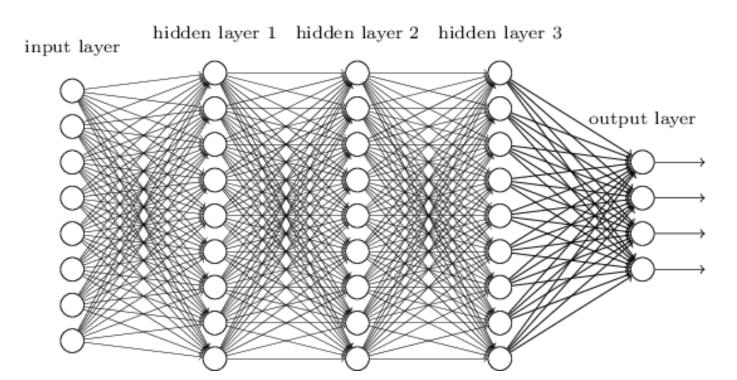


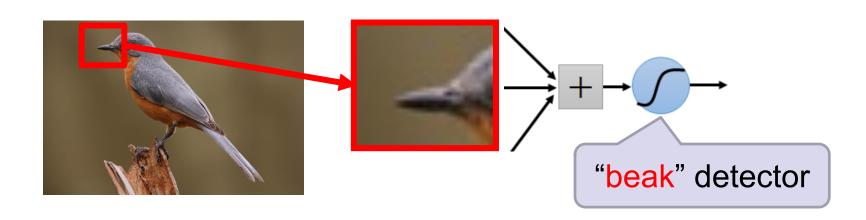
- We know it is good to learn a small model.
- From this fully connected model, do we really need all the edges?
- Can some of these be shared?



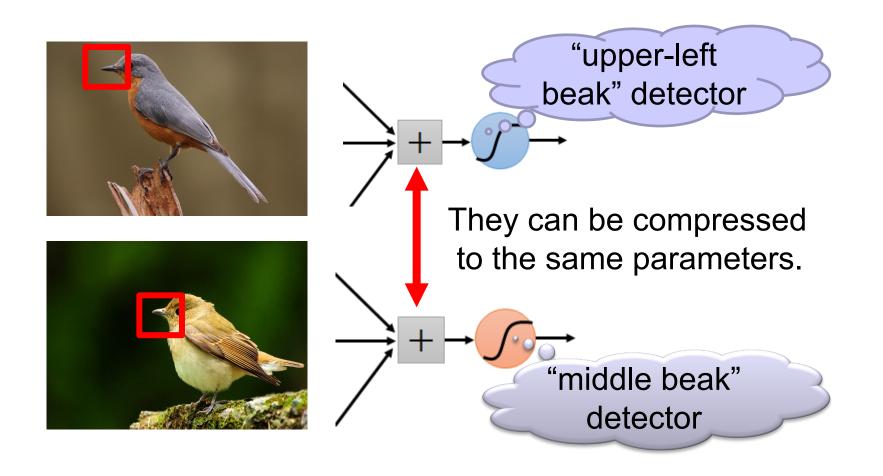
#### Consider learning an image:

 Some patterns are much smaller than the whole image

Can represent a small region with fewer parameters

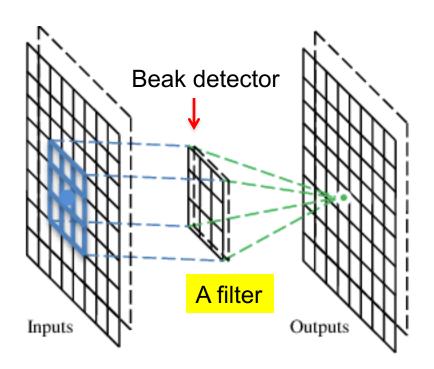


Same pattern appears in different places:
They can be compressed!
What about training a lot of such "small" detectors and each detector must "move around".



#### A convolutional layer

A CNN is a neural network with some convolutional layers (and some other layers). A convolutional layer has a number of filters that does convolutional operation.



