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Title of contribution: Evolving Robot Gaits in Hardware: the Hyperneat Generative Encoding  
via Parameter Optimization

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and Hod Lipson

For the purpose of the publication of the above article in the book tentatively entitled *Advances in Artificial Life, ECAL 2011: Proceedings of the Eleventh European Conference on the Synthesis and Simulation of Living Systems*, edited by Tom Lenaerts, Mario Giacobini, Hugues Bersini, Paul Bourguine, Marco Dorigo and René Doursat, I do

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