

TA: Zhong Yinmin

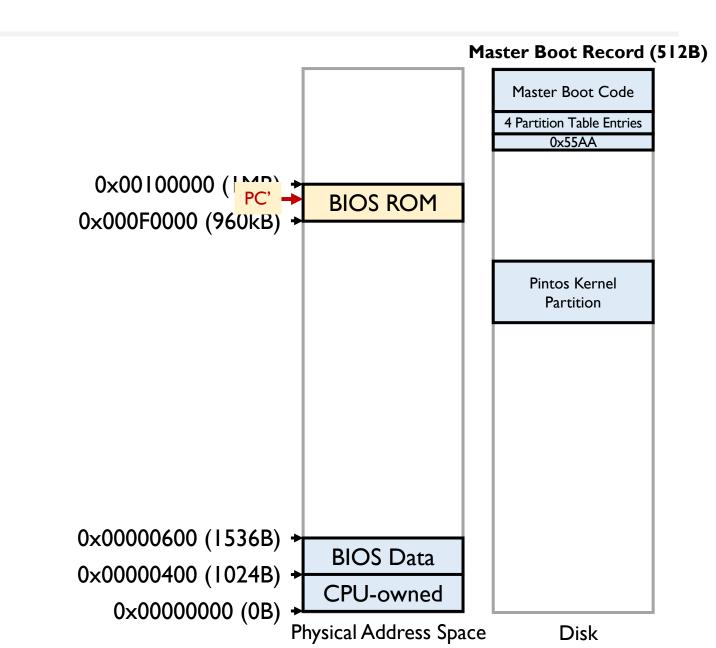
Today

- Lab0 Booting review
- Struct thread
- Switching thread
- Create a new thread
- Synchronization
- List
- Lab I tasks
- Q&A

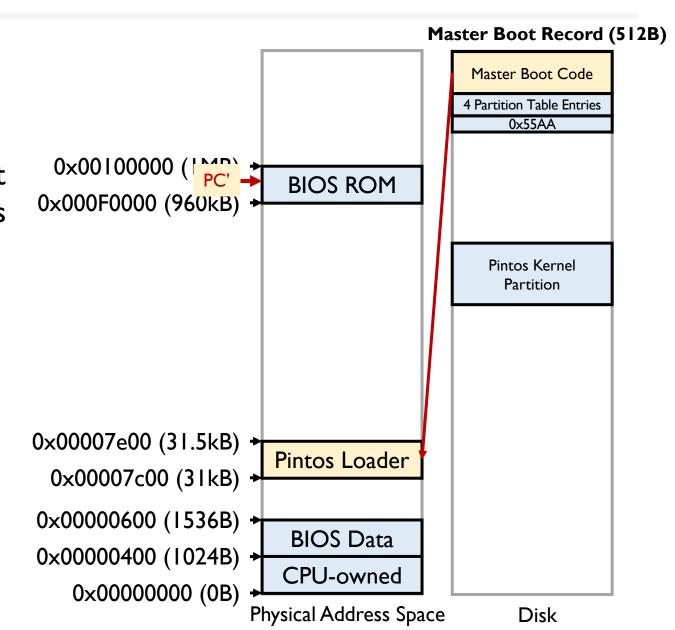
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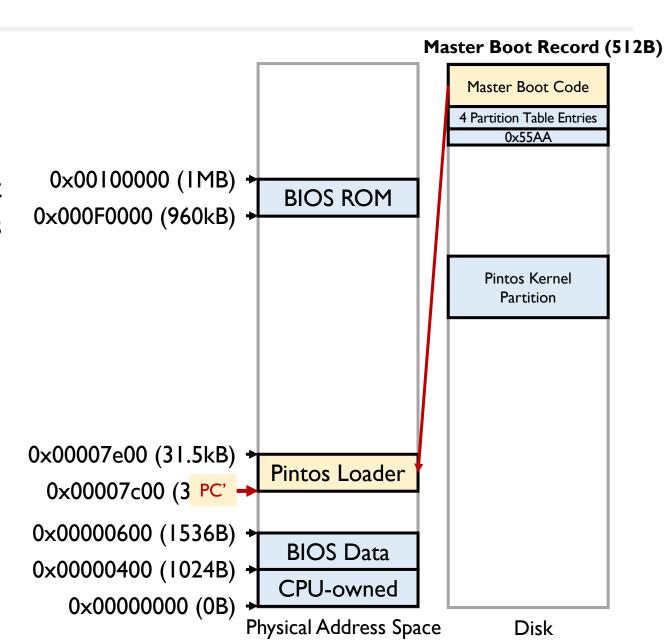
- Power on
- BIOS gets control



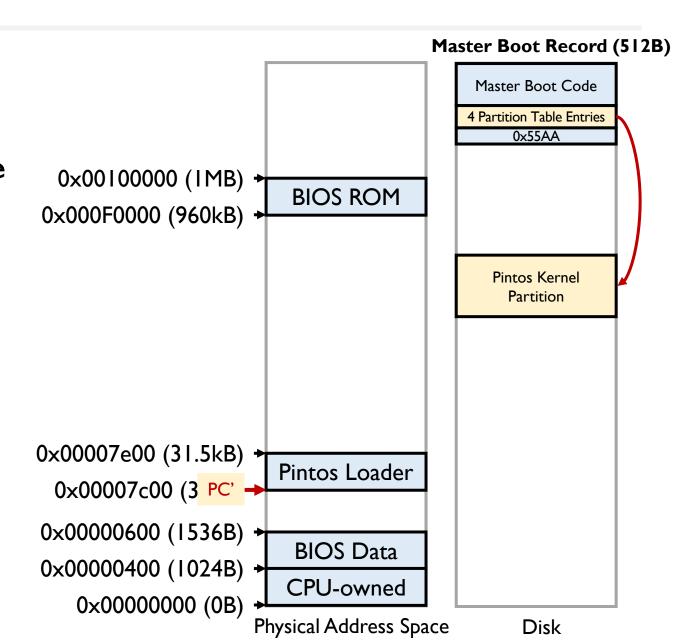
- Power on
- BIOS gets control
- BIOS loads pintos loader from the first sector of a hard disk to physical address 0x7c00-0x7e00 (512B)



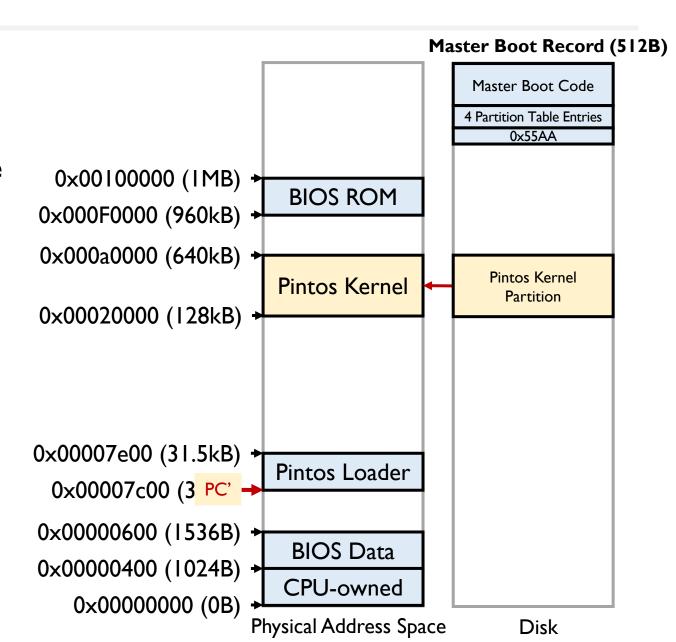
- Power on
- BIOS gets control
- BIOS loads pintos loader from the first sector of a hard disk to physical address 0x7c00-0x7e00 (512B)
- Jump to the beginning of loader