1	0	0	0	0	1
0	~	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

## These are the network parameters to be learned.

1	-1	-1
1	1	1
-1	-1	1

Filter 1



Filter 2

: :

Each filter detects a small pattern (3 x 3).

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
1		1	I .		

Dot product 3

-1

6 x 6 image

1 -1 -1 -1 1 -1 -1 -1 1

Filter 1

If stride=2

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

3

-3

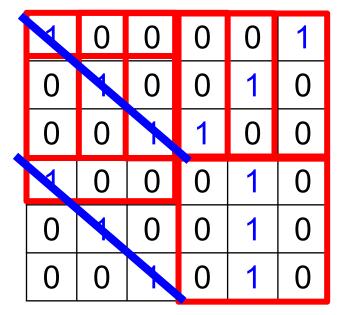
 1
 -1
 -1

 -1
 1
 -1

 -1
 -1
 1

Filter 1

#### stride=1



6 x 6 image



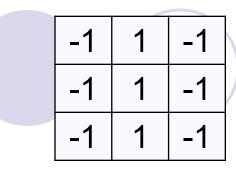




stride=1

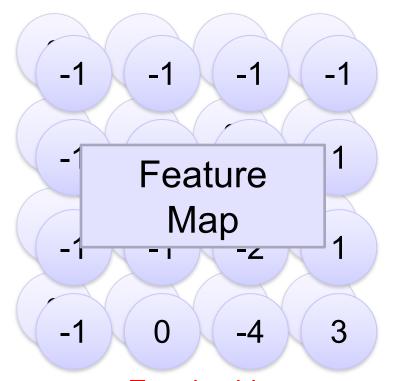
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image



