denoted as Bin(n, p). The random variable N has a binomial distribution, denoted $N \sim Bin(n, p)$, if its probability mass function is

$$p(k) = \Pr[N = k] = \binom{n}{k} p^k (1 - p)^{n - k}, \ p \in (0, 1), \ n \in [1, 2, \dots]$$
 (A.5)

for all $k \in \{0, 1, 2, ..., n\}$. Expectation, variance and variational coefficient of a random variable $N \sim Bin(n, p)$ are

$$E[N] = np, Var[N] = np(1-p), Vco[N] = \sqrt{\frac{1-p}{np}}.$$
 (A.6)

Remark A.1 N is the number of successes in n independent trials, where p is the probability of a success in each trial.

A.1.3 Negative Binomial Distribution, NegBin(r, p)

A negative binomial distribution function is denoted as NegBin(r, p). The random variable N has a negative binomial distribution, denoted $N \sim NegBin(r, p)$, if its probability mass function is

$$p(k) = \Pr[N = k] = \binom{r+k-1}{k} p^r (1-p)^k, \ p \in (0,1), \ r \in (0,\infty)$$
 (A.7)

for all $k \in \{0, 1, 2, \ldots\}$. Here, the generalised binomial coefficient is

$$\binom{r+k-1}{k} = \frac{\Gamma(k+r)}{k!\Gamma(r)},\tag{A.8}$$

where $\Gamma(r)$ is the gamma function.

Expectation, variance and variational coefficient of a random variable $N \sim Neg Bin(r, p)$ are

$$E[N] = \frac{r(1-p)}{p}, Var[N] = \frac{r(1-p)}{p^2}, Vco[N] = \frac{1}{\sqrt{r(1-p)}}.$$
 (A.9)

Remark A.2 If r is a positive integer, N is the number of failures in a sequence of independent trials until r successes, where p is the probability of a success in each trial.

A.2 Continuous Distributions

A.2.1 Uniform Distribution, $\mathcal{U}(a,b)$

A uniform distribution function is denoted as $\mathcal{U}(a, b)$. The random variable X has a uniform distribution, denoted $X \sim \mathcal{U}(a, b)$, if its probability density function is

$$f(x) = \frac{1}{b-a}, \ a < b$$
 (A.10)

for $x \in [a, b]$. Expectation, variance and variational coefficient of a random variable $X \sim \mathcal{U}(a, b)$ are

$$E[X] = \frac{a+b}{2}, Var[X] = \frac{(b-a)^2}{12}, Vco[X] = \frac{b-a}{\sqrt{3}(a+b)}.$$
 (A.11)

A.2.2 Normal (Gaussian) Distribution, $\mathcal{N}(\mu, \sigma)$

A normal (Gaussian) distribution function is denoted as $\mathcal{N}(\mu, \sigma)$. The random variable X has a normal distribution, denoted $X \sim \mathcal{N}(\mu, \sigma)$, if its probability density function is

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right), \ \sigma^2 > 0, \ \mu \in \mathbb{R}$$
 (A.12)

for all $x \in \mathbb{R}$. Expectation, variance and variational coefficient of a random variable $X \sim \mathcal{N}(\mu, \sigma)$ are

$$E[X] = \mu, \text{ Var}[X] = \sigma^2, \text{ Vco}[X] = \sigma/\mu. \tag{A.13}$$

A.2.3 Lognormal Distribution, $\mathcal{L}N(\mu, \sigma)$

A lognormal distribution function is denoted as $\mathcal{L}N(\mu, \sigma)$. The random variable X has a lognormal distribution, denoted $X \sim \mathcal{L}N(\mu, \sigma)$, if its probability density function is

$$f(x) = \frac{1}{x\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(\ln(x) - \mu)^2}{2\sigma^2}\right), \ \sigma^2 > 0, \ \mu \in \mathbb{R}$$
 (A.14)

for x>0. Expectation, variance and variational coefficient of a random variable $X\sim\mathcal{LN}(\mu,\sigma)$ are

$$E[X] = e^{\mu + \frac{1}{2}\sigma^2}, Var[X] = e^{2\mu + \sigma^2}(e^{\sigma^2} - 1), Vco[X] = \sqrt{e^{\sigma^2} - 1}.$$
 (A.15)

