## Experiment - 5

Aim-Calculation of Jacobian and bus voltage using NR method.

Software- Matlab2023a

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Code - clc
clear all
% The Y_bus matrix is
ybus = [20-50j -10+20j -10+30j;
-10+20j 26-52j -16+32j;
-10+30j -16+32j 26-62j];
g=real(ybus);b=imag(ybus);
p=[0; -2.556; -1.102];
q=[0; -1.386; -0.452];
mv_initial=[1.05;1;1];
mv=mv_initial;
th=[0;0;0];
nbus=length(p);
del=1;indx=0;
% The Newton-Raphson iterations starts here
while del>1e-6
% Power Calculation
for i=1:nbus
temp=0;
for k=1:nbus
\label{eq:temp-temp-mv} \footnotesize \texttt{temp-temp+mv(i)*mv(k)*(g(i,k)-j*b(i,k))*exp(j*(th(i)-th(k)));}
pcal(i)=real(temp);qcal(i)=imag(temp);
end
% The mismatches
delp=p-pcal';
delq=q-qcal';
% The Jacobian matrix
%J11 calculation
for i=1:(nbus-1)
ii=i+1;
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for k=1:(nbus-1)
kk=k+1;
j11(i,k)=mv(ii)*mv(kk)*(g(ii,kk)*sin(th(ii)-th(kk))-b(ii,kk)*cos(th(ii)-th(kk)));\\
j11(i,i)=-qcal(ii)-b(ii,ii)*mv(ii)^2;
%J21 calculation
for i=1:(nbus-1)
ii=i+1;
for k=1:(nbus-1)
kk=k+1;
j21(i,k) = -mv(ii) *mv(kk) * (g(ii,kk) * cos(th(ii) - th(kk)) - b(ii,kk) * sin(th(ii) - th(kk)));
j21(i,i)=pcal(ii)-g(ii,ii)*mv(ii)^2;
end
%J12 Calculation
for i=1:(nbus-1)
ii=i+1;
for k=1:(nbus-1)
kk=k+1;
j12(i,k)=mv(ii)*(g(ii,kk)*cos(th(ii)-th(kk))+b(ii,kk)*sin(th(ii)-th(kk)));
end
j12(i,i)=pcal(i+1)/mv(i+1)+g(i+1,i+1)*mv(i+1);
% J22 Calculation
for i=1:(nbus-1)
ii=i+1;
for k=1:(nbus-1)
kk=k+1;
j22(i,k)=mv(ii)*(g(ii,kk)*sin(th(ii)-th(kk))-b(ii,kk)*cos(th(ii)-th(kk)));\\
j22(i,i)=qcal(i+1)/mv(i+1)-b(i+1,i+1)*mv(i+1);
end
jacob=[j11 j12;j21 j22];
delpq=[delp(2:nbus);delq(2:nbus)];
% correction vector
corr=inv(jacob)*delpq;
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```
% update theta
th=th+[0;corr(1:(nbus-1))];
\% update voltage magnitude
mv=mv+[0;corr(nbus:end)];
del=max(abs(delpq));
indx=indx+1; %iteration counter
end
mv
th
indx
Result :
indx = 0
jacob =53.0000 -32.0000
                          25.5000 -16.0000
      -32.0000
                63.5000 -16.0000
                                    25.5000
      -26.5000
                16.0000
                          51.0000
                                   -32.0000
      16.0000 -26.5000 -32.0000
                                    60.5000
mv =1.0500
   0.9766
    1.0000
th = 0
   -0.0548
   -0.0430
 indx =5
```