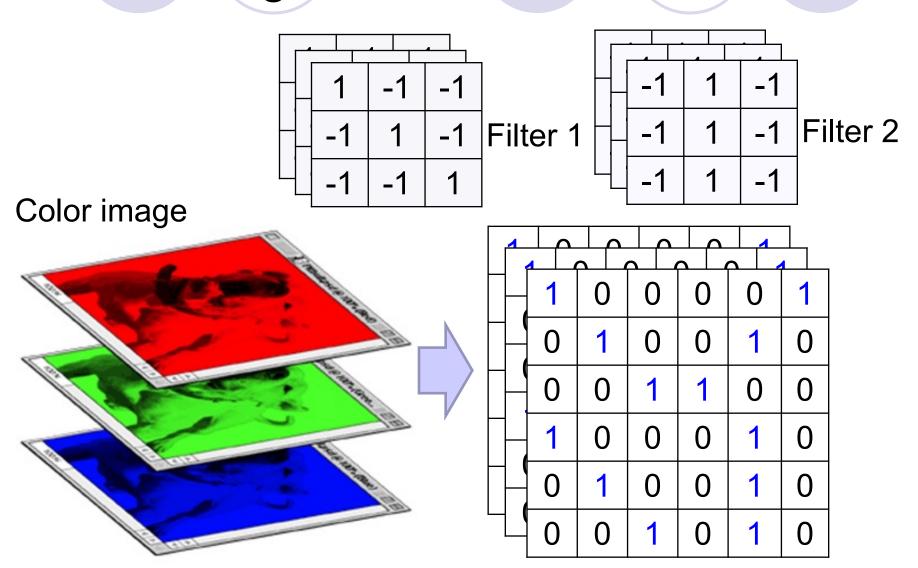
Filter 2

Repeat this for each filter

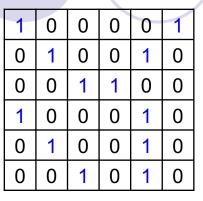


Two 4 x 4 images
Forming 2 x 4 x 4 matrix

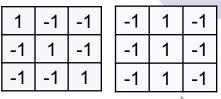
### Color image: RGB 3 channels



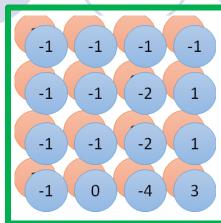
#### Convolution v.s. Fully Connected



image

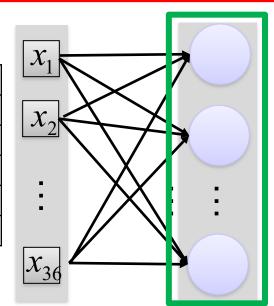


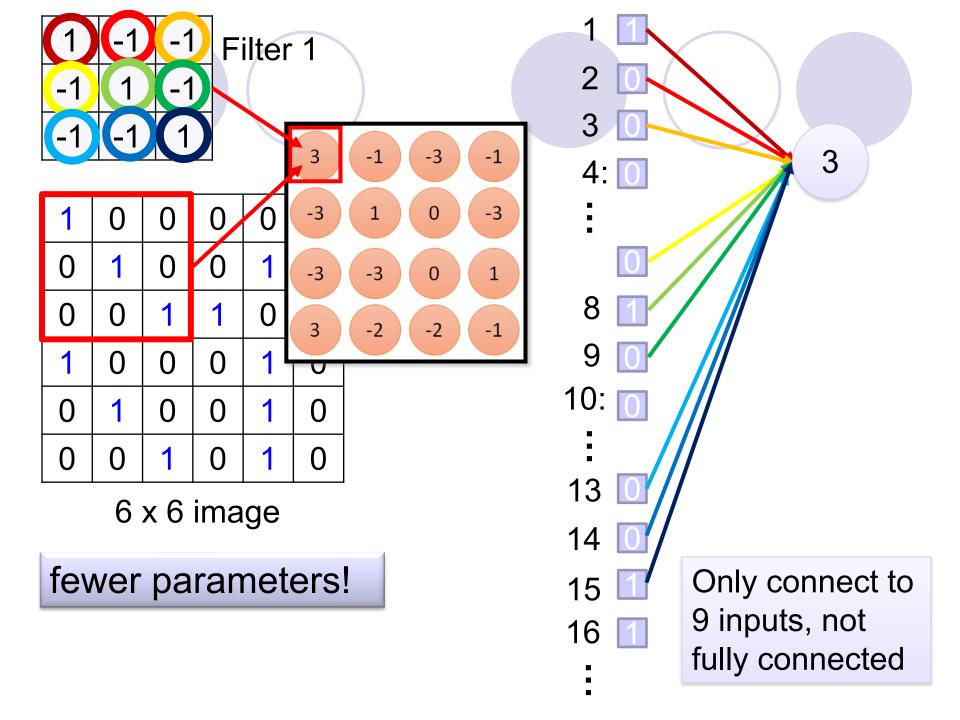
convolution

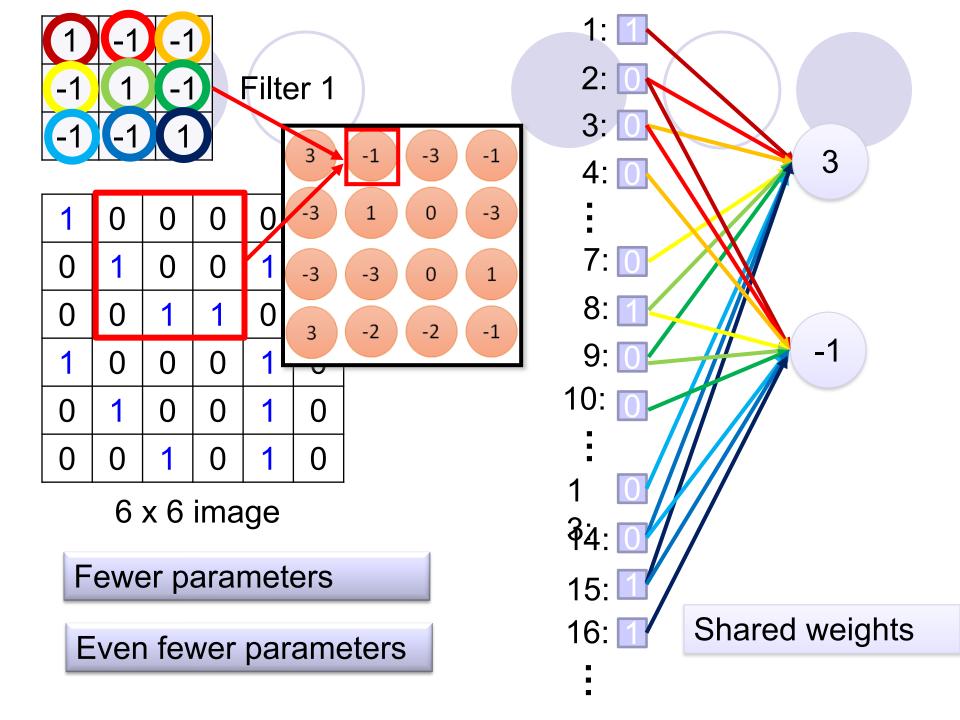


Fully-connected

1	0	0	0	0	1
0	~	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0.
0	~	0	0	1	0:
0	0	1	0	1	0

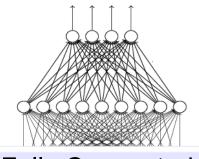




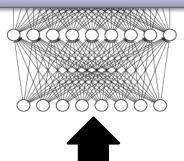


#### The whole CNN

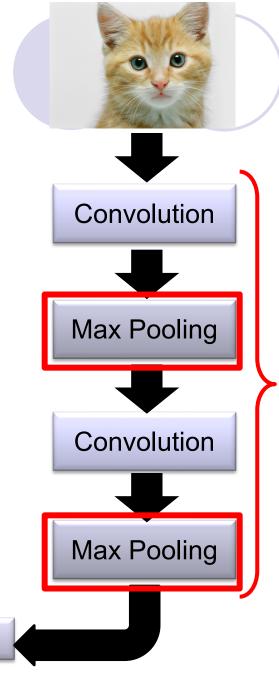
