

# EULER'S METHOD FOR ODEs

FALL SEMESTER 2025

[https://www.phys.uconn.edu/~rozman/Courses/P2200\\_25F/](https://www.phys.uconn.edu/~rozman/Courses/P2200_25F/)

Last modified: September 29, 2025

## Introduction

We are interested in the numerical solution of the following initial value problem (IVP) for an ordinary differential equation:

$$\frac{dy}{dt} = f(t, y), \quad a \leq t \leq b, \quad y(a) = y_1. \quad (1)$$

The idea is to start from  $t = a$  (since we know  $y(a)$ ), increment  $t$  by sufficiently small integration step  $h$ , and use Eq. (1) to determine  $y(t + h)$ . The process is then repeated until we reach  $t = b$ .

We denote the value of independent variable at the  $i$ th integration step by  $t_{i+1}$ ,  $i = 1, 2, \dots$ ,  $t_1 = a$ ; the computed solution at the  $i$ th step by  $y_{i+1}$ ,

$$y_{i+1} \equiv y(t_{i+1}), \quad i = 1, \dots, n-1; \quad (2)$$

the value of the right hand side of Eq. (1) at the  $i$ th integration step by  $f_{i+1}$ ,

$$f_{i+1} \equiv f(t_{i+1}, y_{i+1}). \quad (3)$$

The step size  $h$  (assumed to be a constant for the sake of simplicity) is:

$$h = t_i - t_{i-1} = \frac{b-a}{n-1}. \quad (4)$$

Here  $n-1$  is the total number of integration steps (corresponding to  $n$  function evaluations of the right hand side of Eq. (1)).

The error that is induced at every time-step,  $\epsilon_i$ , is referred to as the *local truncation error* (LTE) of the method. The local truncation error is different from the *global error*  $g_n$ , which is defined as the absolute value of the difference between the true solution and the computed solution,

$$g_n = |y_{\text{exact}}(t_n) - y_n|. \quad (5)$$

In most cases, we do not know the exact solution and hence cannot evaluate the global error. However, it is reasonable to assume that the global error at the  $n$ th time step is  $n$  times the LTE. Since  $h$  is proportional to  $\frac{1}{n}$  (i.e.  $n \sim \frac{1}{h}$  for  $n \gg 1$ ),  $g_n$  should be proportional to  $\frac{\epsilon}{h}$ . A method with LTE  $\epsilon \sim h^{k+1}$  is said to be of  $k$ th order. Therefore, for a  $k$ th order method, the global error scales as  $h^k$ .

## Euler's method

The Taylor series expansion of  $y(t_{j+1})$  about  $t_j$ , up to the  $h^2$  term is as following,

$$y(t_{j+1}) = y(t_j + h) = y(t_j) + h \left. \frac{dy}{dt} \right|_{t_j} + \frac{h^2}{2} \left. \frac{d^2y}{dt^2} \right|_{t_j} + O(h^3). \quad (6)$$

Using Eq. (1) for  $\frac{dy}{dt}$ ,

$$y(t_{j+1}) = y(t_j) + h f(t_j, y_j) + \alpha h^2 + O(h^3), \quad (7)$$

or

$$y_{j+1} = y_j + h f_j + \alpha h^2 + O(h^3), \quad (8)$$

where  $\alpha$  is an unknown constant.

Ignoring the quadratic in  $h$  and higher order terms, we obtain the expression for Euler's integration step:

$$y_{j+1} = y_j + h f_j. \quad (9)$$

In addition to deriving Eq. (9), we learned that the leading in  $h$  error term dropped in Eq. (9) is quadratic in  $h$ , therefore Euler's method is a first order method.

## Richardson extrapolation

Based on our knowledge that the local truncation error for the Euler's method is  $\alpha h^2$ , let's use Richardson extrapolation to construct an integrator with a smaller truncation error than  $O(h^2)$ .

The local error of Euler's method of the step  $h$  is

$$y_{exact}(t+h) - \text{Euler}_h(t+h) = \alpha h^2. \quad (10)$$

The local error of Euler's method of two steps of  $h/2$  is twice as small:

$$y_{exact}(t+h) - \text{Euler}_{h/2}(t+h) = 2\alpha(h/2)^2 = \alpha \frac{h^2}{2}. \quad (11)$$

Combining Eq. (10) and Eq. (11), we can eliminate the leading error term, obtaining

$$y_{\text{exact}}(t+h) - 2\text{Euler}_{h/2}(t+h) + \text{Euler}_h(t+h) = O(h^3). \quad (12)$$

Therefore the integration method

$$y(t+h) = 2\text{Euler}_{h/2}(t+h) - \text{Euler}_h(t+h) \quad (13)$$

has the local truncation error  $O(h^3)$ .

Explicitly,

$$y_{j+1} = y_j + h f(t_j, y_j), \quad (14)$$

$$y_{j+1/2} = y_j + \frac{h}{2} f(t_j, y_j), \quad (15)$$

$$\begin{aligned} y_{j+1/2+1/2} &= y_{j+1/2} + \frac{h}{2} f(t_{j+1/2}, y_{j+1/2}) \\ &= y_j + \frac{h}{2} f(t_j, y_j) + \frac{h}{2} f\left(t_j + h/2, y_j + \frac{h}{2} f(t_j, y_j)\right), \end{aligned} \quad (16)$$

The method that we obtained is called *midpoint method*:

$$y_{j+1} = 2y_{j+1/2+1/2} - y_{j+1} = y_j + h f(t_j + h/2, y_j + h/2 f_j). \quad (17)$$