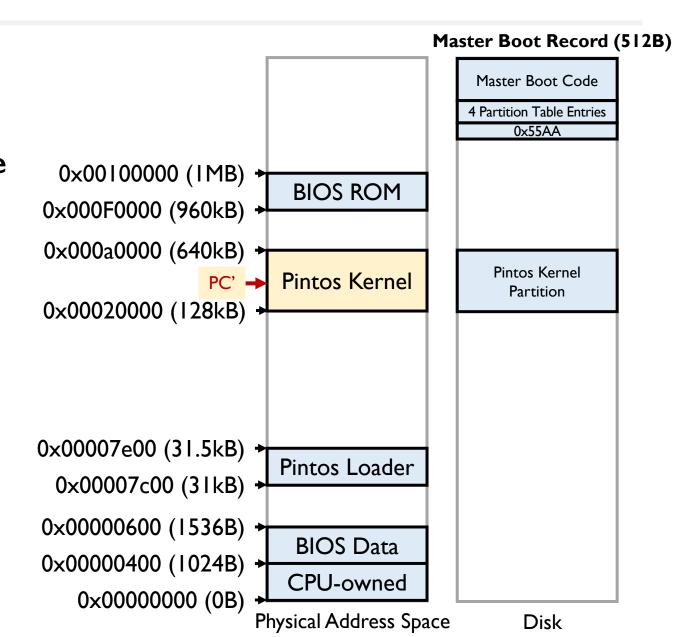
- loader.S
 - Read the partition table on each system disk, looking for a bootable partition of the type used for a Pintos Kernel



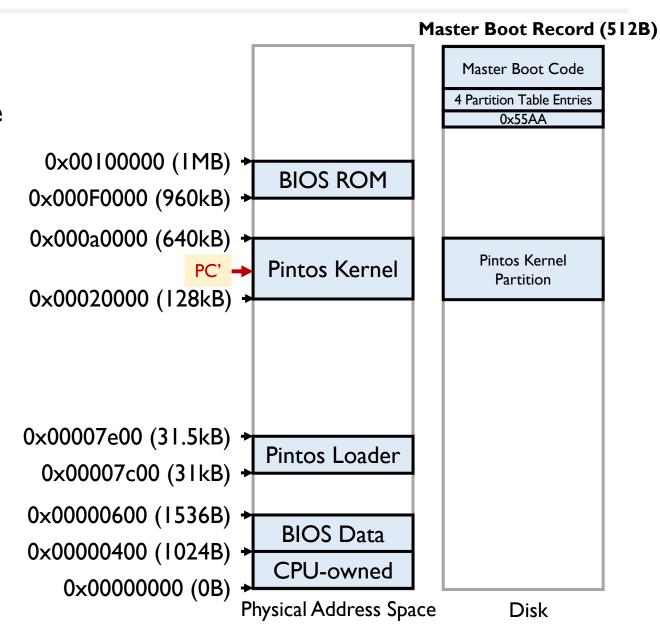
- loader.S
 - Read the partition table on each system disk, looking for a bootable partition of the type used for a Pintos Kernel
 - Read pintos kernel from the disk



- loader.S
 - Read the partition table on each system disk, looking for a bootable partition of the type used for a Pintos Kernel
 - Read pintos kernel from the disk
 - Jump to its start address
 - Read the start address out of ELF header
 - Jump to "start"



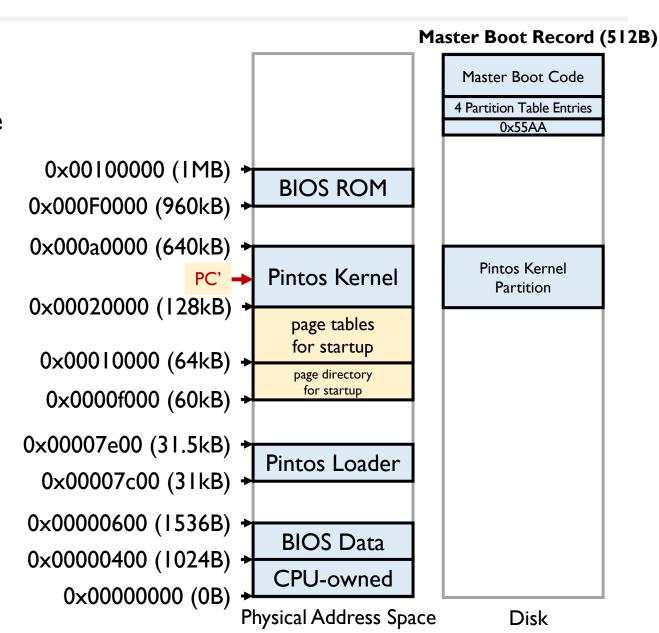
- start.S
 - Obtain the machine's memory size
 - global variable init_ram_pages
 - up to 64MB
 - Enable the A20 line



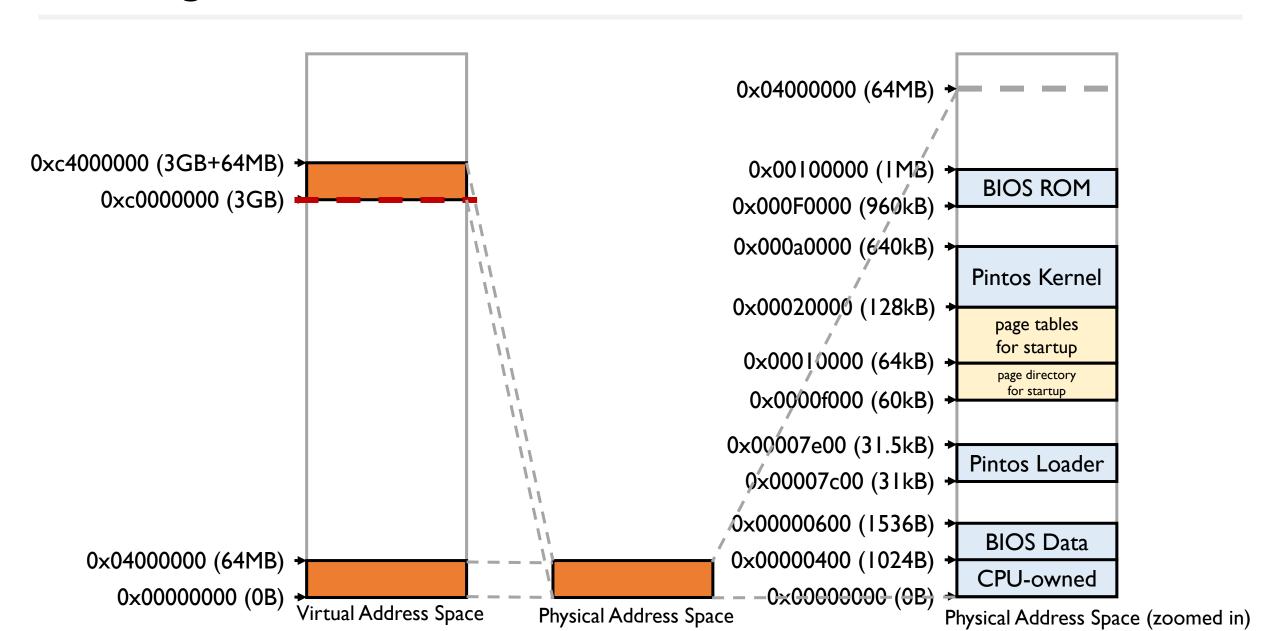
- start.S
 - Obtain the machine's memory size
 - global variable init_ram_pages
 - up to 64MB
 - Enable the A20 line
 - Create a basic page table

```
# Create page directory at 0xf000 (60 kB) and fill with zeroes.
    mov $0xf00, %ax
    mov %ax, %es
    subl %eax, %eax
    subl %edi, %edi
    movl $0x400, %ecx
    rep stosl

# Add PDEs to point to page tables for the first 64 MB of RAM.
# Also add identical PDEs starting at LOADER_PHYS_BASE.
# See [IA32-v3a] section 3.7.6 "Page-Directory and Page-Table Entries"
# for a description of the bits in %eax.
# Set up page tables for one-to-map linear to physical map for the
# first 64 MB of RAM.
# See [IA32-v3a] section 3.7.6 "Page-Directory and Page-Table Entries"
# for a description of the bits in %eax.
```



