

# Operating Systems (Honor Track)

## Memory 5: Memory Management in Modern Computer Systems

Xin Jin

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Acknowledgments: Ion Stoica, Berkeley CS 162

# Memory Management in Modern Computer Systems

- Memory Abstraction
  - NSDI'14 FaRM
- Demand paging: remote memory over RDMA
  - NSDI'17 InfiniSwap
  - OSDI'20 AIFM
- Demand paging: memory swapping between GPU memory and host memory
  - OSDI'20 PipeSwitch
  - NSDI'23 TGS

# FaRM: Fast Remote Memory

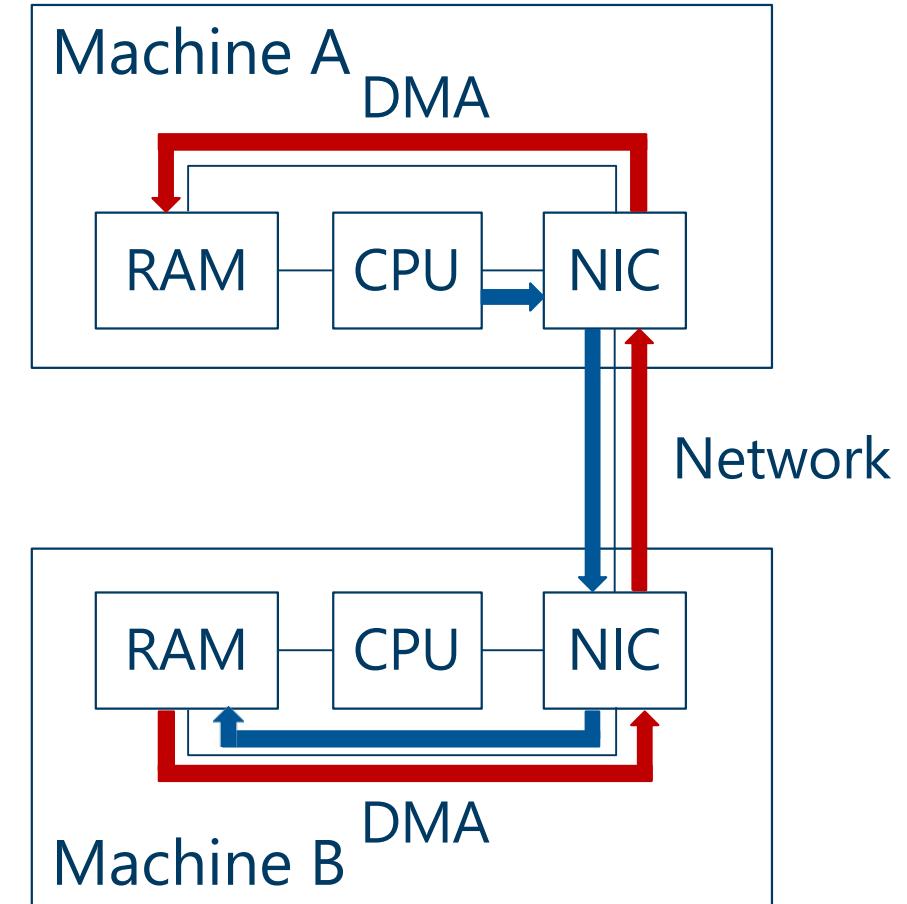
Aleksandar Dragojević, Dushyanth Narayanan,  
Orion Hodson, Miguel Castro

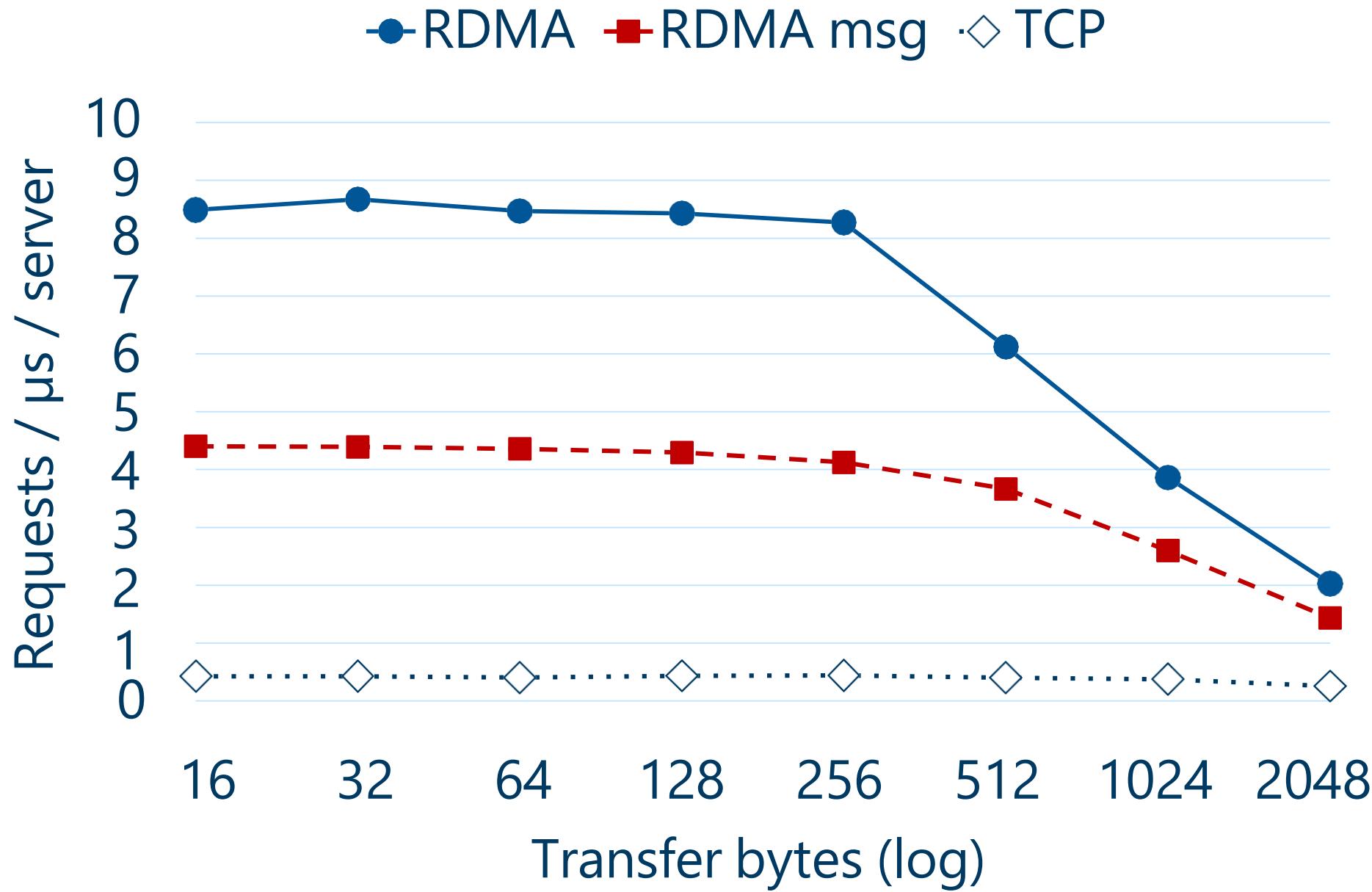
# Hardware trends

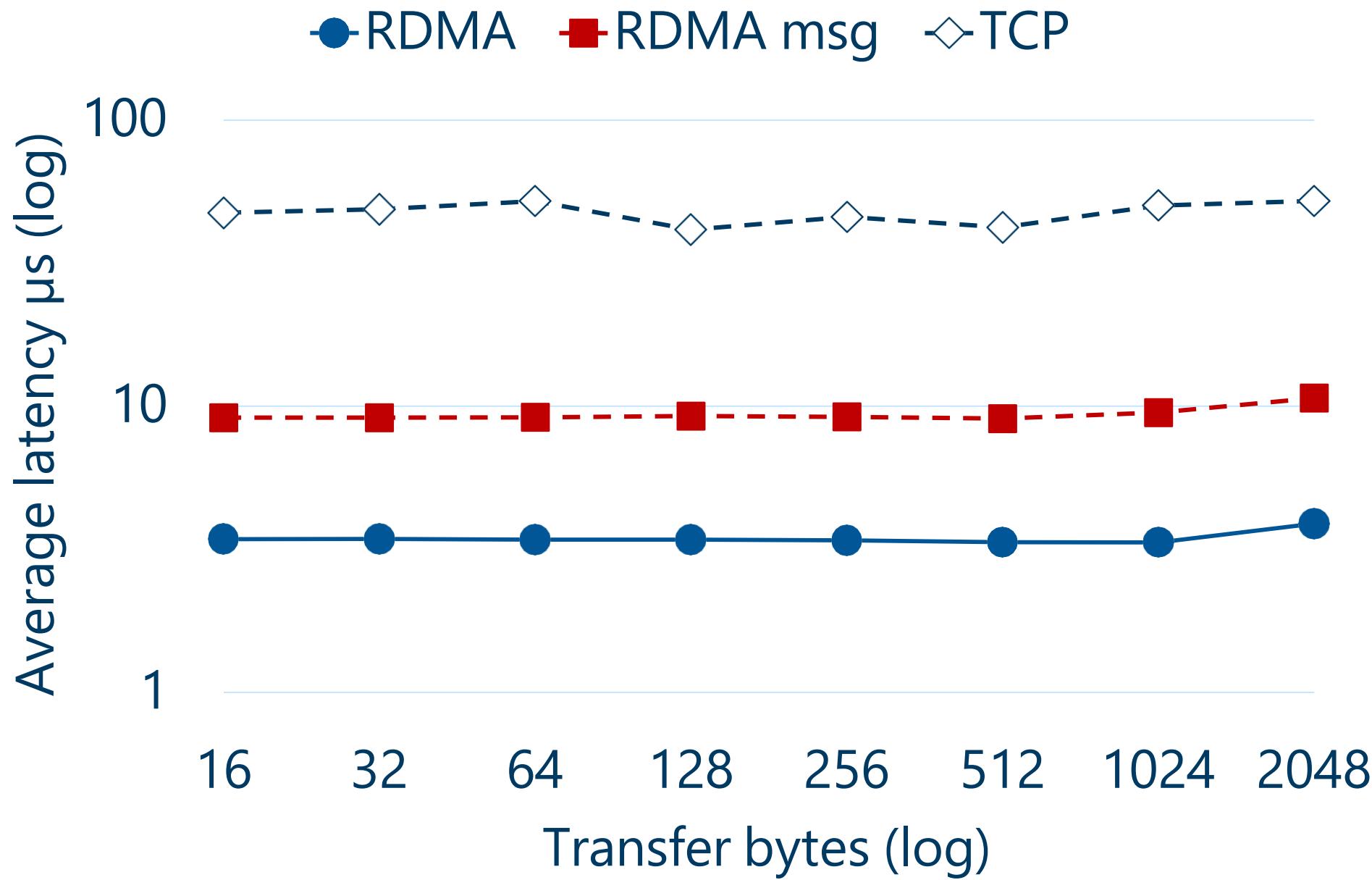
- Main memory is cheap
  - 100 GB – 1 TB per server
  - 10 – 100 TBs in a small cluster
- New data centre networks
  - 40 Gbps throughput (100 this year)
  - 1-3  $\mu$ s latency
  - RDMA primitives

# Remote direct memory access

- Read / write remote memory
  - NIC performs DMA requests
- FaRM uses RDMA extensively
  - Reads to directly read data
  - Writes into remote buffers for messaging
- Great performance
  - Bypasses the kernel
  - Bypasses the remote CPU







# Applications

- Data centre applications
  - Irregular access patterns
  - Latency sensitive
- Data serving
  - Key-value store
  - Graph store
- Enabling new applications

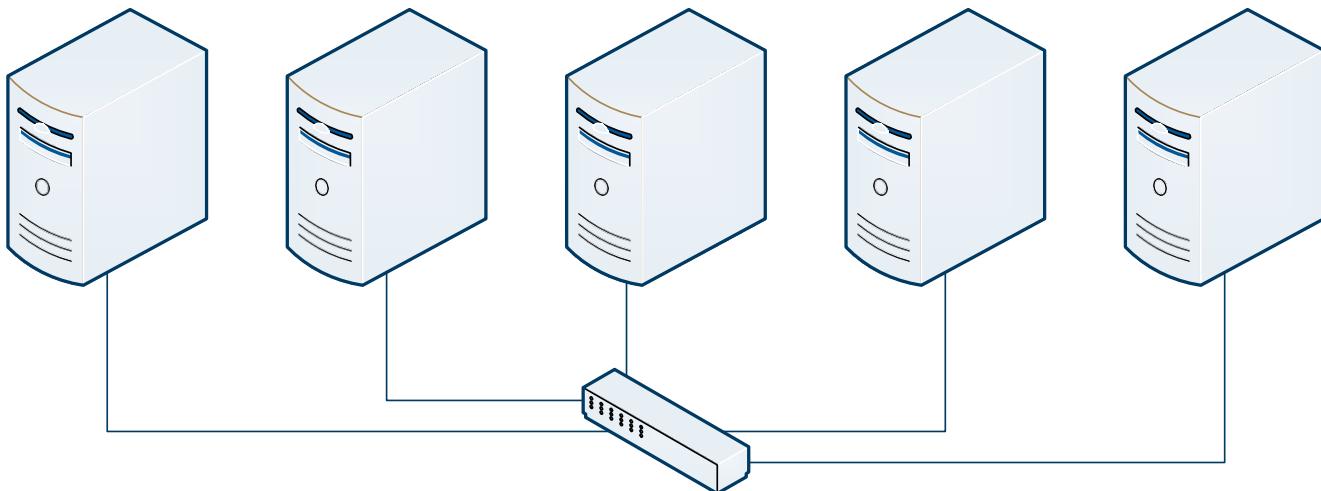
# How to program a modern cluster?

We have:

- TBs of DRAM
- 100s of CPU cores
- RDMA network

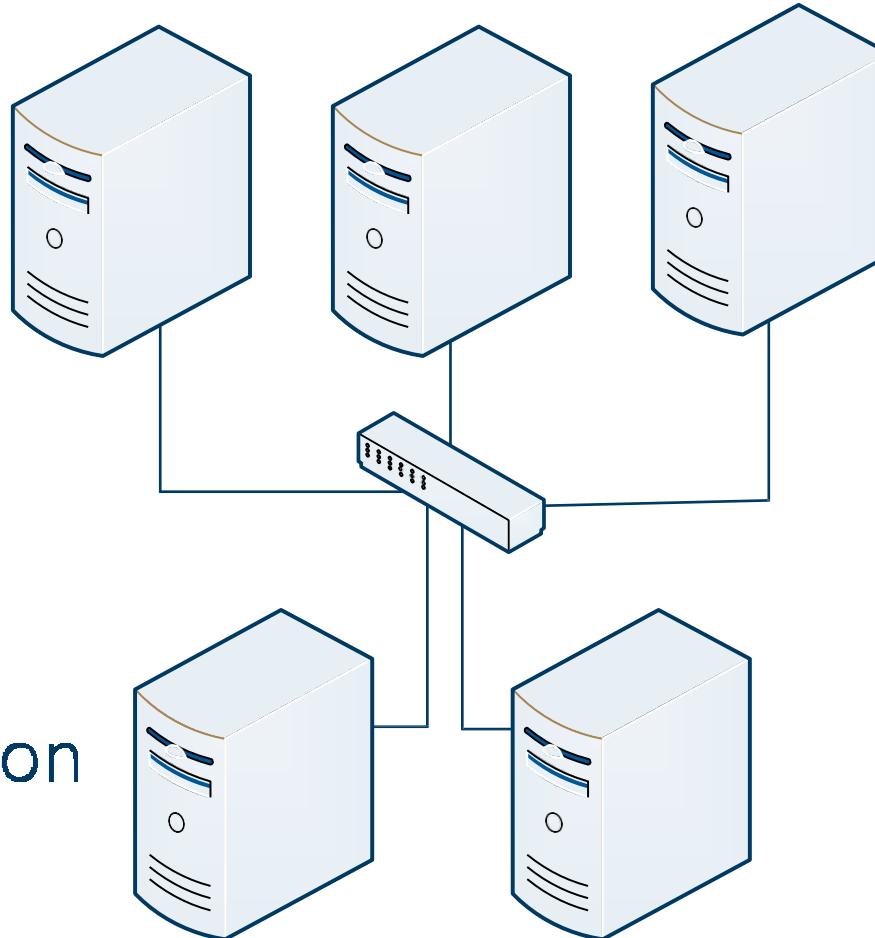
Desirable:

