Overall scheme: <TYPE, NAME, VALUE>

<SERVO, SERVO_NAME, SPEED, TIME (in ms)>
Servo name options:
- owl_wing_left
- owl_wing_right

<AXIS, AXIS_NAME, box>
Axis name options, box options (left to right, top to bottom):
- Lr
    - Left right axis
- ladder
    - Ladder axis

<LIGHT, COLOR>