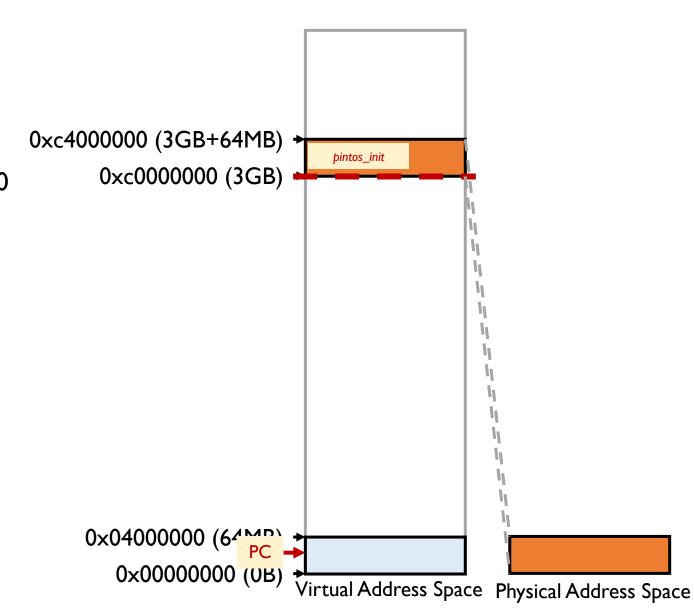
Basic Page Table



Why to map the first 64MB of virtual memory

If not map the first 64MB of virtual memory...

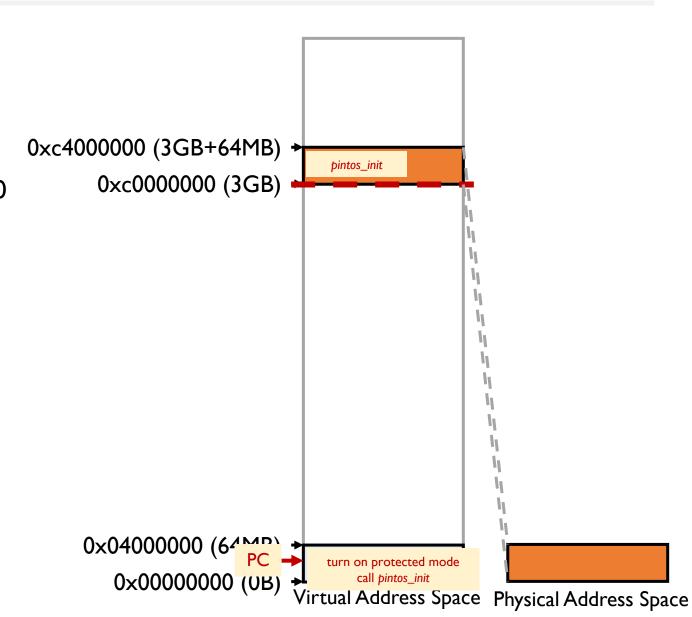
- In raw mode, PC is roughly 0x20000
- The address of pintos_init is about 0xc0020000



Why to map the first 64MB of virtual memory

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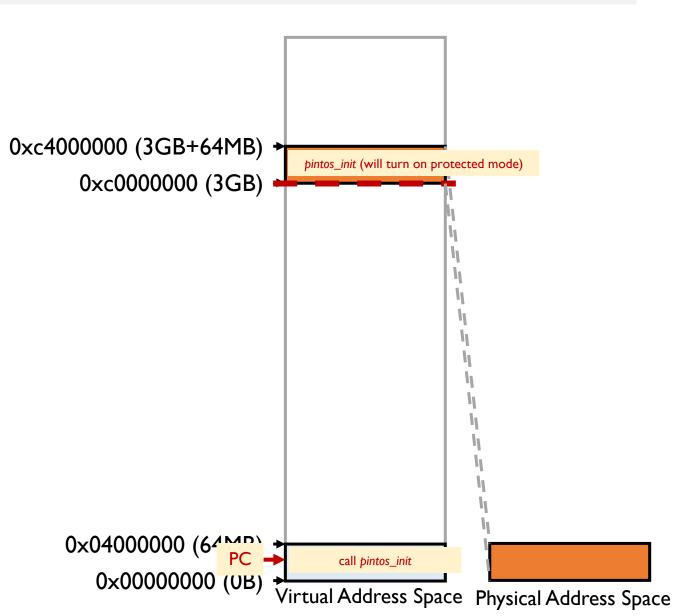
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- The address of pintos_init is about 0xc0020000
- If turn on protected mode before jumping to pintos_init
 - cannot call pintos_init normally for the erroneous address translation



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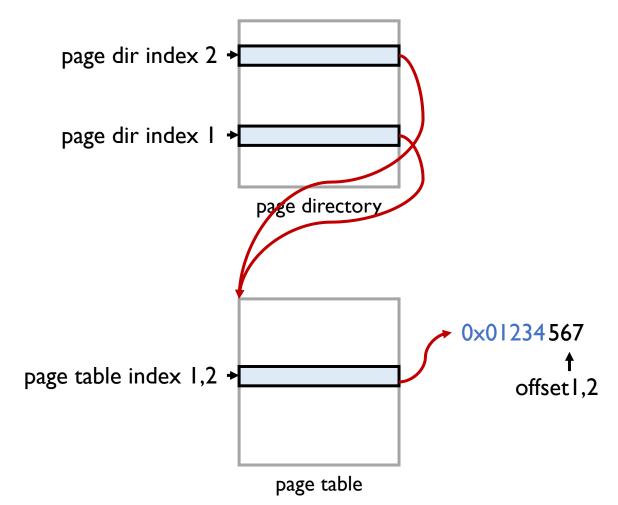
- In raw mode, PC is roughly 0x20000
- The address of pintos_init is about 0xc0020000
- If turn on protected mode before jumping to pintos_init
 - cannot call pintos_init normally for the erroneous address translation
- If jump to pintos_init before turning on protected mode
 - jump over 0xc0000000 without address translation on



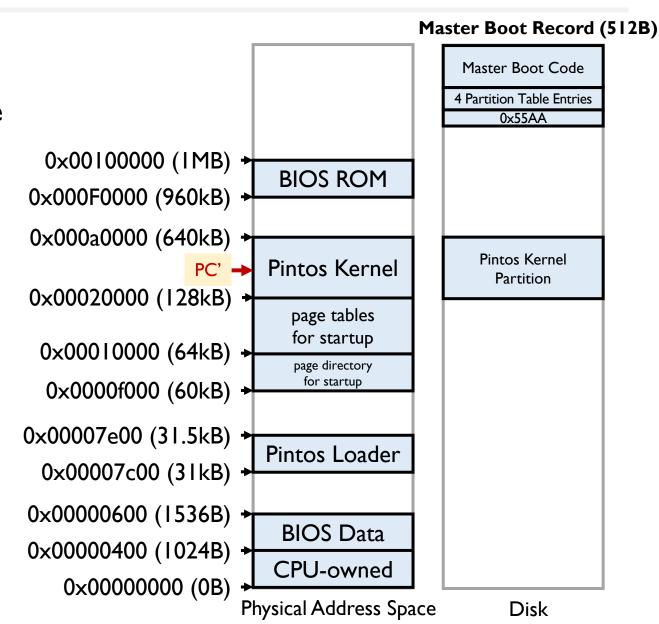
Basic Page Table

- Only map 64MB and multiplex page tables
 - Virtual addresses Oxc0000000 + y and y should be translated to physical address y
 - They have different indices of page directory, same index of page table and offset
- I page directory:
 - I * 4KB = 4KB
- I6 page tables:
 - 64MB/4MB * 4KB = 64KB
- the rest mapping: not used so far