A.2.4 t Distribution, $\mathcal{T}(v, \mu, \sigma^2)$

A *t* distribution function is denoted as $\mathcal{T}(\nu, \mu, \sigma^2)$. The random variable *X* has a *t* distribution, denoted $X \sim \mathcal{T}(\nu, \mu, \sigma^2)$, if its probability density function is

$$f(x) = \frac{\Gamma((\nu+1)/2)}{\Gamma(\nu/2)} \frac{1}{\sqrt{\nu\pi}} \left(1 + \frac{(x-\mu)^2}{\nu\sigma^2} \right)^{-(\nu+1)/2}$$
(A.16)

for $\sigma^2 > 0$, $\mu \in \mathbb{R}$, $\nu = 1, 2, ...$ and all $x \in \mathbb{R}$. Expectation, variance and variational coefficient of a random variable $X \sim \mathcal{T}(\nu, \mu, \sigma^2)$ are

$$E[X] = \mu \text{ if } \nu > 1,$$

$$Var[X] = \sigma^2 \frac{\nu}{\nu - 2} \text{ if } \nu > 2,$$

$$Vco[X] = \frac{\sigma}{\mu} \sqrt{\frac{\nu}{\nu - 2}} \text{ if } \nu > 2.$$
(A.17)

A.2.5 Gamma Distribution, Gamma(α , β)

A gamma distribution function is denoted as $Gamma(\alpha, \beta)$. The random variable X has a gamma distribution, denoted as $X \sim Gamma(\alpha, \beta)$, if its probability density function is

$$f(x) = \frac{x^{\alpha - 1}}{\Gamma(\alpha)\beta^{\alpha}} \exp(-x/\beta), \ \alpha > 0, \ \beta > 0$$
 (A.18)

for x>0. Expectation, variance and variational coefficient of a random variable $X\sim Gamma(\alpha,\beta)$ are

$$E[X] = \alpha \beta$$
, $Var[X] = \alpha \beta^2$, $Vco[X] = 1/\sqrt{\alpha}$. (A.19)

A.2.6 Weibull Distribution, Weibull (α, β)

A Weibull distribution function is denoted as $Weibull(\alpha, \beta)$. The random variable X has a Weibull distribution, denoted as $X \sim Weibull(\alpha, \beta)$, if its probability density function is

$$f(x) = \frac{\alpha}{\beta^{\alpha}} x^{\alpha - 1} \exp(-(x/\beta)^{\alpha}), \ \alpha > 0, \ \beta > 0$$
 (A.20)

for x > 0. The corresponding distribution function is

$$F(x) = 1 - \exp(-(x/\beta)^{\alpha}), \ \alpha > 0, \ \beta > 0.$$
 (A.21)

Expectation and variance of a random variable $X \sim Weibull(\alpha, \beta)$ are

$$E[X] = \beta \Gamma(1 + 1/\alpha), \ Var[X] = \beta^2 \left(\Gamma(1 + 2/\alpha) - (\Gamma(1 + 1/\alpha))^2 \right).$$

A.2.7 Pareto Distribution (One-Parameter), Pareto (ξ, x_0)

A one-parameter Pareto distribution function is denoted as $Pareto(\xi, x_0)$. The random variable X has a Pareto distribution, denoted as $X \sim Pareto(\xi, x_0)$, if its distribution function is

$$F(x) = 1 - \left(\frac{x}{x_0}\right)^{-\xi}, \quad x \ge x_0,$$
 (A.22)

where $x_0 > 0$ and $\xi > 0$. The support starts at x_0 , which is typically known and not considered as a parameter. Therefore the distribution is referred to as a single parameter Pareto. The corresponding probability density function is

$$f(x) = \frac{\xi}{x_0} \left(\frac{x}{x_0}\right)^{-\xi - 1}.$$
 (A.23)

Expectation, variance and variational coefficient of $X \sim Pareto(\xi, x_0)$ are

$$E[X] = x_0 \frac{\xi}{\xi - 1} \text{ if } \xi > 1,$$

$$Var[X^2] = x_0^2 \frac{\xi}{(\xi - 1)^2 (\xi - 2)} \text{ if } \xi > 2,$$

$$Vco[X] = \frac{1}{\sqrt{\xi(\xi - 2)}} \text{ if } \xi > 2.$$

A.2.8 Pareto Distribution (Two-Parameter), Pareto₂(α , β)

