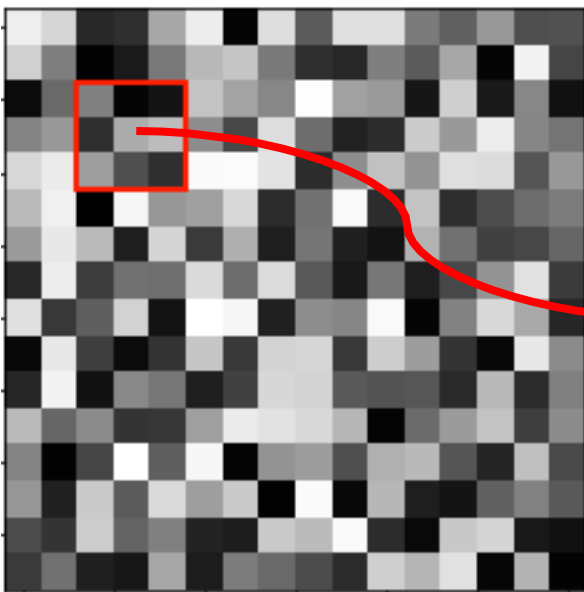


3x3 slidingwindow



512x3x3 feature map



3x3 conv

Output 512

1x1conv
Object

Output 9x2

Output 9x4

1x1conv
Regre.

Loss:

$$\frac{1}{N_{cls}} \sum_i L_{cls}(p_i, p_i^*)$$

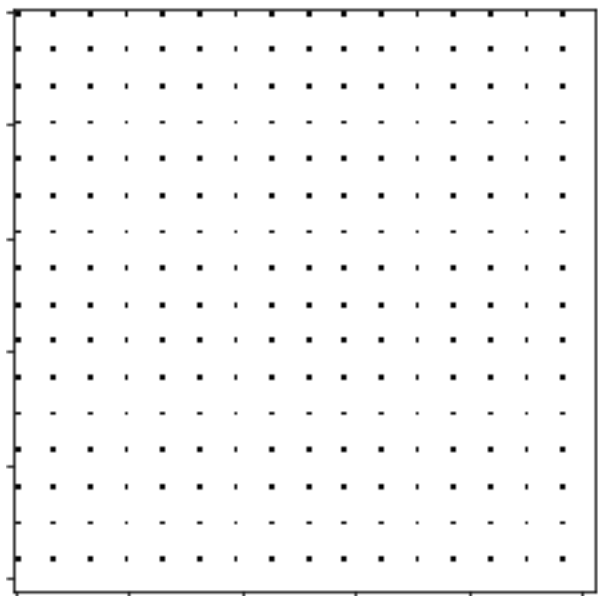
16x16x9
proposals

Proposal:
Objectscore
Boundary box coord

Loss:

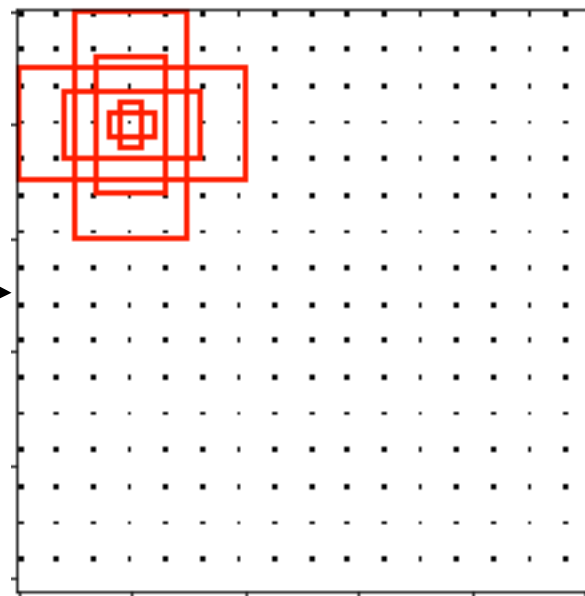
$$\lambda \frac{1}{N_{reg}} \sum_i p_i^* L_{reg}(t_i, t_i^*)$$