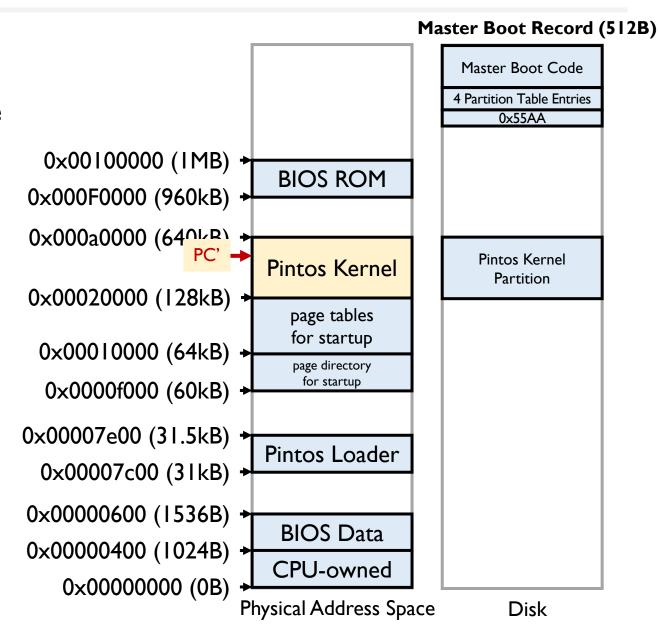
addr1: $0xc1234567 \rightarrow 0x01234567$ addr2: $0x01234567 \rightarrow 0x01234567$



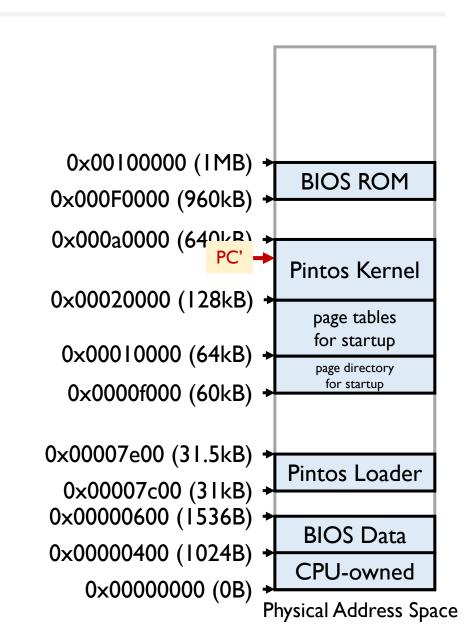
- start.S
 - Obtain the machine's memory size
 - global variable init_ram_pages
 - up to 64MB
 - Enable the A20 line
 - Create a basic page table
 - Turn on protected mode and paging
 - Set up the segment registers



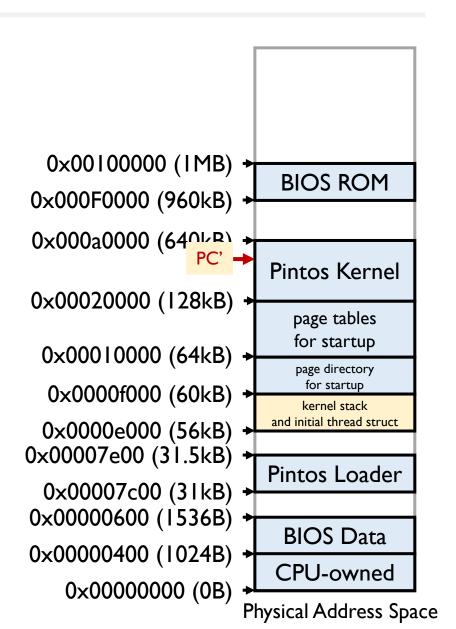
- start.S
 - Obtain the machine's memory size
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 - Enable the A20 line
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 - Turn on protected mode and paging
 - Set up the segment registers
 - Call pintos_init()



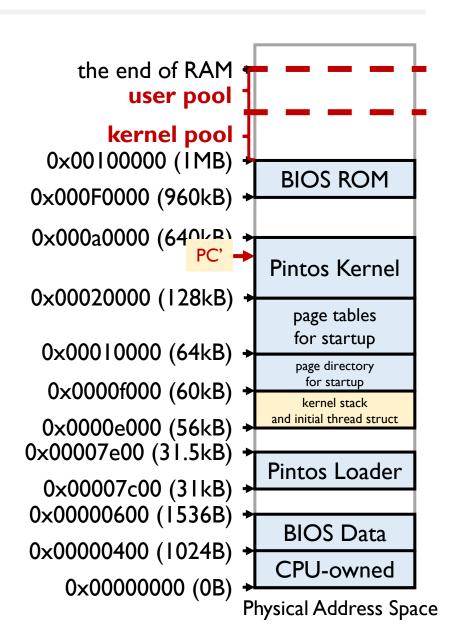
about pintos_init()



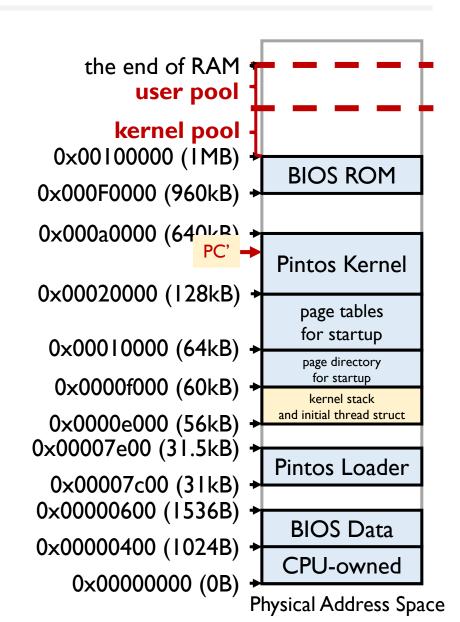
- about pintos_init()
 - Initialize the first thread: thread_init
 - Transform the currently running code into a thread
 - Struct thread later



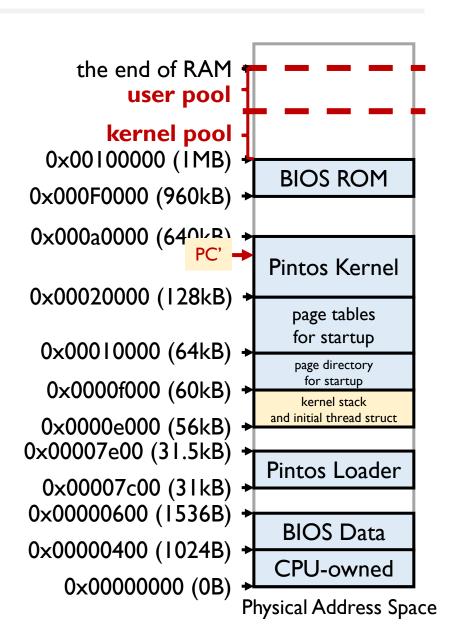
- about pintos_init()
 - Memory management: palloc_init, malloc_init, paging_init
 - Page allocator (palloc)
 - Hand out memory in page-size or page-multiple chunks
 - Free memory starts at IMB and runs to the end of RAM
 - System memory is divided into two pools called kernel pool and user pool respectively. The user pool should be used for allocating memory for user processes and the kernel pool for all other allocations.
 - By default, half of system RAM is given to kernel pool and half to the user pool
 - Until lab3, all allocations should be made from the kernel pool



- about pintos_init()
 - Memory management: palloc_init, malloc_init, paging_init
 - Block allocator (malloc)
 - On top of page allocator, it can allocate blocks of any size
 - Block returned by the block allocator are obtained from the kernel pool
 - Block allocator uses 2 different strategies for allocating memory (see section Block allocator)



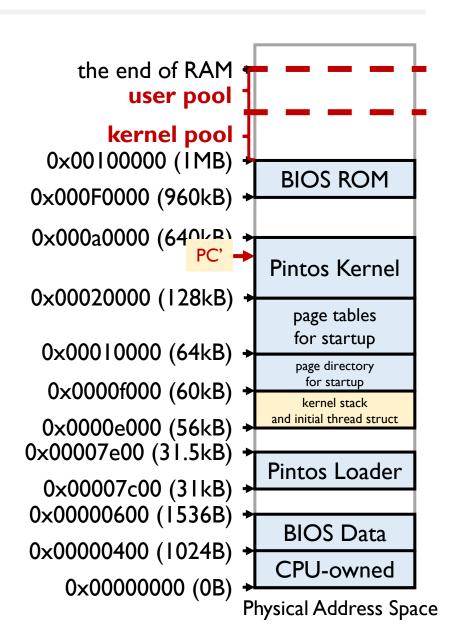
- about pintos_init()
 - Memory management: palloc_init, malloc_init, paging_init
 - paging_init
 - Obtain memory from pools and create a new page directory and page tables with the kernel virtual mapping (only 0xc0000000-0xc0000000+64MB)
 - Set up the CPU to use the new page directory
 - See source code



