

**Concurrent Programming: Languages and Techniques**  
**2024/2025**

# **Erlang Mini-Project**

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## 1. Task 3

Just like task 2, this task is quite similar to the previous ones. But to achieve its objectives it needs to change every loop this time. So, it can send messages back to pause its sender (in the case of the belt and truck) and so it can wait and listen for messages in case it needs to pause after sending each package (in the case of the feeder and belt).