Problem 3: EM Algorithm

1 Main Function

```
1 function [label, model, llh] = emgm(X, init)
2 % Perform EM algorithm for fitting the Gaussian
        mixture model.
3 % X: d x n data matrix
4 % init: k (1 x 1) or label (1 x n, 1<=label(i)<=k
        ) or center (d x k)
5 % Written by Michael Chen (sth4nth@gmail.com).</pre>
```

Implements EM algorithm for Gaussian Mixture Models. **Inputs:**

- X: Data matrix $(d \times n)$ where d = dimensions, n = samples
- init: Flexible initialization:
 - Single number k (number of clusters)
 - Label vector $(1 \times n)$ with assignments
 - Center matrix $(d \times k)$ with initial centers

Outputs:

- label: Final cluster assignments
- model: Learned GMM parameters (μ, Σ, π)
- 11h: Log-likelihood history

2 Initialization

```
6 %% initialization
7 fprintf('EM for Gaussian mixture: running ... \n'
    );
8 R = initialization(X,init);
9 [~,label(1,:)] = max(R,[],2);
10 R = R(:,unique(label));
```

Create initial responsibility matrix R. Convert soft assignments to hard labels: take maximum responsibility to each cluster. Then, remove empty clusters.

3 Algorithm Parameters

```
11
12 tol = 1e-10;
13 maxiter = 500;
14 llh = -inf(1,maxiter);
15 converged = false;
16 t = 1;
```

Set convergence tolerance, maximum number of iterations, and initialize log-likelihood array.

4 Main EM Iteration

```
while ~converged && t < maxiter
t = t+1;
model = maximization(X,R);
[R, llh(t)] = expectation(X,model);</pre>
```

5 Cluster Management

```
21
       [-,label(:)] = max(R,[],2);
22
      u = unique(label);  % non-empty components
      if size(R,2) \sim size(u,2)
24
          R = R(:,u);
                           % remove empty
25
      components
      else
26
           converged = llh(t)-llh(t-1) < tol*abs(llh)
      (t));
28
29
      figure(gcf); clf;
      spread(X,label);
30
      muA = model.mu;
31
      SigmaA = model.Sigma;
32
      wA = model.weight;
33
      k = size(muA, 2);
      % figure(12); clf;
35
      % for i=1:k
36
            mu1 =muA(i,:)
      %
37
            Sigma1=SigmaA(i,:)
      %
38
            w1=wA(i)
39
            xx= mvnrnd(mu1, Sigma1, 1000);
40
            yy= mvnpdf(xx,mu1,Sigma1);
41
             plot3(xx(:,1), xx(:,2), yy, '.b'); hold
42
       on;
      % end
43
44
45
      pause;
47
48 end
49 11h = 11h(2:t);
50 if converged
      fprintf('Converged in %d steps.\n',t-1);
51
52 else
      fprintf('Not converged in %d steps.\n',
      maxiter);
54 end
```

Continue while not converged AND not reach max iteration count.

M-step (Maximization): update model parameters based on current responsibilities.

E-step (Expectation): compute new responsibilities R and log-likelihood history.

Update hard cluster assignments based on maximum responsibilities.

Remove empty clusters from R if any.

Update convergence status based on relative change in log-likelihood and tolerance.

Extract model parameters: number of clusters k, means mu, covariances Sigma, and weights w.

Trim log-likelihood array.

6 Initialization Function

```
56 function R = initialization(X, init)
[d,n] = size(X);
58 if isstruct(init)
                     % initialize with a model
      R = expectation(X,init);
60 elseif length(init) == 1 % random initialization
      k = init;
61
      idx = randsample(n,k);
62
      m = X(:,idx);
      [~,label] = max(bsxfun(@minus,m'*X,dot(m,m,1)
      '/2),[],1);
      [u,~,label] = unique(label);
65
      while k ~= length(u)
66
          idx = randsample(n,k);
67
          m = X(:,idx);
68
          [~,label] = max(bsxfun(@minus,m'*X,dot(m,
      m,1)'/2),[],1);
           [u,~,label] = unique(label);
70
71
      end
      R = full(sparse(1:n,label,1,n,k,n));
72
  elseif size(init,1) == 1 && size(init,2) == n
      label = init;
75
      k = \max(label);
      R = full(sparse(1:n,label,1,n,k,n));
76
77 elseif size(init,1) == d %initialize with only
      centers
      k = size(init,2);
78
      m = init;
79
      [~,label] = max(bsxfun(@minus,m'*X,dot(m,m,1)
      '/2),[],1);
      R = full(sparse(1:n,label,1,n,k,n));
81
82 else
      error('ERROR: init is not valid.');
83
84 end
```

7 E-step Function

Extract data dimensions

- d = number of features
- n = number of data points

6.1 Initialize with a model:

If init is a model struct, use E-step to compute responsibilities R.

6.2 Random initialization:

select k random points as initial centers, then assign points to nearest center using the trick $\arg\max(m'X - \|m\|^2/2) = \arg\min(\|X - m\|^2)$, ensuring consecutive labels (1,2,3...).

Handle empty clusters:

- Keep resampling until all k clusters have members
- Prevents degenerate initialization

Create responsibility matrix R: Using sparse matrix and creates binary $n \times k$ matrix.

6.3 Initialize with labels:

Provides cluster assignments then convert to matrix format.

6.4 Initialize with centers

Provides $d \times k$ center matrix and assign points to nearest center

Extract model parameters

- mu: cluster means
- Sigma: covariance matrices
- w: mixture weights

Compute log probabilities: For each cluster i, compute $\log p(x|\mu_i, \Sigma_i)$

8 Calculate Responsibilities

```
99 logRho = bsxfun(@plus,logRho,log(w));
100 T = logsumexp(logRho,2);
101 llh = sum(T)/n; % loglikelihood
102 logR = bsxfun(@minus,logRho,T);
103 R = exp(logR);
```

9 M-step Function

```
106 function model = maximization(X, R)
107 [d,n] = size(X);
108 k = size(R,2);
110 nk = sum(R,1);
111 w = nk/n;
112 mu = bsxfun(@times, X*R, 1./nk);
113
114 Sigma = zeros(d,d,k);
sqrtR = sqrt(R);
116 for i = 1:k
       Xo = bsxfun(@minus,X,mu(:,i));
       Xo = bsxfun(@times, Xo, sqrtR(:,i)');
118
       Sigma(:,:,i) = Xo*Xo'/nk(i);
119
       Sigma(:,:,i) = Sigma(:,:,i) + eye(d)*(1e-6);
120
121 end
122
123 model.mu = mu;
124 model.Sigma = Sigma;
125 model.weight = w;
```

Add log weights

• $\log(\pi_k \times p(x|\theta_k))$

Logsumexp trick

• $T = \log \sum_k \pi_k \times p(x|\theta_k)$

Compute average log-likelihood.

Calculate responsibilities R(n, k) that represent the posterior probability of point n belonging to cluster k:

Compute effective number of points per cluster.

Update mixture weights and means μ_k .

Update covariance matrices Σ_k :

Assign mu, Sigma, and weight to model struct.

10 Log Gaussian PDF function

Center data by subtracting mean, then compute the Cholesky decomposition of covariance matrix Σ .

Solve U'Q = X efficiently

Compute quadratic term

Compute log normalization constant and final log probability.