- Keep data in memory
- Access data using RDMA
- Collocate data and computation



# Traditional model

Servers: store data

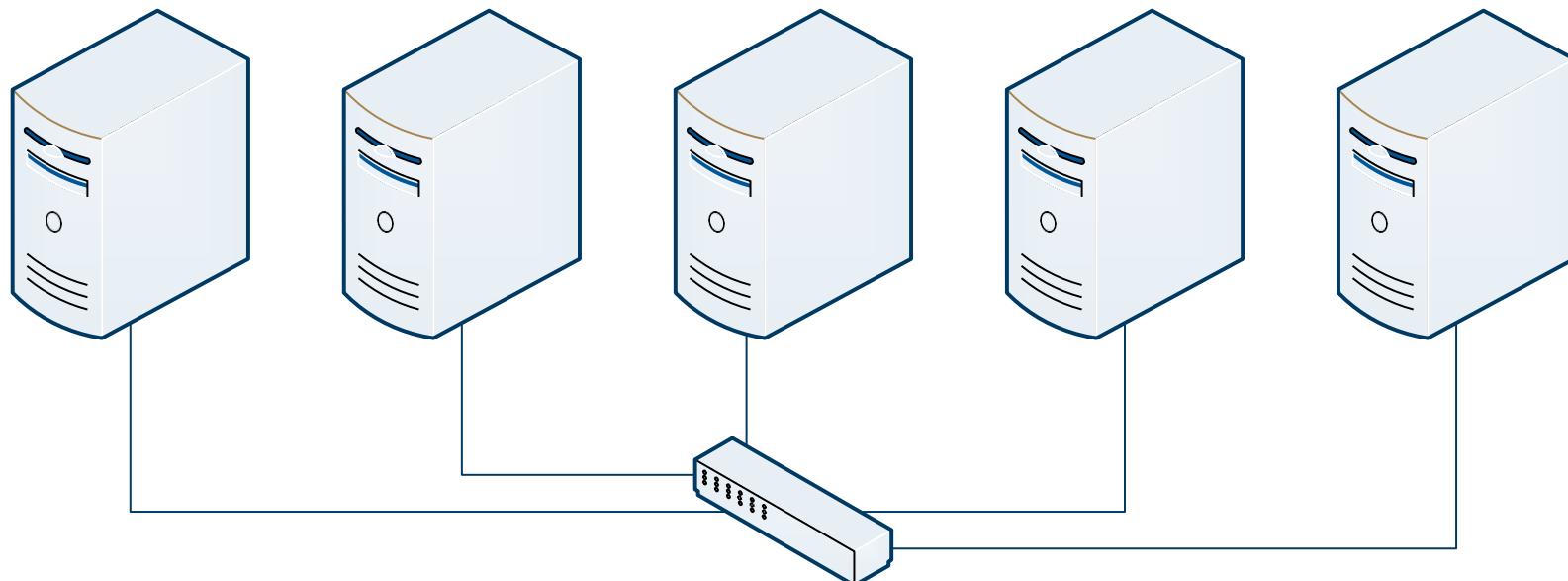


Clients: execute application

# Symmetric model

Access to local  
memory is  
much faster

Server CPUs  
are mostly idle  
with RDMA

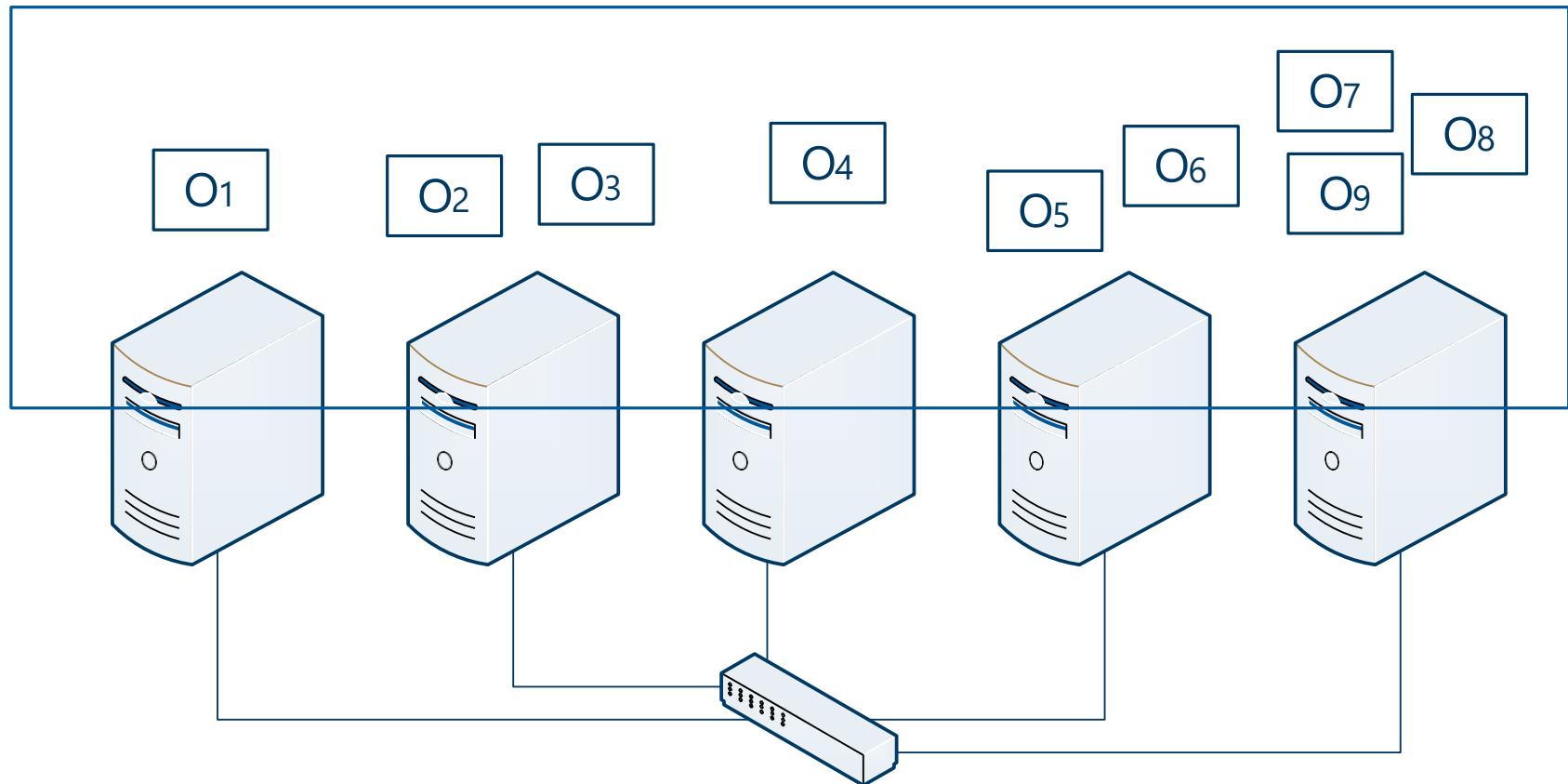


Machines store data and execute application

# Shared address space

Supports direct  
RDMA of objects

Programmability  
a welcome bonus

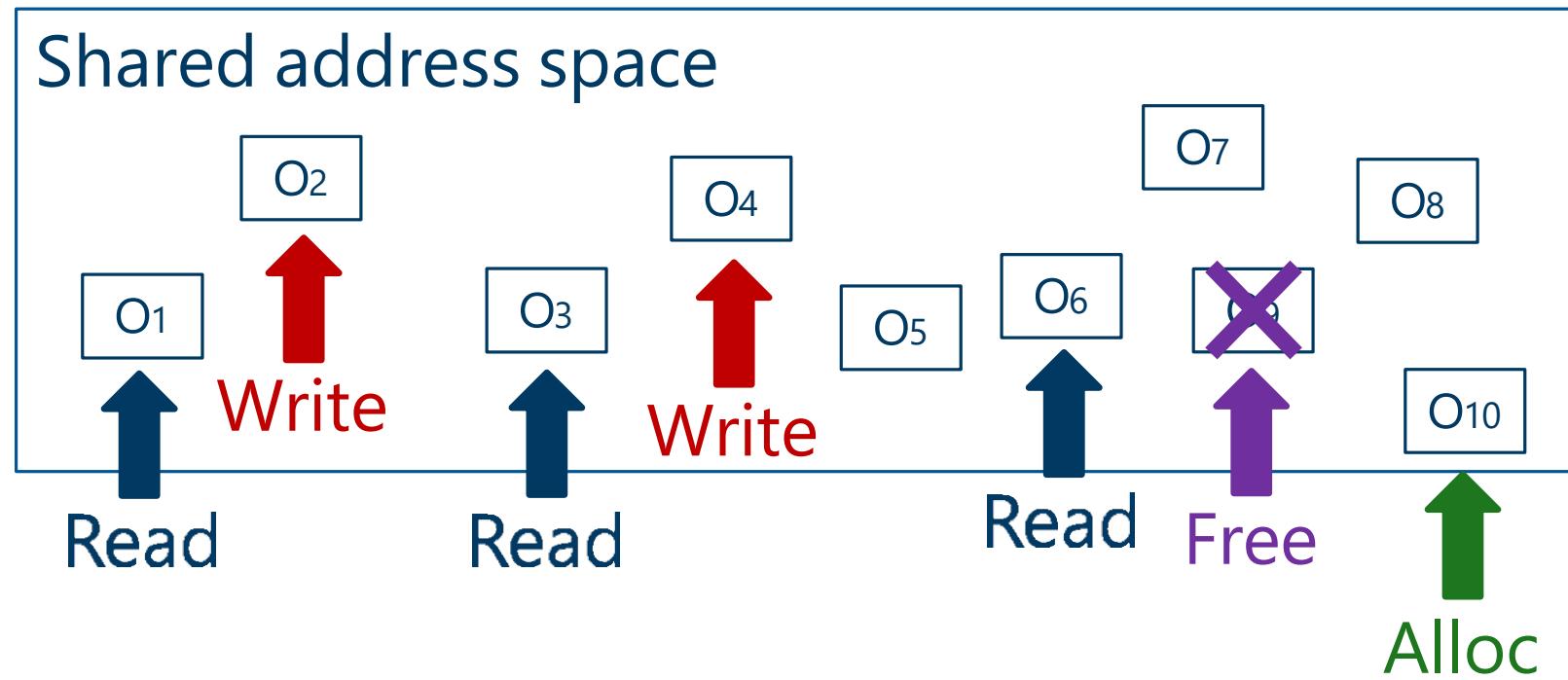


# Shared address space

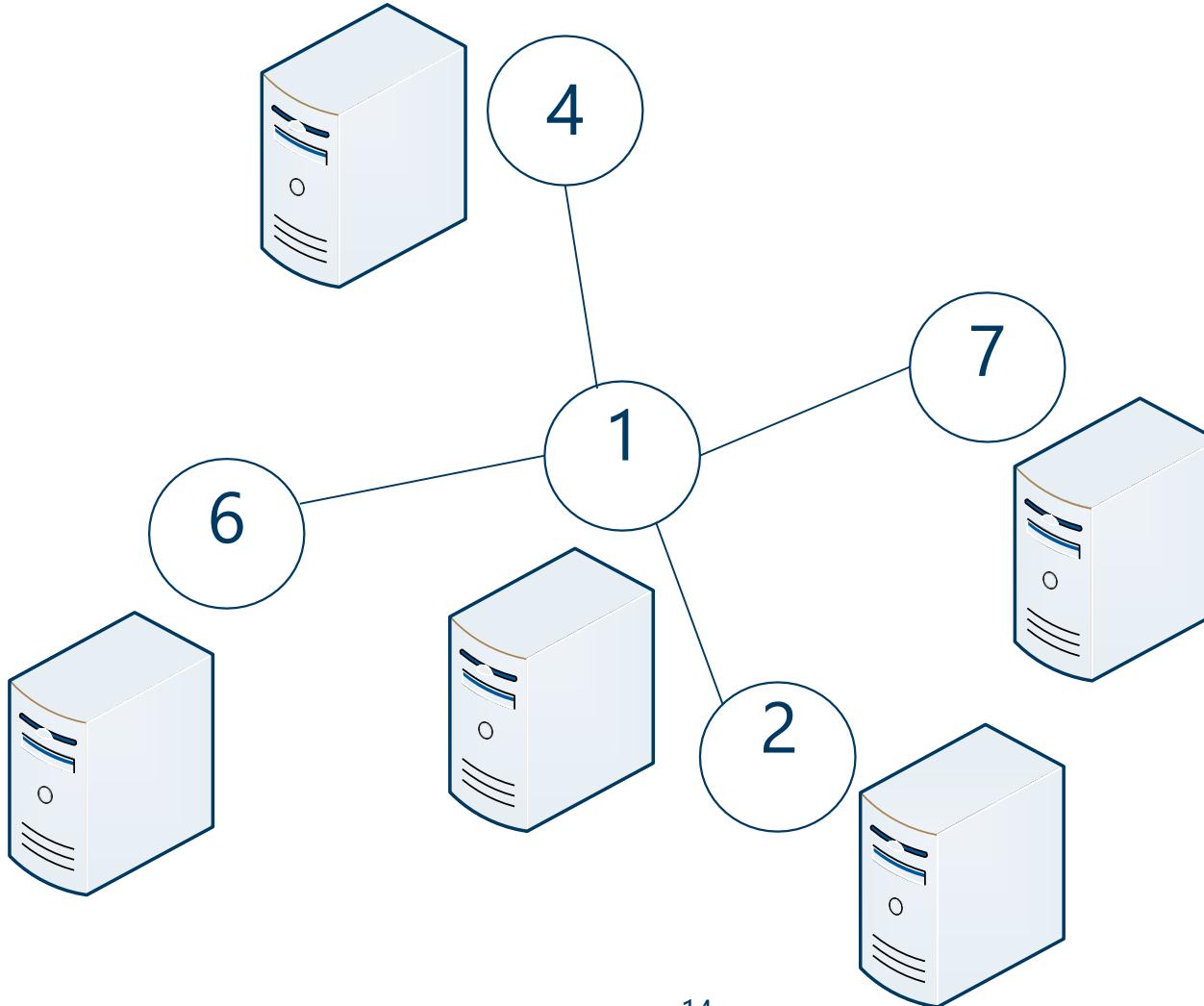
General primitive

Strong consistency:  
serializability

Transparent:  
• location  
• concurrency  
• failures



# Optimizations: locality awareness

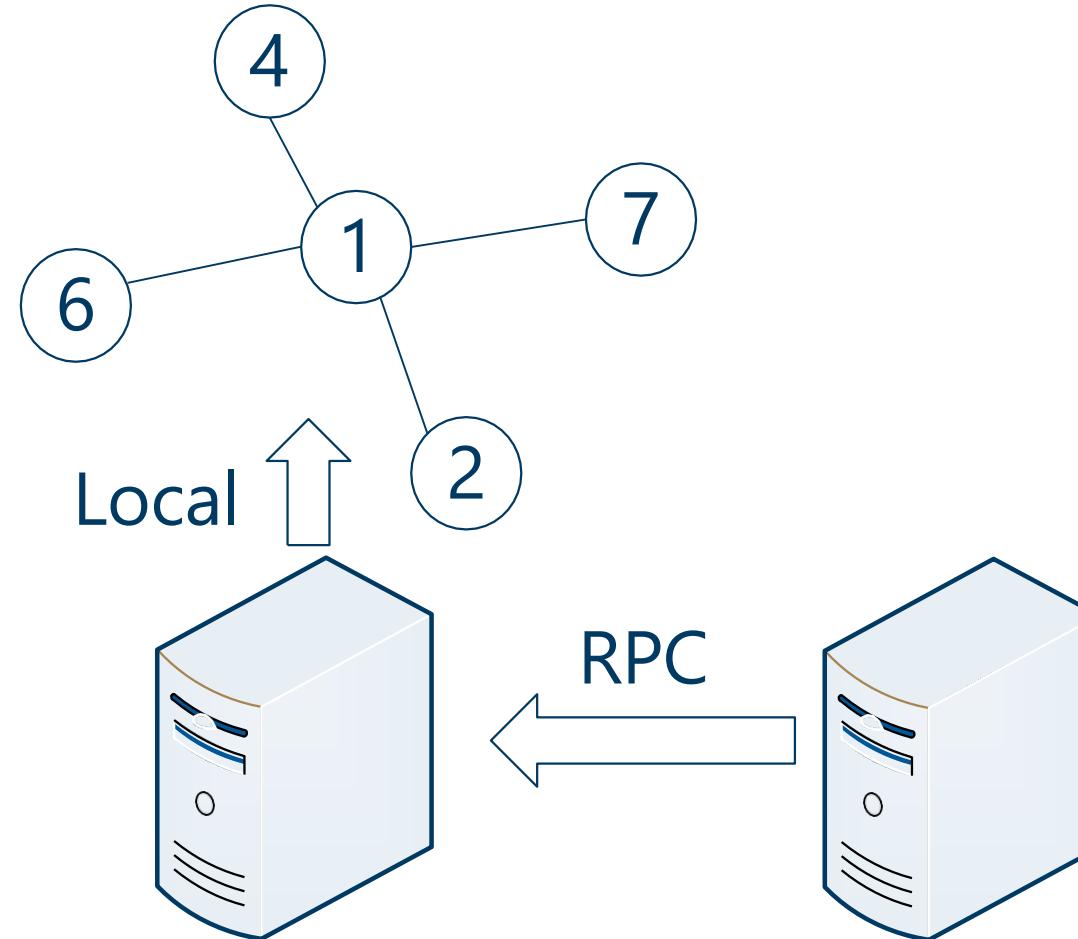


# Optimizations: locality awareness

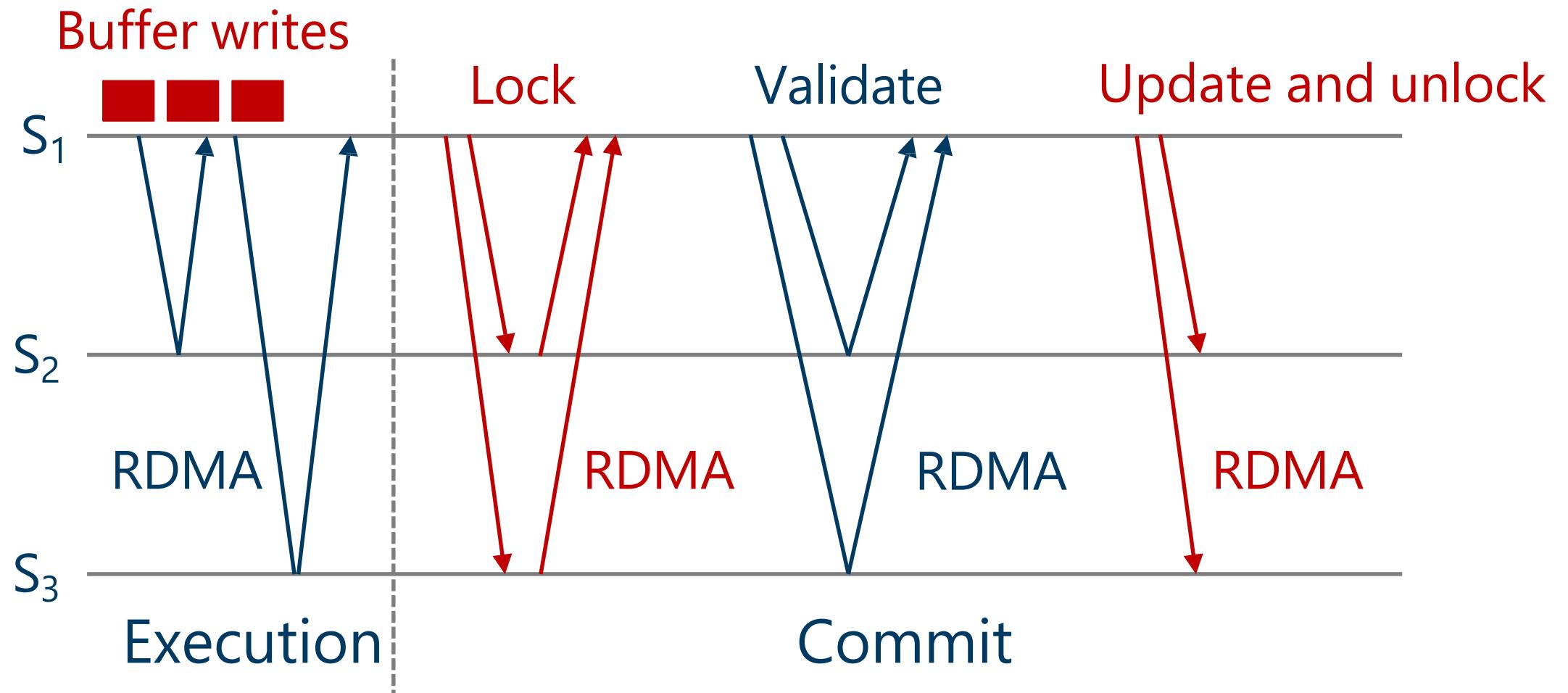
Collocate data accessed together

Ship computation to target data

Optimized single server transactions



# Transactions



# TAO [Bronson '13, Armstrong '13]

- Facebook's in-memory graph store
  - Workload
    - Read-dominated (99.8%)
    - 10 operation types
  - FaRM implementation
    - Nodes and edges are FaRM objects
    - Lock-free reads for lookups
    - Transactions for updates
- 6 Mops/s/srv  
(10x improvement)
- 42  $\mu$ s average latency  
(40 – 50x improvement)

# FaRM

- Platform for distributed computing
  - Data is in memory
  - RDMA
- Shared memory abstraction
  - Transactions
  - Lock-free reads
- Order-of-magnitude performance improvements
  - Enables new applications

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  - NSDI'23 TGS

# **Efficient Memory Disaggregation with Infiniswap**

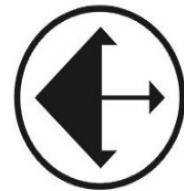
**Juncheng Gu, Youngmoon Lee, Yiwen Zhang,  
Mosharaf Chowdhury, Kang G. Shin**



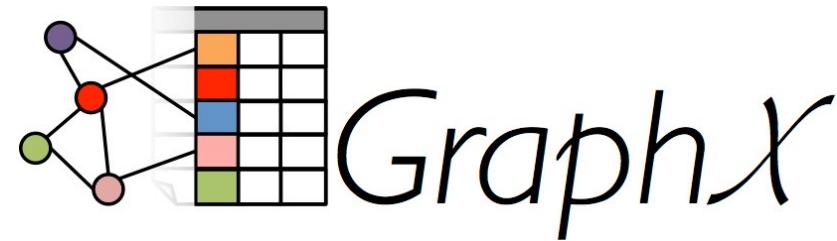
# Agenda

- Motivation and related work
- Design and system overview
- Implementation and evaluation
- Future work and conclusion

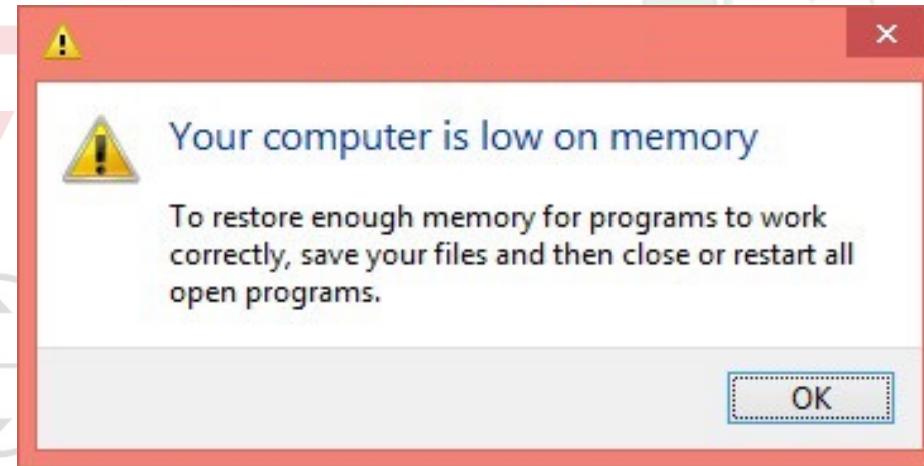
# Memory-intensive applications



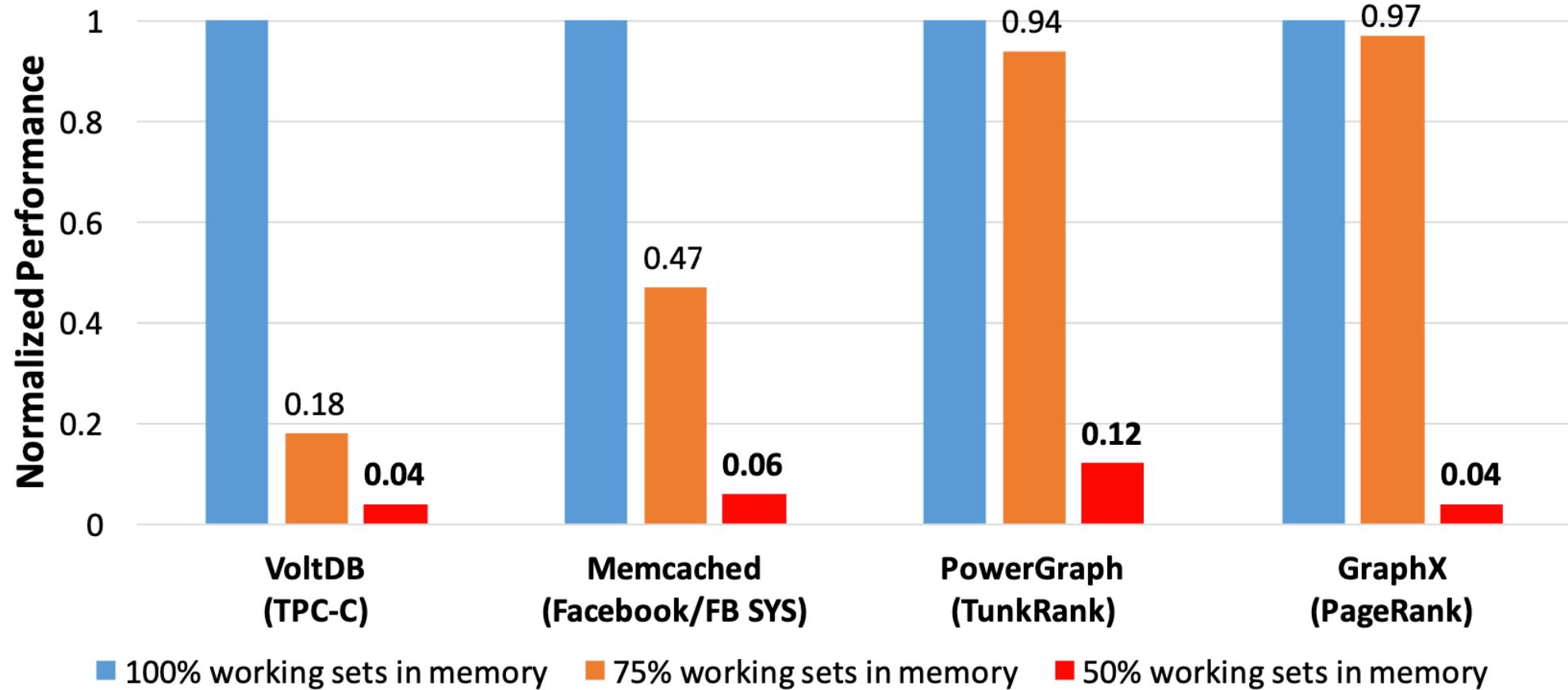
**powergraph**



# Memory-intensive applications

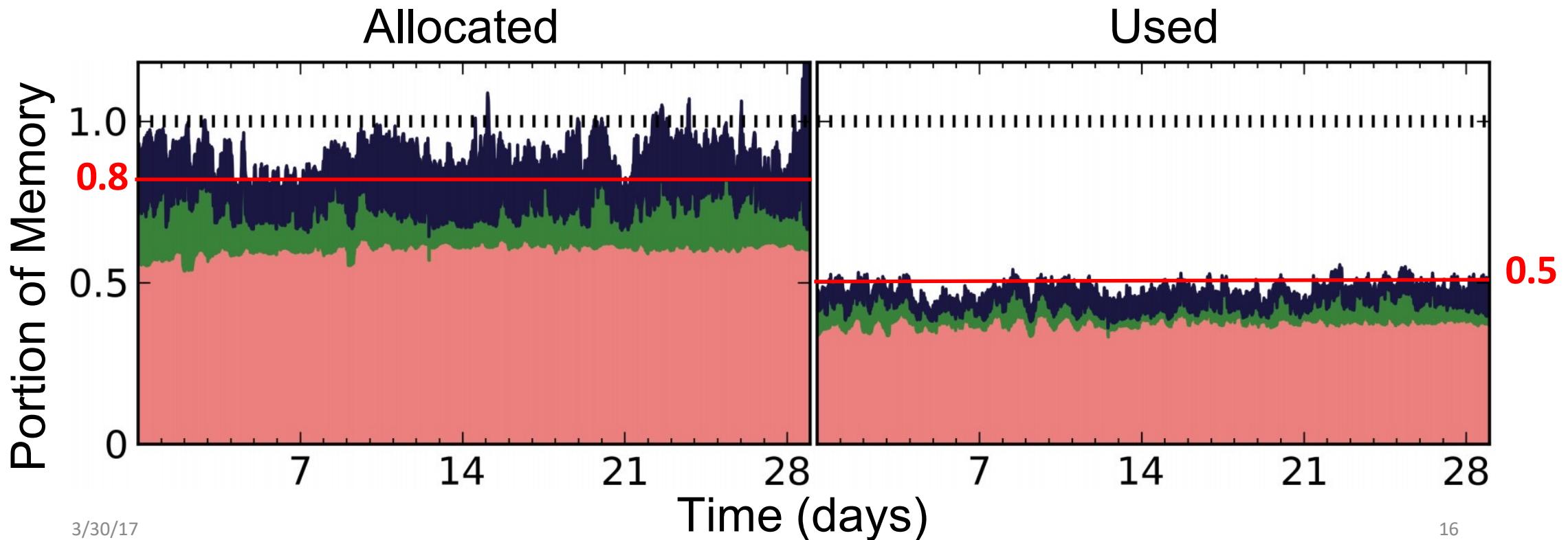


# Performance degradation



# Memory underutilization

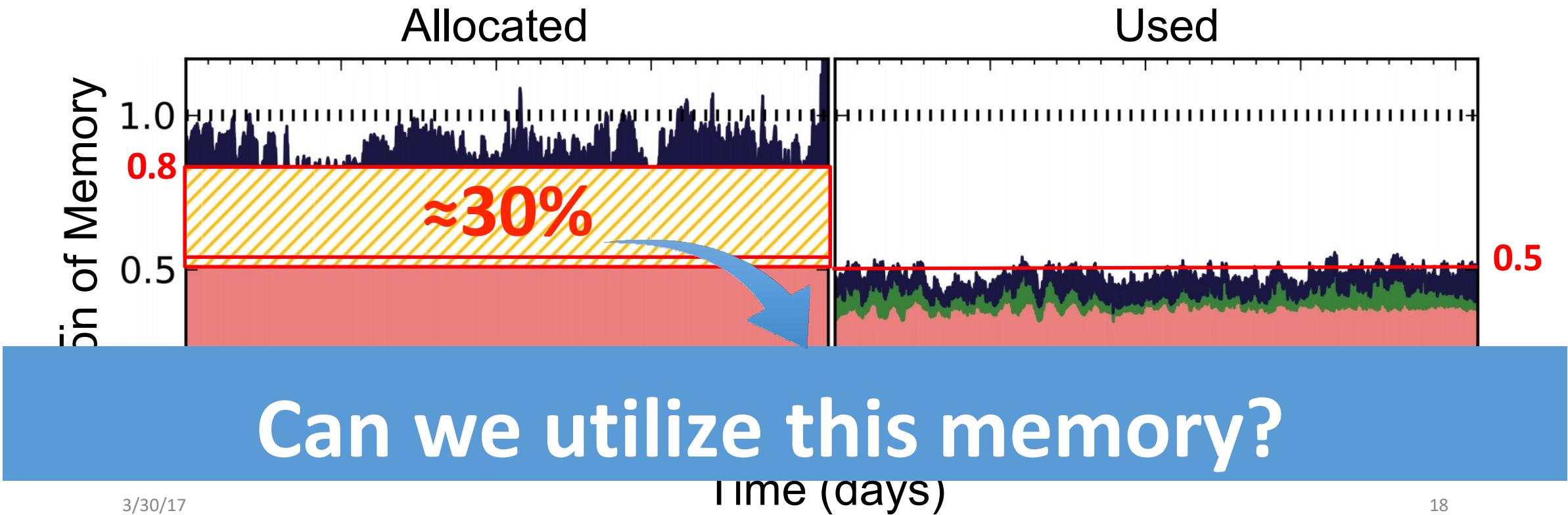
- Google Cluster Analysis<sub>[1]</sub>



[1] Reiss, Charles, et al. "Heterogeneity and dynamicity of clouds at scale: Google trace analysis." *SoCC'12*.

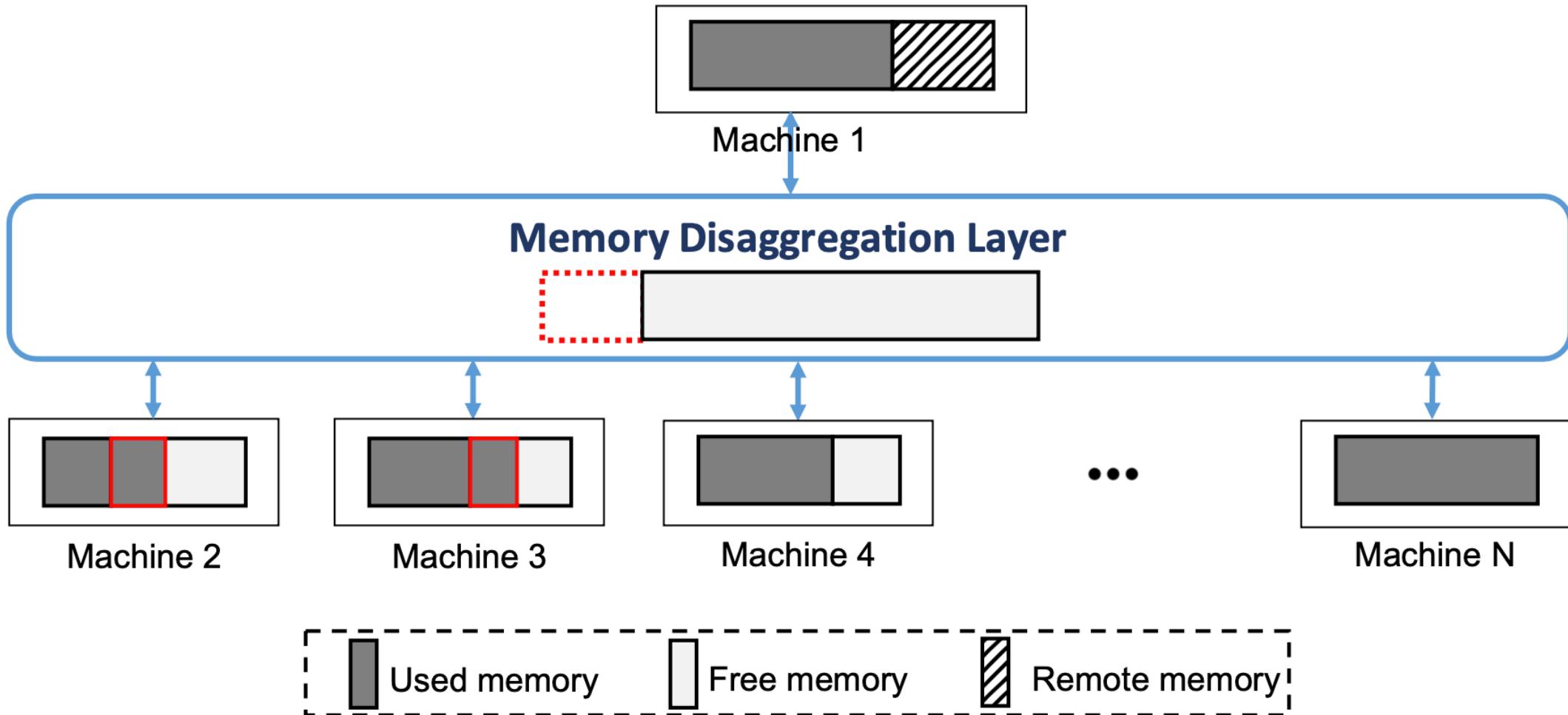
# Memory underutilization

- Google Cluster Analysis<sup>[1]</sup>



[1] Reiss, Charles, et al. "Heterogeneity and dynamicity of clouds at scale: Google trace analysis." *SoCC'12*.

# Disaggregate free memory



# What are the challenges?

- **Minimize deployment overhead**
  - No hardware design
  - No application modification
- **Tolerate failures**
  - e.g. network disconnection, machine crash
- **Manage remote memory at scale**

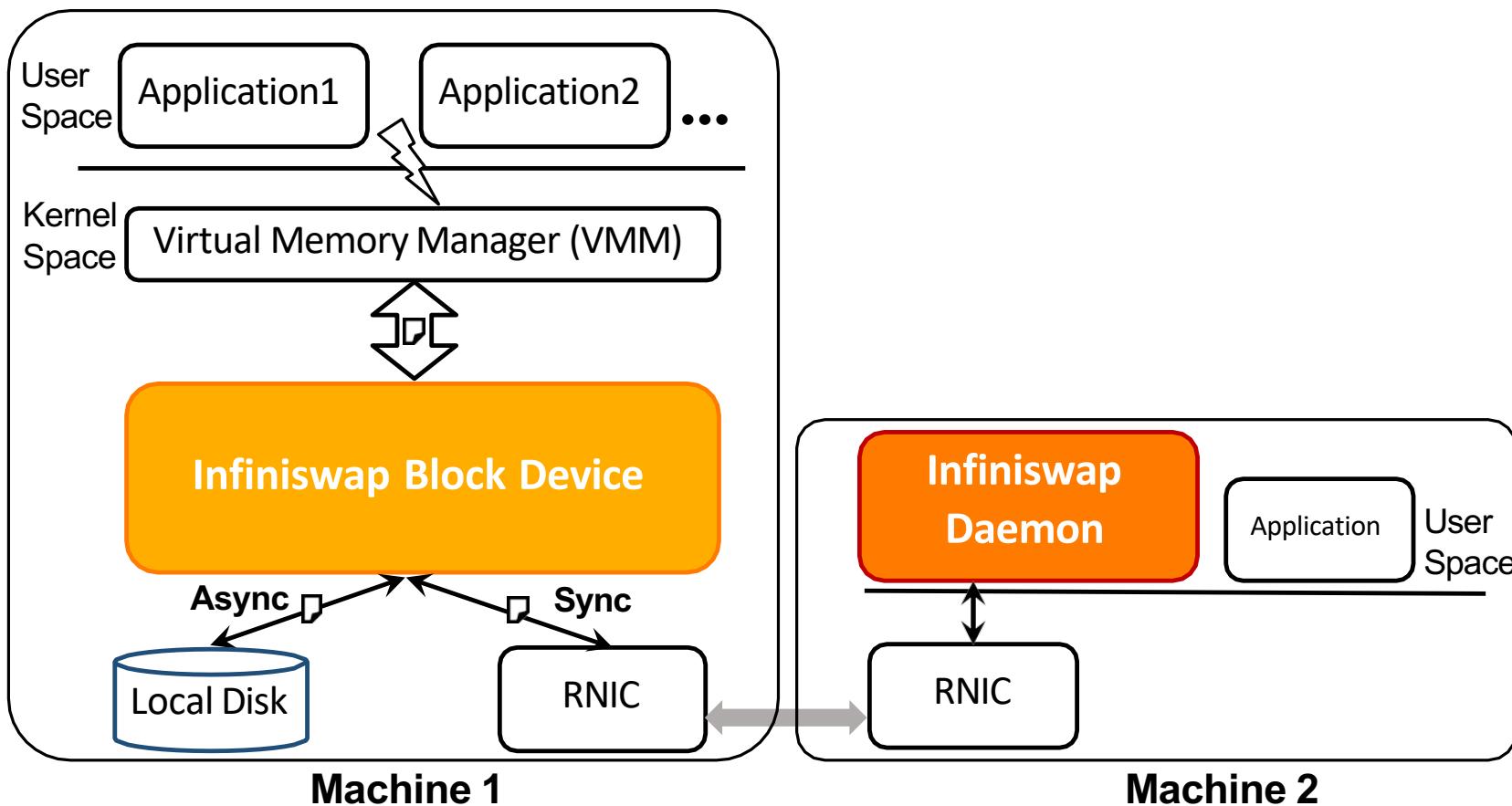
# Recent work on memory disaggregation

|   | No HW design | No app modification | Fault-tolerance | Scalability |
|---|--------------|---------------------|-----------------|-------------|
| <b>Memory Blade</b> [ISCA'09]   | ✗            | ✓                   | ✓               | ✓           |
| <b>HPBD</b> [CLUSTER'05] / <b>NBDX</b> <sup>[1]</sup>                   | ✓            | ✓                   | ✗               | ✗           |
| <b>RDMA key-value service</b><br>(e.g. HERD[SIGCOMM'14], FaRM[NSDI'14]) | ✓            | ✗                   | ✓               | ✓           |
| <b>Intel Rack Scale Architecture (RSA)</b> <sup>[2]</sup>               | ✗            | ✓                   | ✓               | ✓           |
| <b>Infiniswap</b>   | ✓            | ✓                   | ✓               | ✓           |

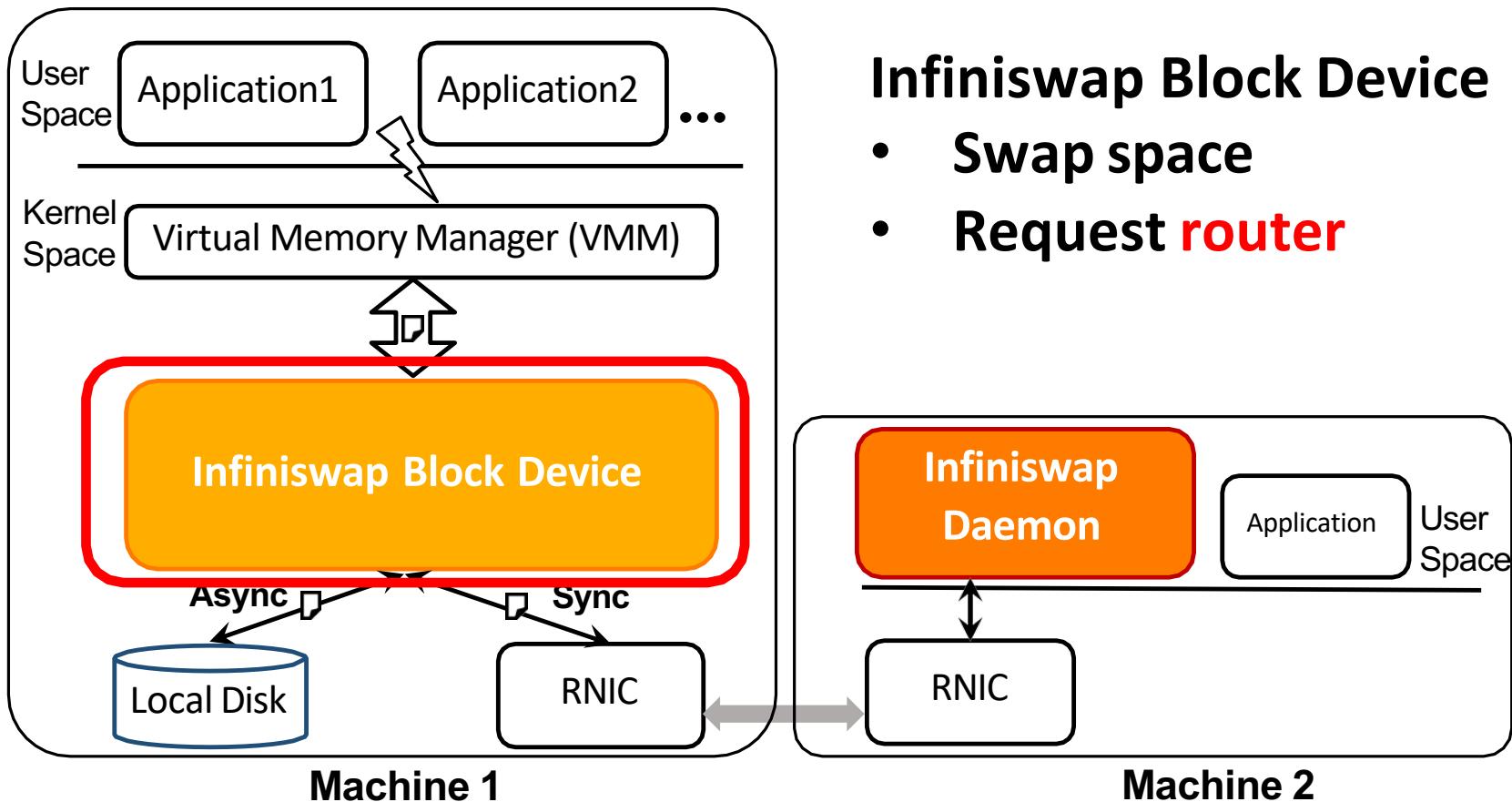
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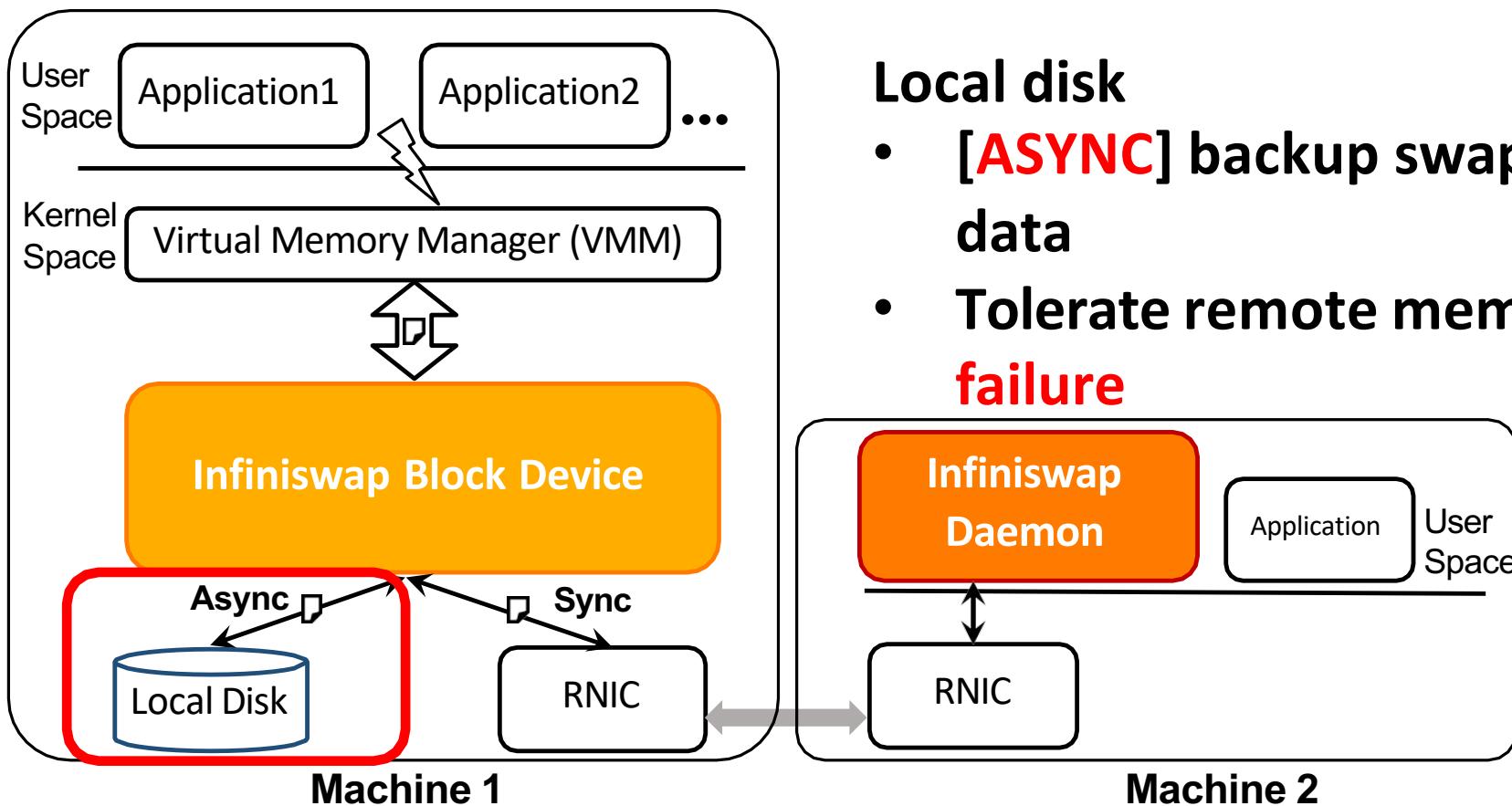
# System Overview