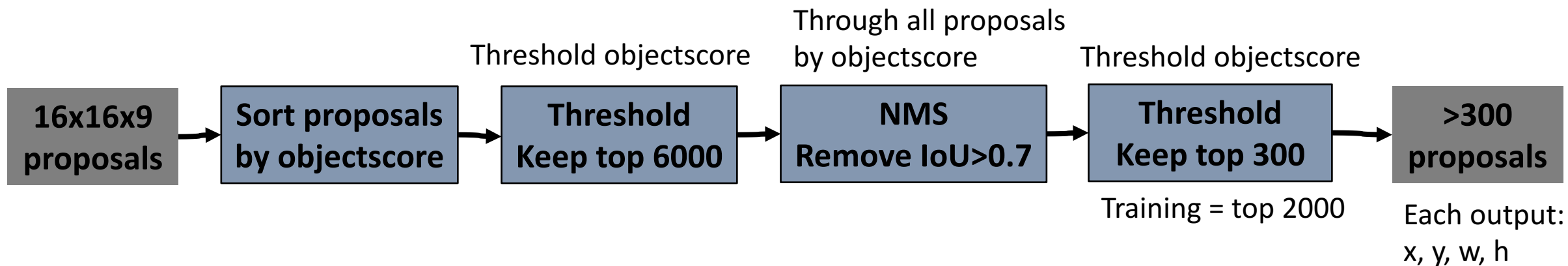
Anchor centers in image

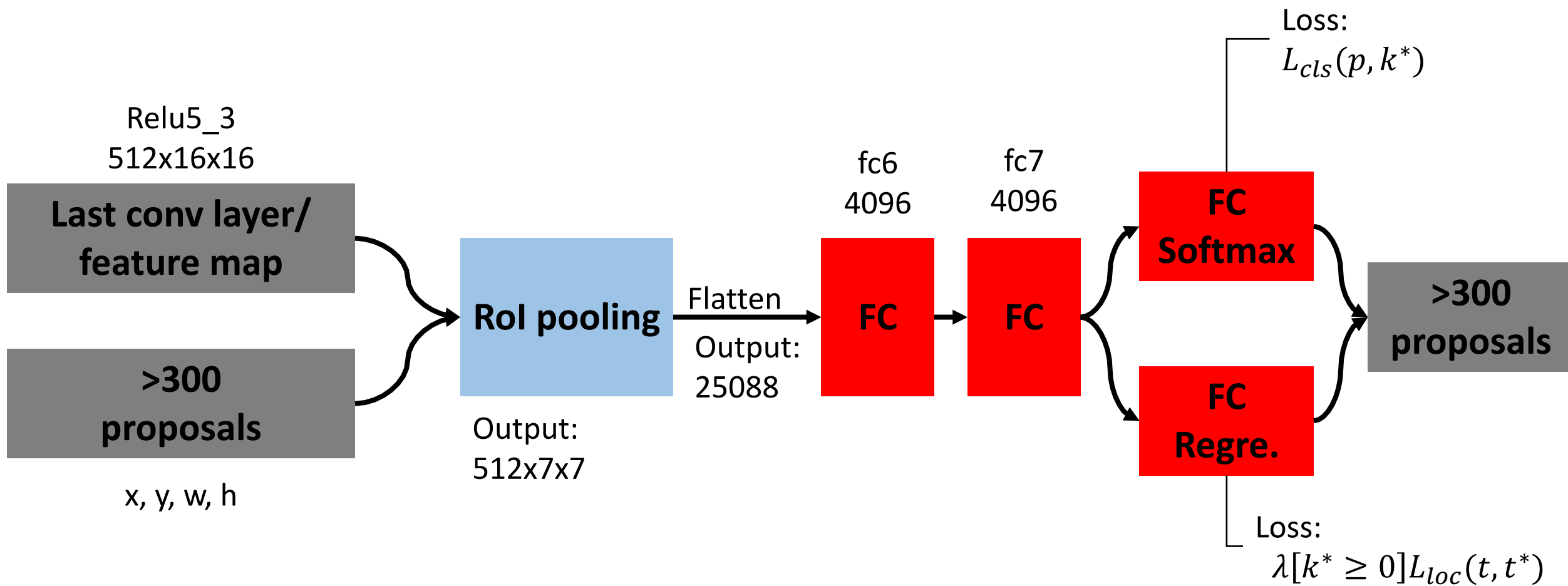


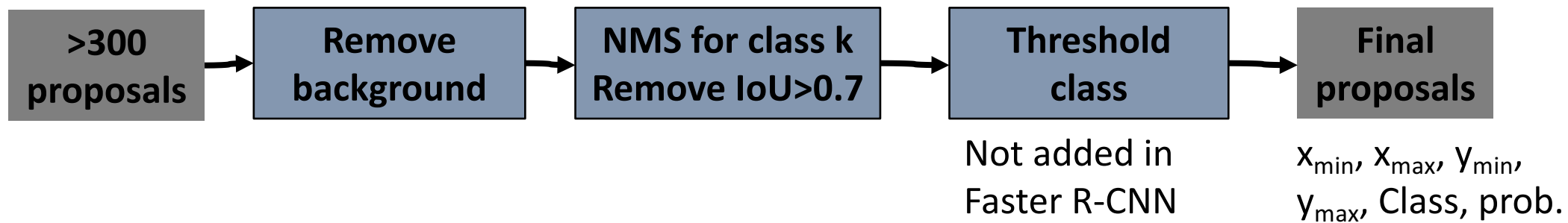
Each anchor=
3 scales
Ex. 10, 30, 50
3 aspect ratios
Ex 1:1, 1:2, 2:1