cat dog .....



Fully Connected Feedforward network



Flattened

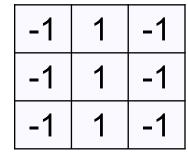


Can repeat many times

### Max Pooling

1	1	1
-1	1	-1
-1	-1	1

Filter 1



Filter 2

3 -1	-3 -1
-3 1	0 -3

-3

-3

-2 -1

-1 -1	-1 -1
-1 -1	-2 1
-1 -1	-2 1
-1 0	-4 3

# Why Pooling

Subsampling pixels will not change the object bird

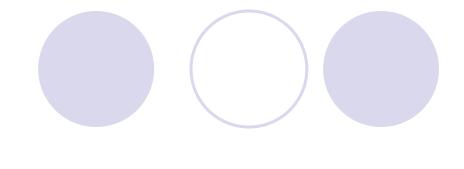


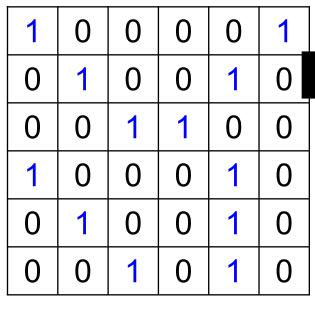
We can subsample the pixels to make image smaller fewer parameters to characterize the image

# A CNN compresses a fully connected network in two ways:

- Reducing number of connections
- Shared weights on the edges
- Max pooling further reduces the complexity