- about pintos_init()
 - Initialize the interrupt system
 - See section Interrupt Handling / more till lab2
 - timer: timer interrupts handled in devices/timer.c
 timer_interrupt

```
/** Timer interrupt handler. */
static void
timer_interrupt (struct intr_frame *args UNUSED)
{
   ticks++;
   thread_tick ();
}
```

- run_actions
 - Parses and executes actions specified on the kernel command line



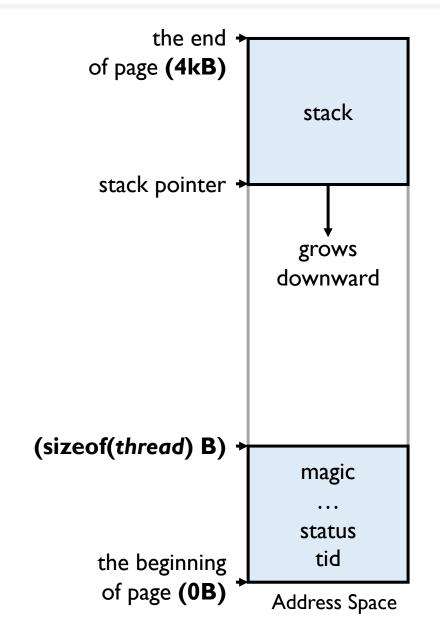
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Struct thread

- Memory layout of a running thread
 - Struct thread represents a thread or a user process
 - Every struct thread occupies the beginning of its own page of memory
 - The rest of the page is used for the thread's stack

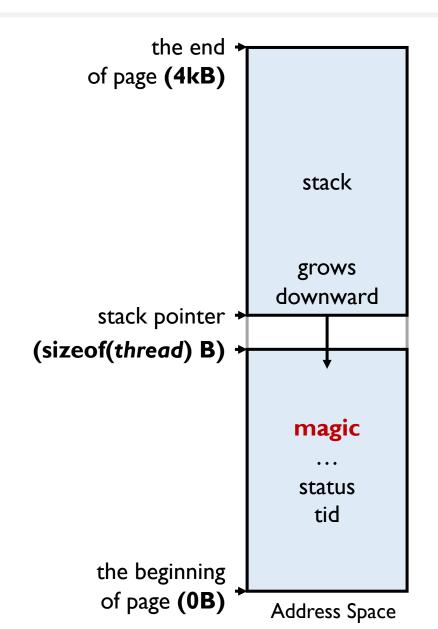
```
struct thread
    /* Owned by thread.c. */
                                         /**< Thread identifier. */
    tid_t tid;
    enum thread_status status;
                                         /**< Thread state. */
    char name[16];
                                         /**< Name (for debugging purposes). */</pre>
    uint8_t *stack;
                                         /**< Saved stack pointer. */
    int priority;
                                         /**< Priority. */
                                         /**< List element for all threads list. */
    struct list_elem allelem;
    /* Shared between thread.c and synch.c. */
    struct list_elem elem;
                                         /**< List element. */
#ifdef USERPROG
    /* Owned by userprog/process.c. */
    uint32_t *pagedir;
                                         /**< Page directory. */
#endif
    /* Owned by thread.c. */
                                         /**< Detects stack overflow. */
    unsigned magic;
```



Struct thread

Caveats

- Struct thread must not be allowed to grow too big
- Kernel stack must not be allowed to grow too large
 - the size of non-static local variables should not be too large
- Add new struct members before *magic*



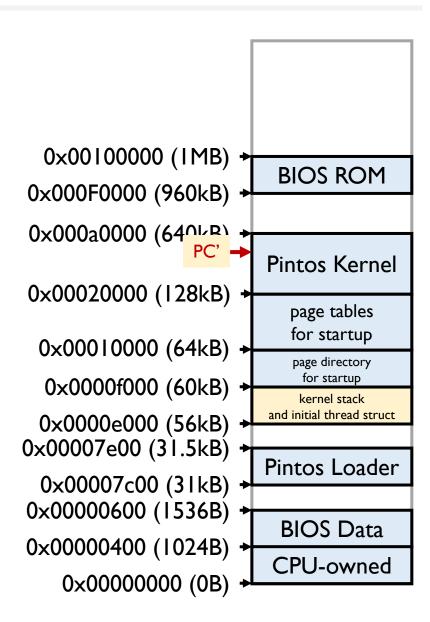
Initialization of the first thread

The first thread is initialized in thread_init

```
/* Set up a thread structure for the running thread. */
initial_thread = running_thread ();
init_thread (initial_thread, "main", PRI_DEFAULT);
```

• The struct address of the first thread depends on %esp, which is initialized in *loader*. S

```
/** Returns the running thread. */
struct thread *
running_thread (void)
  uint32_t *esp;
  /* Copy the CPU's stack pointer into `esp', and then round that
    down to the start of a page. Because `struct thread' is
    always at the beginning of a page and the stack pointer is
    somewhere in the middle, this locates the curent thread. */
  asm ("mov %esp, %0" : "=g" (esp));
  return pg_round_down (esp);
 Set up segment registers.
 Set stack to grow downward from 60 kB (after boot, the kernel
 continues to use this stack for its initial thread).
    sub %ax, %ax
    mov %ax, %ds
    mov %ax, %ss
    mov $0xf000, %esp
```



Struct thread

some handy interfaces

• threads/thread.h

```
extern bool thread_mlfqs;
void thread_init (void);
void thread_start (void);
void thread_tick (void);
void thread_print_stats (void);
typedef void thread_func (void *aux);
tid_t thread_create (const char *name, int priority, thread_func *, void *);
void thread_block (void);
void thread_unblock (struct thread *);
struct thread *thread_current (void);
tid_t thread_tid (void);
const char *thread_name (void);
void thread_exit (void) NO_RETURN;
void thread_yield (void);
```

```
/** Performs some operation on thread t, given auxiliary data AUX. */
typedef void thread_action_func (struct thread *t, void *aux);
void thread_foreach (thread_action_func *, void *);

int thread_get_priority (void);
void thread_set_priority (int);

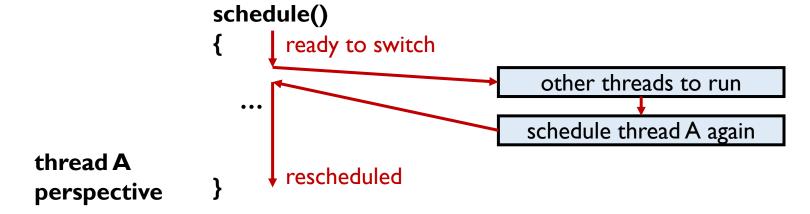
int thread_get_nice (void);
void thread_set_nice (int);
int thread_get_recent_cpu (void);
int thread_get_load_avg (void);
```

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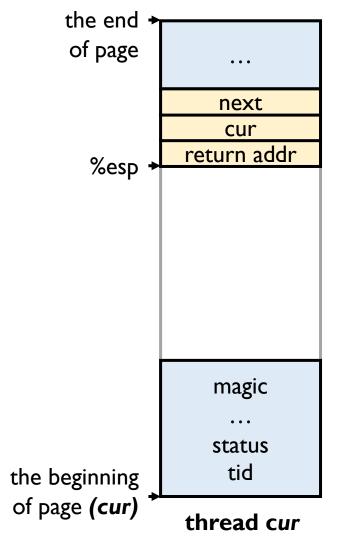
Switching thread in Pintos

- Function **schedule()** is responsible for switching threads
- When
 - schedule() is called only by three public thread functions:
 - thread_block(), thread_exit(), thread_yield()
- How (from a thread's perspective)
 - When a thread calls schedule(), try to find another thread to run and switch to it
 - When a thread **returns from schedule()**, it is scheduled again