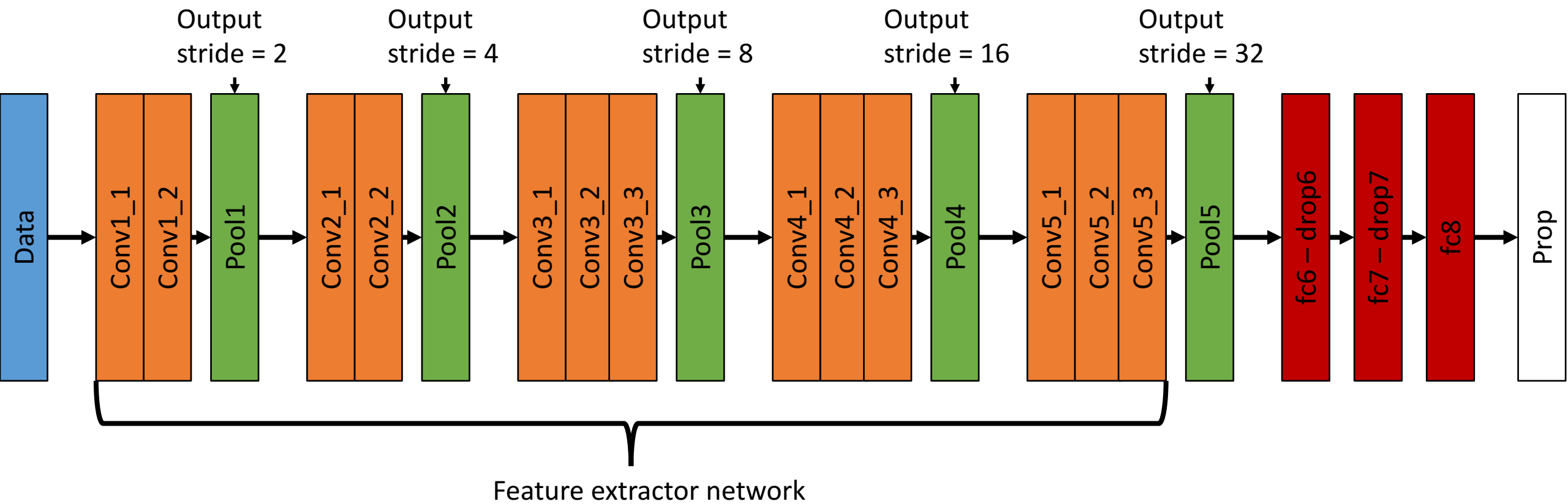
Anchors in image for 1 center

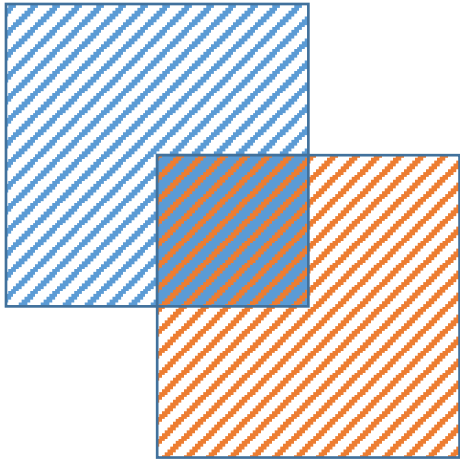




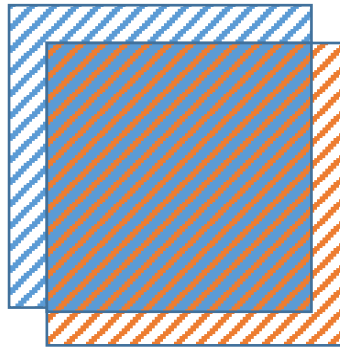