# Max Pooling





Max Pooling

6 x 6 image

New image but smaller

-1 1

0 3

2 x 2 image

Each filter is a channel

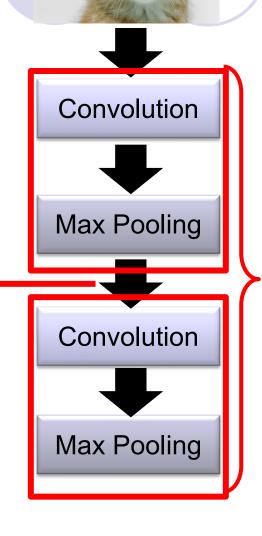
#### The whole CNN

0 3

A new image

Smaller than the original image

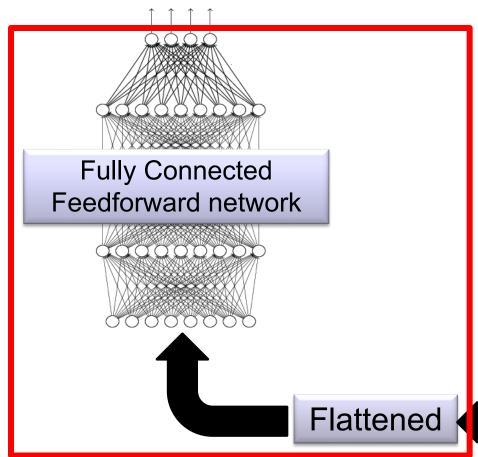
The number of channels is the number of filters

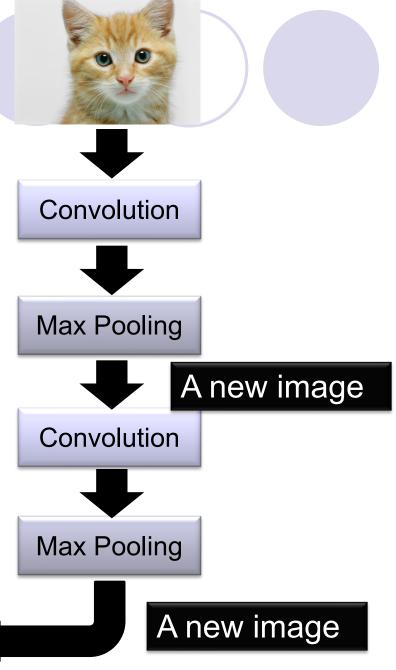


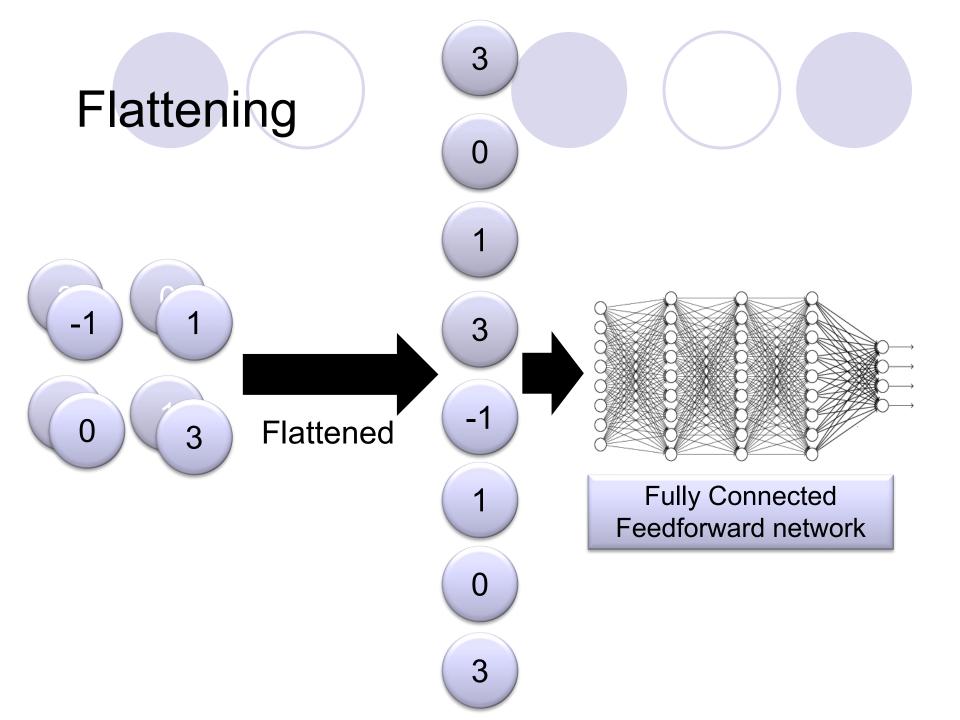
Can repeat many times

#### The whole CNN

cat dog .....