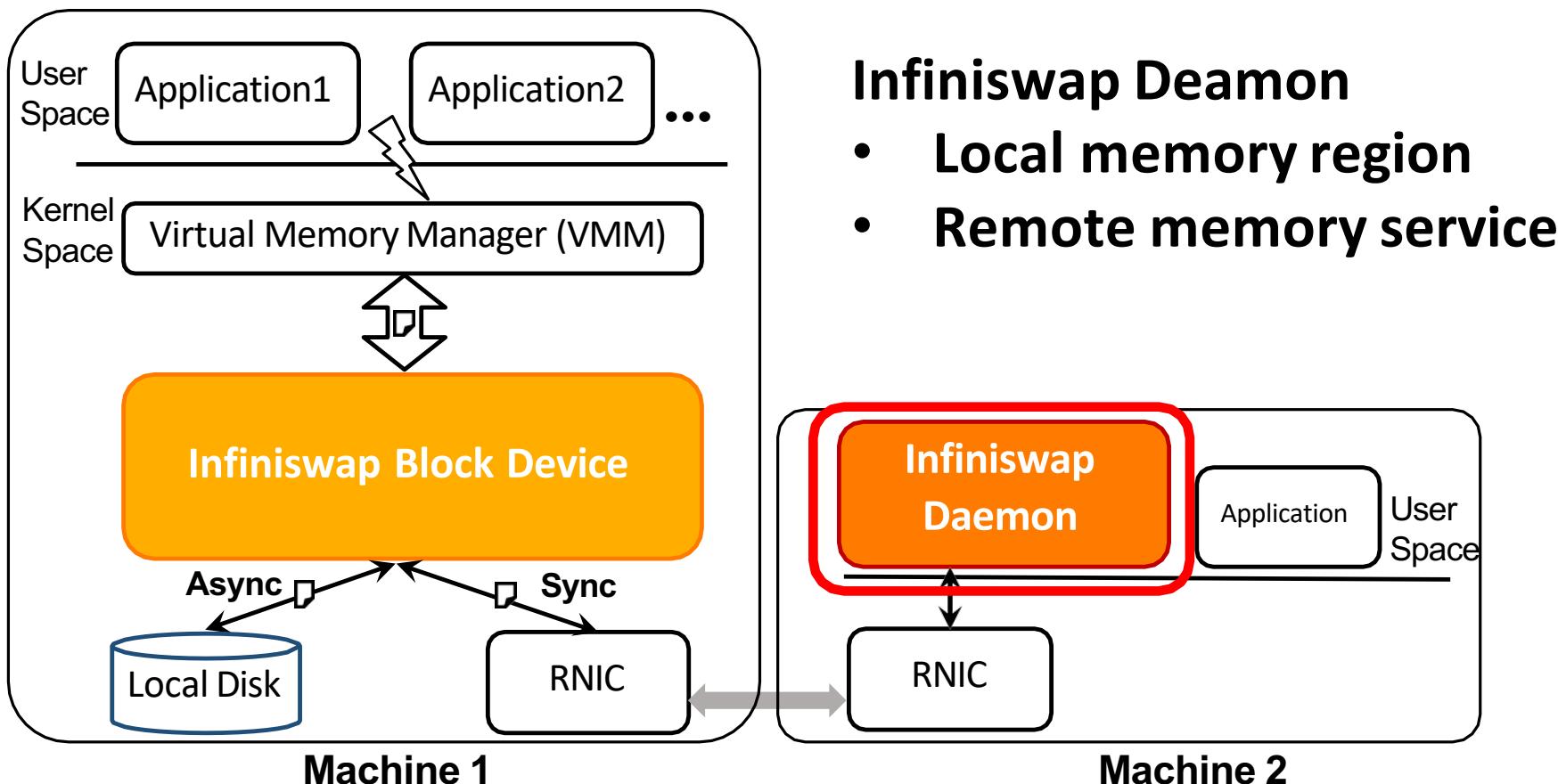
# System Overview



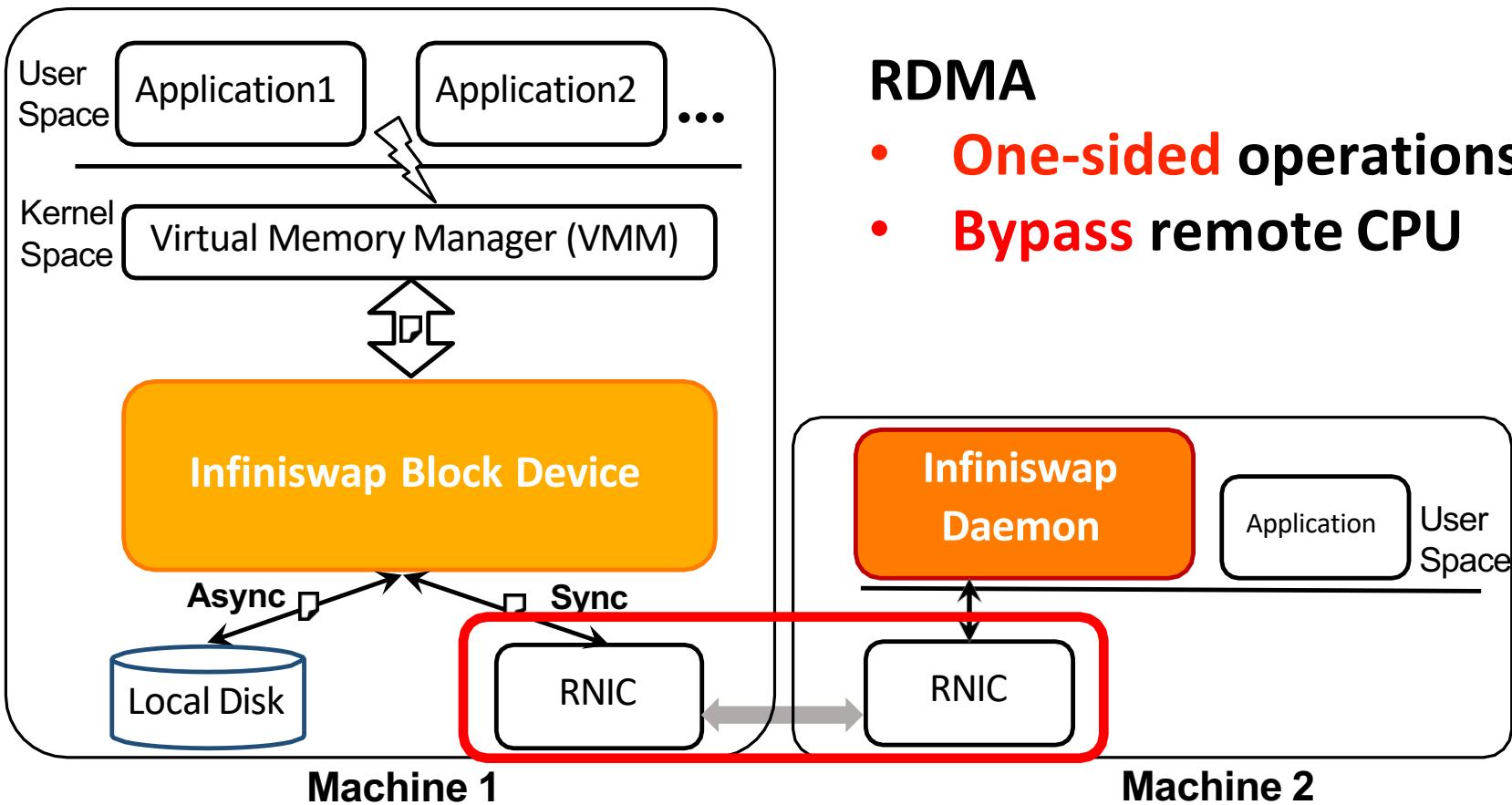
# System Overview



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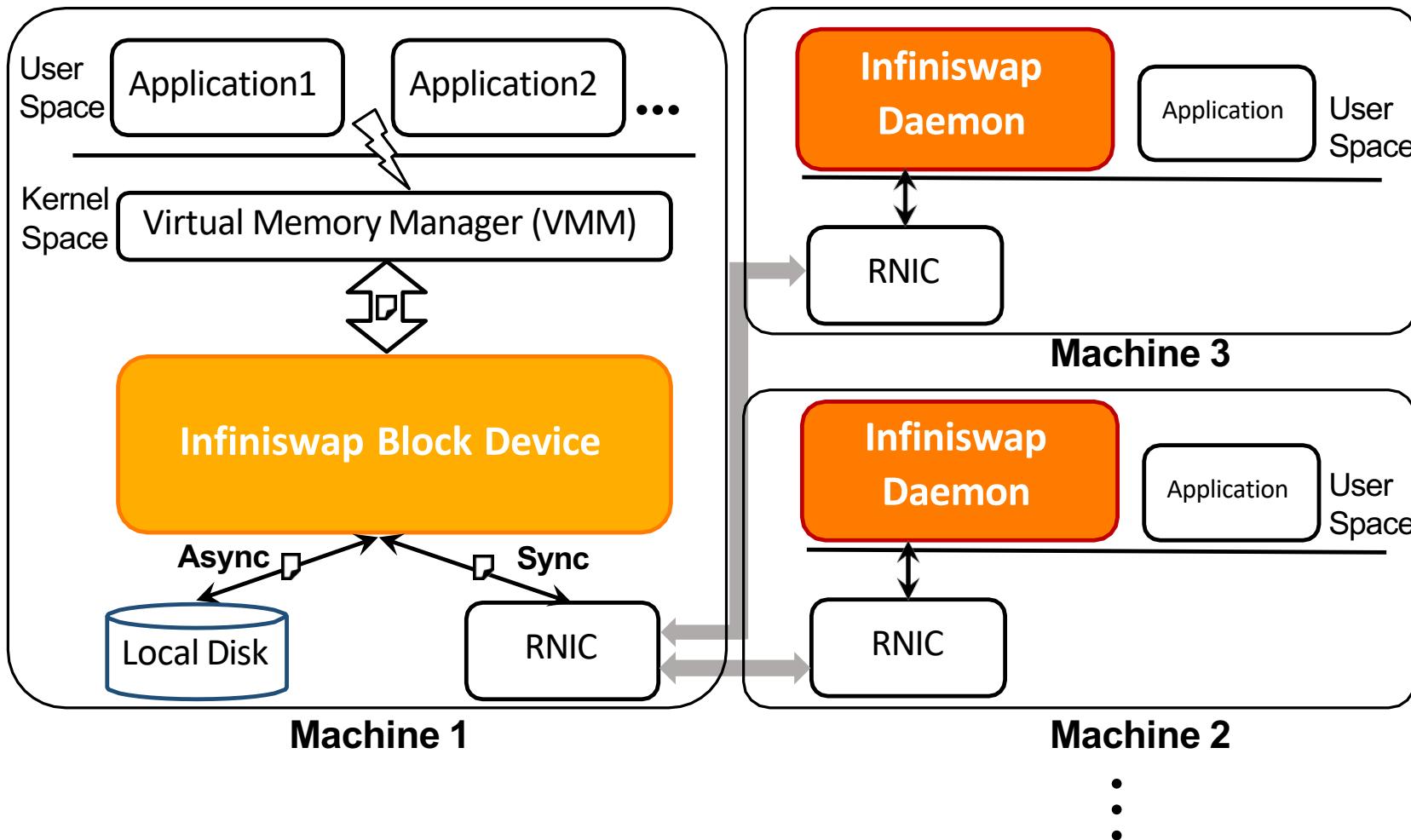
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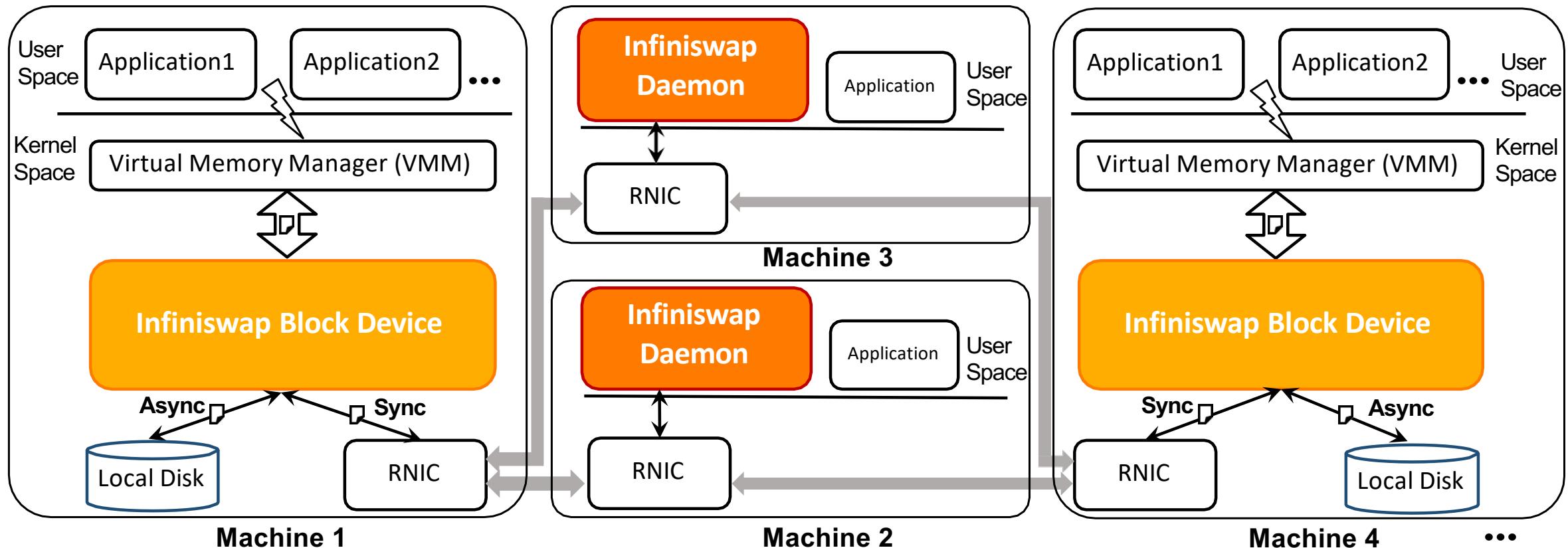
# How to meet the design objectives?

| Objectives                         | Ideas             |
|------------------------------------|-------------------|
| <b>No hardware design</b>          | Remote paging     |
| <b>No application modification</b> |                   |
| <b>Fault-tolerance</b>             | Local backup disk |

# One-to-many



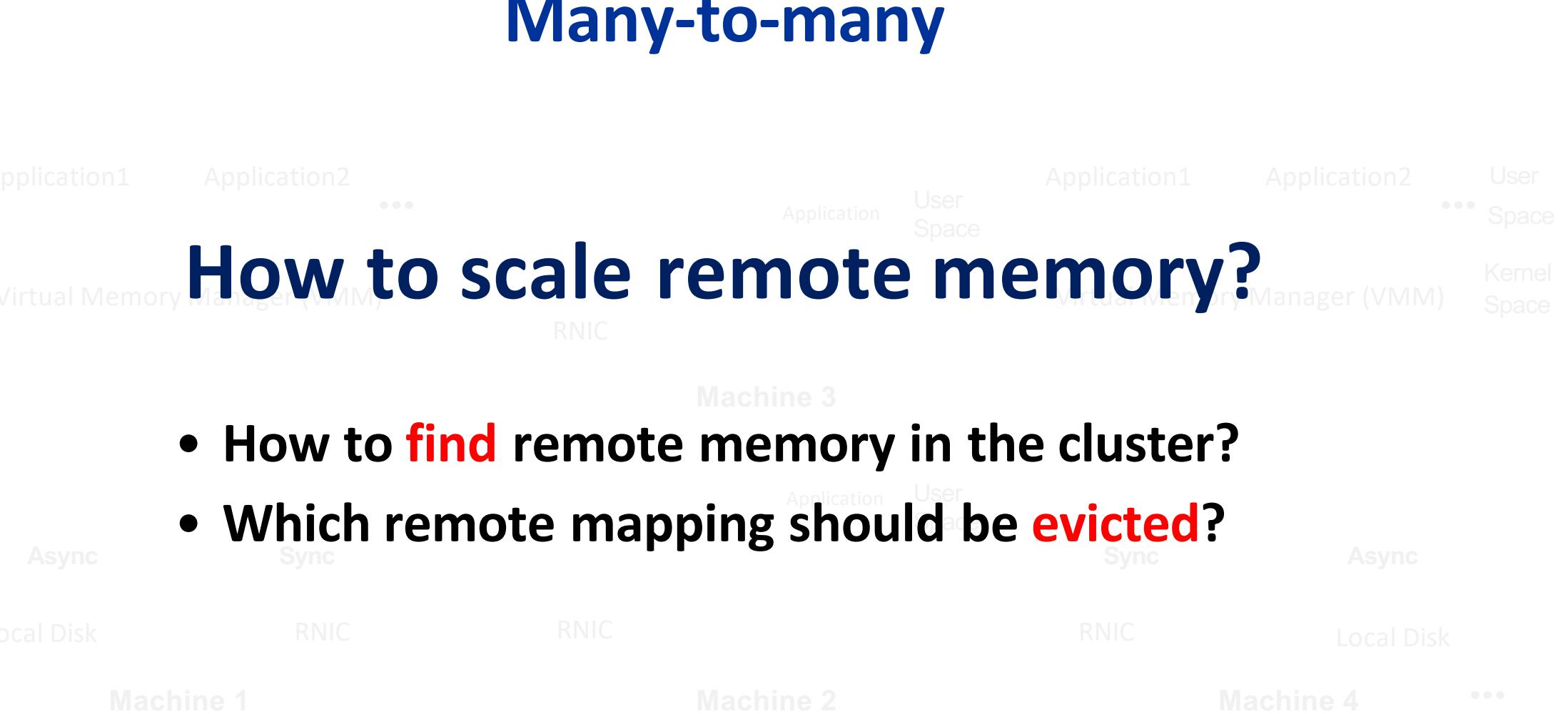
# Many-to-many



# Many-to-many

## How to scale remote memory?

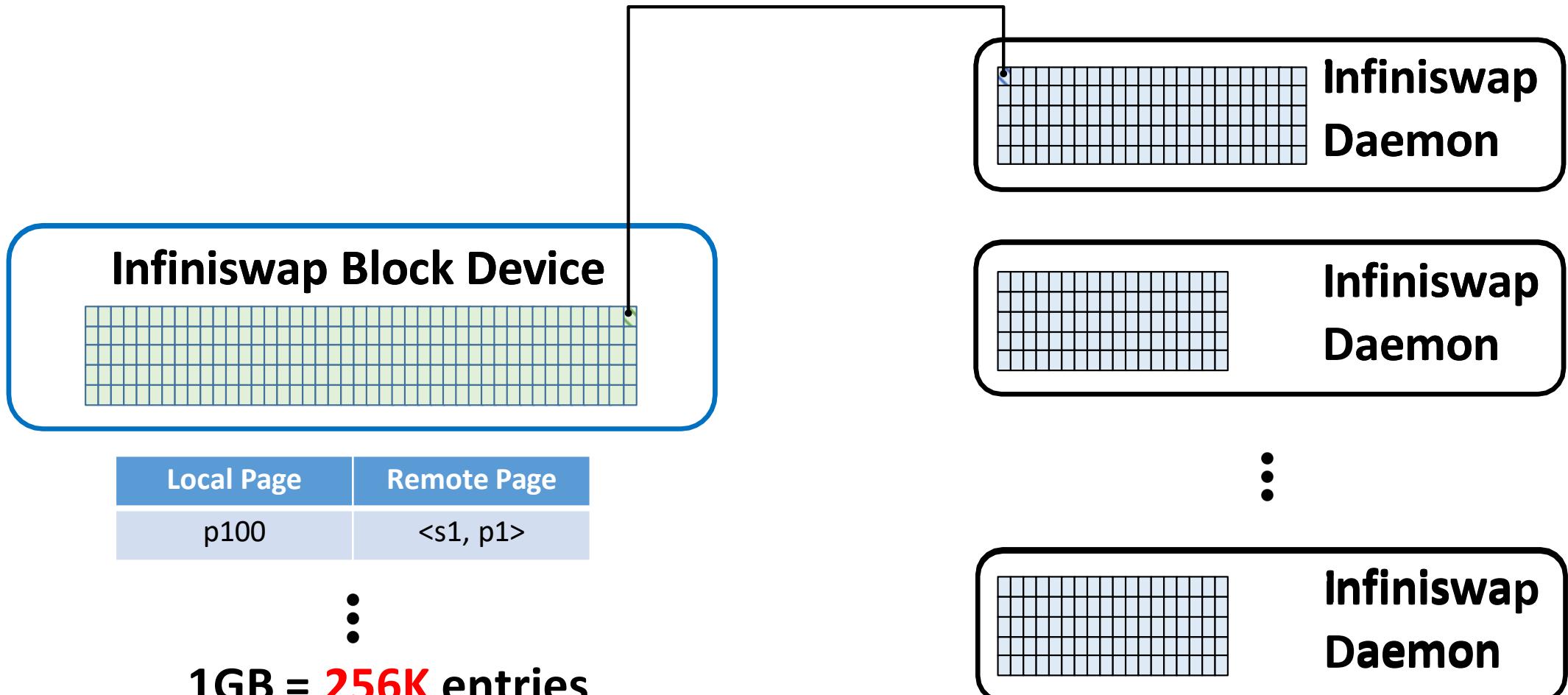
- How to **find** remote memory in the cluster?
- Which remote mapping should be **evicted**?



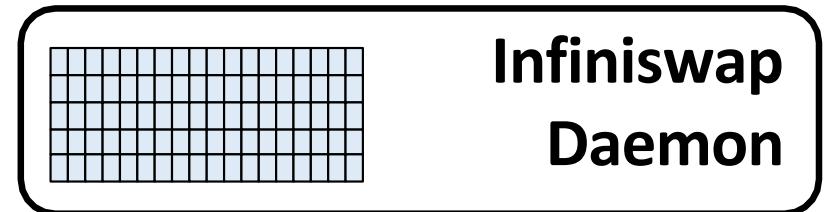
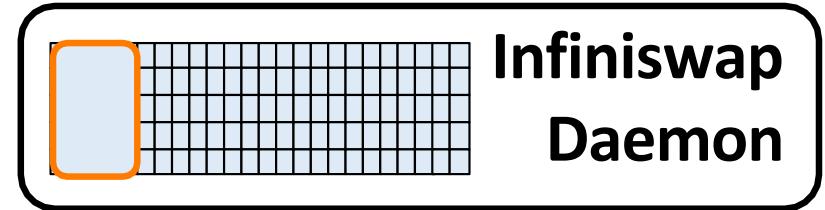
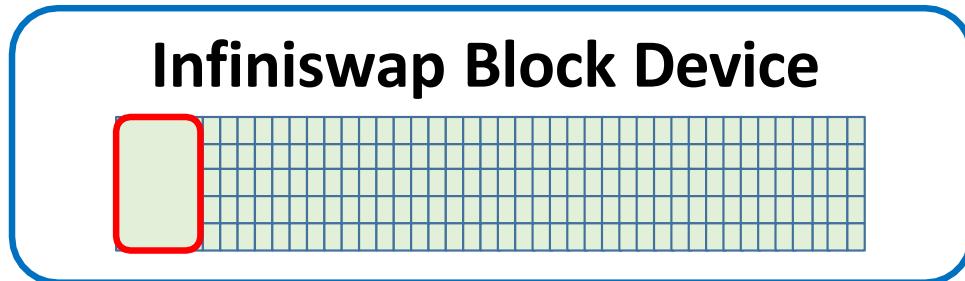
# How to meet the design objectives?

| Objectives                  | Ideas   |
|-----------------------------|---|
| No hardware design          | Remote paging                                 |
| No application modification | Local backup disk                             |
| Fault-tolerance             |   |
| <b>Scalability</b>          | <b>Decentralized remote memory management</b> |

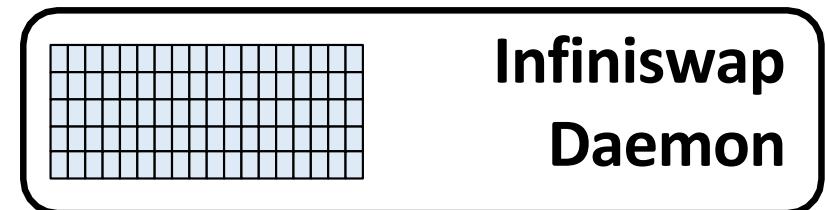
# Management unit: memory page?



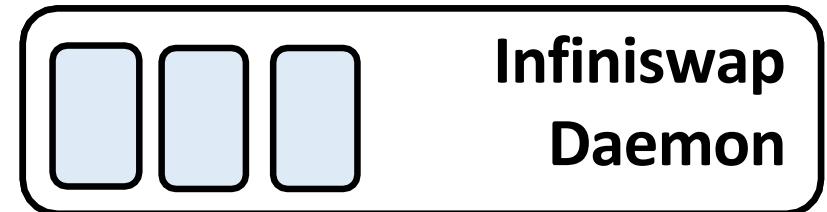
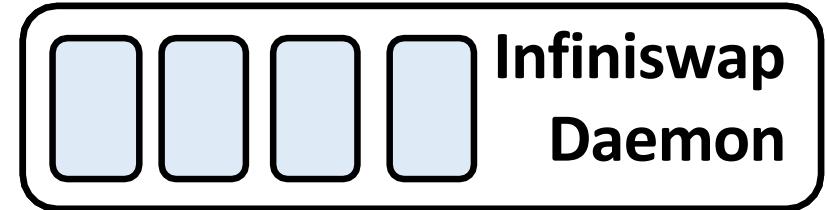
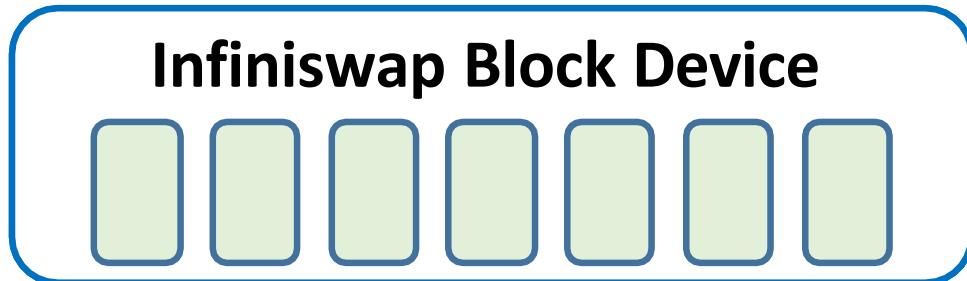
# Management unit: memory slab!



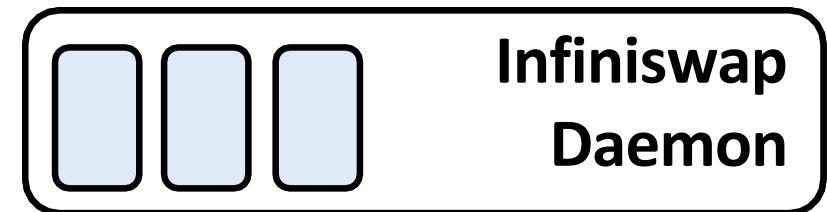
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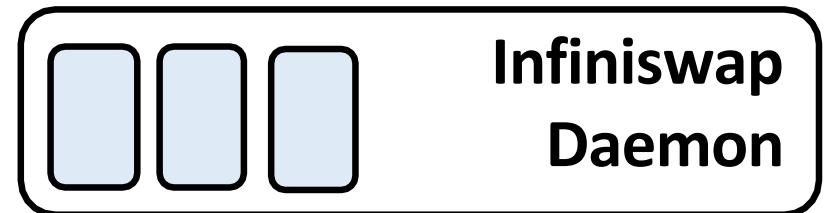
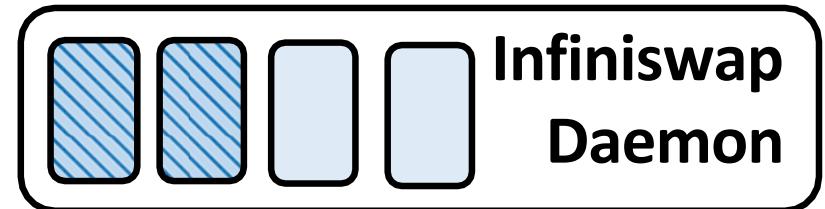
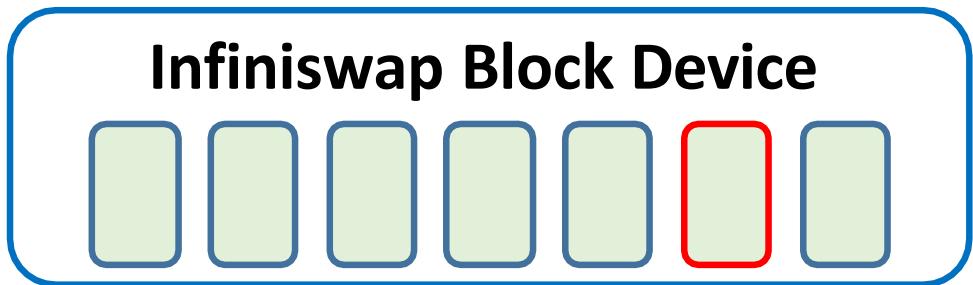
# Management unit: memory slab!



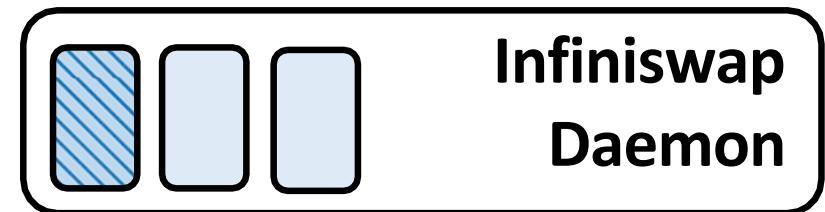
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# Which remote machine should be selected?