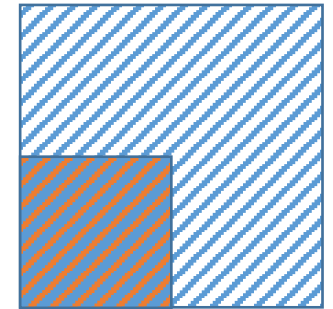




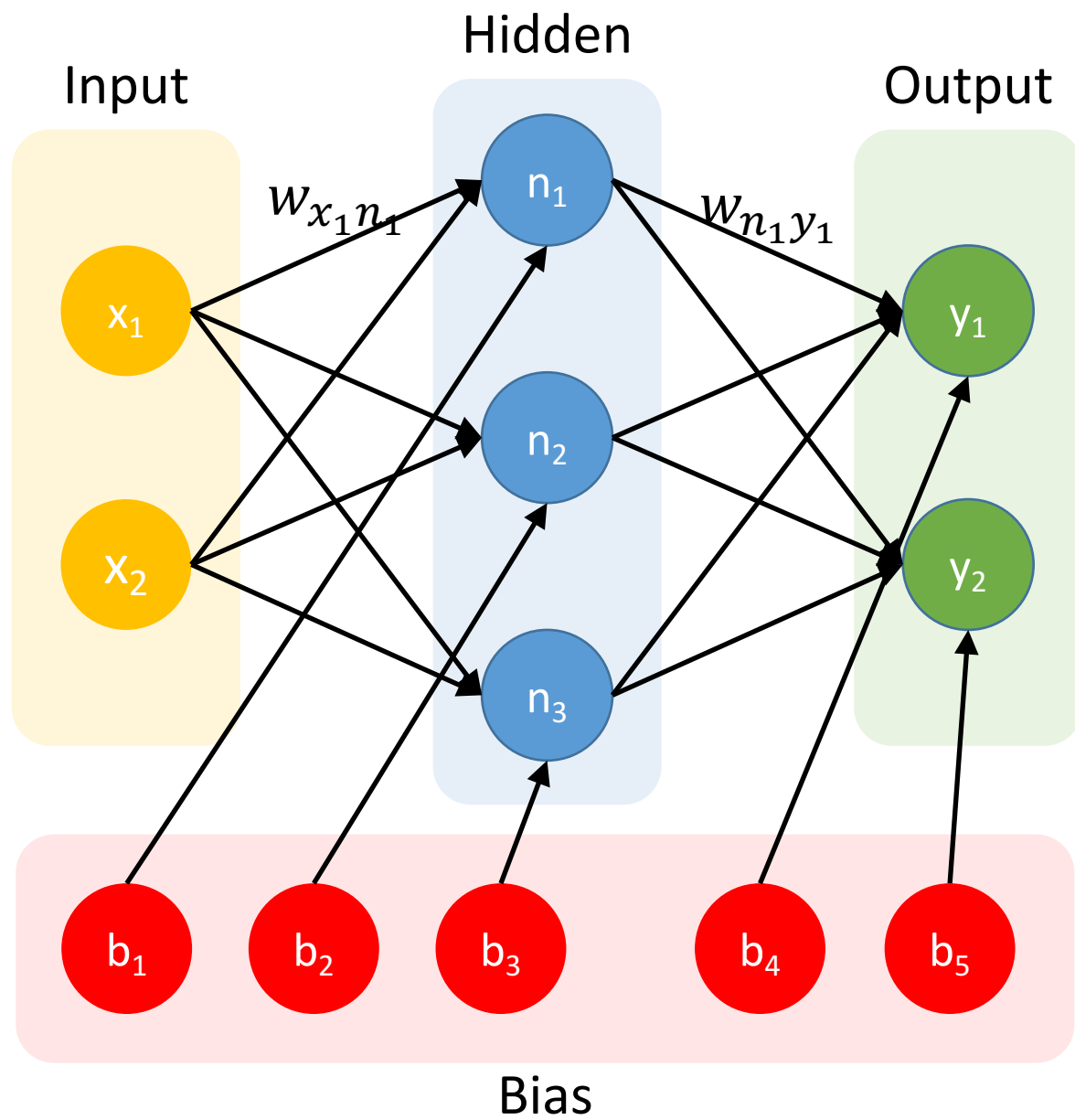
IoU = 0.1429