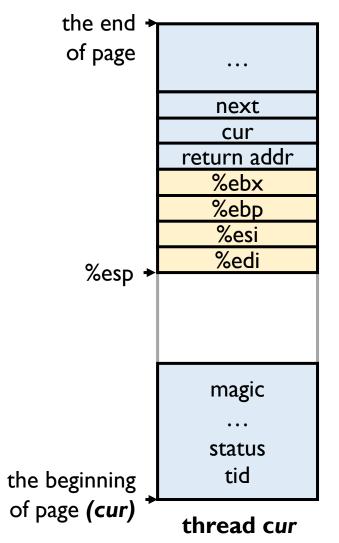


- schedule()
 - Before calling schedule(), make sure interrupts are disabled
 - Record the current thread in cur
 - Determine the next thread to run (next)
 - Call switch_threads(cur, next) to do the actual switch

```
static void
schedule (void)
 struct thread *cur = running_thread ();
  struct thread *next = next_thread_to_run ();
  struct thread *prev = NULL;
  ASSERT (intr_get_level () == INTR_OFF);
  ASSERT (cur->status != THREAD_RUNNING);
  ASSERT (is_thread (next));
  if (cur != next)
   prev = switch_threads (cur, next);
  thread schedule tail (prev);
```

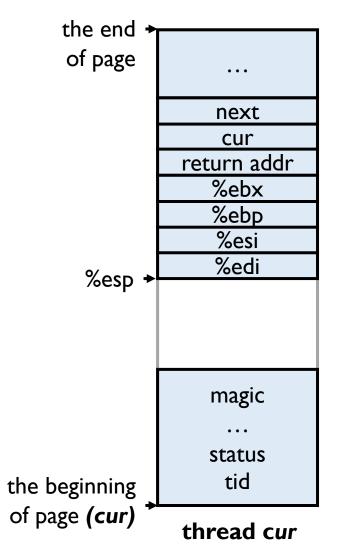


```
.globl switch_threads
.func switch_threads
switch_threads:
       # Save caller's register state.
        # Note that the SVR4 ABI allows us to destroy %eax, %ecx, %edx,
        # but requires us to preserve %ebx, %ebp, %esi, %edi. See
       # [SysV-ABI-386] pages 3-11 and 3-12 for details.
        # This stack frame must match the one set up by thread_create()
        # in size.
        pushl %ebx
        pushl %ebp
        pushl %esi
        pushl %edi
       # Get offsetof (struct thread, stack).
.globl thread_stack_ofs
       mov thread_stack_ofs, %edx
       # Save current stack pointer to old thread's stack, if any.
       movl SWITCH_CUR(%esp), %eax
       movl %esp, (%eax,%edx,1)
        # Restore stack pointer from new thread's stack.
       movl SWITCH_NEXT(%esp), %ecx
       movl (%ecx,%edx,1), %esp
       # Restore caller's register state.
        popl %edi
        popl %esi
        popl %ebp
       popl %ebx
        ret
.endfunc
```



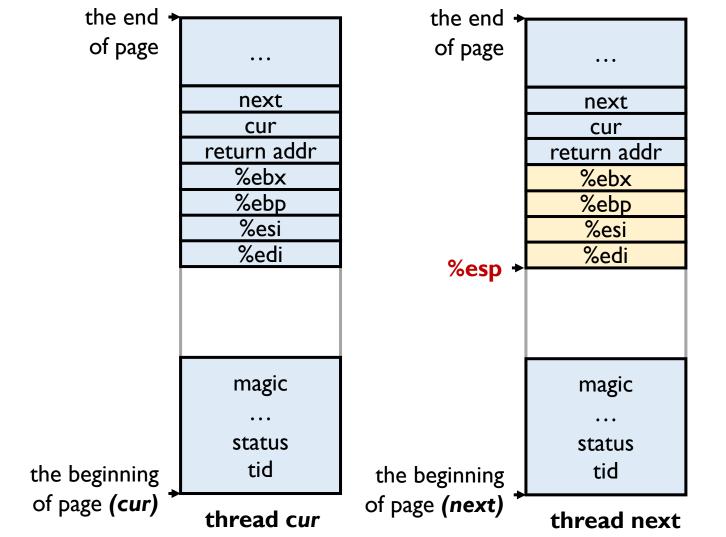
```
/** Offset of `stack' member within `struct thread'.
| Used by switch.S, which can't figure it out on its own. */
uint32_t thread_stack_ofs = offsetof (struct thread, stack);
```

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        # Restore stack pointer from new thread's stack.
       movl SWITCH_NEXT(%esp), %ecx
       movl (%ecx,%edx,1), %esp
       # Restore caller's register state.
       popl %edi
       popl %esi
       popl %ebp
       popl %ebx
        ret
.endfunc
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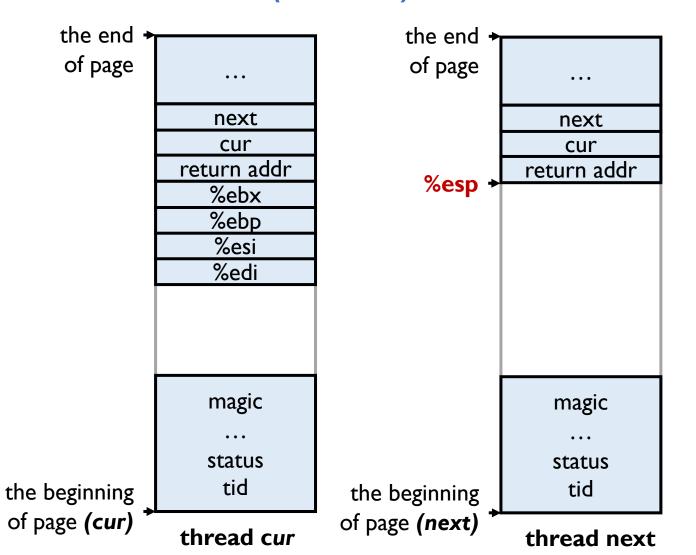
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       pushl %esi
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       # Save devent stack pointer to old thread's stack, if any.
       movl SWITCH_CUR %esp), %eax CU
       movl %esp, (%eax,%edx,1)
                            save the stack pointer of cur
       # Restore stack pointer from new thread's stack.
       movl SWITCH_NEXT %esp), %ecx next
       movl (%ecx,%edx,1), %esp
       # Restore caller's register state.
       popl %edi
       popl %esi
       popl %ebp
       popl %ebx
       ret
.endfunc
```



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       # Restore stack pointer from new thread's stack.
       movl SWITCH_NEXT %esp), %ecx next
       movl (%ecx,%edx,1), %esp
                                the stack pointer of next
       # Restore caller's register state.
       popl %edi
       popl %esi
       popl %ebp
       popl %ebx
       ret
.endfunc
```

switch_threads(cur, next)



```
/** Offset of `stack' member within `struct thread'.
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       # Restore stack pointer from new thread's stack.
       movl SWITCH_NEXT %esp), %ecx next
       movl (%ecx,%edx,1), %esp
                                 the stack pointer of next
       # Restore caller's register state.
       popl %edi
       popl %esi
       popl %ebp
       popl %ebx
       ret
.endfunc
```

- schedule()
 - Before calling schedule(), make sure interrupts are disabled
 - Record the current thread in cur
 - Determine the next thread to run (next)
 - Call switch_threads(cur, next) to do the actual switch
 - Returning from switch_threads means the thread is scheduled again
 - Return value is the previous thread
 - Call thread_schedule_tail(prev)

```
static void
schedule (void)
  struct thread *cur = running thread ();
  struct thread *next = next_thread_to_run ();
  struct thread *prev = NULL;
  ASSERT (intr_get_level () == INTR_OFF);
  ASSERT (cur->status != THREAD_RUNNING);
  ASSERT (is_thread (next));
  if (cur != next)
    prev = switch_threads (cur, next);
  thread_schedule_tail (prev);
```