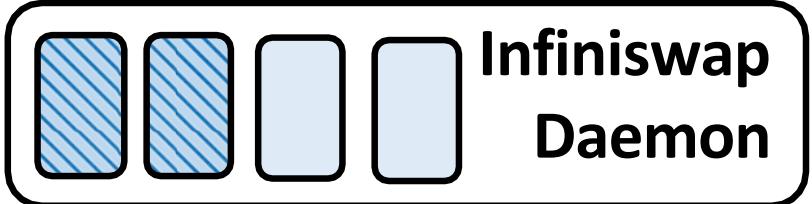
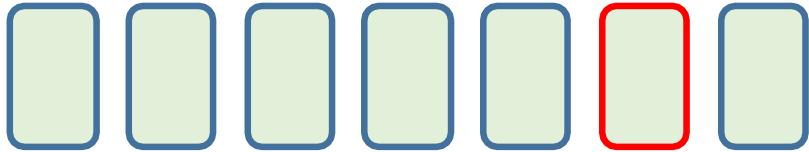


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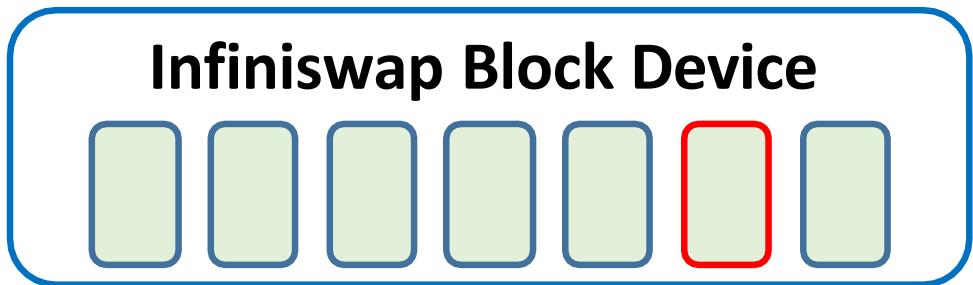
Infiniswap Block Device



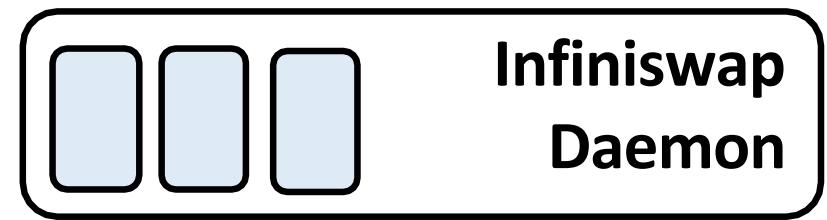
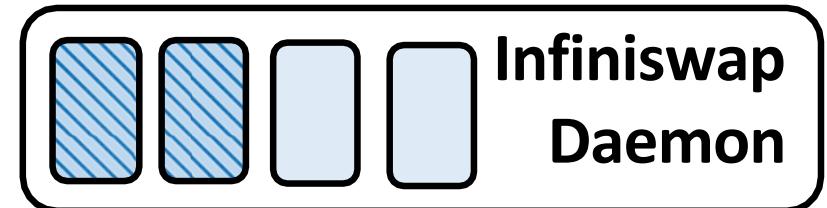
⋮

Goal: **balance** memory utilization

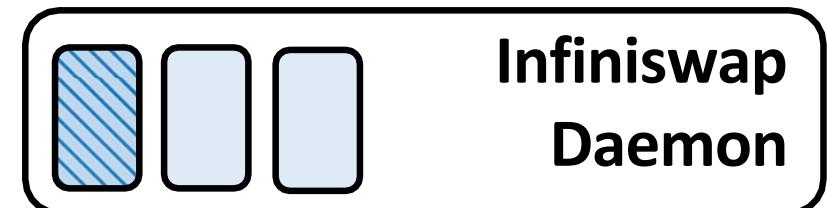
# Which remote machine should be selected?



► Central controller

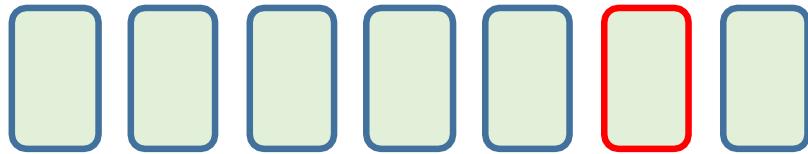


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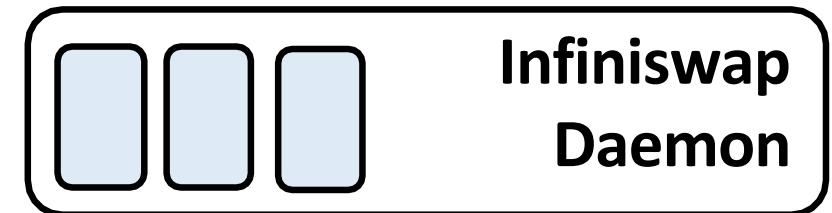
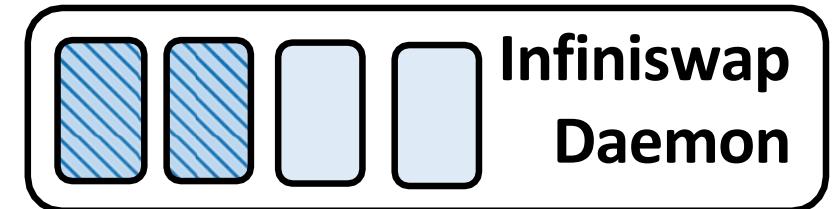


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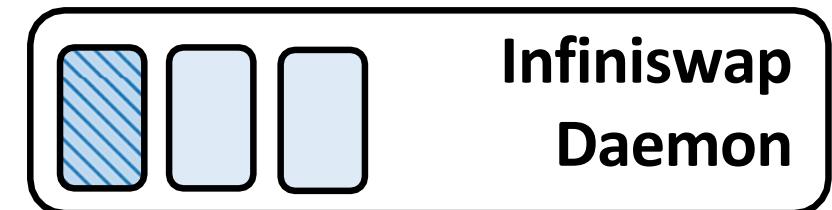
Infiniswap Block Device



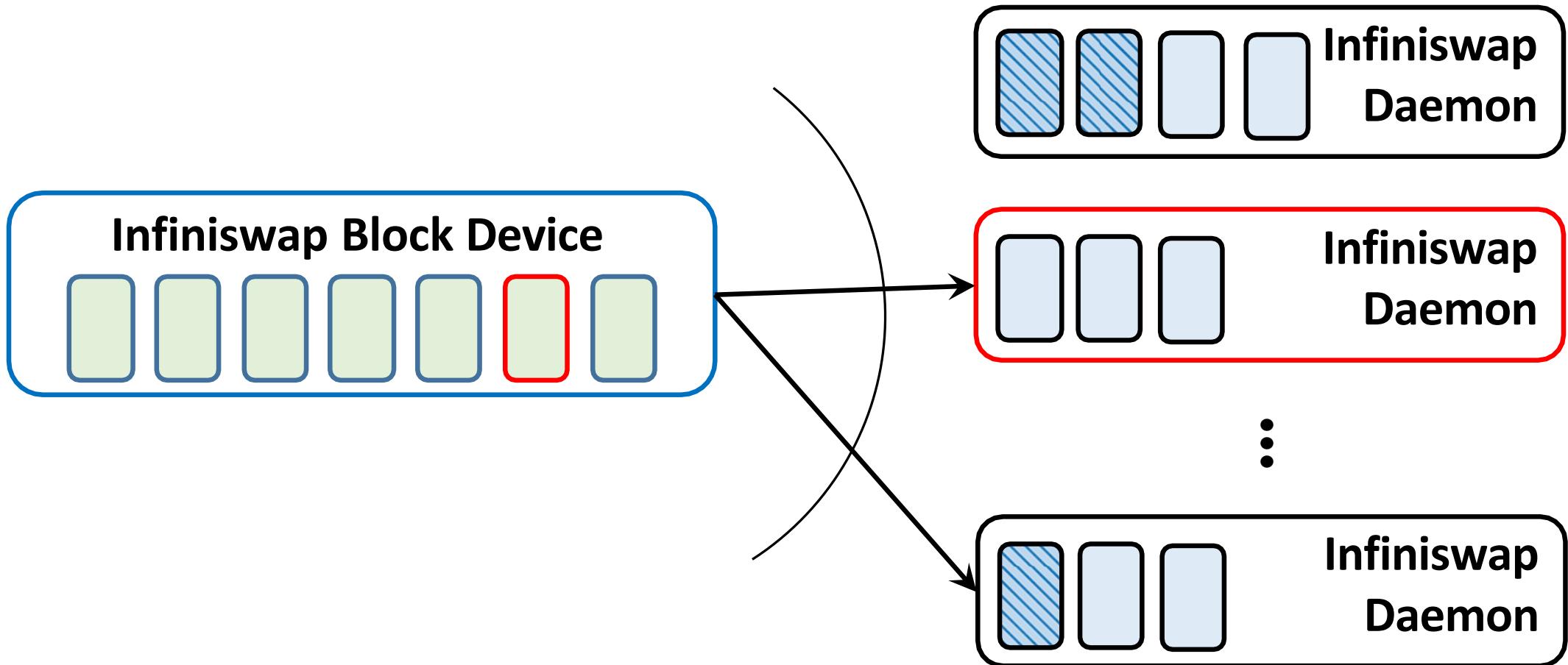
- ▶ ~~Central controller~~
- ▶ Decentralized approach



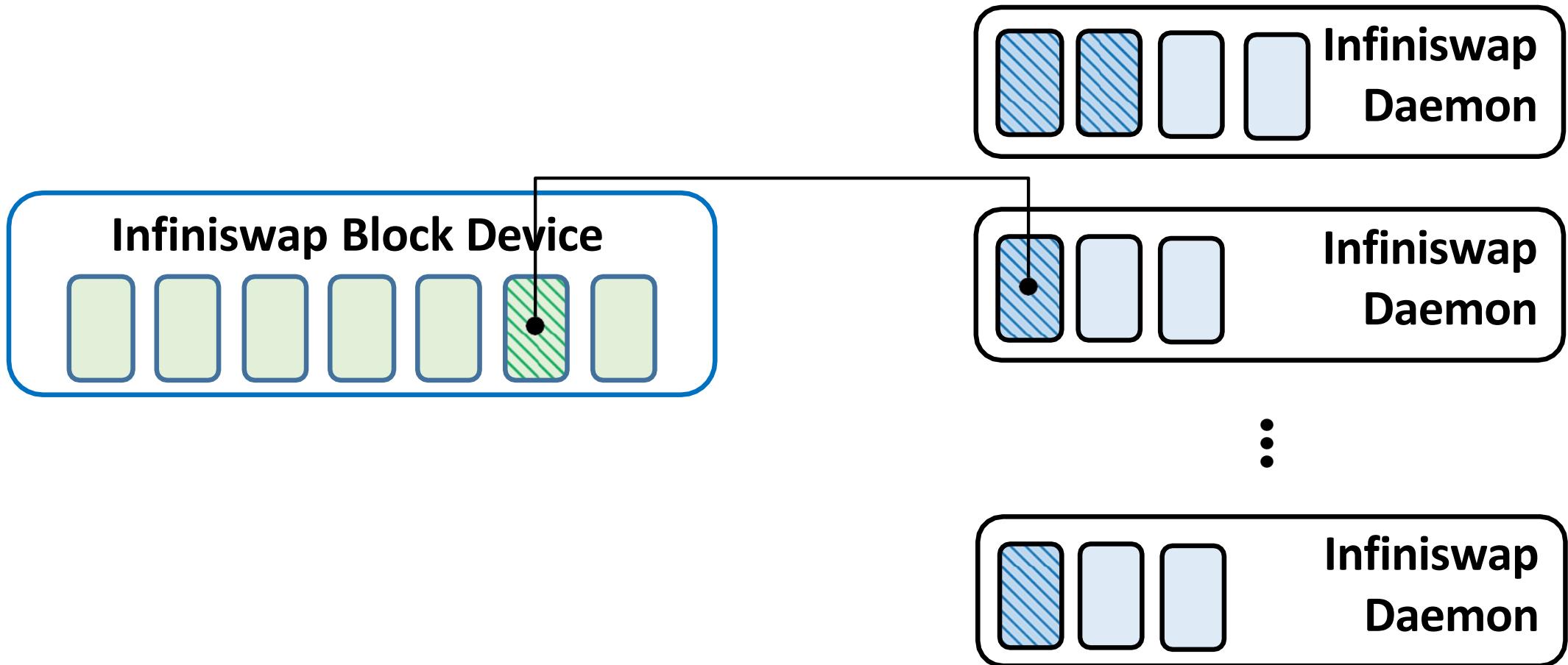
⋮



# Power of **two** choices<sup>[1]</sup>



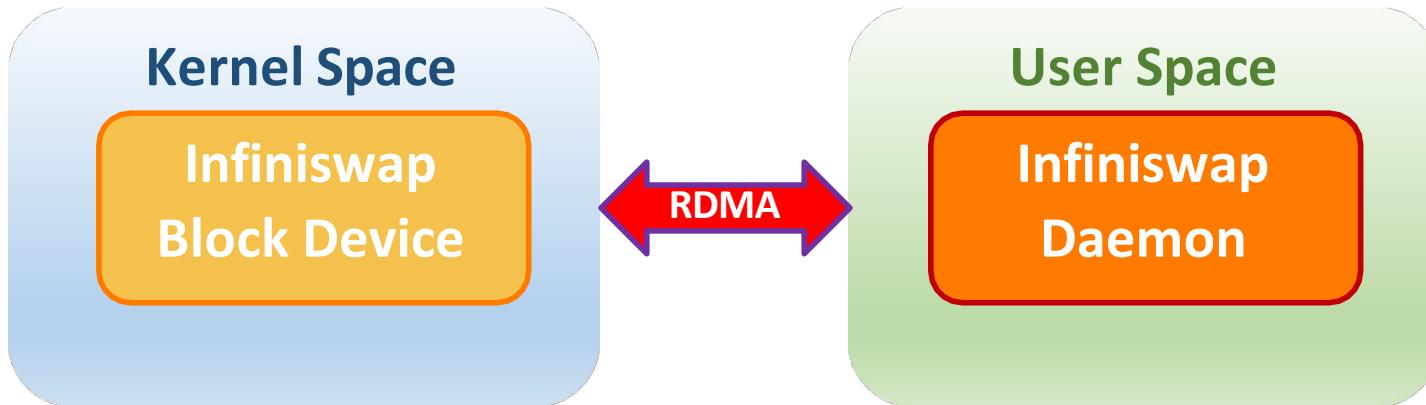
# Power of **two** choices<sup>[1]</sup>



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# Implementation



- **Connection Management**
  - One RDMA connection per active block device - daemon pair
- **Control Plane**
  - SEND, RECV
- **Data Plane**
  - **One-sided RDMA READ, WRITE**

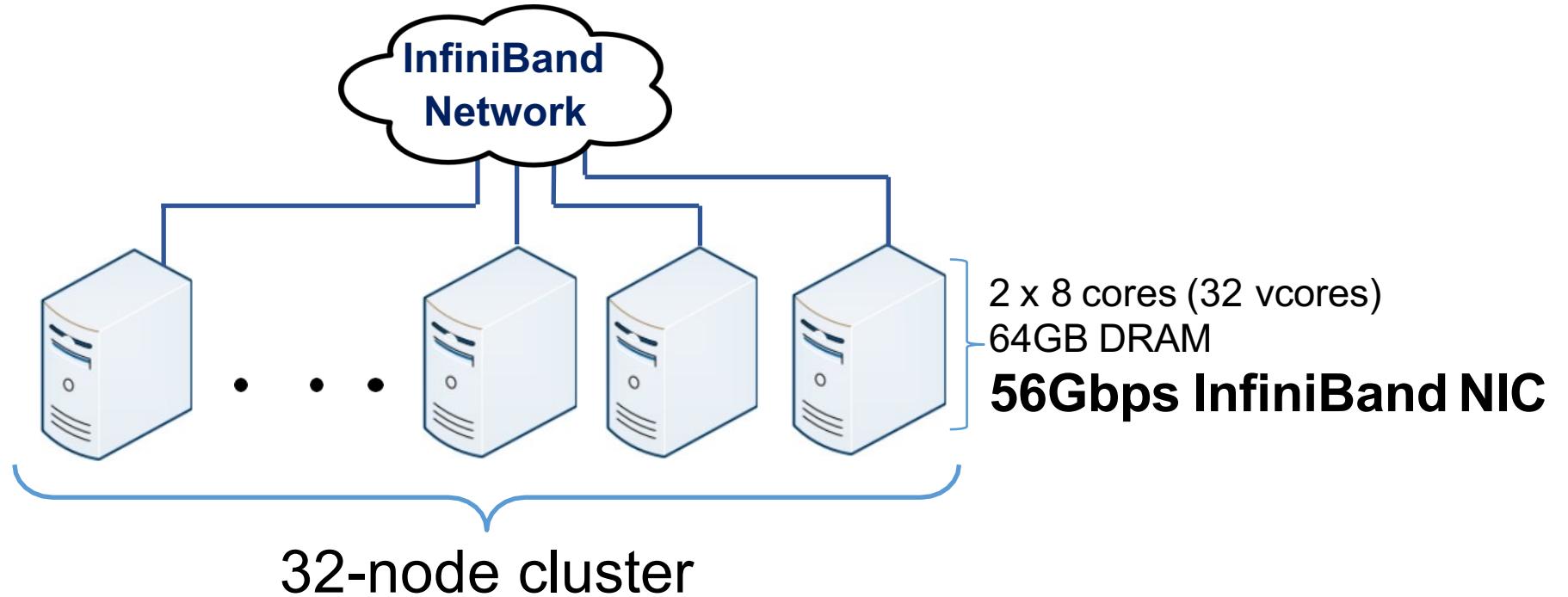
3/30/17

# What are we expecting from Infiniswap?

- Application performance
- Cluster memory utilization
- Network usage
- Eviction overhead
- Fault-tolerance overhead
- Performance as a block device

:

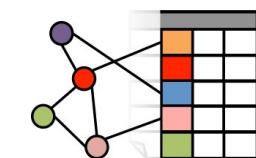
# Evaluation



**memcached**



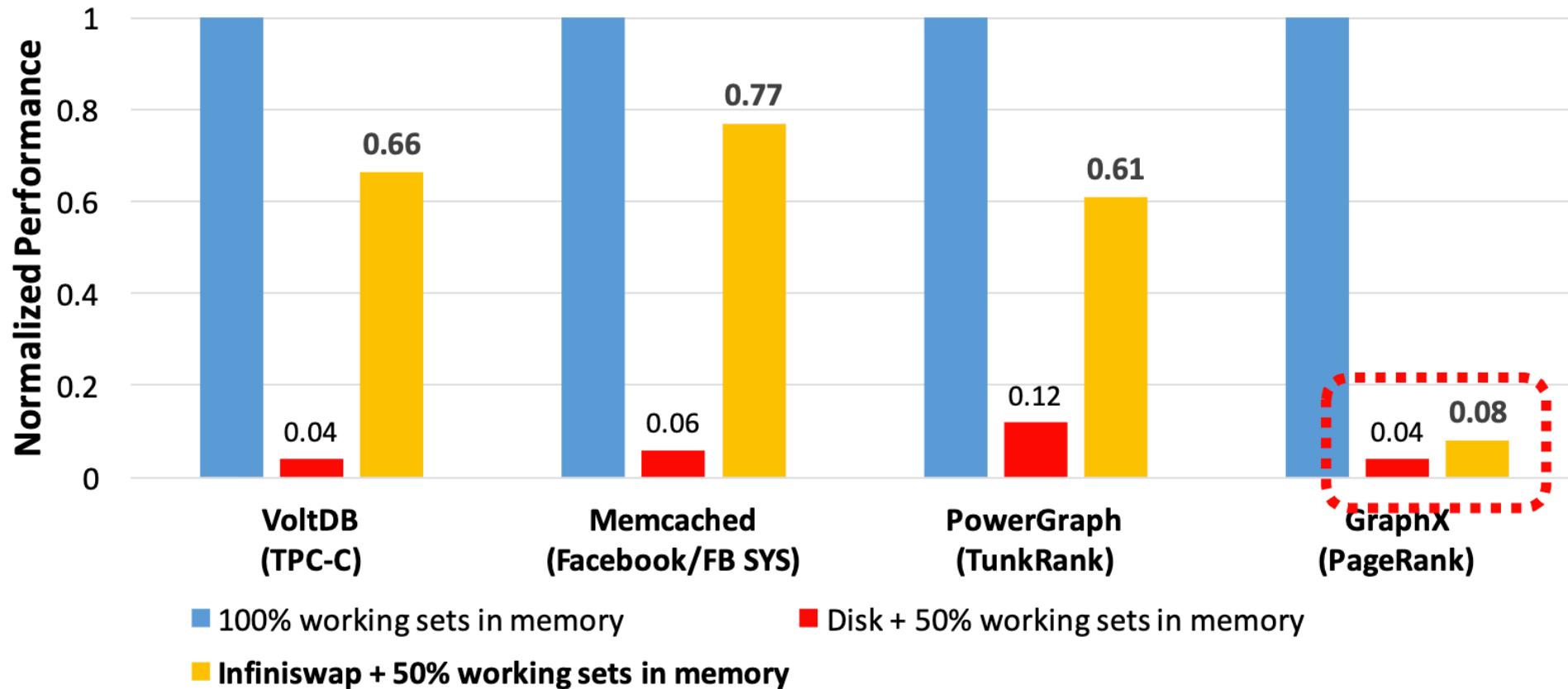
**powergraph**



**GraphX**

# Application performance

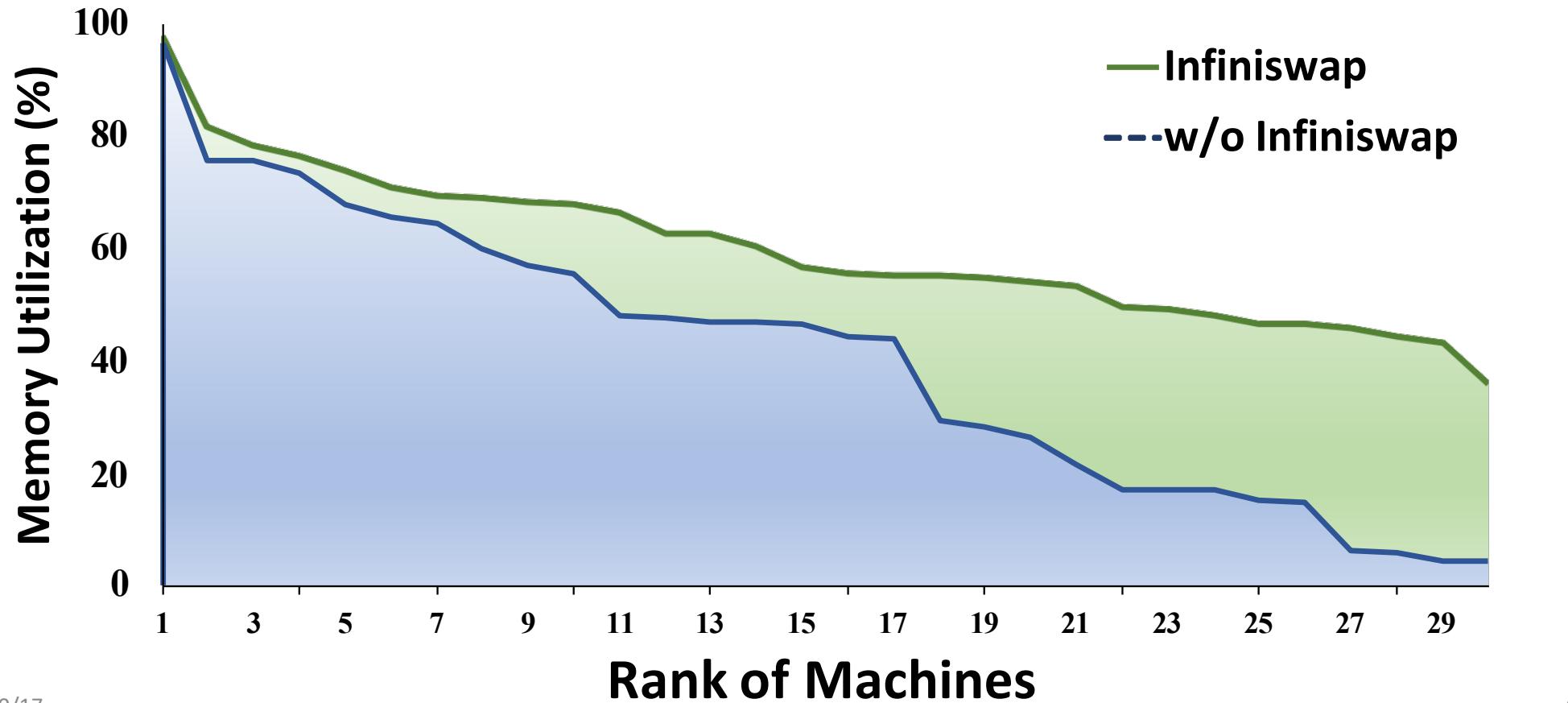
- 50% working sets in memory



- Application performance is improved by 2-16x

# Cluster memory utilization

- 90 containers (applications), mixing all applications and memory constraints.



- 3/30/17 60
- Cluster memory utilization is improved from **40.8%** to **60%** (**1.47x**)

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# Limitations and future work

- **Trade-off in fault-tolerance**
  - Local disk is the bottleneck
  - Multiple remote replicas
    - Fault-tolerance vs. space-efficiency
- **Performance isolation among applications**

# Conclusion

- **Infiniswap: remote paging over RDMA**
  - Application performance
  - Cluster memory utilization
- **Efficient, practical memory disaggregation**
  - No hardware design
  - No application modification
  - **Fault-tolerance**
  - **Scalability**

<https://github.com/Infiniswap/infiniswap.git>

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# AIFM: High-Performance, Application-Integrated Far Memory

Zain (Zhenyuan) Ruan\*    Malte Schwarzkopf<sup>†</sup>    Marcos K. Aguilera<sup>‡</sup>    Adam Belay\*

\*MIT CSAIL

<sup>†</sup>Brown University

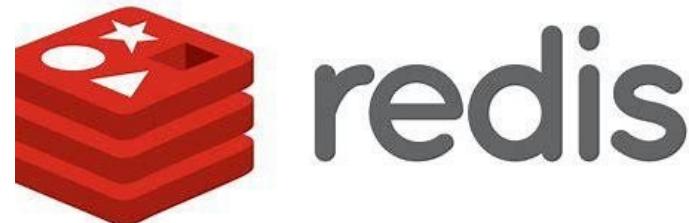
<sup>‡</sup>VMware Research



# In-Memory Applications



Data Analytics



Web Caching



Database



Graph Processing

# Memory Is Inelastic

- Limited by the server physical boundary.
- Applications cannot overcommit memory.

## Opening a 20GB file for analysis with pandas

Asked 2 years, 8 months ago   Active 1 year, 4 months ago   Viewed 81k times



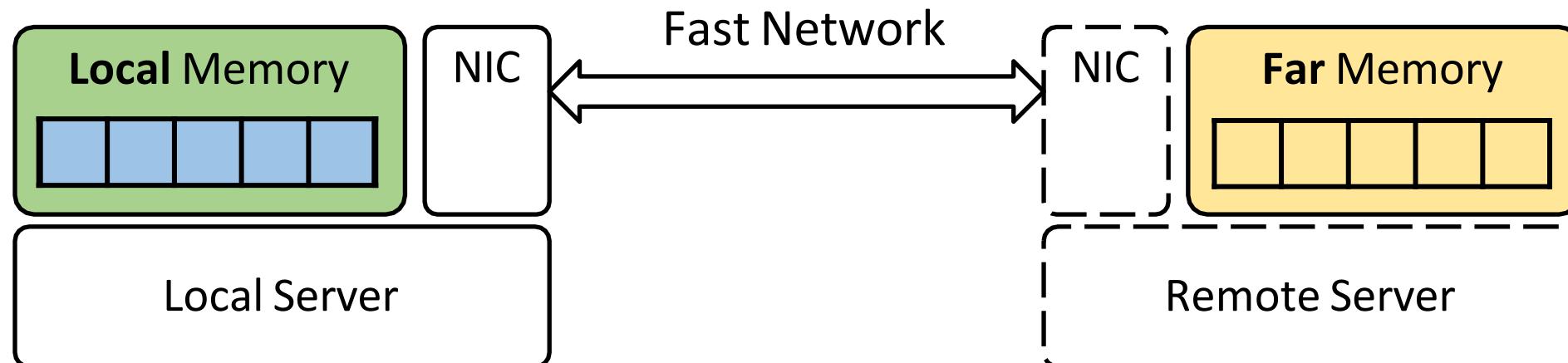
I am currently trying to open a file with pandas and python for machine learning purposes it would be ideal for me to have them all in a DataFrame. My RAM is 32 GB. I keep getting memory errors.

20

➤ Expensive solution: overprovision memory for peak usage.

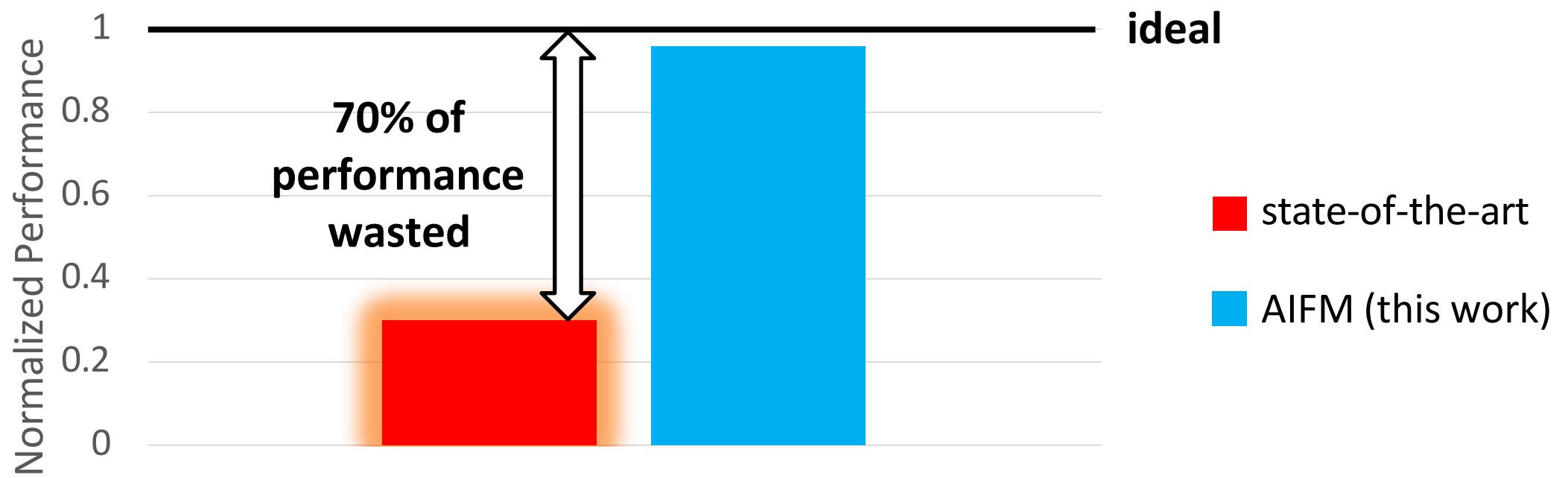
# Trending Solution: Far Memory

- Leverage the idle memory of remote servers (with fast network).



# Existing Far-Memory Systems Perform Poorly

- Real-world Data Analytics from Kaggle.
  - Provision **25%** of working set in local mem.
- Goal: reclaim the wasted performance.

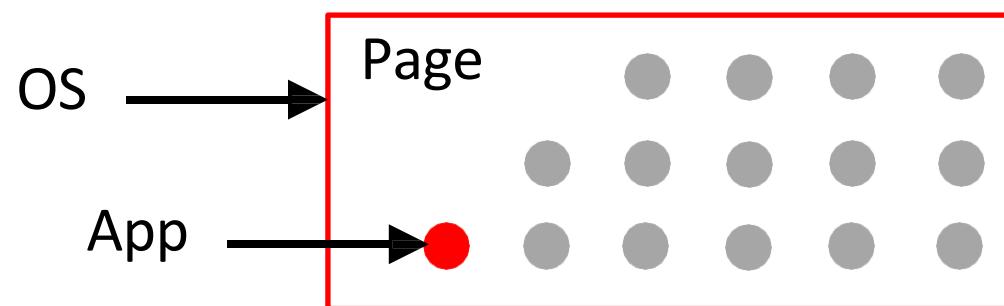


# Why Do Existing Systems Waste Performance?

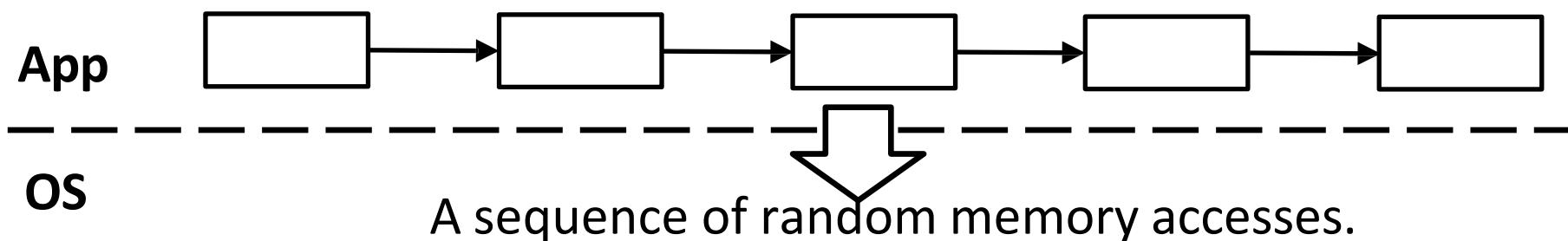
- Problem: based on **OS paging**.
  - Semantic gap.
  - High kernel overheads.