A two-parameter Pareto distribution function is denoted as $Pareto_2(\alpha, \beta)$. The random variable X has a Pareto distribution, denoted as $X \sim Pareto_2(\alpha, \beta)$, if its distribution function is

$$F(x) = 1 - \left(1 + \frac{x}{\beta}\right)^{-\alpha}, \quad x \ge 0,$$
 (A.24)

where $\alpha > 0$ and $\beta > 0$. The corresponding probability density function is

$$f(x) = \frac{\alpha \beta^{\alpha}}{(x+\beta)^{\alpha+1}}.$$
 (A.25)

The moments of a random variable $X \sim Pareto_2(\alpha, \beta)$ are

$$E[X^k] = \frac{\beta^k k!}{\prod_{i=1}^k (\alpha - i)}; \quad \alpha > k.$$

A.2.9 Generalised Pareto Distribution, $GPD(\xi, \beta)$

A GPD distribution function is denoted as $GPD(\xi, \beta)$. The random variable X has a GPD distribution, denoted as $X \sim GPD(\xi, \beta)$, if its distribution function is

$$H_{\xi,\beta}(x) = \begin{cases} 1 - (1 + \xi x/\beta)^{-1/\xi}, & \xi \neq 0, \\ 1 - \exp(-x/\beta), & \xi = 0, \end{cases}$$
(A.26)

where $x \ge 0$ when $\xi \ge 0$ and $0 \le x \le -\beta/\xi$ when $\xi < 0$. The corresponding probability density function is

$$h(x) = \begin{cases} \frac{1}{\beta} (1 + \xi x/\beta)^{-\frac{1}{\xi} - 1}, & \xi \neq 0, \\ \frac{1}{\beta} \exp(-x/\beta), & \xi = 0. \end{cases}$$
 (A.27)

Expectation, variance and variational coefficient of $X \sim GPD(\xi, \beta), \xi \geq 0$, are

$$E[X^{n}] = \frac{\beta^{n} n!}{\prod_{k=1}^{n} (1 - k\xi)}, \ \xi < \frac{1}{n}; \ E[X] = \frac{\beta}{1 - \xi}, \ \xi < 1;$$

$$Var[X^{2}] = \frac{\beta^{2}}{(1 - \xi)^{2} (1 - 2\xi)}, \ Vco[X] = \frac{1}{\sqrt{1 - 2\xi}}, \ \xi < \frac{1}{2}.$$
 (A.28)

A.2.10 Beta Distribution, Beta(α , β)

A beta distribution function is denoted as $Beta(\alpha, \beta)$. The random variable X has a beta distribution, denoted as $X \sim Beta(\alpha, \beta)$, if its probability density function is

$$f(x) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} x^{\alpha - 1} (1 - x)^{\beta - 1}, \quad 0 \le x \le 1,$$
 (A.29)

for $\alpha > 0$ and $\beta > 0$. Expectation, variance and variational coefficient of a random variable $X \sim Beta(\alpha, \beta)$ are

$$E[X] = \frac{\alpha}{\alpha + \beta}, \ Var[X] = \frac{\alpha\beta}{(\alpha + \beta)^2 (1 + \alpha + \beta)}, \ Vco[X] = \sqrt{\frac{\beta}{\alpha(1 + \alpha + \beta)}}.$$

A.2.11 Generalised Inverse Gaussian Distribution, $GIG(\omega, \phi, v)$

A GIG distribution function is denoted as $GIG(\omega, \phi, \nu)$. The random variable X has a GIG distribution, denoted as $X \sim GIG(\omega, \phi, \nu)$, if its probability density function is

$$f(x) = \frac{(\omega/\phi)^{(\nu+1)/2}}{2K_{\nu+1} \left(2\sqrt{\omega\phi}\right)} x^{\nu} e^{-x\omega - x^{-1}\phi}, \quad x > 0,$$
 (A.30)

where $\phi > 0$, $\omega \ge 0$ if $\nu < -1$; $\phi > 0$, $\omega > 0$ if $\nu = -1$; $\phi \ge 0$, $\omega > 0$ if $\nu > -1$; and

$$K_{\nu+1}(z) = \frac{1}{2} \int_0^\infty u^{\nu} e^{-z(u+1/u)/2} du.$$

 $K_{\nu}(z)$ is called a modified Bessel function of the third kind; see for instance Abramowitz and Stegun ([3], p. 375).