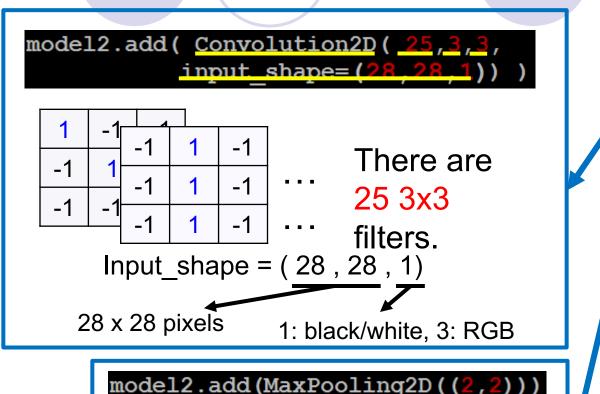


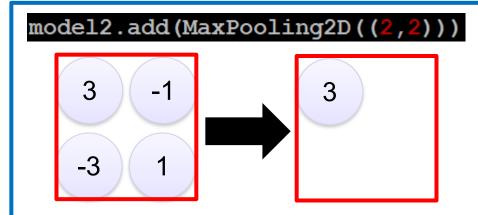


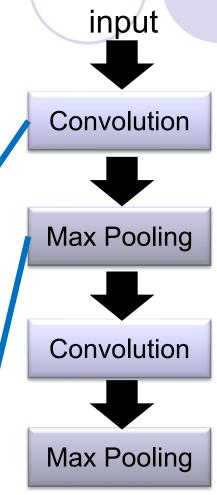


#### **CNN** in Keras

Only modified the *network structure* and *input format (vector -> 3-D tensor)* 

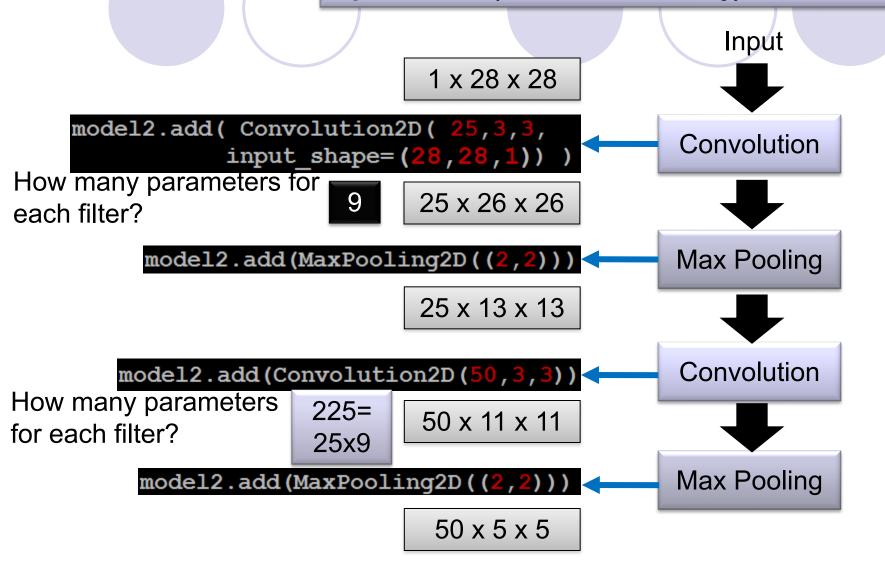






#### **CNN in Keras**

Only modified the *network structure* and *input format (vector -> 3-D array)* 



#### CNN in Keras

Only modified the *network structure* and *input format (vector -> 3-D array)* 