# Challenge 1: Semantic Gap

- Page granularity → **R/W amplification.**

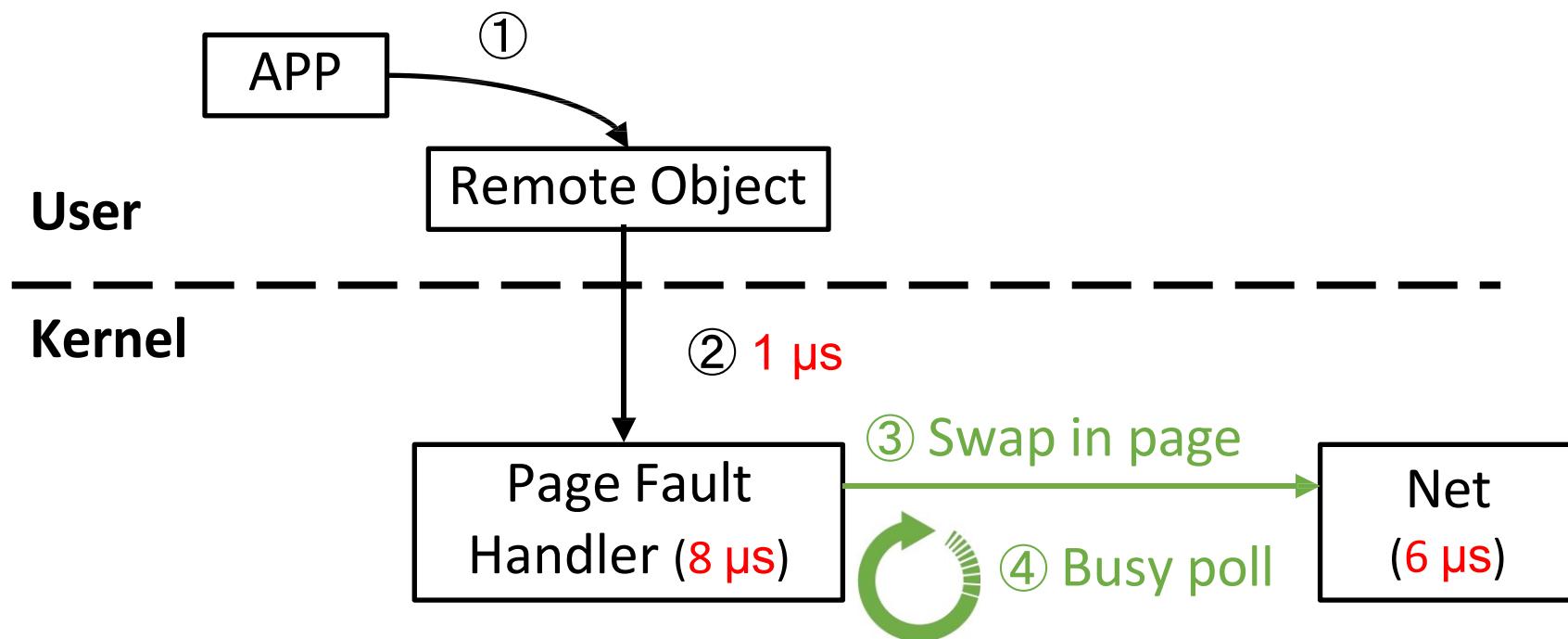


- OS lacks app knowledge → **hard to prefetch, etc.**

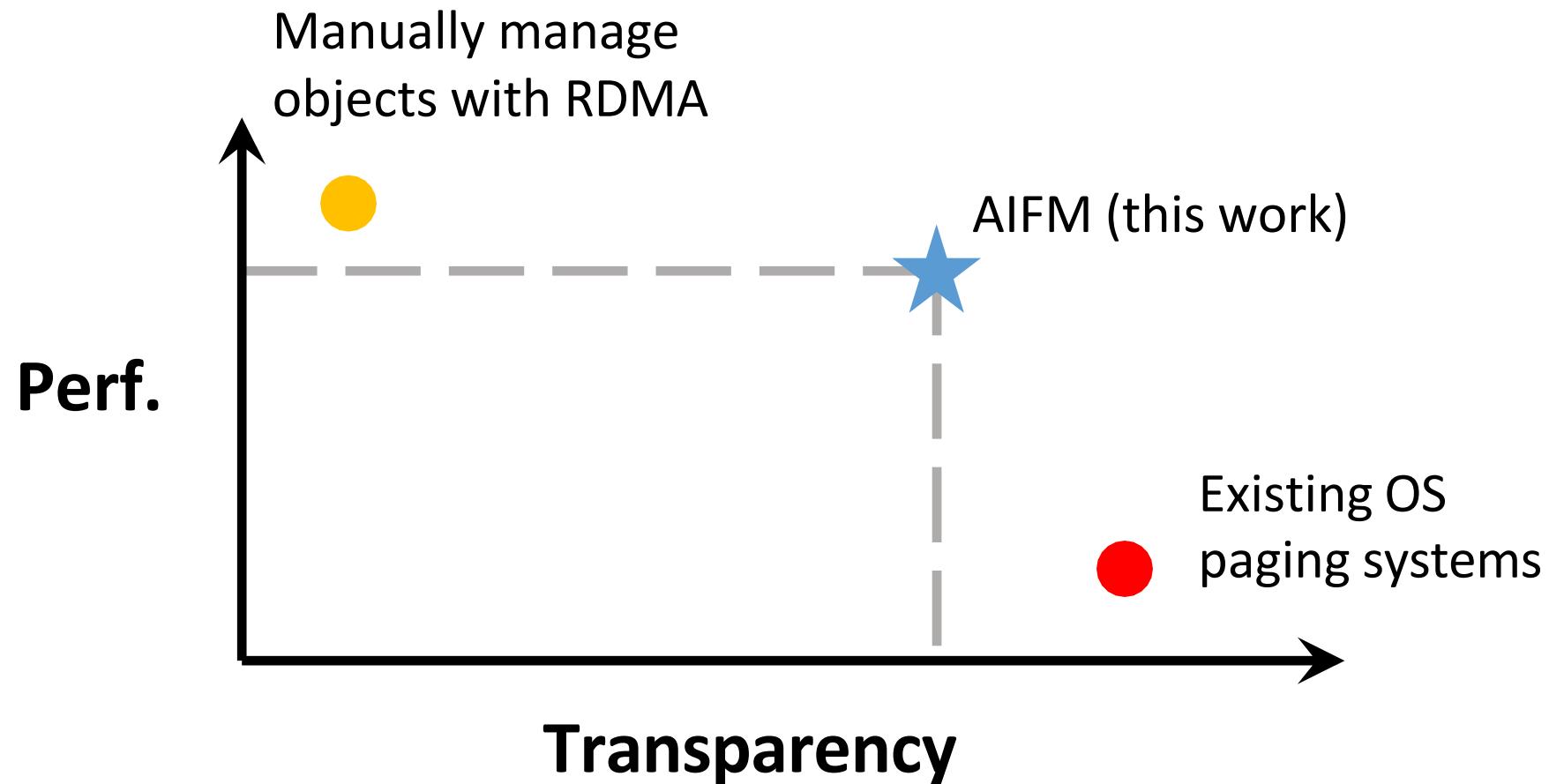


# Challenge 2: High Kernel Overheads

- **Expensive page faults.**
- Busy Polling for in-kernel net I/O → **burn CPU cycles.**



# Design Space



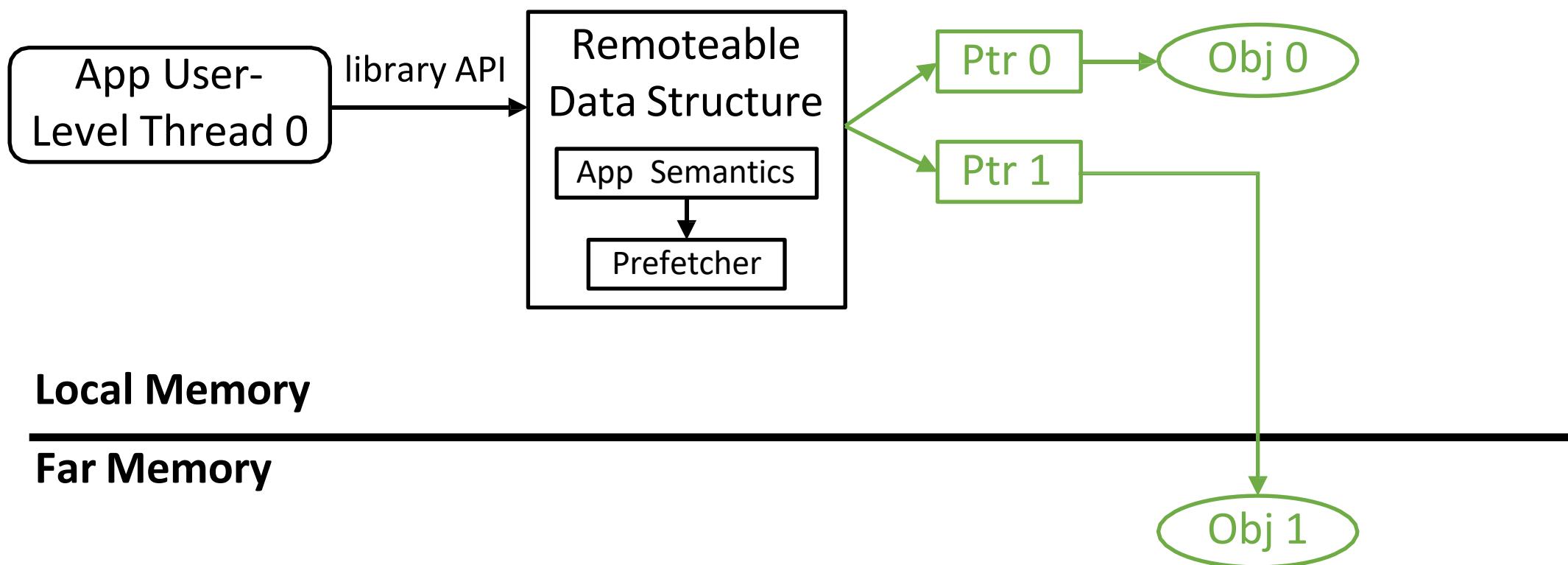
# AIFM's Design Overview

- Key idea: swap memory using a userspace runtime.

| Challenge  | Solution                          |
|--|-----------------------------------|
| <b>1. Semantic gap</b><br>(Amplification, Hard to prefetch)        | Remoteable Data structure library |
| <b>2. Kernel overheads</b><br>(page faults, busy poll for net I/O) | Userspace runtime                 |
| <b>3. Impact of Memory Reclamation</b><br>(pause app threads)      | Pauseless evacuator               |
| <b>4. network BW &lt; DRAM BW</b>                                  | Remote Agent                      |

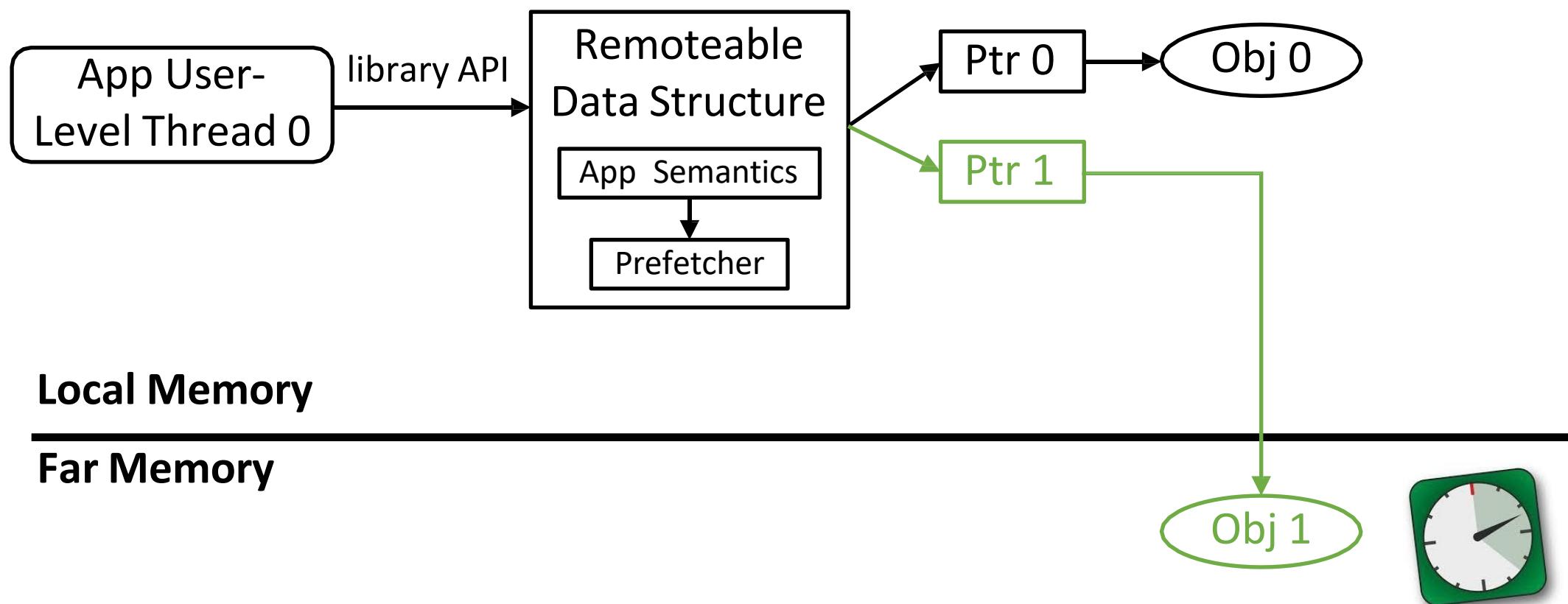
# 1. Remoteable Data Structure Library

➤ Solved challenge: semantic gap.



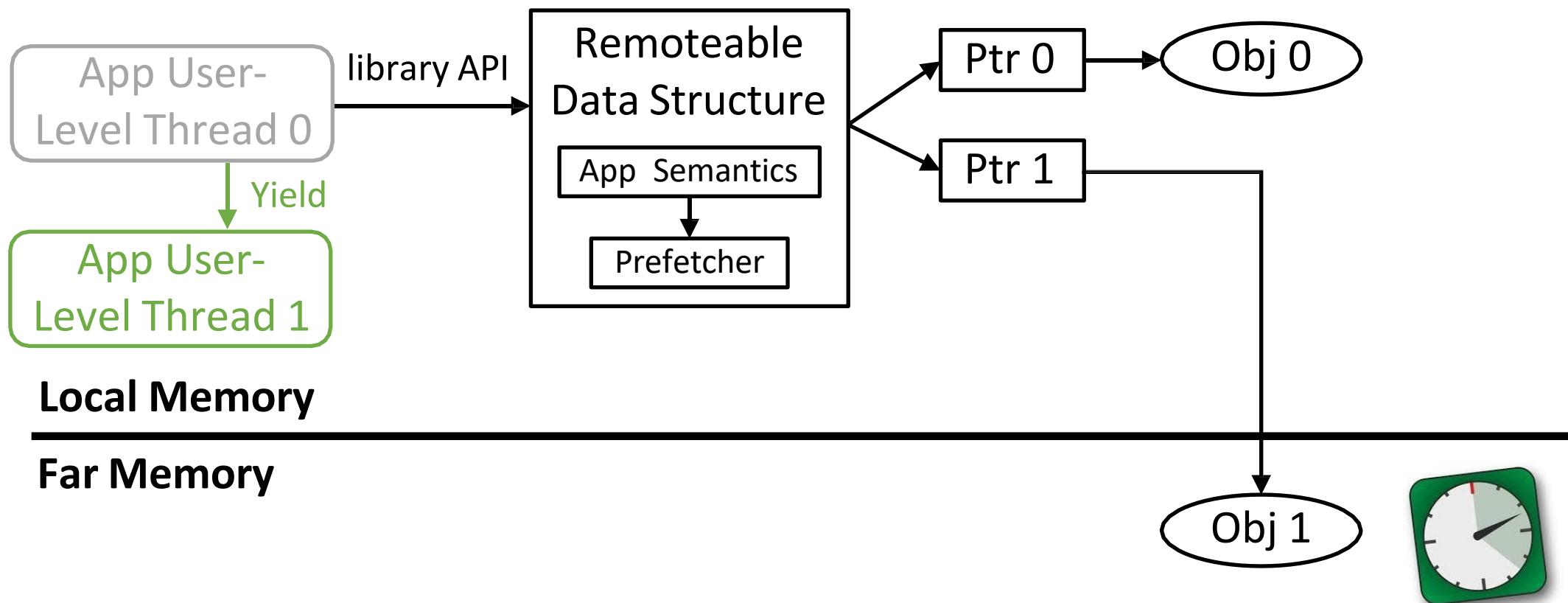
## 2. Userspace Runtime

- Solved challenge: kernel overheads.



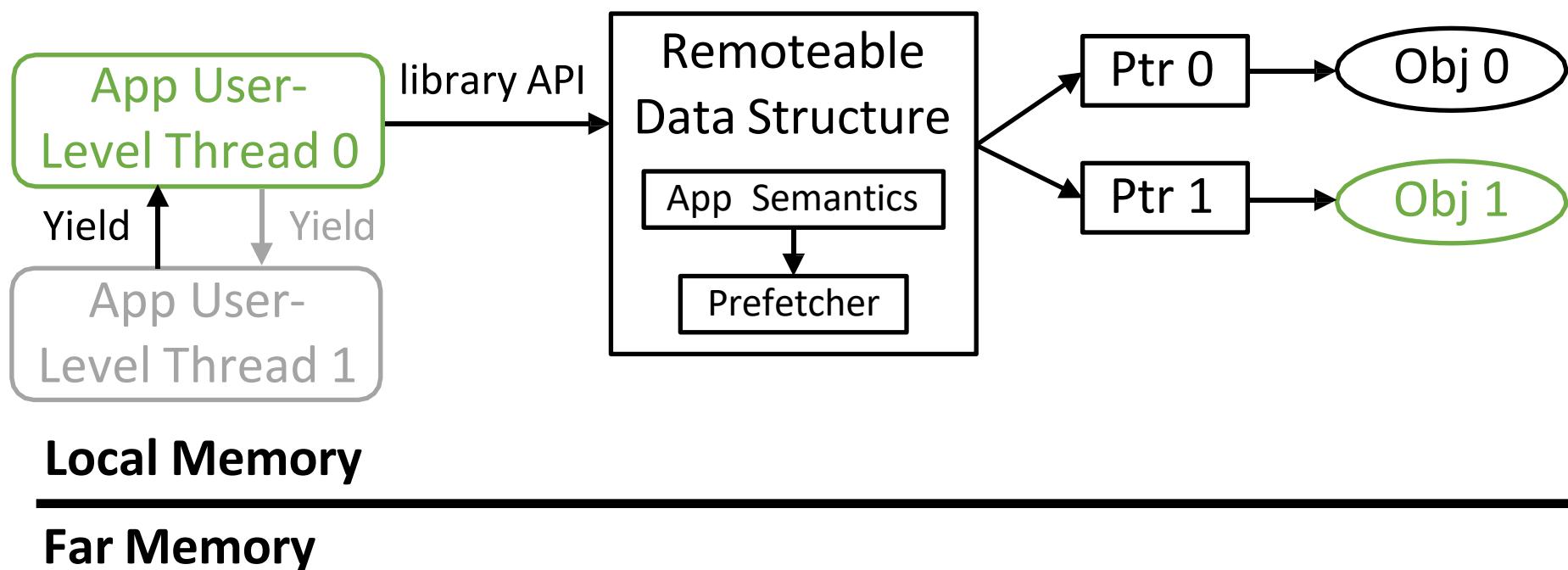
## 2. Userspace Runtime

- Solved challenge: kernel overheads.



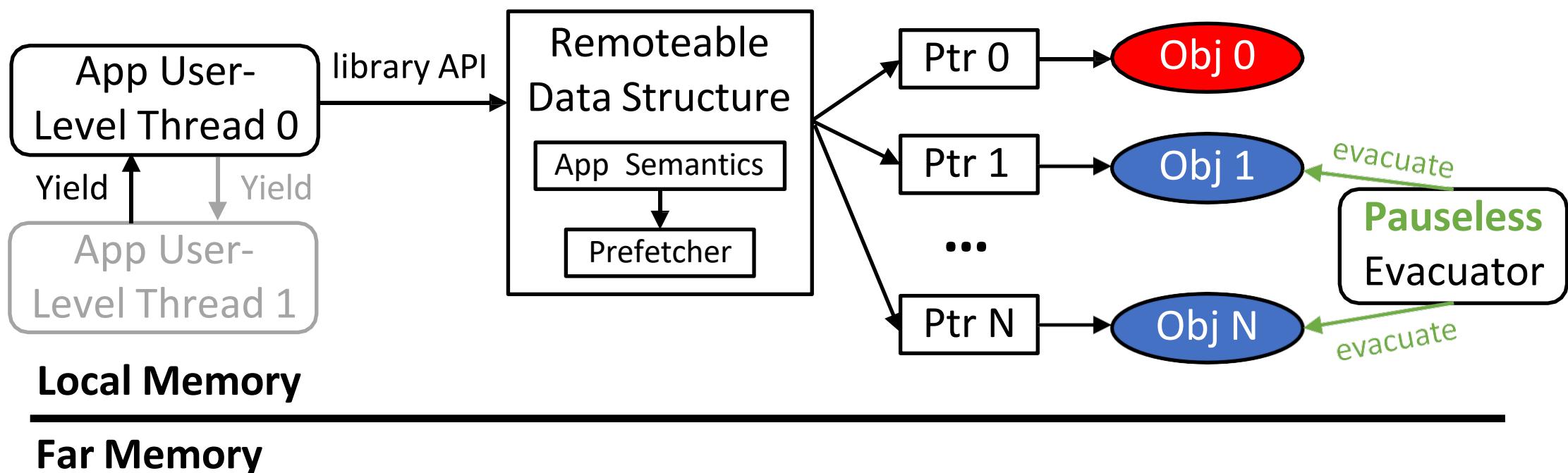
## 2. Userspace Runtime

- Solved challenge: kernel overheads.



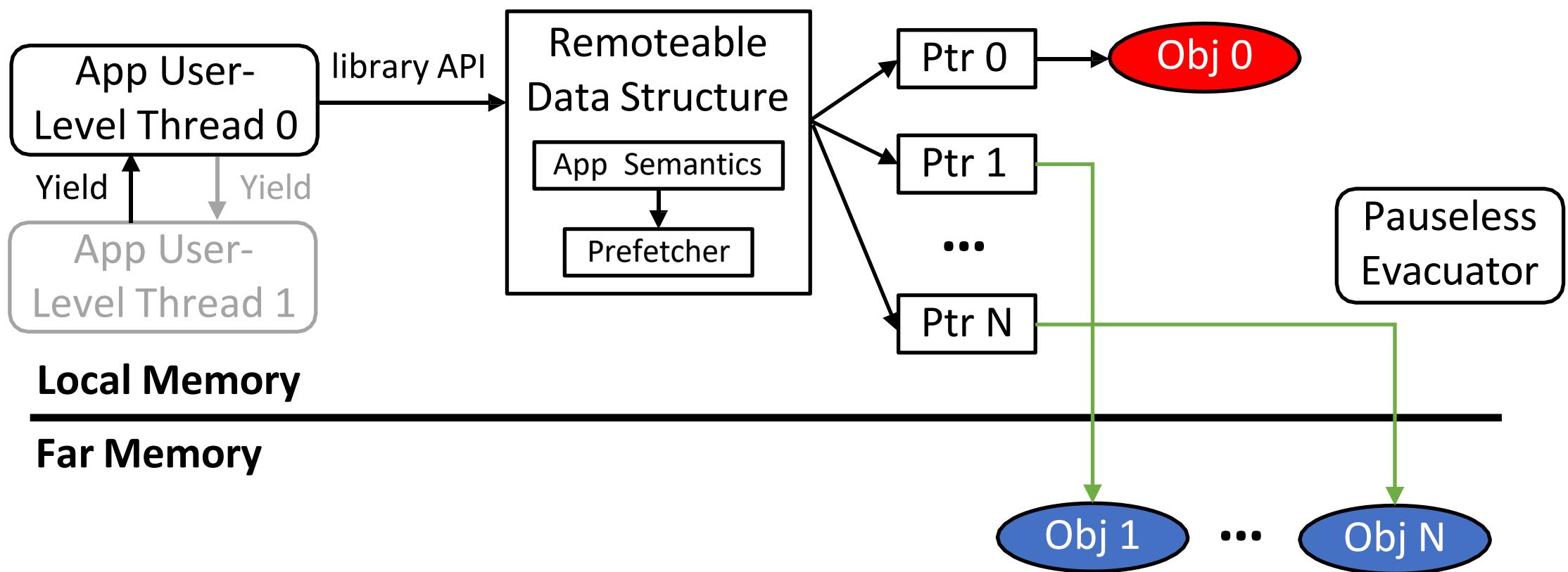
### 3. Pauseless Evacuator

➤ Solved challenge: impact of memory reclamation.



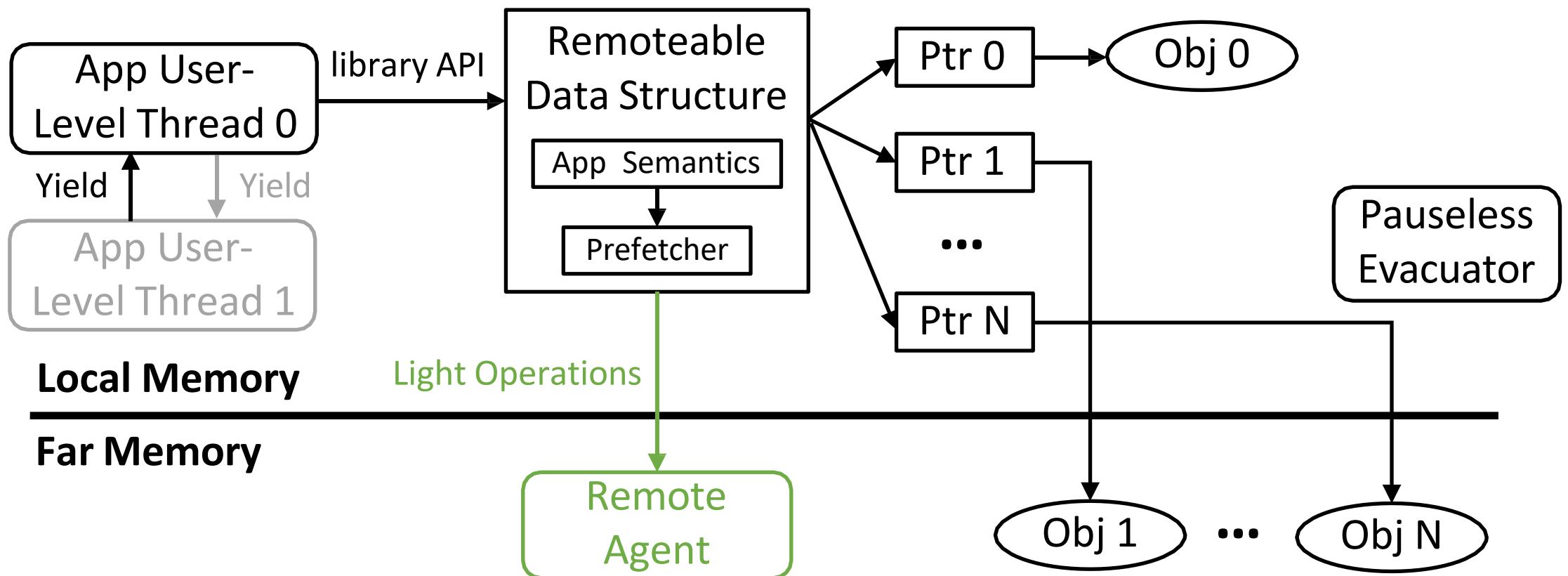
### 3. Pauseless Evacuator

➤ Solved challenge: impact of memory reclamation.



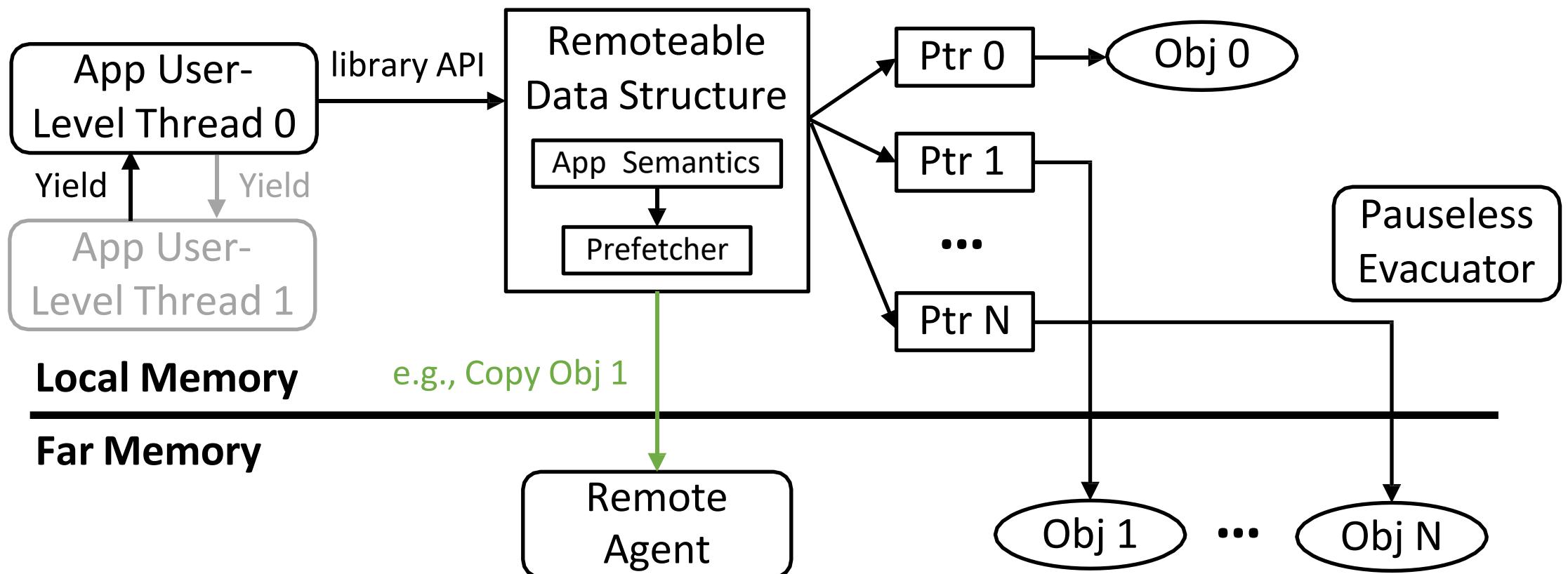
## 4. Remote Agent

➤ Solved challenge: network BW < DRAM BW.



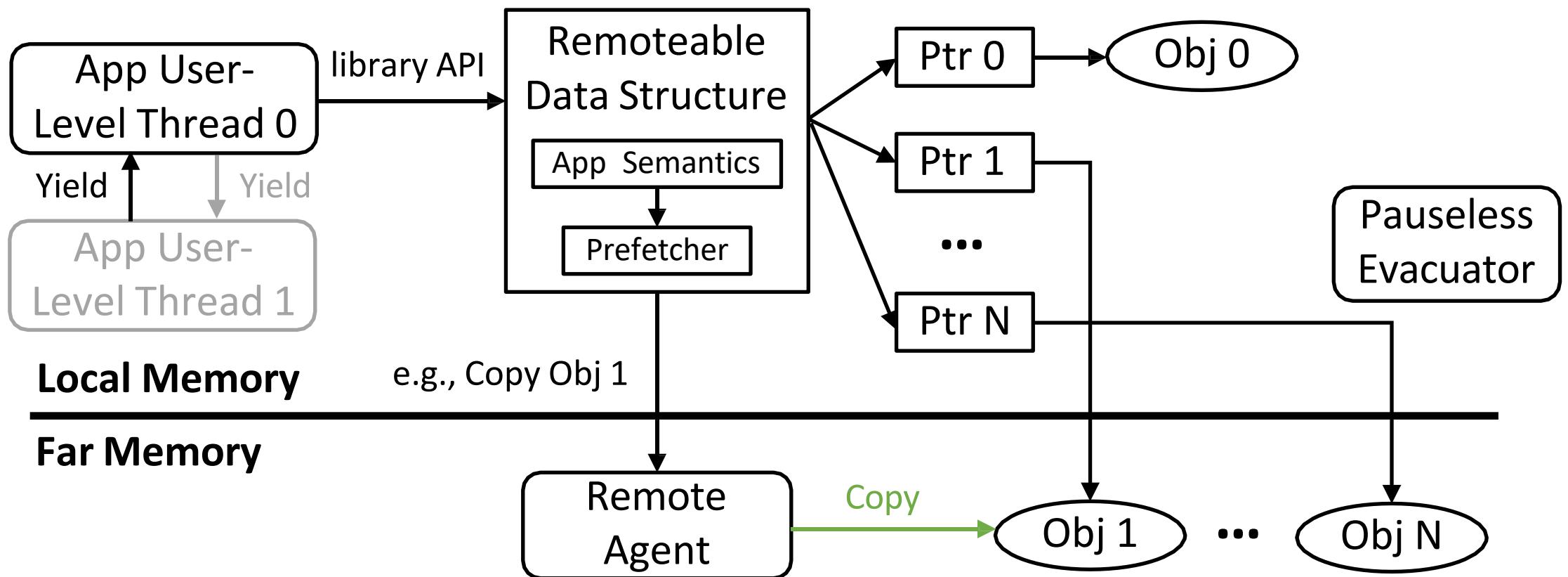
## 4. Remote Agent

➤ Solved challenge: network BW < DRAM BW.