The moments of a random variable $X \sim GIG(\omega, \phi, \nu)$ are not available in a closed form through elementary functions but can be expressed in terms of Bessel functions:

$$E[X^{\alpha}] = \left(\frac{\phi}{\omega}\right)^{\alpha/2} \frac{K_{\nu+1+\alpha} \left(2\sqrt{\omega\phi}\right)}{K_{\nu+1} \left(2\sqrt{\omega\phi}\right)}, \quad \alpha \ge 1, \ \phi > 0, \ \omega > 0.$$

Often, using notation $R_{\nu}(z) = K_{\nu+1}(z)/K_{\nu}(z)$, it is written as

$$E[X^{\alpha}] = \left(\frac{\phi}{\omega}\right)^{\alpha/2} \prod_{k=1}^{\alpha} R_{\nu+k} \left(2\sqrt{\omega\phi}\right), \quad \alpha = 1, 2, \dots$$

The mode is easily calculated from $\frac{\partial}{\partial x}x^{\nu}e^{-(\omega x + \phi/x)} = 0$ as

$$mode[X] = \frac{1}{2\omega} \left(\nu + \sqrt{\nu^2 + 4\omega\phi} \right),$$

that differs only slightly from the expected value for large ν , i.e.

$$mode[X] \to E[X]$$
 for $\nu \to \infty$.

A.2.12 d-variate Normal Distribution, $\mathcal{N}_d(\mu, \Sigma)$

A *d*-variate normal distribution function is denoted as $\mathcal{N}_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, where $\boldsymbol{\mu} = (\mu_1, \dots \mu_d)' \in \mathbb{R}^d$ and $\boldsymbol{\Sigma}$ is a positive definite matrix $(d \times d)$. The corresponding probability density function is

$$f(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} \sqrt{\det \mathbf{\Sigma}}} \exp\left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})' \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right), \ \mathbf{x} \in \mathbb{R}^d,$$
 (A.31)

where Σ^{-1} is the inverse of the matrix Σ . Expectations and covariances of a random vector $\mathbf{X} = (X_1, \dots, X_d)' \sim \mathcal{N}_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ are

$$E[X_i] = \mu_i, Cov[X_i, X_j] = \Sigma_{i,j}, i, j = 1, ..., d.$$
 (A.32)

A.2.13 d-variate t-Distribution, $\mathcal{T}_d(v, \mu, \Sigma)$

A *d*-variate *t*-distribution function with ν degrees of freedom is denoted as $\mathcal{T}_d(\nu, \mu, \Sigma)$, where $\nu > 0$, $\mu = (\mu_1, \dots \mu_d)' \in \mathbb{R}^d$ is a location vector and Σ is a positive definite matrix $(d \times d)$. The corresponding probability density function is

$$f(\mathbf{x}) = \frac{\Gamma\left(\frac{\nu+d}{2}\right)}{(\nu\pi)^{d/2}\Gamma\left(\frac{\nu}{2}\right)\sqrt{\det \Sigma}} \left(1 + \frac{(\mathbf{x} - \boldsymbol{\mu})'\Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})}{\nu}\right)^{-\frac{\nu+d}{2}}, \quad (A.33)$$

where $\mathbf{x} \in \mathbb{R}^d$ and $\mathbf{\Sigma}^{-1}$ is the inverse of the matrix $\mathbf{\Sigma}$. Expectations and covariances of a random vector $\mathbf{X} = (X_1, \dots, X_d)' \sim \mathcal{T}_d(\nu, \boldsymbol{\mu}, \boldsymbol{\Sigma})$ are

$$E[X_i] = \mu_i, \text{ if } \nu > 1, i = 1, \dots, d;$$

$$Cov[X_i, X_j] = \nu \sum_{i,j} /(\nu - 2), \text{ if } \nu > 2, i, j = 1, \dots, d.$$
(A.34)