- thread_schedule_tail(prev)
 - Mark the new thread status as running
 - Reset the thread_ticks
 - If the thread we just switched from (except initial_thread) is in the dying state, free its thread page

```
thread_schedule_tail (struct thread *prev)
 struct thread *cur = running_thread ();
  ASSERT (intr_get_level () == INTR_OFF);
  /* Mark us as running. */
  cur->status = THREAD_RUNNING;
  /* Start new time slice. */
  thread_ticks = 0;
#ifdef USERPROG
 /* Activate the new address space. */
 process_activate ();
#endif
  /* If the thread we switched from is dying, destroy its struct
     thread. This must happen late so that thread_exit() doesn't
    pull out the rug under itself. (We don't free
     initial_thread because its memory was not obtained via
  if (prev != NULL && prev->status == THREAD_DYING && prev != initial_thread)
     ASSERT (prev != cur);
     palloc_free_page (prev);
```

- next_thread_to_run(void)
 - Chooses and returns the next thread to be scheduled
 - Should return a thread from the run queue, unless the run queue is empty
 - If the run queue is empty, return idle_thread which is created by thread_start() in pintos_init()

```
static struct thread *
next_thread_to_run (void)
{
   if (list_empty (&ready_list))
     return idle_thread;
   else
     return list_entry (list_pop_front (&ready_list), struct thread, elem);
}
```

Today

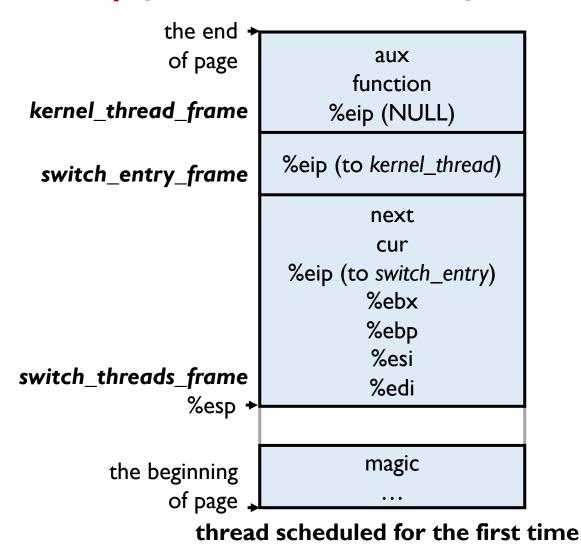
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Usually, we call thread_create to create a new thread

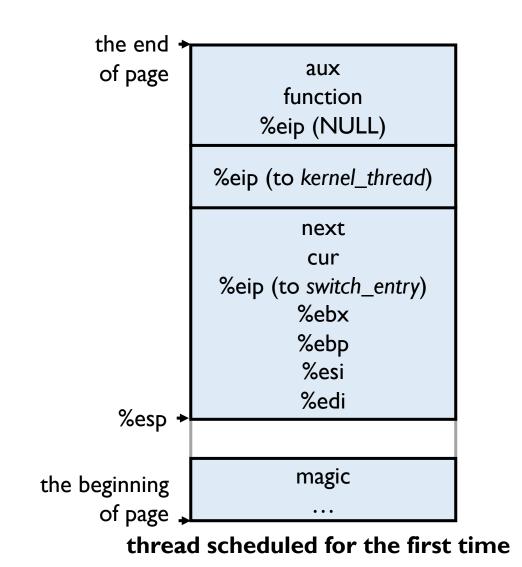
```
typedef void thread_func (void *aux);
tid_t thread_create (const char *name, int priority, thread_func *, void *);
```

- What do we expect thread_create to do?
 - Thread A calls thread_create to create thread B and return
 - Thread B starts running when scheduled for the first time, well...
 - switch_threads will execute several pop instructions and ret
 - The stack frame for the thread_func to run may have not been formed yet
 - Leverage some fake stack frames!

Utilize 3 frames: kernel_thread_frame, switch_entry_frame, switch_threads_frame



The thread is scheduled for the first time

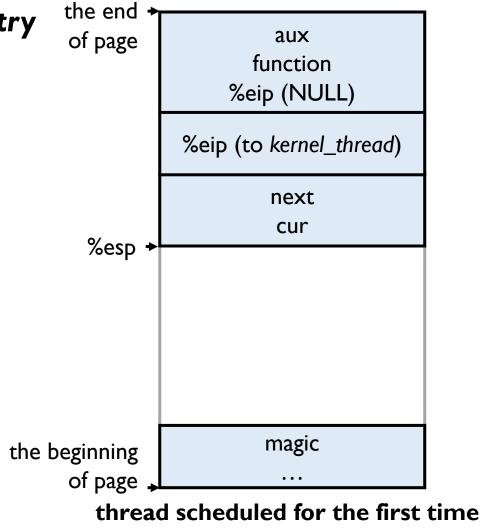


- The thread is scheduled for the first time
- Return from switch_threads and execute switch_entry

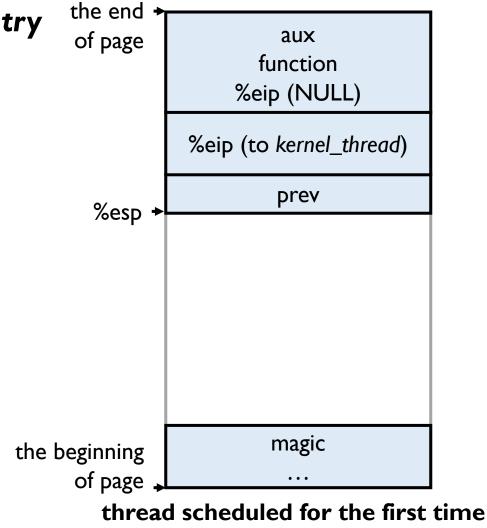
```
.globl switch_entry
.func switch_entry
switch_entry:
     # Discard switch_threads() arguments.
     addl $8, %esp

# Call thread_schedule_tail(prev).
     pushl %eax
.globl thread_schedule_tail
     call thread_schedule_tail
     addl $4, %esp

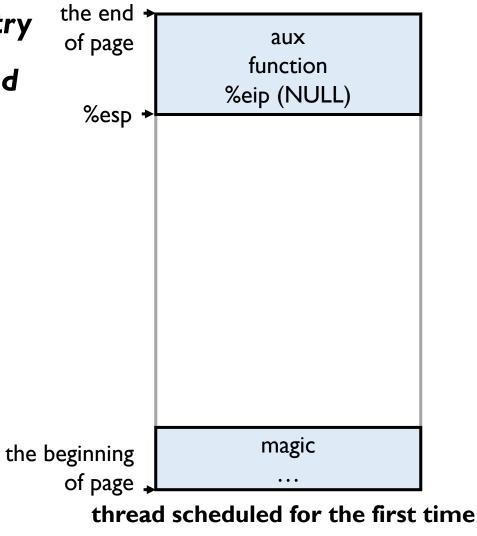
# Start thread proper.
     ret
.endfunc
```



- The thread is scheduled for the first time
- Return from switch_threads and execute switch_entry



- The thread is scheduled for the first time
- Return from switch_threads and execute switch_entry
- Return from switch_entry and execute kernel_thread
 - enable interrupt
 - call function(aux)
 - call thread_exit()



Today

- Lab0 Booting review
- Struct thread
- Switching thread
- Create a new thread
- Synchronization
- List
- Lab I tasks
- Q & A

Synchronization

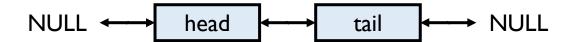
- disable interrupts
- semaphore
- lock
 - based on semaphore
- condition and monitor
- optimization barrier *

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List in Pintos

- doubly linked list
- an empty list

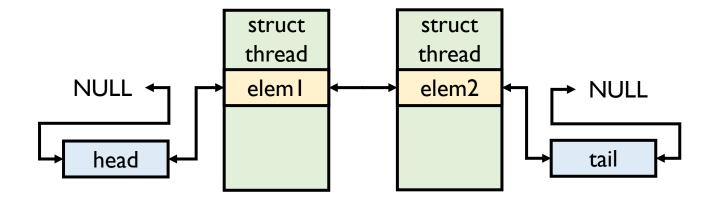


a list with 2 elements

/**< List tail. */

```
NULL ←→ head ←→ elem1 ←→ elem2 ←→ tail ←→ NULL
```

- a list of complex struct
 - embed a list_elem in the struct
 - manipulate the inner list_elem



struct list_elem tail;