## 4. Remote Agent

➤ Solved challenge: network BW < DRAM BW.



# Sample Code

```
std::unordered_map<key_t, int> hashtable;
std::array<LargeData> arr;

LargeData foo(std::list<key_t> &keys_list) {
    int sum = 0;
    for (auto key : keys_list) {

        sum += hashtable.at(key);
    }

    LargeData ret = arr.at(sum);
    return ret;
}
```

# Sample Code

```
RemHashTable<key_t, int> hashtable;
```

```
RemArray<LargeData> arr;
```

```
LargeData foo(RemList<key_t> &keys_list) {
```

```
    int sum = 0;
```

```
    for (auto key : keys_list) {
```

*Prefetch list data.*

```
        DerefScope scope;
```

```
        sum += hashtable.at(key, scope);
```

*Cache hot objects.*

```
}
```

```
    DerefScope scope;
```

```
    LargeData ret = arr.at</*don't cache*/ true>(sum, scope);
```

*Avoid polluting local mem.*

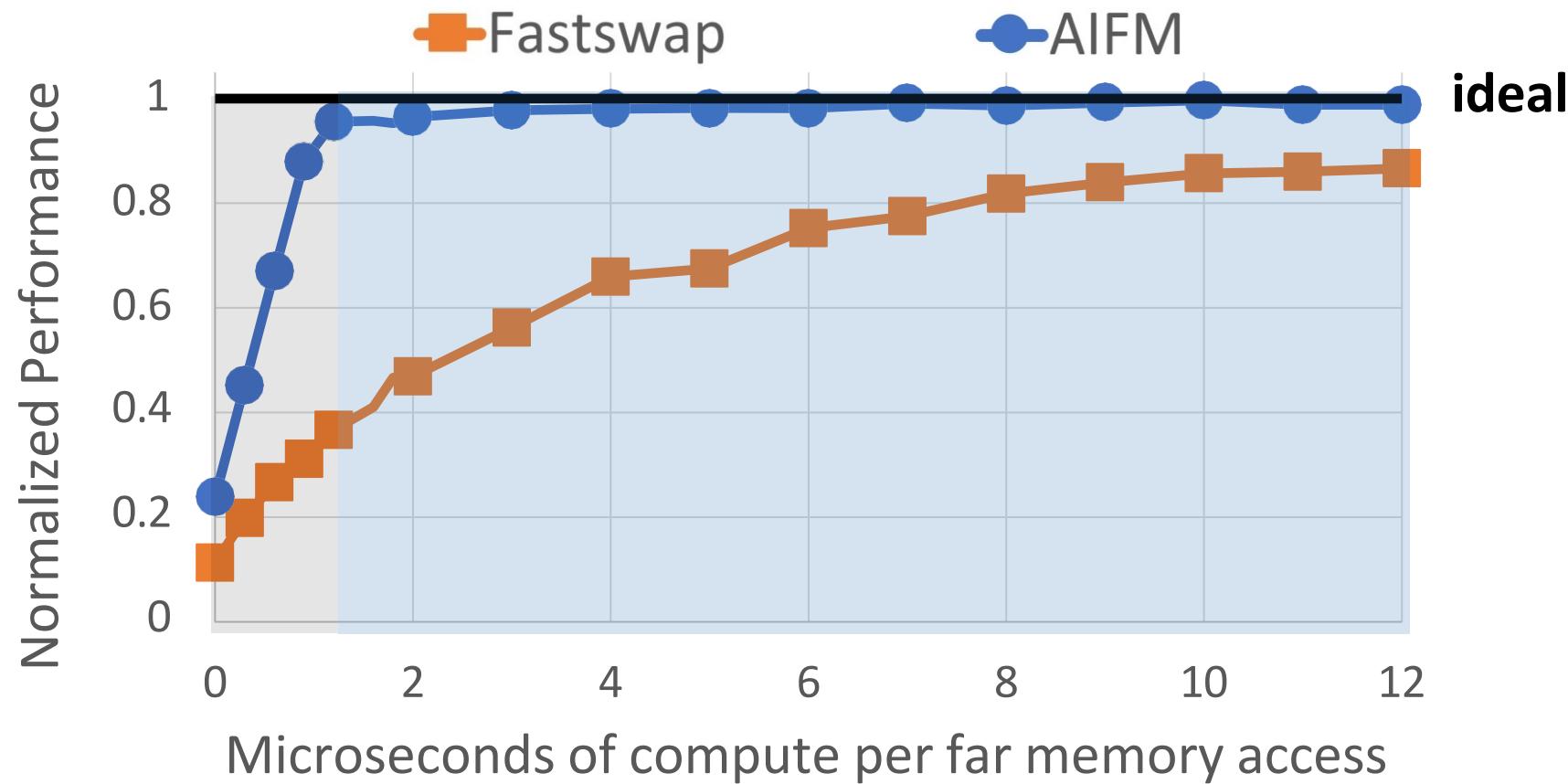
```
    return ret;
```

```
}
```

# Implementation

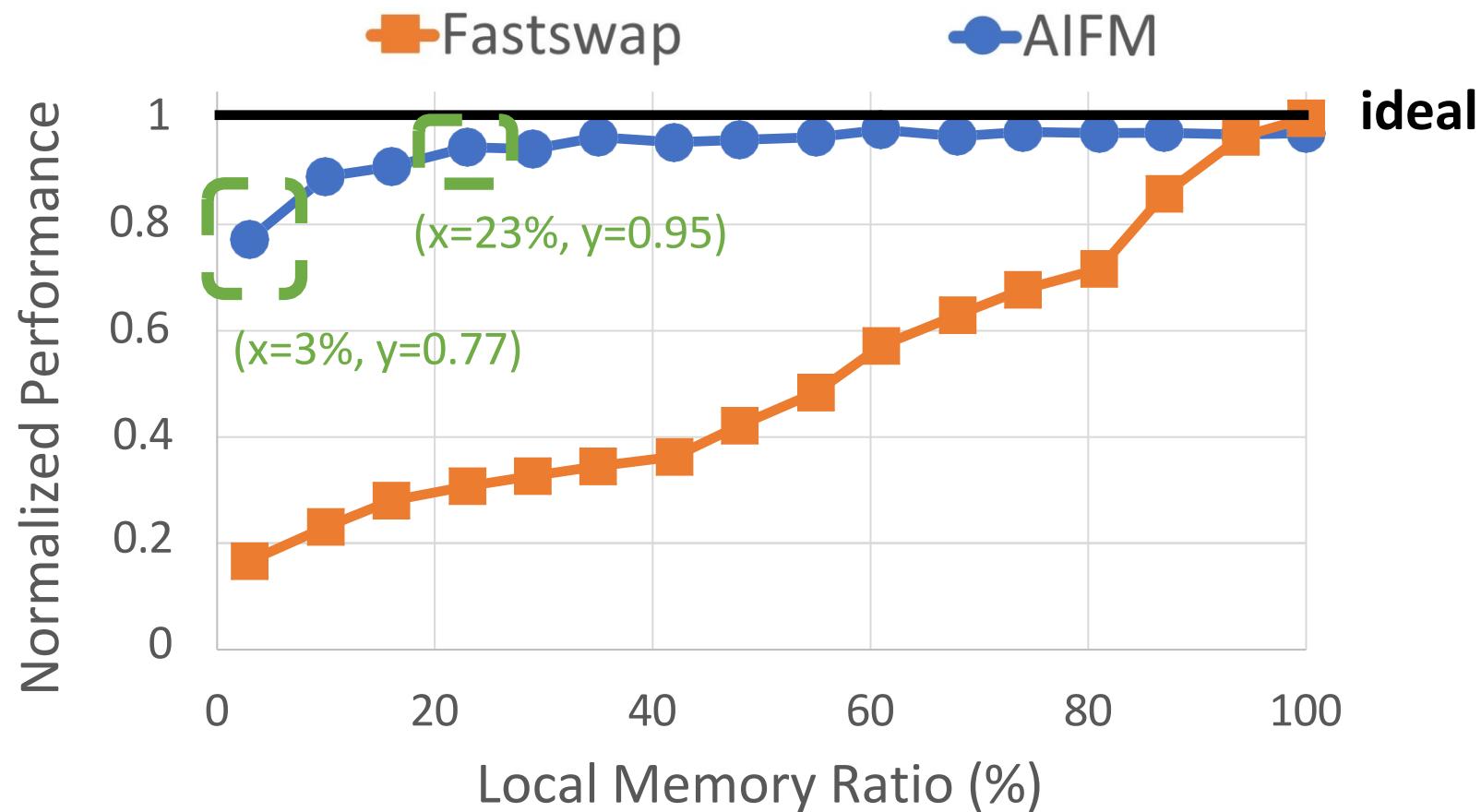
- Implemented 6 data structures.
    - Array, List, Hashtable, Vector, Stack, and Queue.
  - Runtime is built on top of Shenango [NSDI' 19].
  - TCP far-memory backend.
- LoC: 6.5K (runtime) + 5.5K (data structures) + 0.8K (Shenango)

# Performance on Different Compute Intensities



**AIFM hides far memory latency with moderate compute.**

# NYC Taxi Analysis (C++ DataFrame)



**AIFM achieves near-ideal performance with small local memory.**

# Other Experiments

- Synthetic web frontend: up to **13X end-to-end** speedup.
- Data structures microbenchmarks: up to **61X** speedup.
- Design Drill-Down.

Read our paper for details.

# Related Work

- OS-paging systems.
  - Fastswap [EuroSys' 20], Leap [ATC' 20]
- Distributed shared memory.
  - Treadmarks [IEEE Computer' 96]
- Garbage collection (GC).

# Conclusion

- AIFM: Application-Integrated Far Memory.
  - Key idea: swap memory using a userspace runtime.
    - Data Structure Library: captures application semantics.
    - Userspace Runtime: efficiently manages objects and memory.
  - Achieves 13X end-to-end speedup over Fastswap.
- Code released at <https://github.com/AIFM-sys/AIFM>

Please send your questions to us

[zainruan@csail.mit.edu](mailto:zainruan@csail.mit.edu)

# Memory Management in Modern Computer Systems

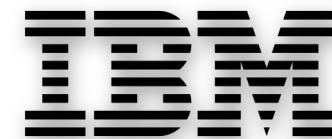
- Memory Abstraction
  - NSDI'14 FaRM
- Demand paging: remote memory over RDMA
  - NSDI'17 InfiniSwap
  - OSDI'20 AIFM
- Demand paging: memory swapping between GPU memory and host memory
  - OSDI'20 PipeSwitch
  - NSDI'23 TGS

# *PipeSwitch*: Fast Pipelined Context Switching for Deep Learning Applications

Zhihao Bai, Zhen Zhang, Yibo Zhu, Xin Jin



Deep learning powers intelligent applications in many domains



# Training and inference

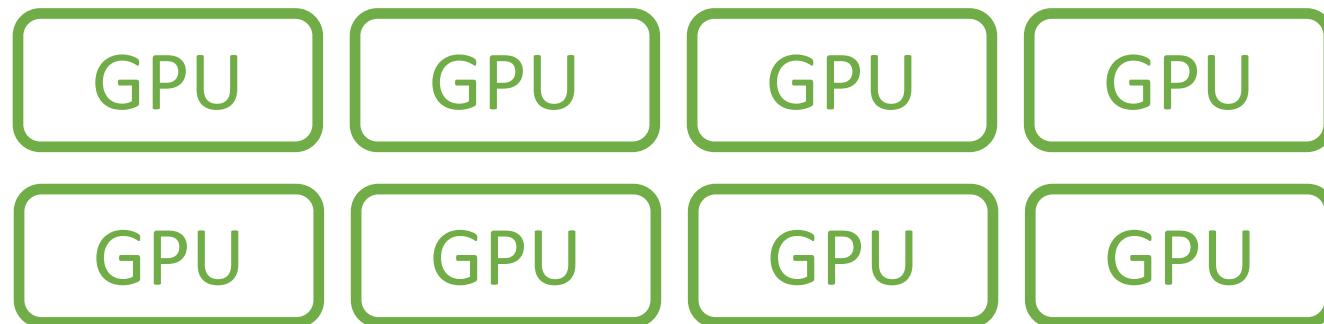


High throughput

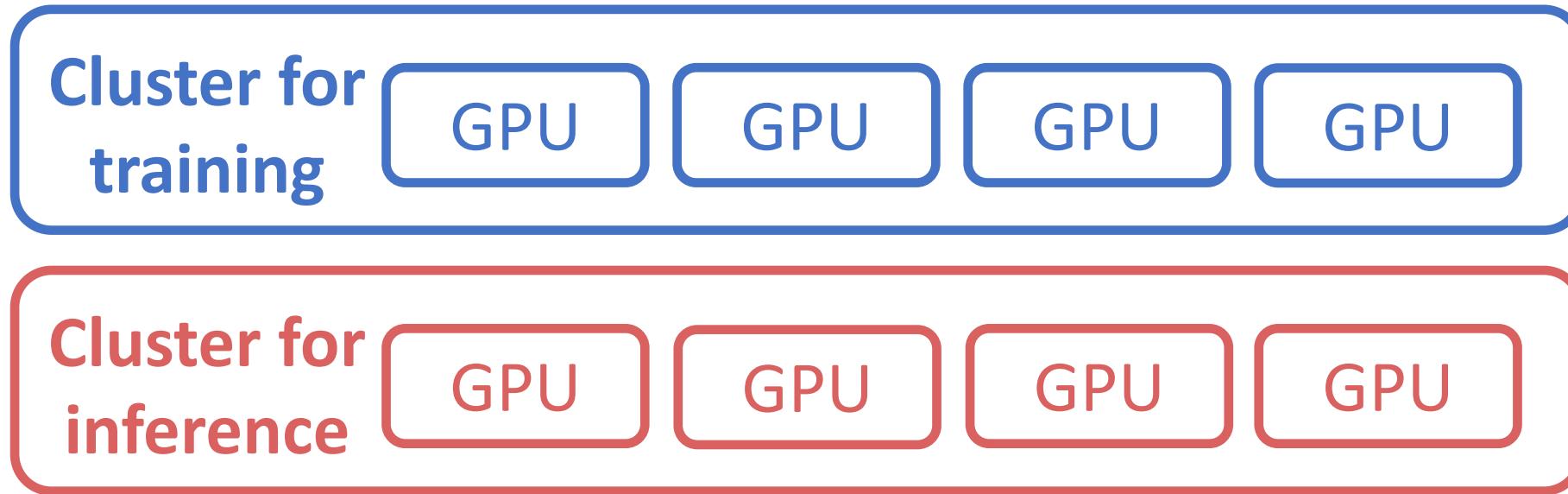


Low latency

# GPUs clusters for DL workloads

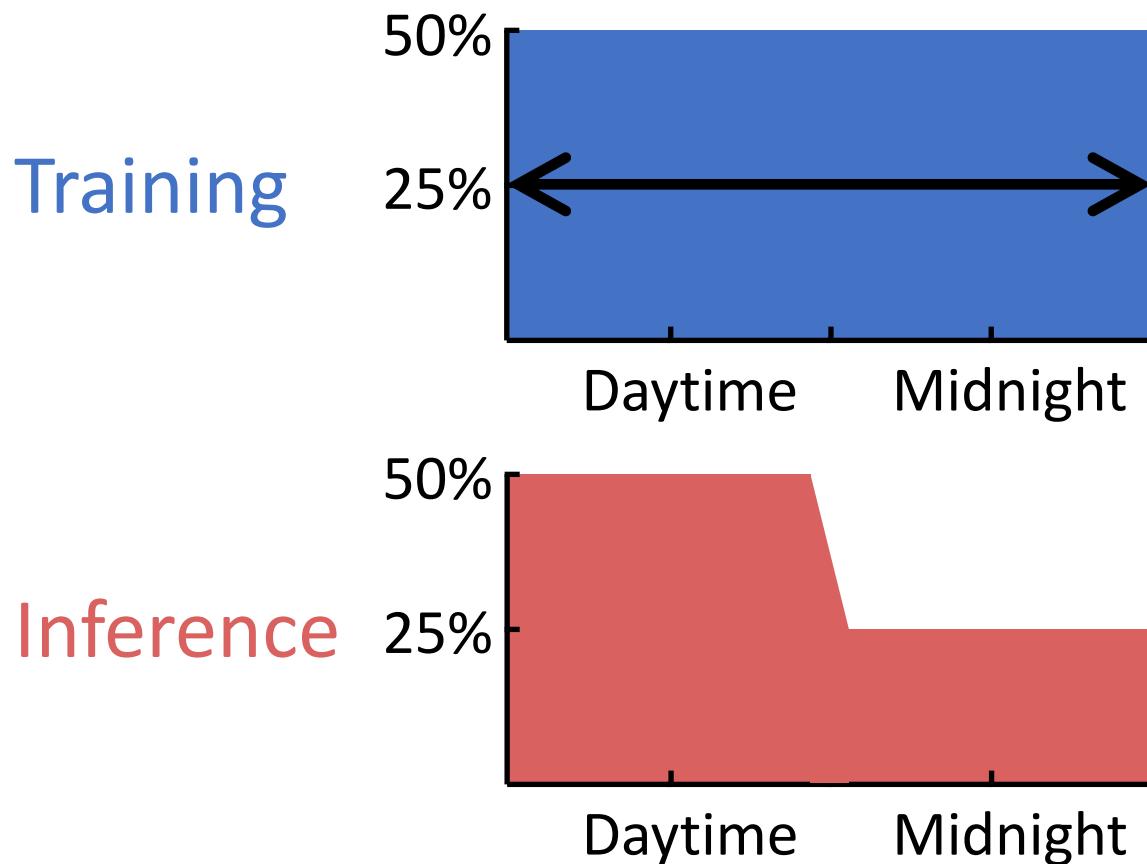


# Separate clusters for training and inference

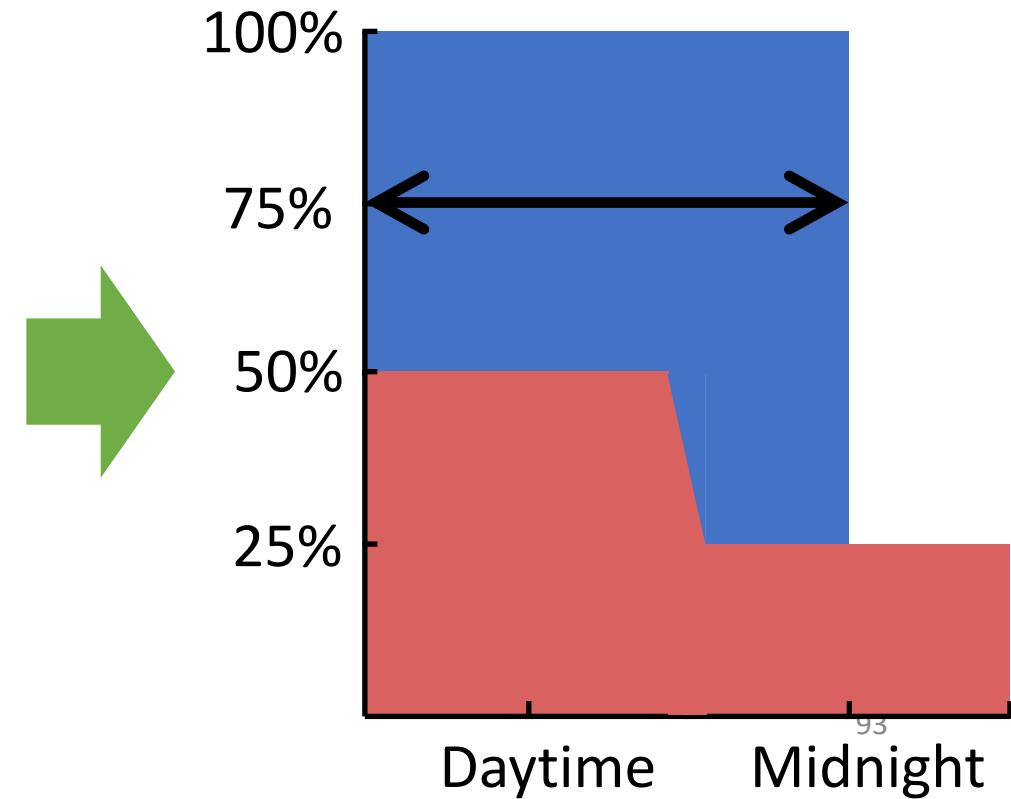


# Utilization of GPU clusters is low

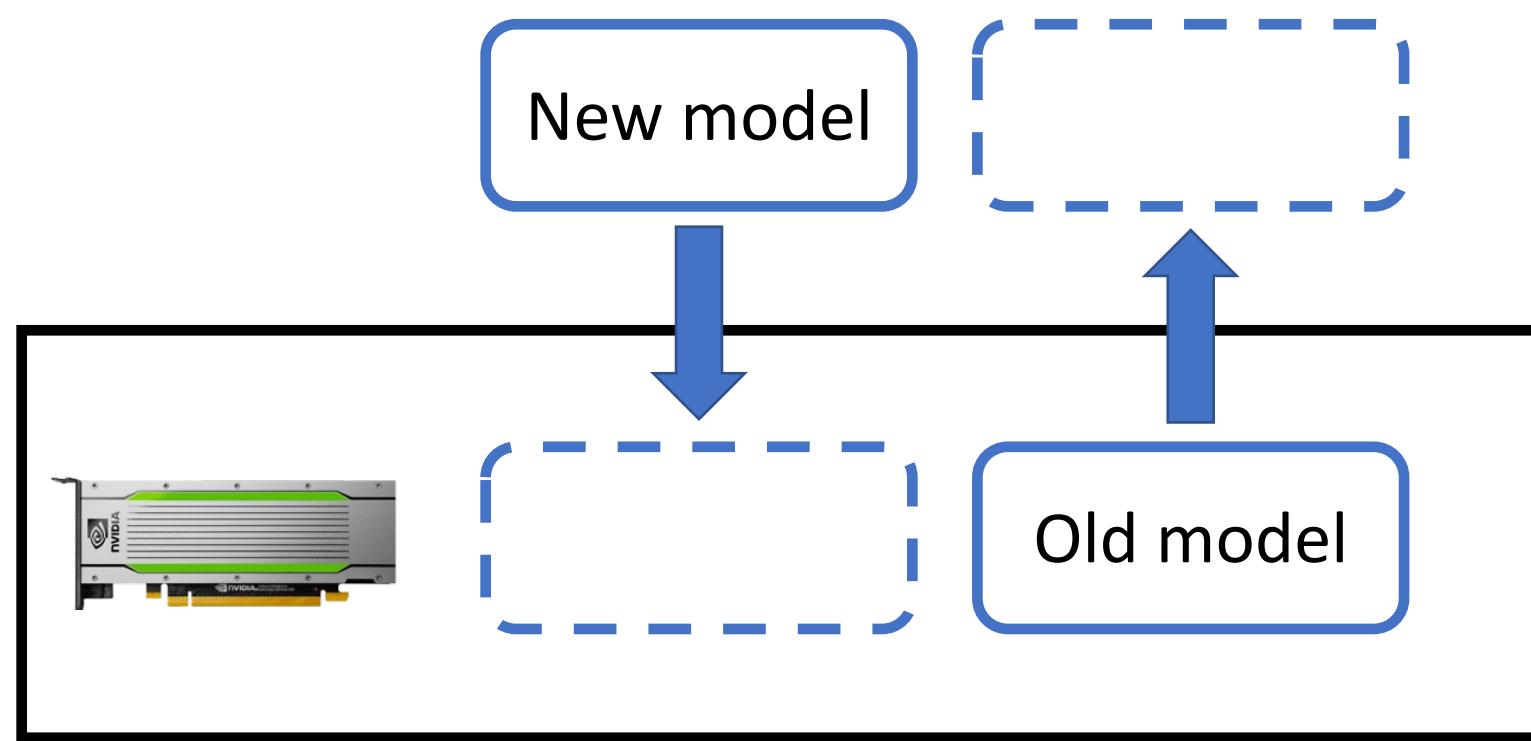
Today: separate clusters



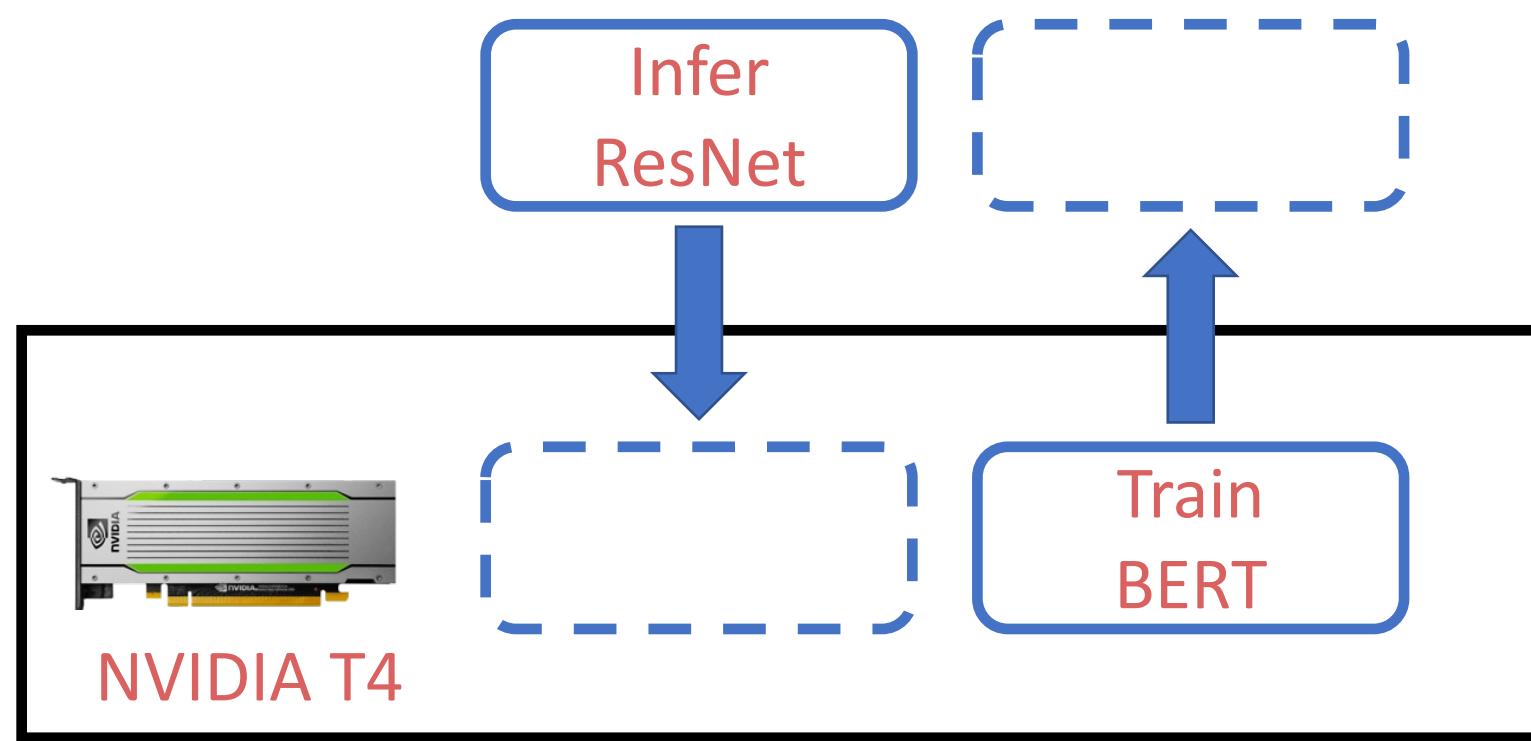
Ideal: shared clusters



# Context switching overhead is high



# Context switching overhead is high



**Latency: 6s**

# Drawbacks of existing solutions

- NVIDIA MPS
  - High overhead due to contention
- Salus[MLSys'20]
  - Requires all the models to be preloaded into the GPU memory

**Latency: 6s**

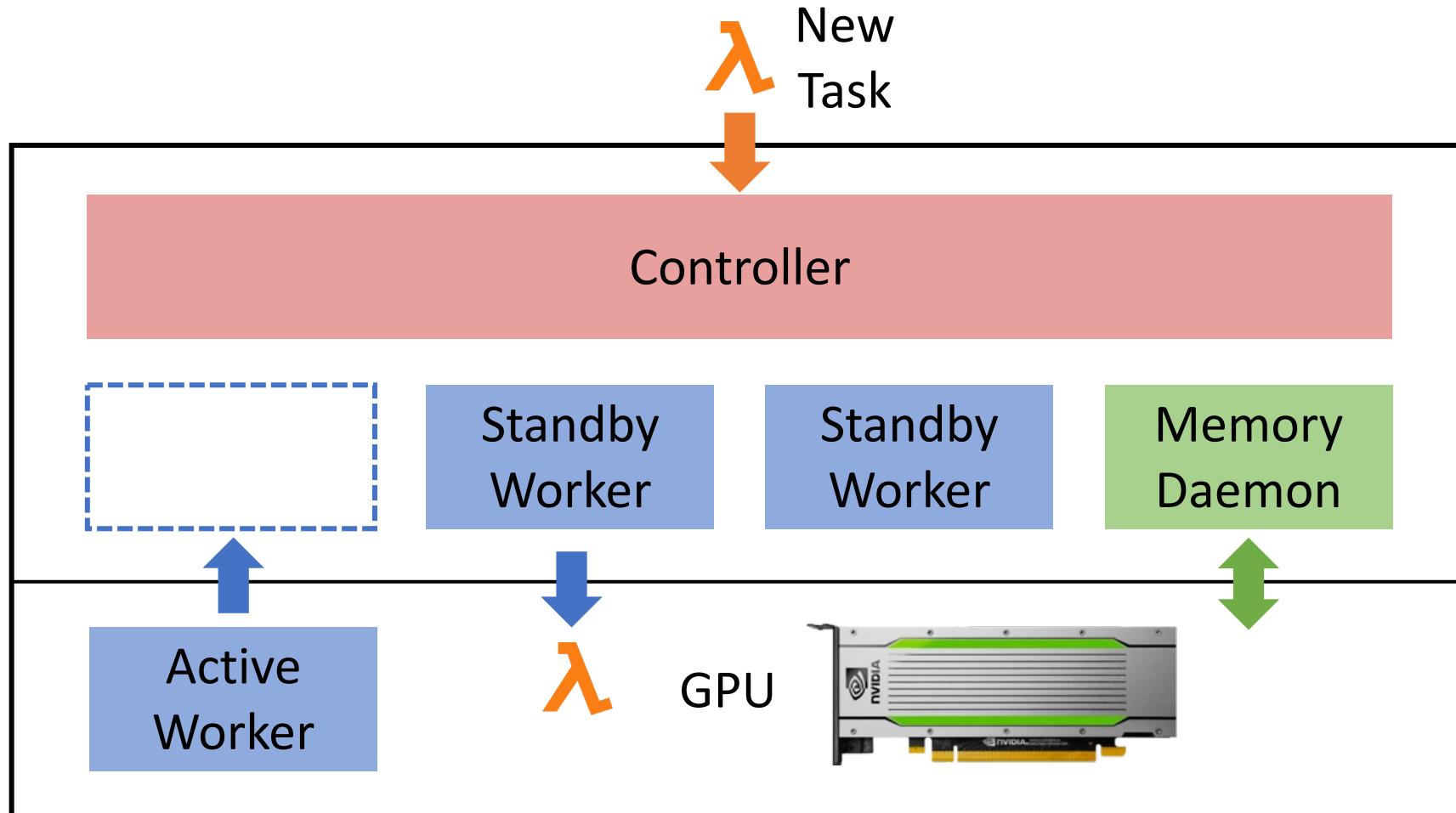
# Goal: fast context switching



- Enable GPU-efficient **multiplexing** of multiple DL apps with **fine-grained time-sharing**
- Achieve **millisecond-scale** context switching latencies and high throughput

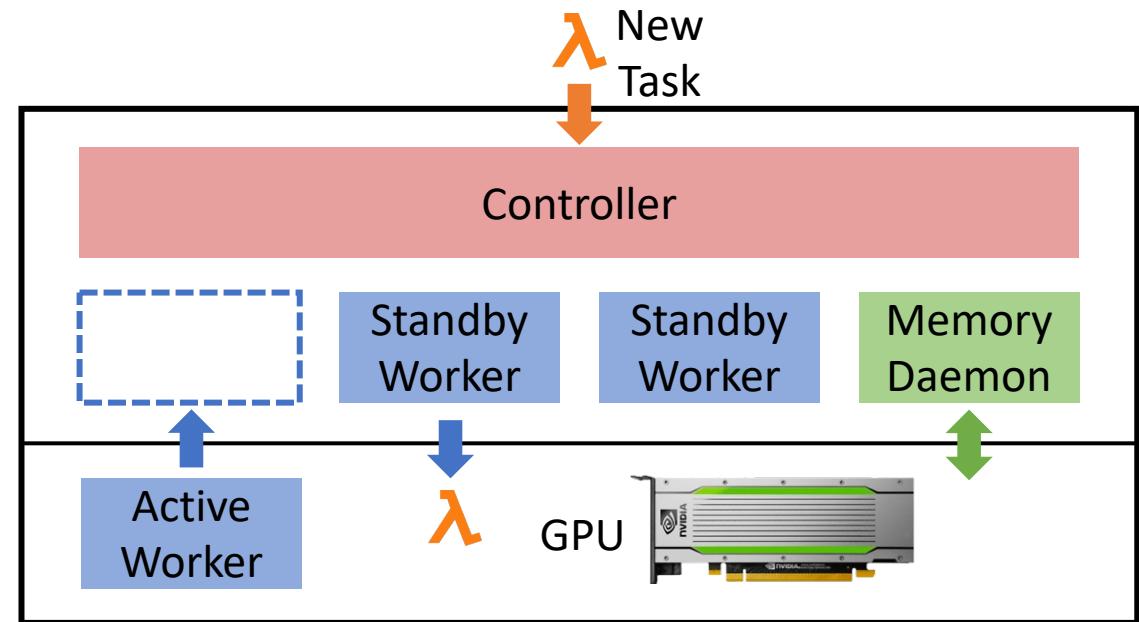
**Latency: 6s**

# PipeSwitch overview: architecture



# PipeSwitch overview: execution

- Stop the current task and prepare for the next task.
- Execute the task with pipelined model transmission.
- Clean the environment for the previous task.