Appendix B Selected Simulation Algorithms

B.1 Simulation from GIG Distribution

To generate realisations of a random variable $X \sim \text{GIG}(\omega, \phi, \nu)$ with $\omega, \phi > 0$, a special algorithm is required because we cannot invert the distribution function in closed form. The following algorithm can be found in Dagpunar [67]:

Algorithm B.1 (Simulation from GIG distribution)

1.
$$\alpha = \sqrt{\omega/\phi}$$
; $\beta = 2\sqrt{\omega\phi}$,
 $m = \frac{1}{\beta} \left(\nu + \sqrt{\nu^2 + \beta^2} \right)$,
 $g(y) = \frac{1}{2}\beta y^3 - y^2 \left(\frac{1}{2}\beta m + \nu + 2 \right) + y \left(\nu m - \frac{\beta}{2} \right) + \frac{1}{2}\beta m$.

2. Set $y_0 = m$,

While $g(y_0) \le 0$ do $y_0 = 2y_0$,

 y_+ : root of g in the interval (m, y_0) ,

 y_{-} : root of g in the interval (0, m).

3.
$$a = (y_{+} - m) \left(\frac{y_{+}}{m}\right)^{\nu/2} \exp\left(-\frac{\beta}{4}\left(y_{+} + \frac{1}{y_{+}} - m - \frac{1}{m}\right)\right),$$

 $b = (y_{-} - m) \left(\frac{y_{-}}{m}\right)^{\nu/2} \exp\left(-\frac{\beta}{4}\left(y_{-} + \frac{1}{y_{-}} - m - \frac{1}{m}\right)\right),$
 $c = -\frac{\beta}{4}\left(m + \frac{1}{m}\right) + \frac{\nu}{2}\ln(m).$

4. Repeat
$$U, V \sim \mathcal{U}(0, 1), Y = m + a\frac{U}{V} + b\frac{1-V}{U},$$

until $Y > 0$ and $-\ln U \ge -\frac{v}{2}\ln Y + \frac{1}{4}\beta\left(Y + \frac{1}{Y}\right) + c,$
Then $X = \frac{Y}{\alpha}$ is $\mathrm{GIG}(\omega, \phi, v)$.

To generate a sequence of *n* realisations from a GIG random variable, step 4 is repeated *n* times.

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B.2 Simulation from α -stable Distribution

To generate realisations of a random variable $X \sim \alpha \text{Stable}(\alpha, \beta, \sigma, \mu)$, defined by (6.56), a special algorithm is required because the density of α -stable distribution is not available in closed form. An elegant and efficient solution was proposed in Chambers, Mallows and Stuck [50]; also see Nolan [176].

Algorithm B.2 (Simulation from α -stable distribution)

- 1. Simulate W from the exponential distribution with mean = 1.
- 2. Simulate *U* from $\mathcal{U}\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$.
- 3. Calculate

$$Z = \begin{cases} S_{\alpha,\beta} \frac{\sin(\alpha(U + B_{\alpha,\beta}))}{(\cos U)^{1/\alpha}} \left(\frac{\cos(U - \alpha(U + B_{\alpha,\beta}))}{W} \right)^{-1 + \frac{1}{\alpha}}, & \alpha \neq 1, \\ \\ \frac{2}{\pi} \left(\left(\frac{\pi}{2} + \beta U \right) \tan U - \beta \ln \left(\frac{\pi W \cos U}{\pi + 2\beta U} \right) \right), & \alpha = 1, \end{cases}$$

where

$$S_{\alpha,\beta} = (1 + \beta^2 \tan^2(\pi \alpha/2))^{\frac{1}{2\alpha}},$$

$$B_{\alpha,\beta} = \frac{1}{\alpha} \arctan(\beta \tan(\pi \alpha/2)).$$

The obtained Z is a sample from α Stable(α , β , 1, 0).

4. Then,

$$X = \begin{cases} \mu + \sigma Z, & \alpha \neq 1, \\ \mu + \sigma Z + \frac{2}{\pi} \beta \sigma \ln \sigma, & \alpha = 1, \end{cases}$$

is a sample from α Stable(α , β , σ , μ).

Note that there are different parameterisations of the α -stable distribution. The algorithm above is for representation (6.56).

