



**DEPARTMENT OF COMPUTER &  
SOFTWARE ENGINEERING  
COLLEGE OF E&ME, NUST, RAWALPINDI**



**Microprocessor and Microcontroller Based Design**

**Lab 05**

**SUBMITTED TO:**  
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**Objectives:**

2-3 lines

**Related Topic/Chapter in theory class:**

None

**Hardware/Software required:**

Hardware: PC

Software Tool: emu8086 v2.57

**Task 1:**

**What do POPF and PUSHF instructions do? Do they affect flags in any way?**

**Solution:**

PUSHF simply pushes the current contents of the Flags register onto the top of the stack. *The top of the stack* is defined as the word at SS:SP, and there is no way to override that with prefixes.

SP is decremented *before* the word goes onto the stack. Remember that SP always points to either an empty stack or else real data. There is a separate pair of instructions, PUSH and POP, for pushing and popping other register data and memory data.

The Flags register is not affected when you *push* the flags, but only when you pop them back with POPF.

PUSHF and POPF are most used in writing interrupt service routines, where you must be able to save and restore the environment, that is, all machine registers, to avoid disrupting machine operations while servicing the interrupt.

**2. Prompt the user for entering a word terminated by enter. Display the characters of the word in reverse order using stack.**

**Solution:**

; You may customize this and other start-up templates.

; The location of this template is c:\emu8086\inc\0\_com\_template.txt

org 100h

.data

str db 13,10, 'Enter your name:\$'

buffer DB 13,10, 08, 09 DUP(?) 13,0ah

space DB 20h

.code

main proc

mov AX, @data

mov ds,ax

mov dx,offset str  
mov ah,9  
int 21h

MOV AH, 0AH  
MOV DX, OFFSET buffer  
INT 21H

mov SI,OFFSET buffer+2  
mov cx,8

L1:

mov bx,[SI]  
push bx  
inc SI  
Loop L1  
mov cx,8

L2:

pop dx

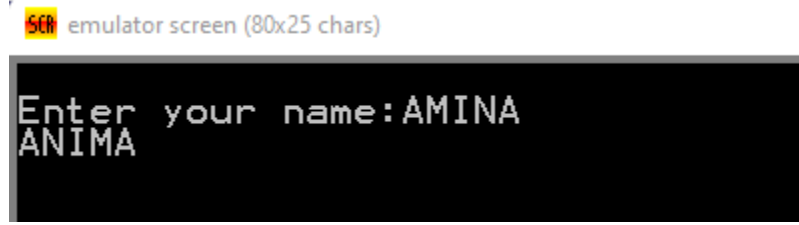
mov ah,2  
int 21h

loop L2  
mov ah,4ch  
int 21h

main endp

ret

### **Output:**



### **Task 3:**

Write an assembly code for calculating the factorial of a number input by user. Attach code and screenshot of console.

### **Solution:**

; You may customize this and other start-up templates;  
; The location of this template is c:\emu8086\inc\0\_com\_template.txt

org 100h

org 100h

.data

str db 13,10, 'Enter your name:\$'

buffer DB 13,10, 08, 09 DUP(?) 13,0ah

space DB 20h

.code

main proc

mov AX, @data

mov ds,ax

mov ax,5

mov cx,ax

dec cx

label:

mul cx

loop label

mov ah,4ch

int 21h

main endp

ret

**Output:**

registers		
	H	L
AX	4C	78
BX	00	00
CX	00	00
DX	00	00
CS	F400	
IP	0204	
SS	0700	
SP	FFF8	
BP	0000	
SI	0000	
DI	0000	

extended value viewer

watch: **AX**

☒ word
 ☐ byte

	H	L
hex:	<b>4C</b>	<b>78</b>
bin:	<b>01001100</b>	<b>01111000</b>
oct:	<b>114</b>	<b>170</b>

decimal 8 bit
 

unsigned:	<b>76</b>	<b>120</b>
signed:	<b>76</b>	<b>120</b>
ascii:	<b>L</b>	<b>x</b>

decimal 16 bit
 

unsigned:	<b>19576</b>
signed:	<b>19576</b>

## **Conclusion:**

The FAR CALL can call a procedure anywhere in the system memory.

The near call pushes the 16 bit offset of the next instruction following the call onto the stack. It copies the 16 bit effective address into the IP register. The CALL instruction transfers the flow of the program to the procedure. The CALL instruction differs from the jump instruction in the sense that a CALL saves a return address on the stack. The RET instruction return control to the instruction that immediately follows the CALL. There exist two types of calls: FAR and NEAR. .