# Sources of context switching overhead

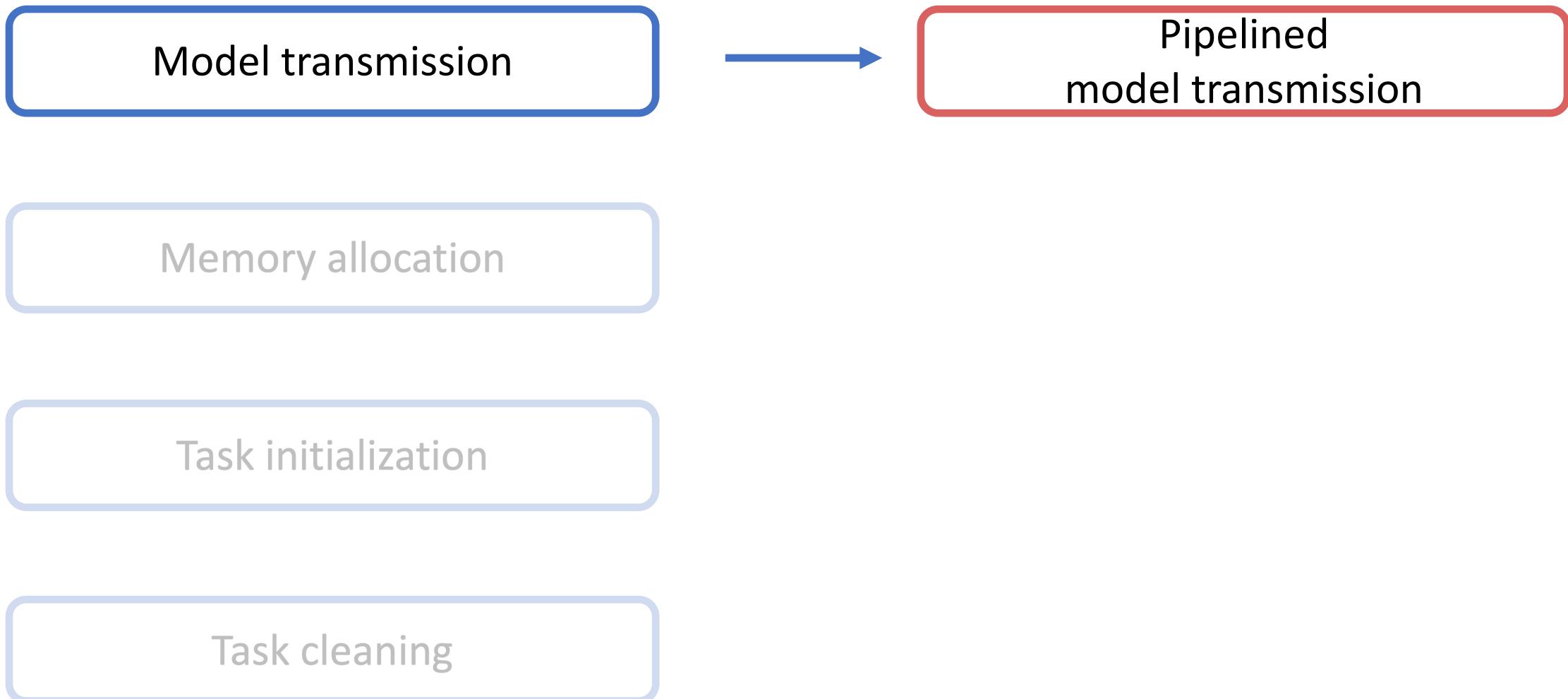
Model transmission

Memory allocation

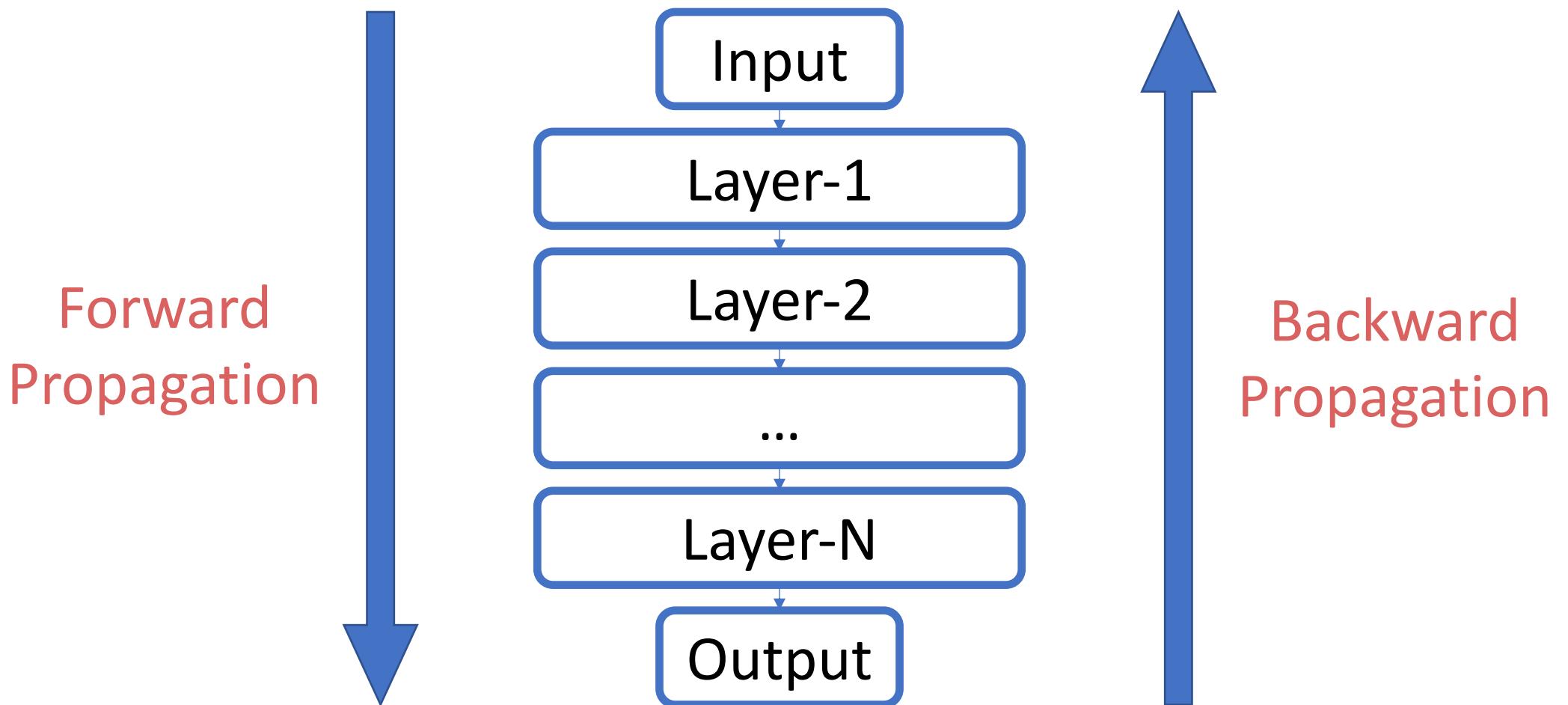
Task initialization

Task cleaning

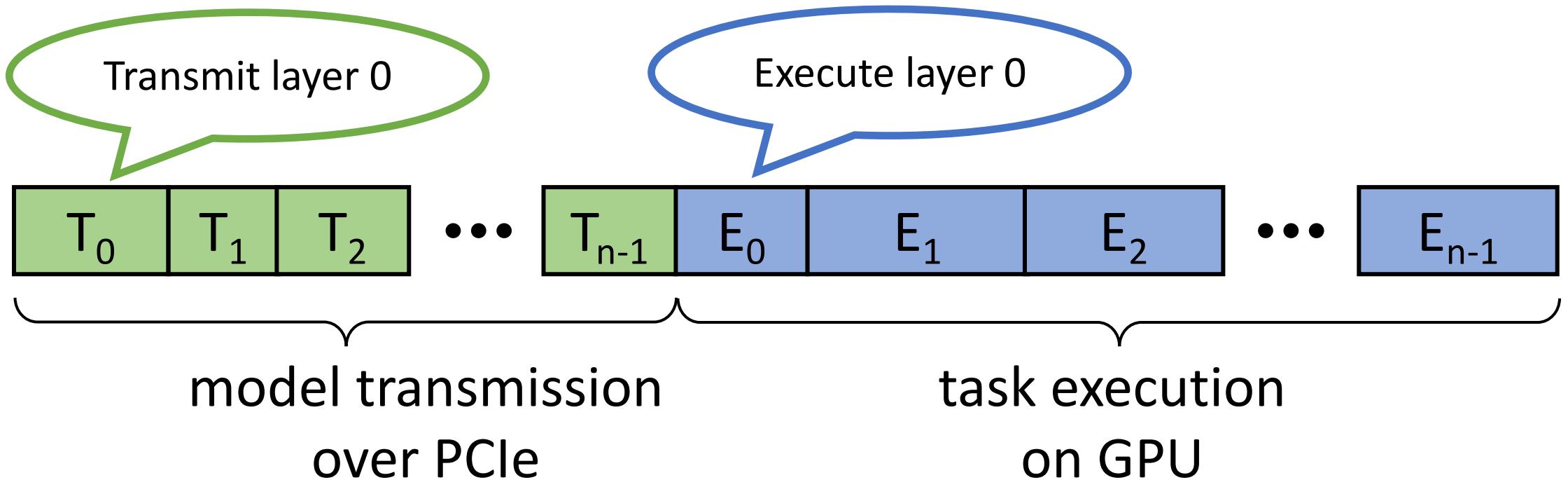
# How to reduce the overhead?



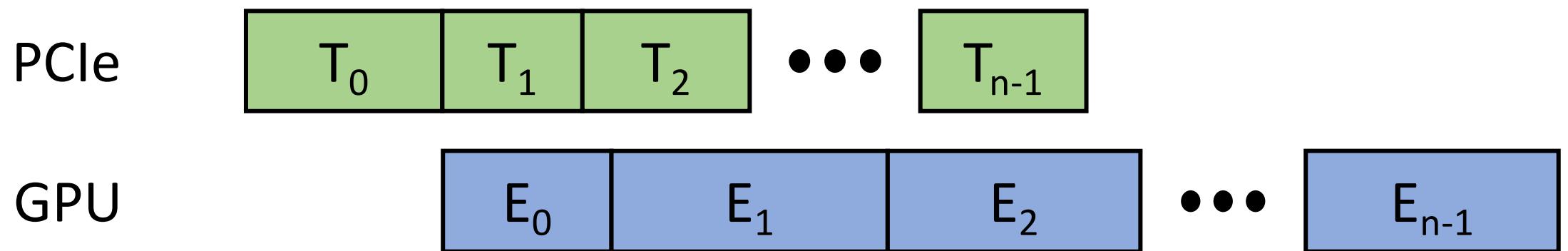
# DL models have layered structures



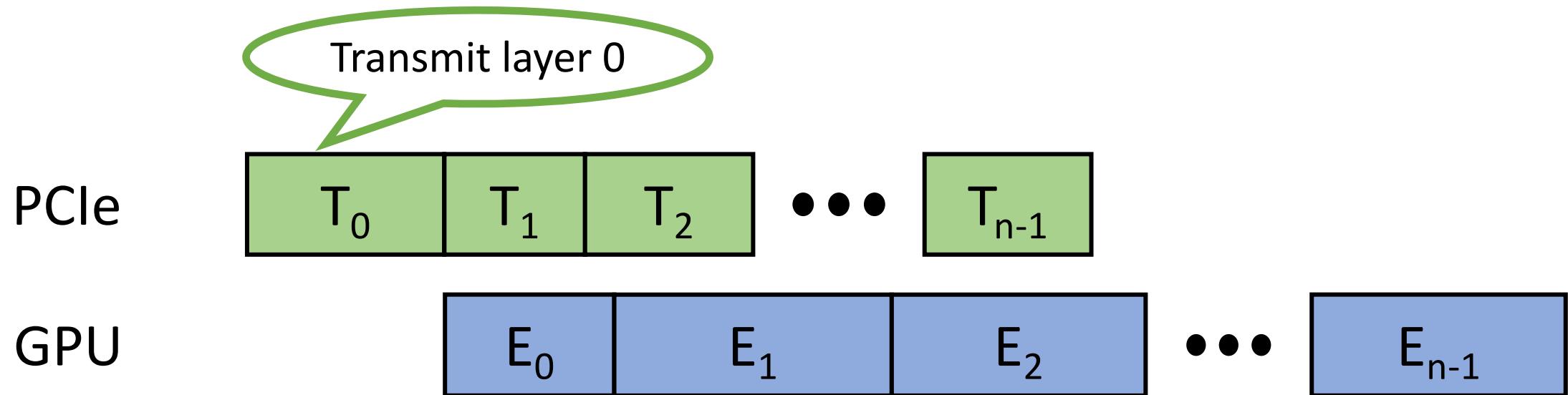
# Sequential model transmission and execution



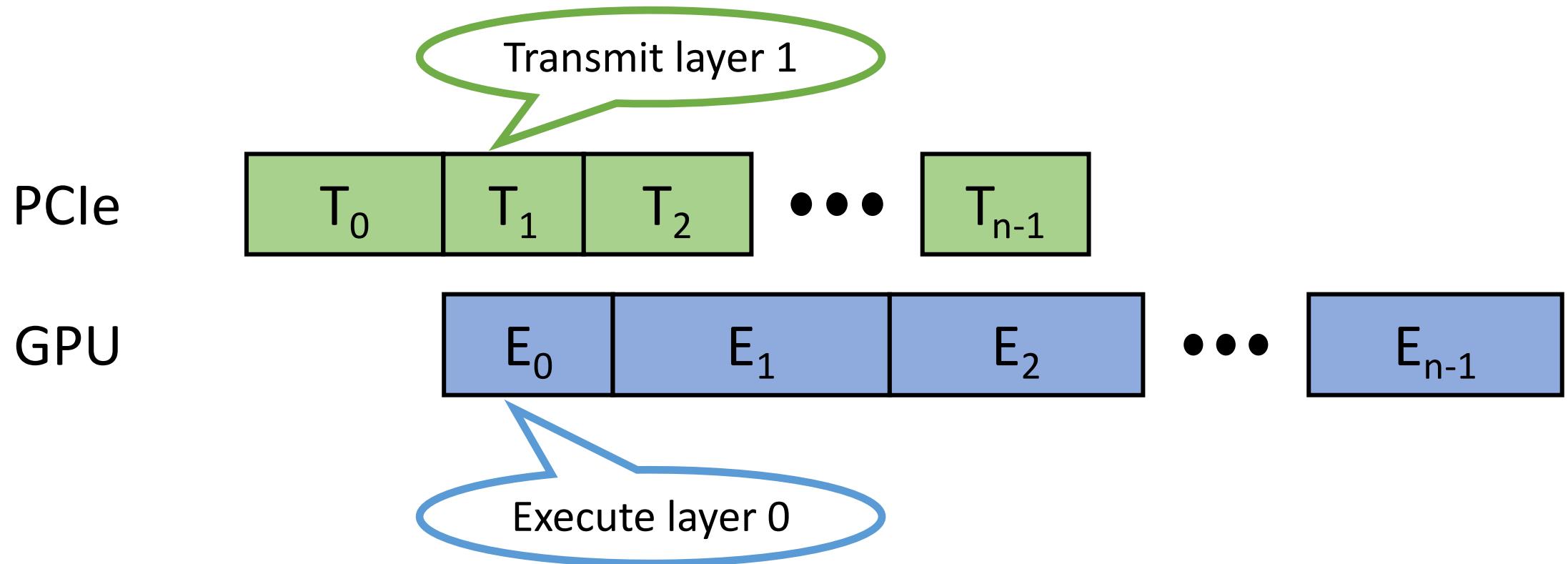
# Pipelined model transmission and execution



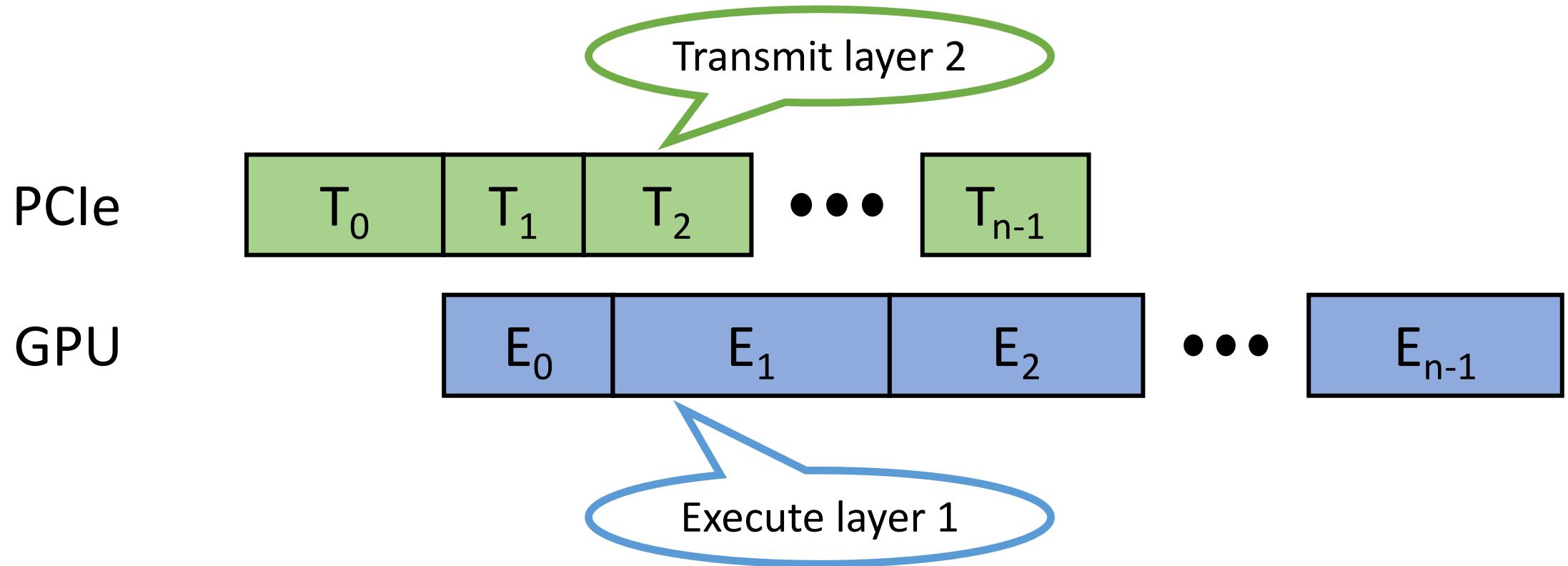
# Pipelined model transmission and execution



# Pipelined model transmission and execution



# Pipelined model transmission and execution



# Pipelined model transmission and execution

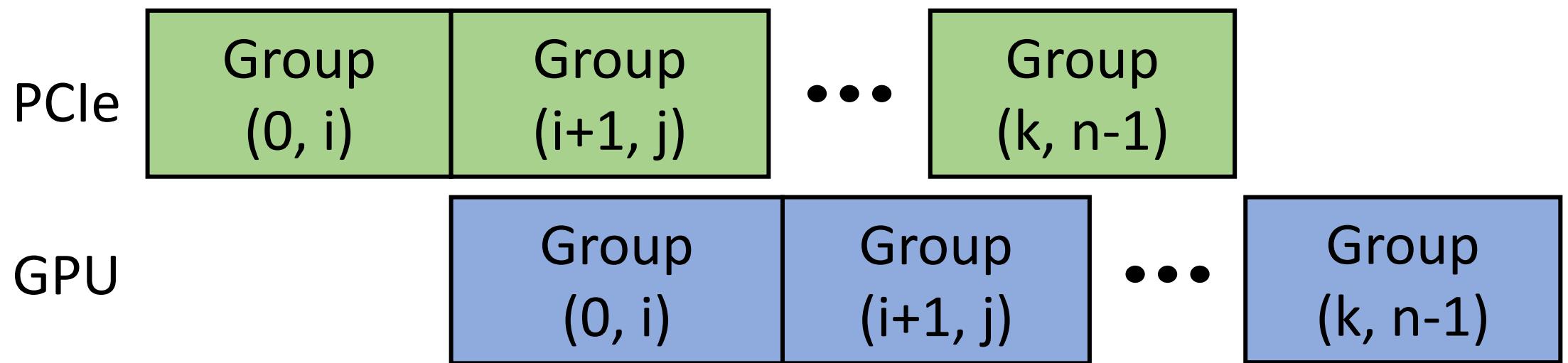
PCIe

GPU

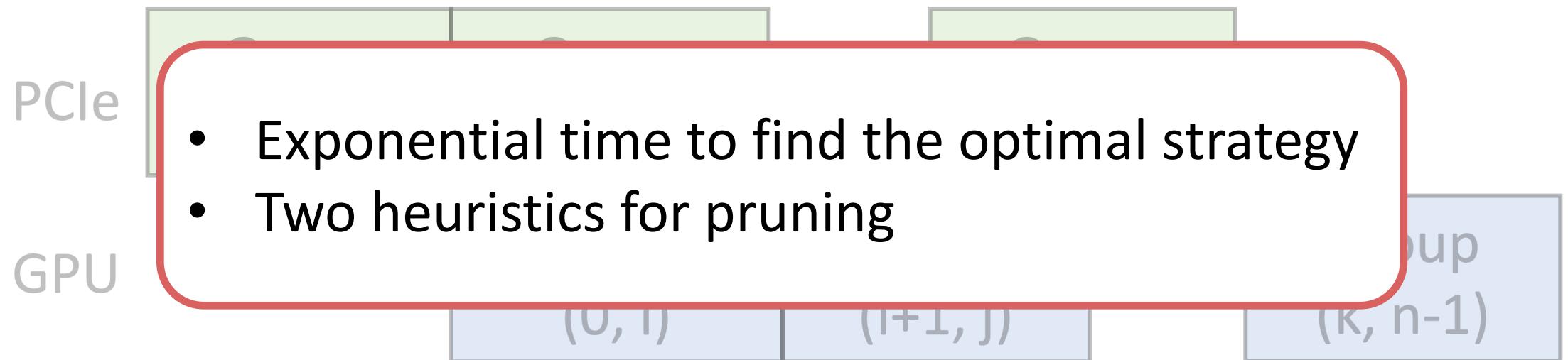
1. Multiple calls to PCIe;
2. Synchronize transmission and execution.

$E_{n-1}$

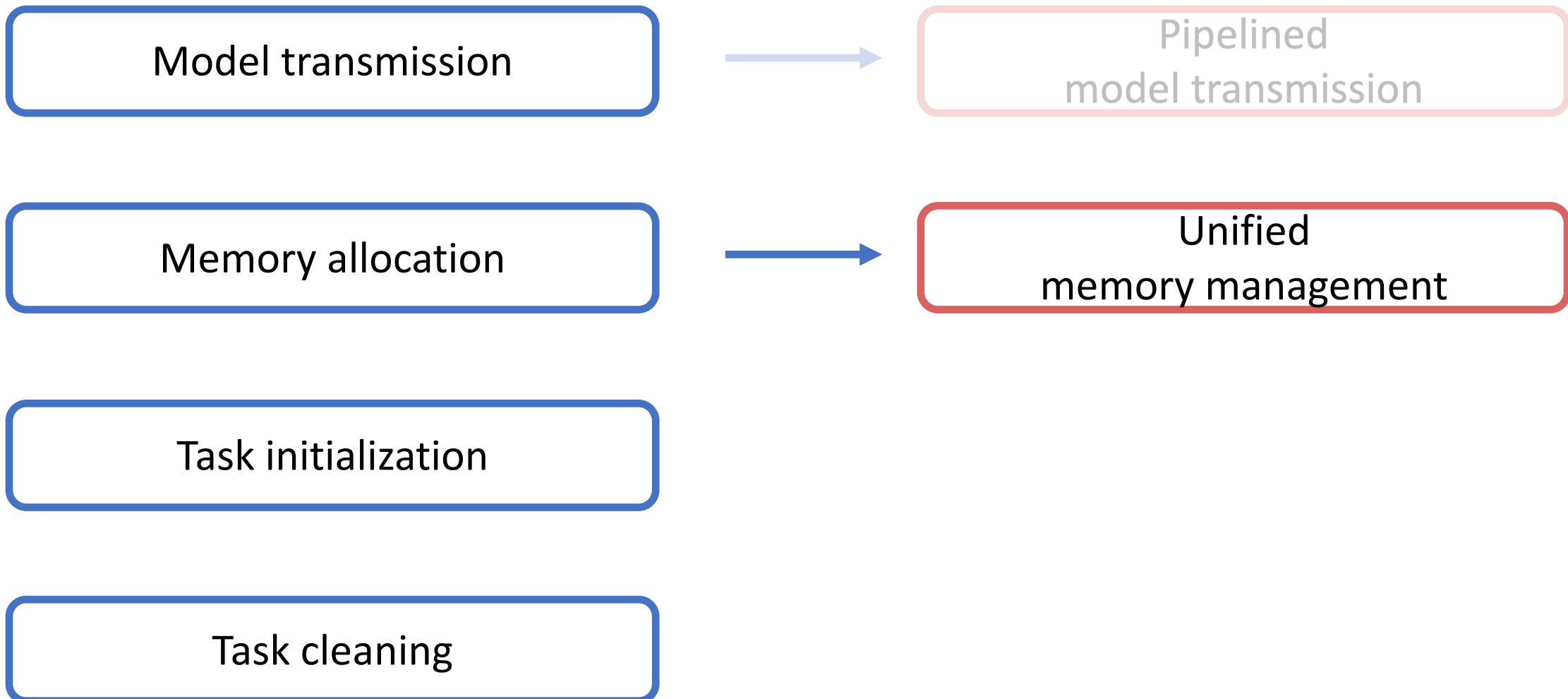
# Pipelined model transmission and execution



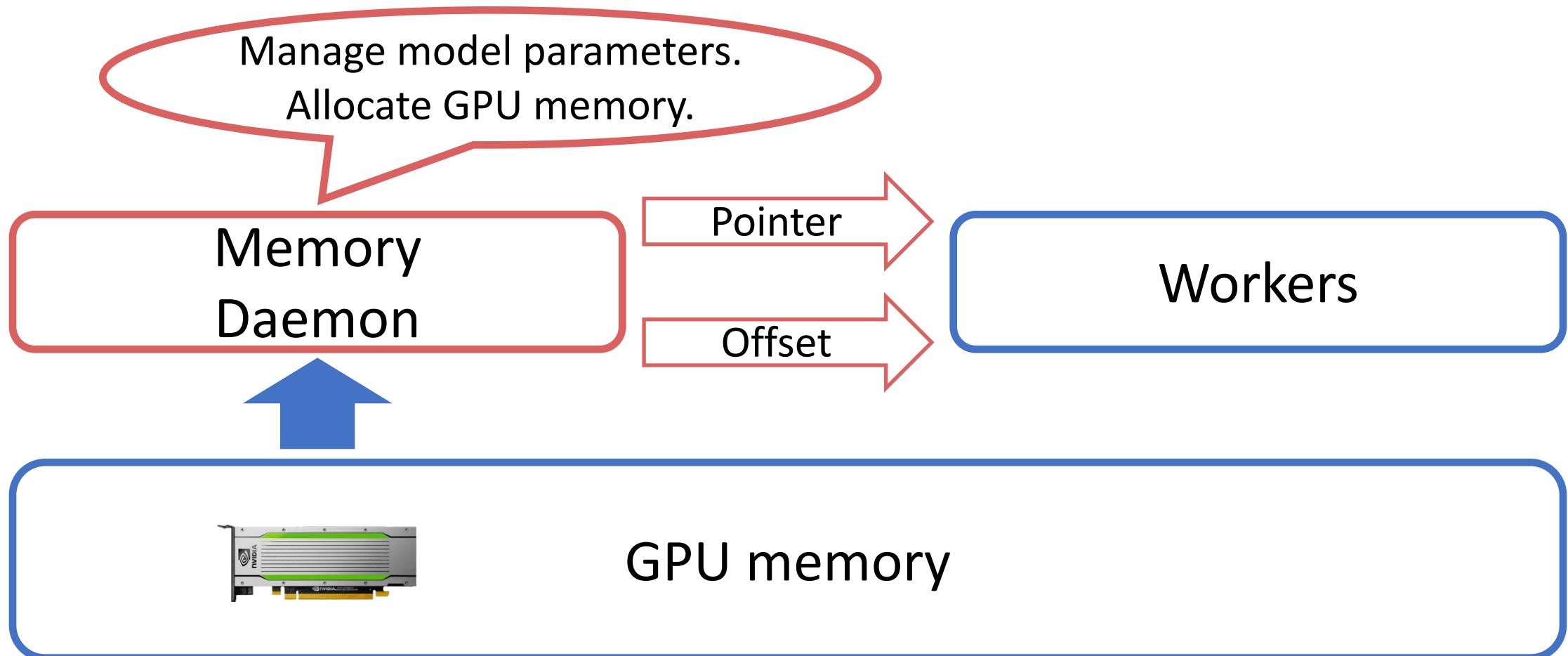
# Pipelined model transmission and execution



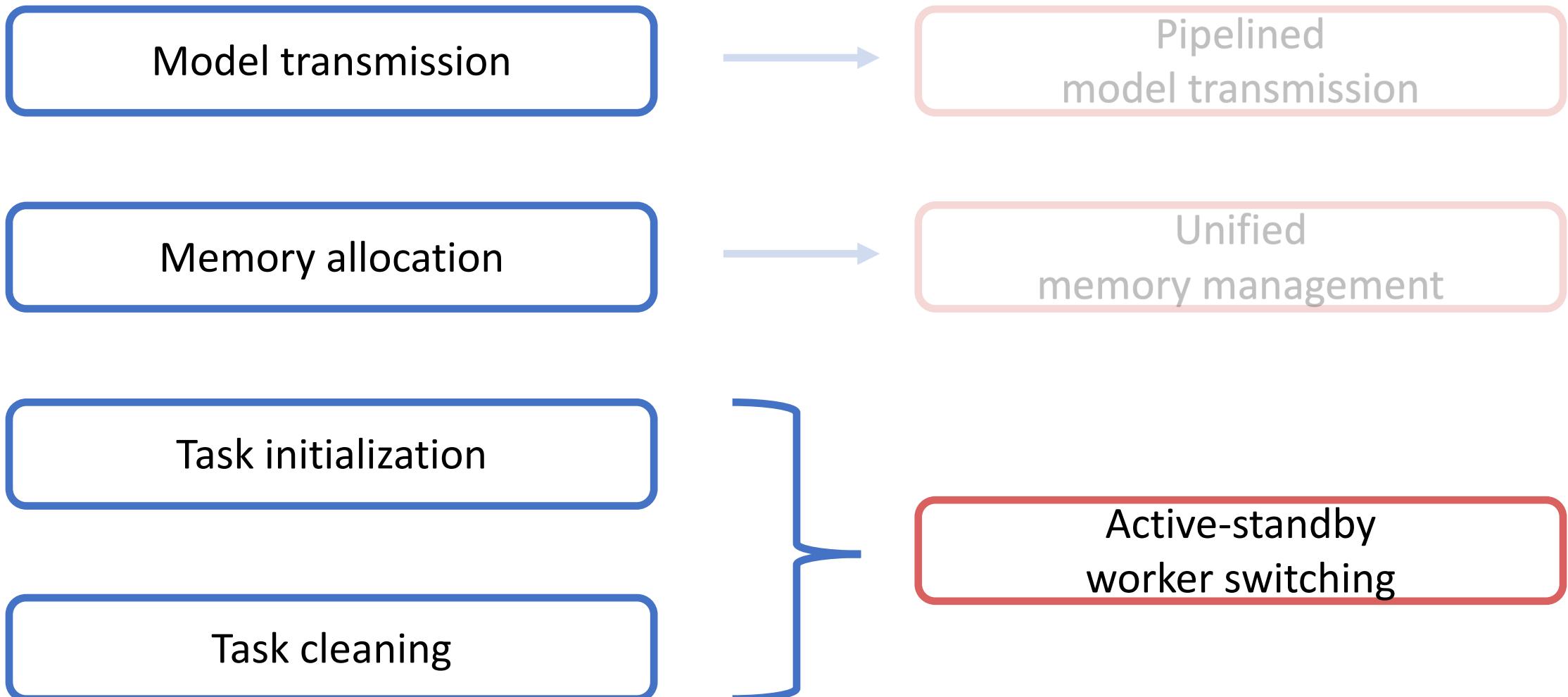
# How to reduce the overhead?