List in Pintos

example: ready_list

```
thread_yield (void)
 struct thread *cur = thread_current ();
 enum intr_level old_level;
 ASSERT (!intr_context ());
 old_level = intr_disable ();
 if (cur != idle_thread)
  list_push_back (&ready_list, &cur->elem);
 cur->status = THREAD READY;
 schedule ();
 intr_set_level (old_level);
static struct thread *
next_thread_to_run (void)
 if (list_empty (&ready_list))
   return idle_thread;
 else
   return list_entry (list_pop_front (&ready_list) struct thread, elem);
```

 list_entry: convert pointer to LIST_ELEM into the pointer to the struct containing it

```
struct thread
    /* Owned by thread.c. */
    tid_t tid;
                                     /**< Thread identifier. */
    enum thread_status status;
                                     /**< Thread state. */
    char name[16];
                                     /**< Name (for debugging purposes). */</pre>
    uint8_t *stack;
                                     /**< Saved stack pointer. */
    int priority;
                                     /**< Priority. */
    struct list_elem allelem;
                                     /**< List element for all threads list. */
    /* Shared between thread.c and synch.c. */
    struct list_elem elem;
                                     /**< List element. */
#ifdef USERPROG
    /* Owned by userprog/process.c. */
    uint32_t *pagedir;
                                     /**< Page directory. */
#endif
    /* Owned by thread.c. */
    unsigned magic;
                                     /**< Detects stack overflow. */
/** List of processes in THREAD_READY state, that is, processes
static struct list ready_list;
#define list_entry(LIST_ELEM, STRUCT, MEMBER)
           ((STRUCT *) ((uint8_t *) &(LIST_ELEM)->next
                           - offsetof (STRUCT, MEMBER.next)))
```

List in Pintos

some handy interfaces

lib/kernel/list.h

```
/** List traversal. */
struct list_elem *list_begin (struct list *);
struct list_elem *list_next (struct list_elem *);
struct list_elem *list_end (struct list *);
struct list_elem *list_rbegin (struct list *);
struct list_elem *list_prev (struct list_elem *);
struct list_elem *list_rend (struct list *);
struct list_elem *list_head (struct list *);
struct list_elem *list_tail (struct list *);
/** List insertion. */
void list_insert (struct list_elem *, struct list_elem *);
void list_splice (struct list_elem *before,
                  struct list_elem *first, struct list_elem *last);
void list_push_front (struct list *, struct list_elem *);
void list_push_back (struct list *, struct list_elem *);
/** List removal. */
struct list_elem *list_remove (struct list_elem *);
struct list_elem *list_pop_front (struct list *);
struct list_elem *list_pop_back (struct list *);
/** List elements. */
struct list_elem *list_front (struct list *);
struct list_elem *list_back (struct list *);
```

```
/** List properties. */
size_t list_size (struct list *);
bool list_empty (struct list *);
/** Miscellaneous. */
void list_reverse (struct list *);
/** Compares the value of two list elements A and B, given
   auxiliary data AUX. Returns true if A is less than B, or
   false if A is greater than or equal to B. */
typedef bool list_less_func (const struct list_elem *a,
                             const struct list_elem *b,
                             void *aux);
/** Operations on lists with ordered elements. */
void list_sort (struct list *,
                list_less_func *, void *aux);
void list_insert_ordered (struct list *, struct list_elem *,
                          list_less_func *, void *aux);
void list_unique (struct list *, struct list *duplicates,
                  list_less_func *, void *aux);
/** Max and min. */
struct list_elem *list_max (struct list *, list_less_func *, void *aux);
struct list_elem *list_min (struct list *, list_less_func *, void *aux);
```

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Lab I Task I: Alarm Clock

Exercise 1.1

Reimplement timer_sleep(), defined in devices/timer.c.

- Although a working implementation is provided, it "busy waits," that is, it spins in a loop checking the current time and calling thread_yield() until enough time has gone by.
- Reimplement it to avoid busy waiting.

- Synchronization
- Read FAQ

```
/** Sleeps for approximately TICKS timer ticks. Interrupts must
   be turned on. */
void
timer_sleep (int64_t ticks)
{
   int64_t start = timer_ticks ();

   ASSERT (intr_get_level () == INTR_ON);
   while (timer_elapsed (start) < ticks)
        thread_yield ();
}</pre>
```

Exercise 2.1

Implement priority scheduling in Pintos.

- When a thread is added to the ready list that has a higher priority than the currently running thread, the current thread should **immediately yield** the processor to the new thread.
- Similarly, when threads are waiting for a lock, semaphore, or condition variable, the highest priority waiting thread should be awakened first.
- A thread may raise or lower its own priority at any time, but lowering its priority such that it no longer has the highest priority must cause it to immediately yield the CPU.

- Consider all the scenarios where the priority must be enforced
- 2 types of yield
- Read FAQ

Exercise 2.2.1

Implement priority donation.

- You will need to account for all different situations in which priority donation is required.
- You must implement priority donation **for locks**. You need **not** implement priority donation for the other Pintos synchronization constructs.
- You do need to implement priority scheduling in all cases.
- Be sure to **handle multiple donations**, in which multiple priorities are donated to a single thread.

- Implement priority donation only for locks but priority scheduling for all!
- Read FAQ

Exercise 2.2.2

Support nested priority donation:

- if H is waiting on a lock that M holds and M is waiting on a lock that L holds, then both M and L should be boosted to H's priority.
- If necessary, you may impose a reasonable limit on depth of nested priority donation, such as 8 levels.

- Implement priority donation only for locks but priority scheduling for all!
- Read FAQ

 \bigcirc

Exercise 2.3

Implement the following functions that allow a thread to examine and modify its own priority.

Skeletons for these functions are provided in **threads/thread.c**.

- Function: void thread_set_priority (int new_priority)
 - Sets the current thread's priority to new_priority.
 - If the current thread no longer has the highest priority, yields.
- Function: int thread_get_priority (void)
 - Returns the current thread's priority. In the presence of priority donation, returns the higher (donated) priority.

- Implement priority donation only for locks but priority scheduling for all!
- Read FAQ

Lab I Task 3: Advanced Scheduler

 $\langle \mathbf{v} \rangle$

Exercise 3.1

Implement a multilevel feedback queue scheduler similar to the 4.4BSD scheduler to reduce the average response time for running jobs on your system.

See section **4.4BSD Scheduler**, for detailed requirements.

- When to update
- How to update
- Read FAQ

About tests

- All the test code in lab I run as part of the kernel
- Efficiency Problem
 - esp. mlfqs-load-60, mlfqs-load-avg
 - load_avg is dynamically updated and sensitive to the some properties, e.g., the number of threads that are either running or ready to run at time of update
 - If your implementation is not efficient, then it will effect the system properties and the final output
 - The acceptable error range for $load_avg$ is within ± 2.5 which can be known from .ck file.

```
The expected output is this (some margin of error is allowed):
After 0 seconds, load average=1.00.
After 2 seconds, load average=2.95.
After 4 seconds, load average=4.84.
After 6 seconds, load average=6.66.
After 8 seconds, load average=8.42.
After 10 seconds, load average=10.13.
After 12 seconds, load average=11.78.
After 14 seconds, load average=13.37.
After 16 seconds, load average=14.91.
After 18 seconds, load average=16.40.
After 20 seconds, load average=17.84.
After 22 seconds, load average=19.24.
After 24 seconds, load average=20.58.
After 26 seconds, load average=21.89.
After 28 seconds, load average=23.15.
After 30 seconds, load average=24.37.
After 32 seconds, load average=25.54.
After 34 seconds, load average=26.68.
After 36 seconds, load average=27.78.
After 38 seconds, load average=28.85.
After 40 seconds, load average=29.88.
After 42 seconds, load average=30.87.
After 44 seconds, load average=31.84.
After 46 seconds, load average=32.77.
After 48 seconds, load average=33.67.
After 50 seconds, load average=34.54.
```

Today

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Thanks for your listening.