Pierre JOYFT

Professional experience

2022 RESEARCH ENGINEER (fixed-term contract), *Institut national de recherche pour l'agriculture,* March-August *l'alimentation et l'environnement (INRAE)*, Unité Technologies et systèmes d'information pour

les agrosystèmes (TSCF), Clermont-Ferrand, France

The objective of this mission was to study two approaches for coupling a robotic manipulator arm with a

mobile wheel base.

2021 INTERNSHIP, INRAE, Unité TSCF, Clermont-Ferrand, France

March-August Internship carried out in the ROMEA team of the TSCF research unit. The goal of this internship was the study of a control command coupling a manipulator robot arm with a mobile wheel base.

2019 INTERNSHIP, *Institut National de la Recherche Agronomique*, Laboratoire de Génie et Micro-January-May biologie des Procédés Alimentaires, AgroParisTech's campus, Thiverval-Grignon, France

Internship realized within the mixed research unit GMPA. The objective of this training course was the development of an apparatus allowing the follow-up of samples in a cooking tank, by near infrared and visible spectrometry.

Education

2019-2021 MASTER of Science, Advanced Systems and Robotics, Sorbonne University, Faculty of

Science & Engineering, Paris, France

2014-2019 BACHELOR of Sciences, Mechanics, Sorbonne University, Department of Mechanical Engi-

neering, Paris, France

Languages

French Native language English Upper Intermediate

Skills

Softwares Solidworks

FreeCAD Office Suite

Git

Systems ROS

Linux

Languages C++

Python/object oriented

LATΕX

Matlab / Octave Fortran 90

Support Universal Robots

3D printer Arduino Raspberry pi