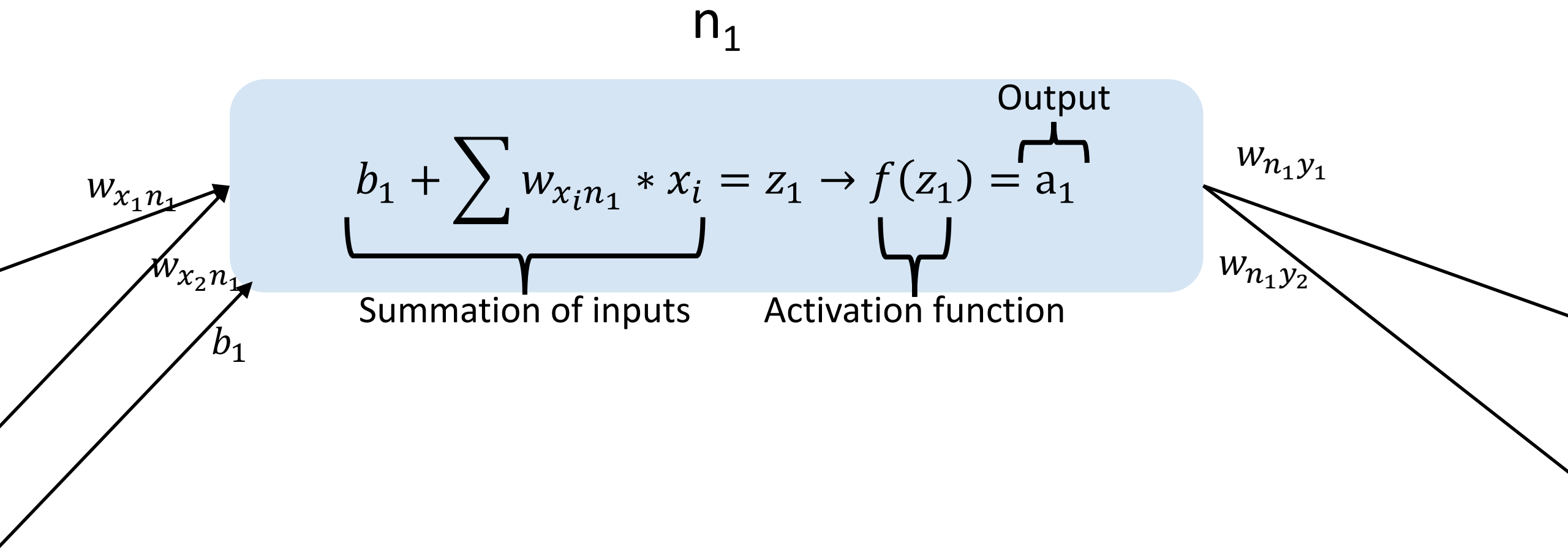


IoU = 0.6203



IoU = 0.2500





8	8	6	1
7	5	4	9
12	0	4	16
4	20	2	10

Max pooling

8	9
20	16

Avg. pooling

7	5
9	8

