

s · x1

c + x2

2.0

3.0

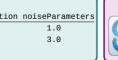
Observable1

Observable2

Condition table	Observable table
conditionId p1 p2	observableId observableFormula noiseDistribut

1.0

1.0



1.0

3.0



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ĺ	Measurement table						
l	observableId	simulationCo	nditionId	time	measurement		

Condition1

Condition2

Condition1

Condition2

Observable1

Observable2

1.0 1.0

5.0 4.0

П	Parameter table						
	parameterId	estimate	nominalValue				
	Parameter1	1					
	Parameter2	0	3.0				

normal

laplace