Solutions for Selected Problems

Problems of Chapter 2

2.1 The likelihood function for independent data $\mathbf{N} = \{N_1, N_2, \dots, N_M\}$ from $Poisson(\lambda)$ is

$$\ell_{\mathbf{n}}(\lambda) = \prod_{i=1}^{M} e^{-\lambda} \frac{\lambda^{n_i}}{n_i!},$$

$$\ln \ell_{\mathbf{n}}(\lambda) = -\lambda M + \ln \lambda \sum_{i=1}^{M} n_i - \sum_{i=1}^{M} \ln(n_i!).$$

The MLE $\widehat{\varLambda}$ maximising the log-likelihood function $\mbox{ln}\,\ell_N(\lambda)$ is

$$\widehat{\Lambda} = \frac{1}{M} \sum_{i=1}^{M} N_i.$$

Using the properties of the Poisson distribution, $E[N_i] = Var[N_i] = \lambda$, it is easy to get

$$E[\widehat{\Lambda}] = \frac{1}{M} \sum_{i=1}^{M} E[N_i] = \lambda;$$

$$Var[\widehat{\Lambda}] = \frac{1}{M^2} \sum_{i=1}^{M} Var[N_i] = \frac{\lambda}{M}.$$

To estimate the variance of \widehat{A} using a normal approximation, find the information matrix

$$I(\lambda) = -\frac{1}{M} E\left[\frac{\partial^2 \ln \ell_{\mathbf{N}}(\lambda)}{\partial \lambda^2}\right] = \frac{1}{M\lambda^2} E\left[\sum_{i=1}^M N_i\right] = \frac{1}{\lambda}.$$

Thus, using asymptotic normal distribution approximation,

$$\operatorname{Var}[\widehat{\Lambda}] \approx \mathrm{I}^{-1}(\lambda)/M = \lambda/M.$$

In both cases the variance depends on unknown true parameter λ that can be estimated, for a given realisation \mathbf{n} , as $\widehat{\lambda}$.

2.4 Consider

$$L(\mathbf{u}) = u_1 L_1 + \dots + u_J L_J,$$

where $\mathbf{u} \in \mathbb{R}^J$ and set

$$\phi_{\mathbf{u}}(t) = \varrho[tL(\mathbf{u})], \quad t > 0.$$

Then using homogeneity property $\varrho[tL] = t\varrho[L]$,

$$\frac{d\phi_{\mathbf{u}}(t)}{dt} = \varrho[L(u)].$$

From another side

$$\frac{d\phi_{\mathbf{u}}(t)}{dt} = \sum_{j=1}^{J} \frac{\varrho[L(\mathbf{x})]}{\partial x_j} \bigg|_{\mathbf{x}=t\mathbf{u}} u_j = \sum_{j=1}^{J} \frac{\varrho[L(\mathbf{u})]}{\partial u_j} u_j,$$

where to get the last equality we used homogeneity property. Thus

$$\varrho[L(\mathbf{1})] = \sum_{j=1}^{J} \frac{\varrho[L_1 + \dots + L_j + hL_j]}{\partial h} \bigg|_{h=0}$$

completes the proof.

2.5 The sum of risks is gamma distributed:

$$Z_1 + Z_2 + Z_3 \sim Gamma(\alpha_1 + \alpha_2 + \alpha_3, \beta).$$

Thus $VaR_{0.999}[Z_i] = F_G^{-1}(0.999|\alpha_i, \beta)$ and

$$VaR_{0.999}[Z_1 + Z_2 + Z_3] = F_G^{-1}(0.999|\alpha_1 + \alpha_2 + \alpha_3, \beta),$$

where $F_G^{-1}(\cdot|\alpha,\beta)$ is the inverse of the $Gamma(\alpha,\beta)$. Using, for example, MS Excel spreadsheet function GAMMAINV(·), find

$$VaR_{0.999}[Z_1] \approx 5.414$$
, $VaR_{0.999}[Z_2] \approx 6.908$,
 $VaR_{0.999}[Z_3] \approx 8.133$, $VaR_{0.999}[Z_1 + Z_2 + Z_3] \approx 11.229$.

The sum of VaRs is $VaR_{0.999}[Z_1] + VaR_{0.999}[Z_2] + VaR_{0.999}[Z_3] \approx 20.455$ and thus the diversification is $\approx 45\%$.

Problems of Chapter 3

3.1 By definition of the expected shortfall we have

$$\begin{split} \mathrm{E}[Z|Z>L] &= \frac{1}{1-H(L)} \int\limits_{L}^{\infty} z h(z) dz \\ &= \frac{\mathrm{E}[Z]}{1-H(L)} - \frac{1}{1-H(L)} \int\limits_{0}^{L} z h(z) dz. \end{split}$$

Substituting h(z) calculated via characteristic function (3.11) and changing variable $x = t \times L$, we obtain

$$\int_0^L zh(z)dz = \frac{2}{\pi} \int_0^L z \int_0^\infty \text{Re}[\chi(t)]\cos(tz)dtdz$$
$$= \frac{2L}{\pi} \int_0^\infty \text{Re}[\chi(x/L)] \left[\frac{\sin(x)}{x} - \frac{1 - \cos(x)}{x^2}\right] dx.$$

Recognizing that the term involving $\sin(x)/x$ corresponds to H(L), we obtain

$$E[Z|Z > L] = \frac{1}{1 - H(L)} \left[E[Z] - H(L)L + \frac{2L}{\pi} \int_{0}^{\infty} \text{Re}[\chi(x/L)] \frac{1 - \cos x}{x^2} dx \right].$$

Problems of Chapter 4

4.1 The linear estimator $\widehat{\theta}_{tot} = w_1 \widehat{\theta}_1 + \dots + w_K \widehat{\theta}_K$ is unbiased, i.e. $E[\widehat{\theta}_{tot}] = \theta$, if $w_1 + \dots + w_K = 1$ because $E[\widehat{\theta}_k] = \theta$. Minimisation of the variance

$$\operatorname{Var}[\widehat{\theta}_{tot}] = w_1^2 \sigma_1^2 + \dots + w_K^2 \sigma_K^2$$

under the constraint $w_1 + \cdots + w_K$ is equivalent to unconstrained minimisation of the

$$\Psi = \operatorname{Var}[\widehat{\theta}_{tot}] - \lambda(w_1 + \dots + w_K),$$

which is a well-known method of Lagrange multipliers. Optimisation of the above requires solution of the following equations:

$$\frac{\partial \Psi}{\partial w_i} = 2w_i \sigma_i^2 - \lambda = 0, \quad i = 1, \dots, K;$$

$$\frac{\partial \Psi}{\partial \lambda} = -(w_1 + \dots + w_K) = 0.$$

That gives

$$\frac{1}{2}\lambda = \left(\sum_{k=1}^{K} \left(1/\sigma_k^2\right)\right)^{-1}, \quad w_i = \frac{1/\sigma_i^2}{\sum_{k=1}^{K} \left(1/\sigma_k^2\right)}.$$

4.2 Given $\Theta = \theta$, the joint density of the data at $\mathbf{N} = \mathbf{n}$ is

$$f(\mathbf{n}|\theta) \propto \prod_{i=1}^{T} \theta^{n_i} (1-\theta)^{V_i - n_i}.$$

From Bayes's theorem, the posterior density of θ is $\pi(\theta|\mathbf{n}) \propto f(\mathbf{n}|\theta)\pi(\theta)$, where $\pi(\theta)$ is the prior density. Thus

$$\pi(\theta|\mathbf{n}) \propto \theta^{\alpha-1} (1-\theta)^{\beta-1} \prod_{i=1}^{T} \theta^{n_i} (1-\theta)^{V_i - n_i}$$
$$= \theta^{\alpha_T - 1} (1-\theta)^{\beta_T - 1},$$

where

$$\alpha_T = \alpha + \sum_{i=1}^{T} n_i, \quad \beta_T = \beta + \sum_{i=1}^{T} V_i - \sum_{i=1}^{T} n_i.$$

Thus the posterior distribution of Θ is $Beta(\alpha_T, \beta_T)$.

Problems of Chapter 5

5.1 Denote the data above L as $\widetilde{\mathbf{X}} = (\widetilde{X}_1, \widetilde{X}_2, \dots, \widetilde{X}_k)'$. These random variables are independent with a common density $f(x|\xi)/(1-F(L|\xi))$, $x \ge L$, where $f(x|\xi)$ is the density of the Pareto distribution $F(x|\xi) = 1 - (x/a)^{-\xi}$, $x \ge a > 0$. Thus the likelihood function for given data above L is

$$\ell_{\widetilde{\mathbf{x}}}(\xi) = \prod_{i=1}^{k} \frac{f(\widetilde{x}_i|\xi)}{1 - F(L|\xi)}.$$

Substituting the Pareto density

$$f(x|\xi) = \frac{\xi}{a} \left(\frac{x}{a}\right)^{-\xi - 1}$$

gives

$$\ln \ell_{\widetilde{\mathbf{x}}}(\xi) = K\xi \ln(L/a) + K \ln(\xi/a) - (\xi+1) \sum_{i=1}^{K} \ln(\widetilde{x}_i/a).$$

Then, solving $\partial \ln \ell_{\widetilde{\mathbf{x}}}(\xi)/\partial \xi = 0$, we obtain

$$\widehat{\xi}^{\text{MLE}} = \left(-\ln(L/a) + \frac{1}{K} \sum_{i=1}^{K} \ln(\widetilde{x}_i/a)\right)^{-1}.$$

Problems of Chapter 6

6.1 The probability generating function of the negative binomial, NegBin(r, p), is $\psi(t) = (1 - (t - 1)(1 - p)/p)^{-r}$. Then, using formula (6.29), we obtain that the distribution of the maximum loss over one year is

$$F_M(x) = \psi(F(x)) = \left(1 + \frac{1-p}{p}(1-F(x))\right)^{-r},$$

where $F(x) = 1 - \exp(-x/\beta)$ is the severity distribution. The distribution of the maximum loss over m years is simply

$$(F_M(x))^m = \left(1 + \frac{1-p}{p}(1-F(x))\right)^{-r \times m}.$$

Problems of Chapter 7

7.1 Consider random variables U_1 and U_2 from the *t*-copula $C_{\nu,\rho}^{(t)}(u_1,u_2)$. By definition, the lower tail dependence is

$$\lambda_L = \lim_{q \to 0+} \frac{C_{\nu,\rho}^{(t)}(q,q)}{q}.$$

Due to the radial symmetry of the t-copula, the upper tail dependence λ_U is the same as λ_L . Applying L'Hôpital's rule, that is, taking derivatives of the nominator and denominator,

$$\lambda_L = \lim_{q \to 0+} \frac{dC_{v,\rho}^{(t)}(q,q)}{dq} = \lim_{q \to 0+} \{ \Pr[U_2 \le q | U_1 = q] + \Pr[U_1 \le q | U_2 = q] \}.$$

Let $X_1 = F_{\nu}^{(-1)}(U_1)$ and $X_2 = F_{\nu}^{(-1)}(U_2)$, where $F_{\nu}(\cdot)$ is a standard univariate t-distribution with ν degrees of freedom, $\mathcal{T}(\nu, 0, 1)$. Thus $(X_1, X_2)'$ is from a bivariate t-distribution $\mathcal{T}_2(\nu, 0, \Sigma)$, where Σ is a correlation matrix with off-diagonal element ρ . Then, one can calculate the conditional density of X_2 given $X_1 = x_1$:

$$f(x_2|x_1) = \frac{f(x_1,x_2)}{f(x_1)} \propto \left(1 + \frac{\nu+1}{(1-\rho^2)(\nu+x_1^2)} \frac{(x_2-\rho x_1)^2}{\nu+1}\right)^{-(\nu+2)/2}.$$

This can be recognised as a univariate t distribution $\mathcal{T}(\nu+1,\mu,\sigma^2)$ with the mean $\mu=\rho x_1,\,\sigma^2=\frac{(1-\rho^2)(\nu+x_1^2)}{\nu+1}$ and $\nu+1$ degrees of freedom. Thus

$$\Pr[X_2 \le x | X_1 = x] = F_{\nu+1} \left(\frac{(x - x\rho)\sqrt{\nu + 1}}{\sqrt{(1 - \rho^2)(\nu + x^2)}} \right).$$

Finally, using that $\Pr[X_1 \le x | X_2 = x] = \Pr[X_2 \le x | X_1 = x]$ and taking limit $x \to -\infty$ we get

$$\lambda = 2F_{\nu+1} \left(-\sqrt{\frac{(\nu+1)(1-\rho)}{1+\rho}} \right).$$

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