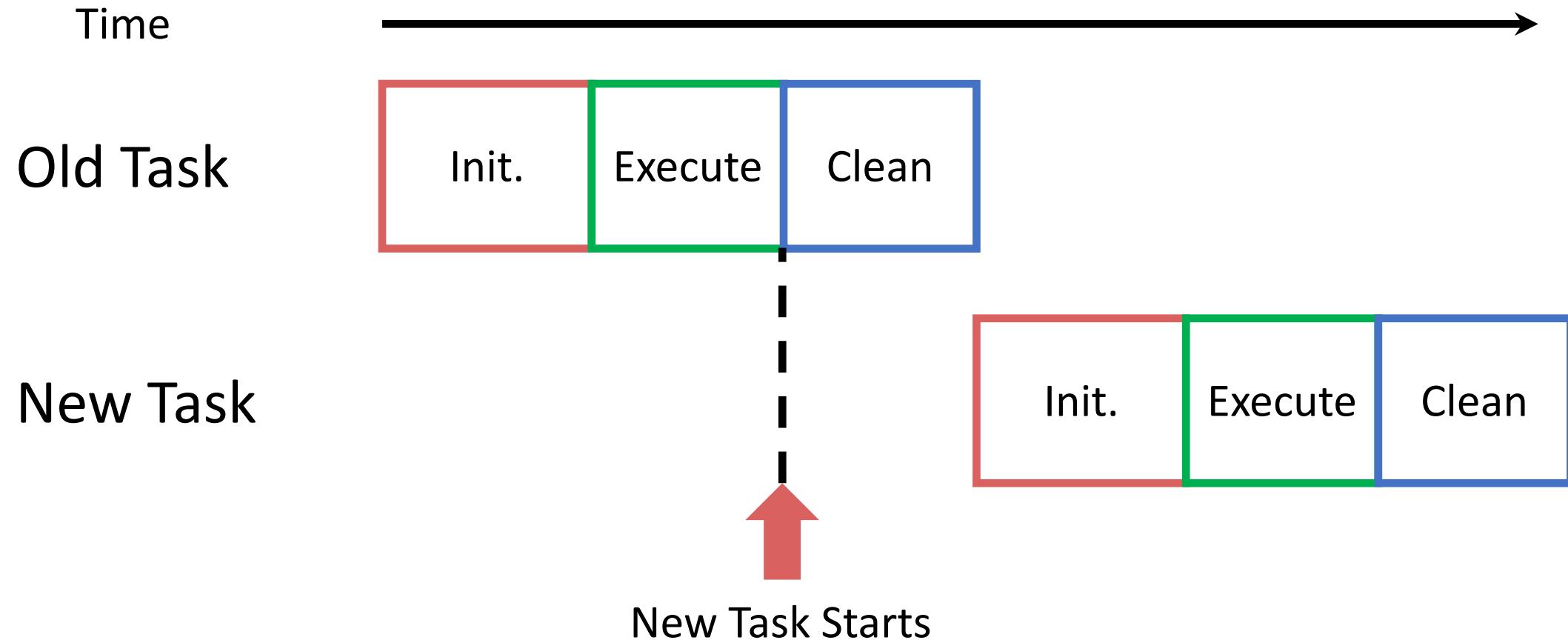
# Unified memory management



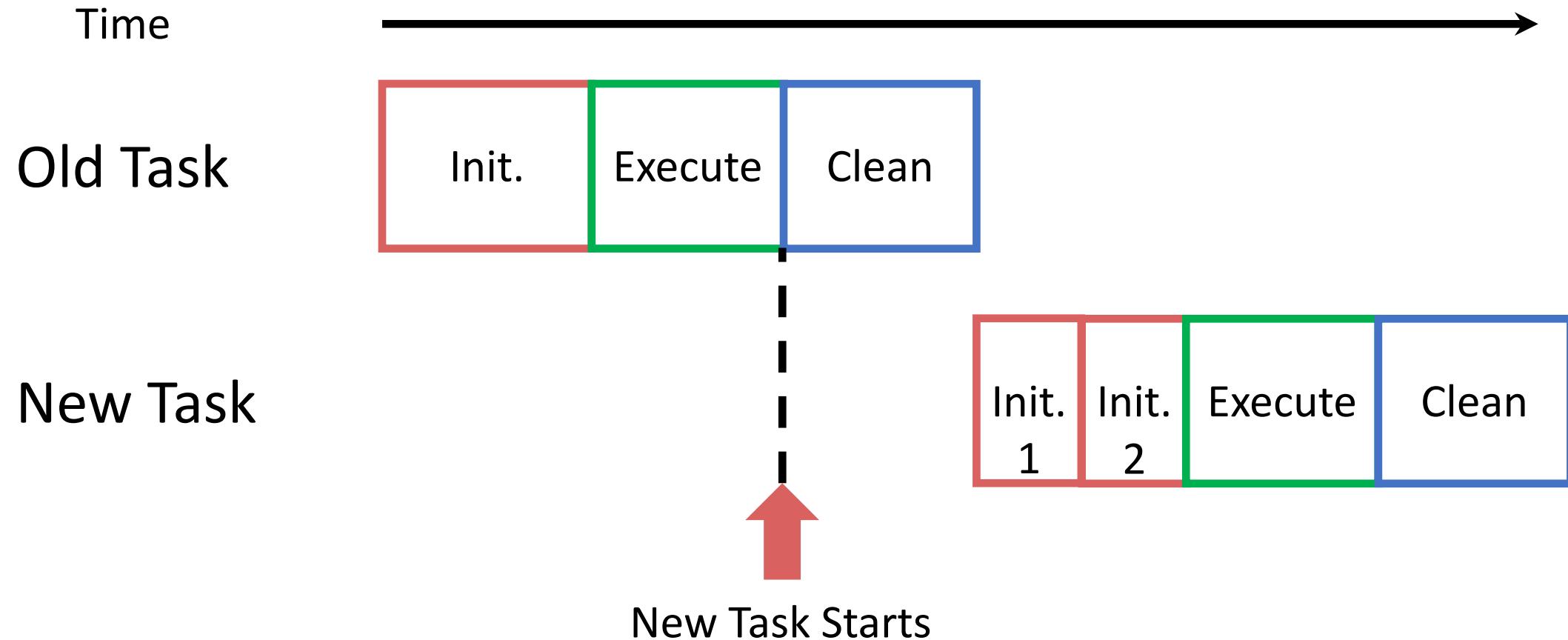
# How to reduce the overhead?



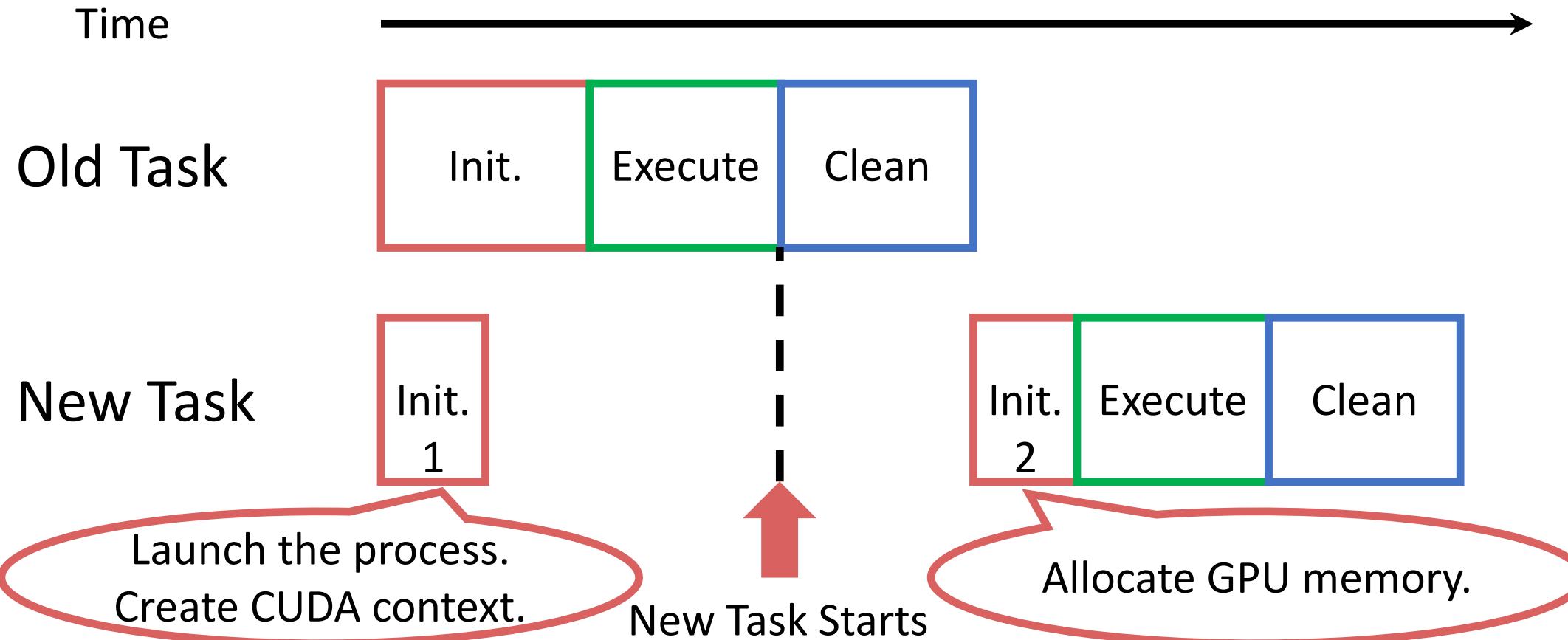
# Active-standby worker switching



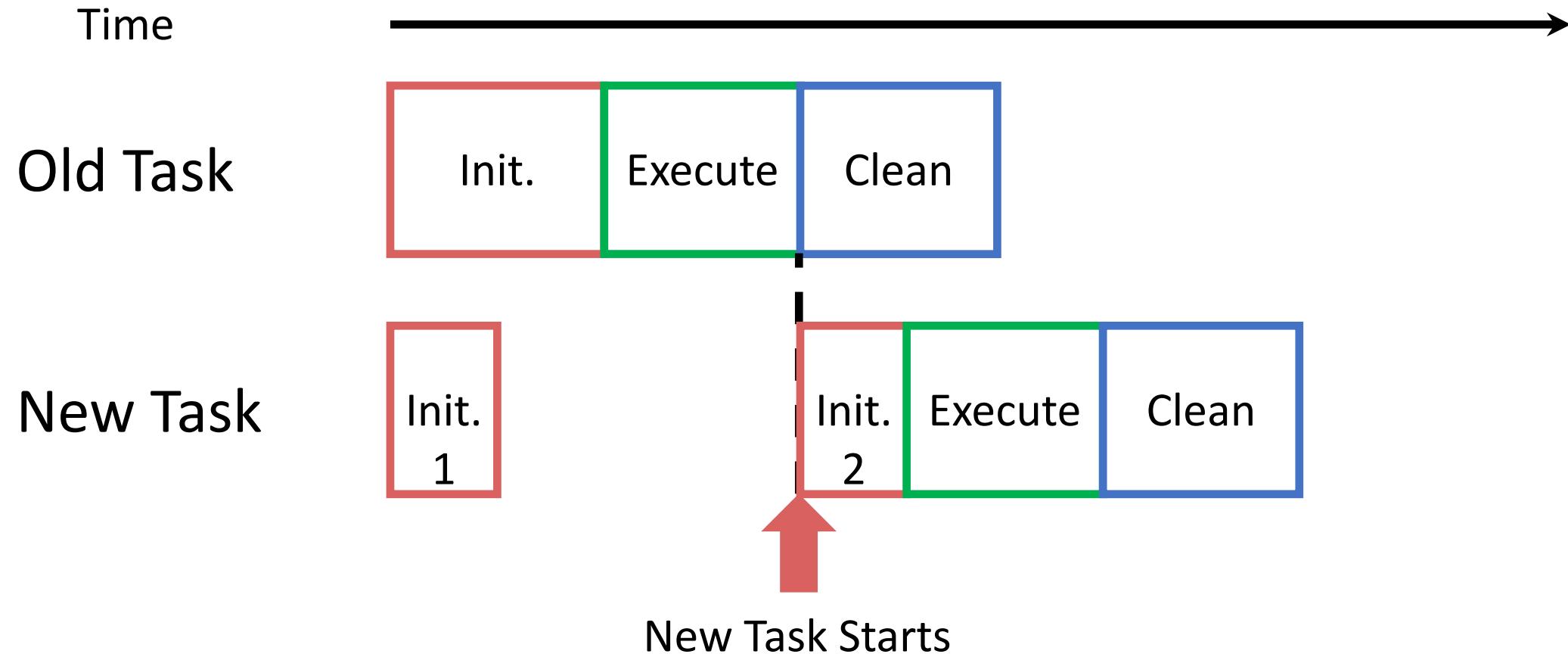
# Active-standby worker switching



# Active-standby worker switching



# Active-standby worker switching



# Implementation

- Testbed: AWS EC2
  - p3.2xlarge: **PCIe 3.0x16**, NVIDIA Tesla **V100** GPU
  - g4dn.2xlarge: **PCIe 3.0x8**, NVIDIA Tesla **T4** GPU
- Software
  - CUDA 10.1
  - PyTorch 1.3.0
- Models
  - ResNet-152
  - Inception-v3
  - BERT-base

# Evaluation

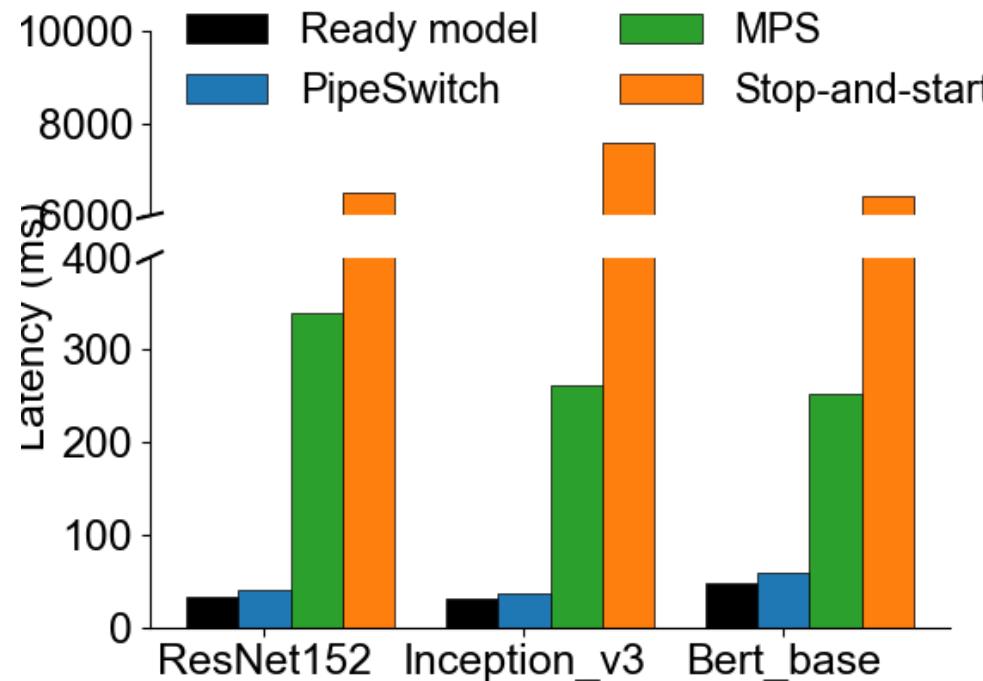
- Can PipeSwitch satisfy SLOs?
- Can PipeSwitch provide high utilization?
- How well do the design choices of PipeSwitch work?

# Evaluation

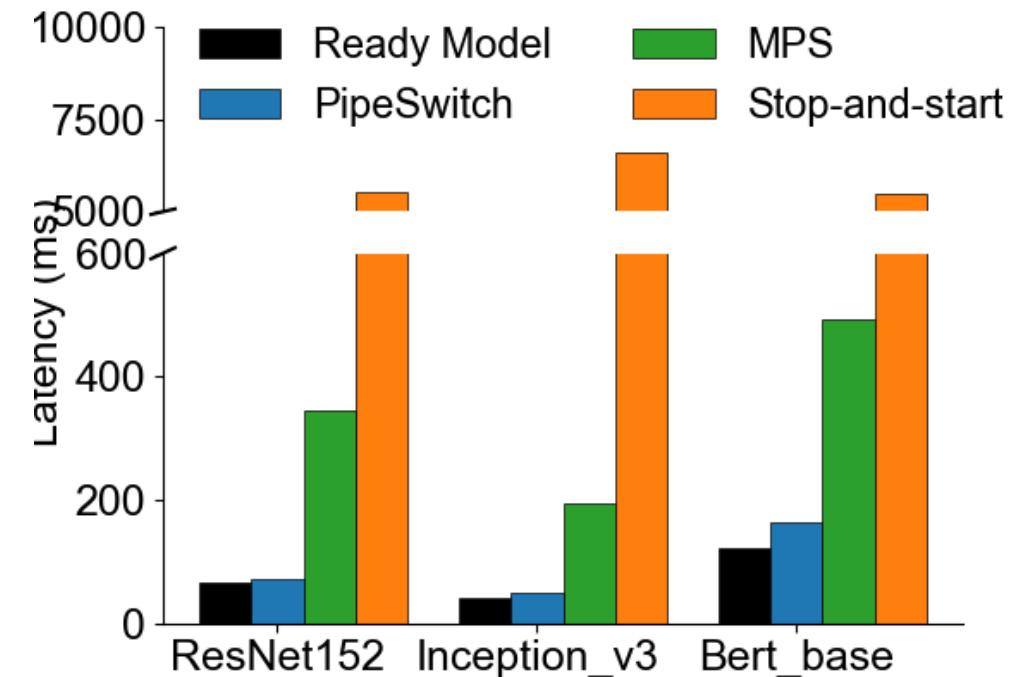
- Can PipeSwitch satisfy SLOs?
- Can PipeSwitch provide high utilization?
- How well do the design choices of PipeSwitch work?

# PipeSwitch satisfies SLOs

NVIDIA Tesla V100

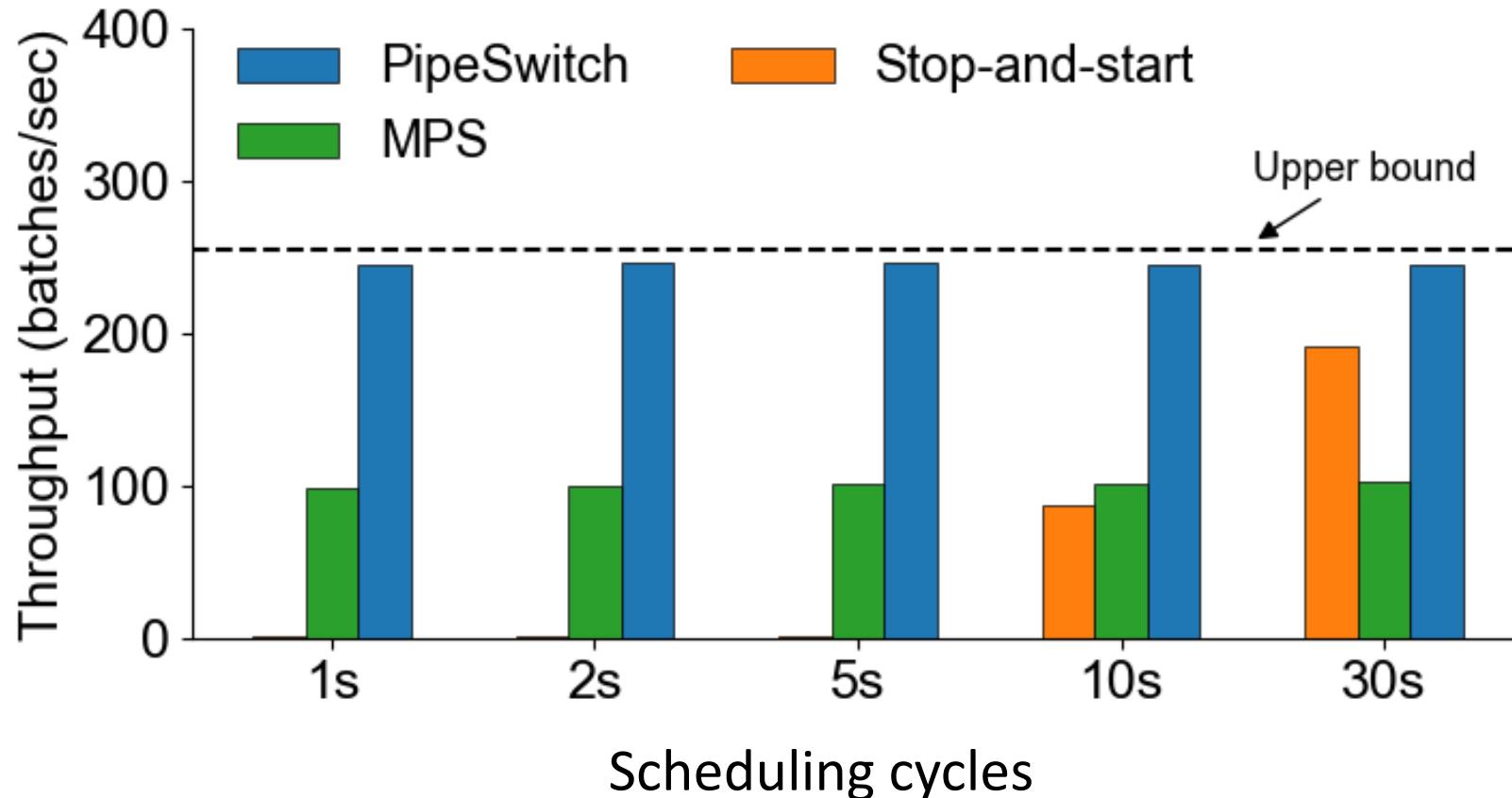


NVIDIA Tesla T4



PipeSwitch achieves low context switching latency.

# PipeSwitch provide high utilization



**PipeSwitch achieves near 100% utilization.**

# Summary

- GPU clusters for DL applications suffer from low utilization
  - Limited share between training and inference workloads
- PipeSwitch introduces pipelined context switching
  - Enable GPU-efficient multiplexing of DL apps with fine-grained time-sharing
  - Achieve millisecond-scale context switching latencies and high throughput

# Memory Management in Modern Computer Systems

- Memory Abstraction
  - NSDI'14 FaRM
- Demand paging: remote memory over RDMA
  - NSDI'17 InfiniSwap
  - OSDI'20 AIFM
- Demand paging: memory swapping between GPU memory and host memory
  - OSDI'20 PipeSwitch
  - NSDI'23 TGS



# Transparent GPU Sharing in Container Clouds for Deep Learning Workloads

Bingyang Wu, Zili Zhang, Zhihao Bai, Xuanzhe Liu, Xin Jin



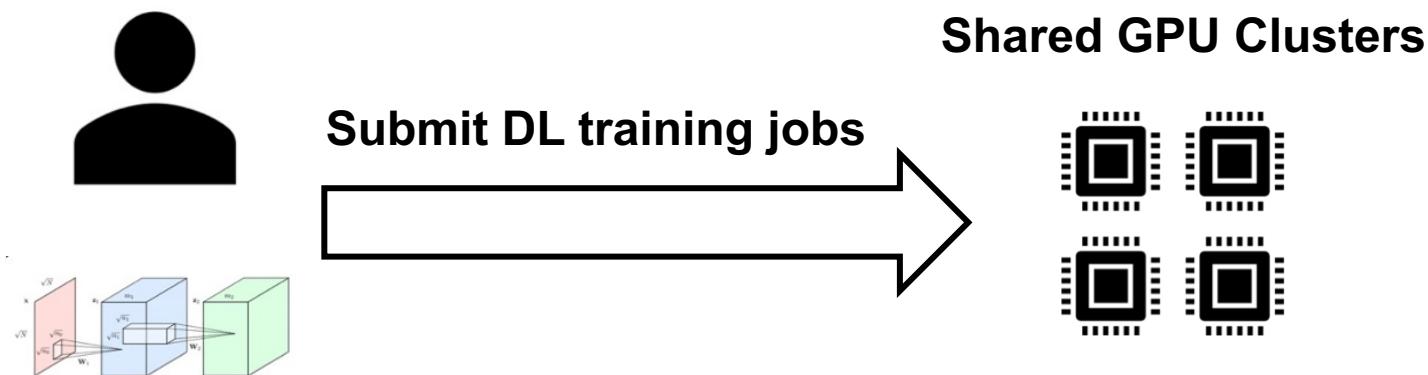
北京大学  
PEKING UNIVERSITY



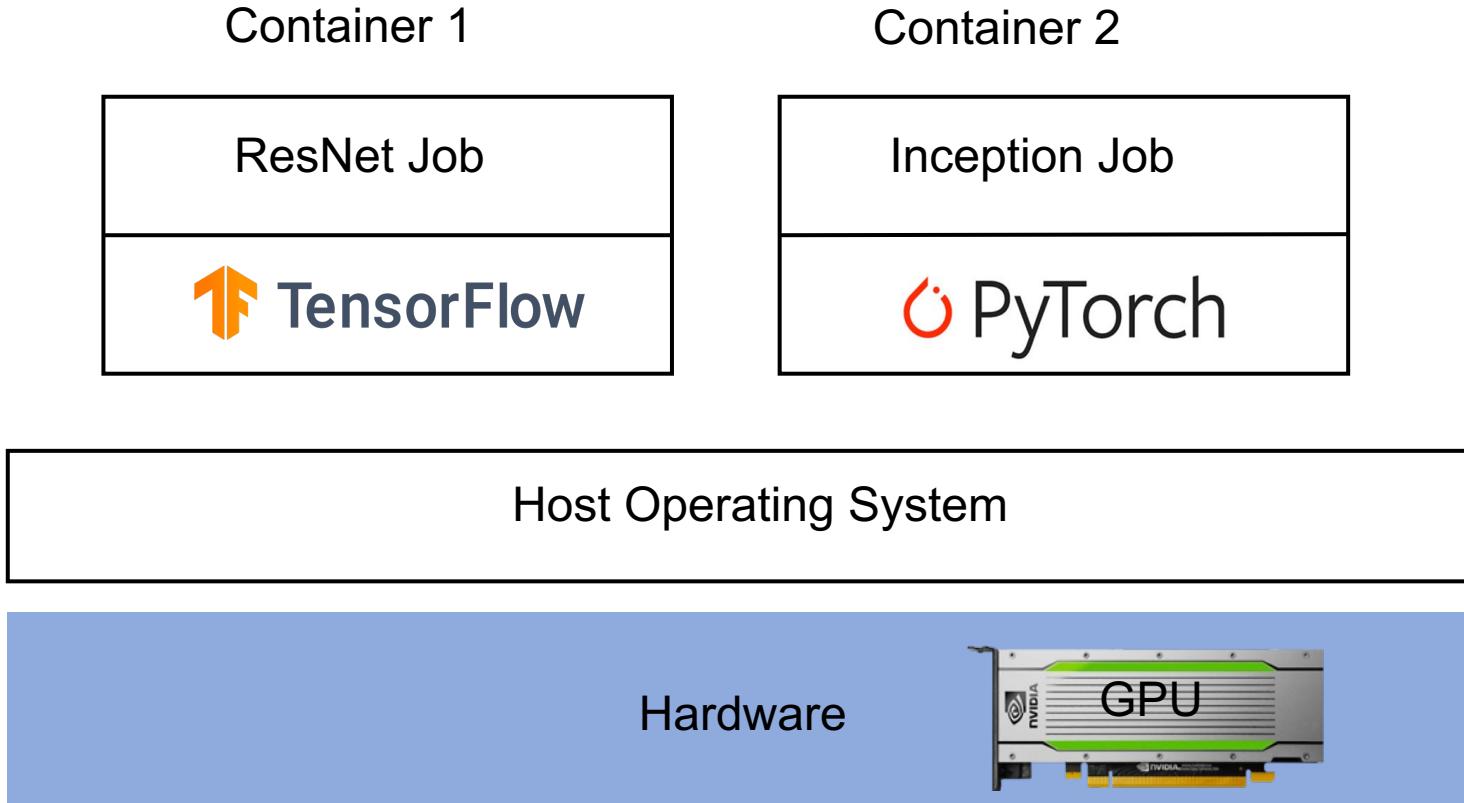
JOHNS HOPKINS  
UNIVERSITY

# Deep learning training jobs: important workloads in datacenters

- Deep learning is widely used in many applications
  - Recommendation
  - Machine Translation
  - Voice Assistant
  - .....
- Deep learning models are often trained in **shared GPU clusters**



# Deep learning training jobs in container clouds



# Low GPU utilization in production

- Microsoft [1]: the average GPU utilization is only 52%
- Alibaba [2]: the median GPU utilization is no more than 10%
- Low GPU utilization is bad
  - Container clouds: idle GPUs are a huge waste
  - Users: longer queueing delay, longer job completion time
- **Root cause:** Each GPU is statically assigned to a single container

[1] M. Jeon, et al., “Analysis of large-scale multitenant GPU clusters for DNN training workloads,” in *USENIX ATC 2019*.

[2] W. Xiao, et al., “Antman: Dynamic scaling on GPU clusters for deep learning,” in *USENIX OSDI 2020*.

# Existing GPU sharing solutions

- **Key idea:** Share GPUs to improve GPU utilization
- Classify DLT jobs into two classes
  - Production job: Run without performance degradation
  - Opportunistic job: Utilize spare GPU resources to execute
- SOTA solutions:
  - Application-layer solution: AntMan [OSDI' 20]
  - OS-layer solution: NVIDIA MPS, NVIDIA MIG

# Application-layer solution: AntMan

- Custom DL framework
  - Modify TensorFlow (~4000 LoC) or PyTorch (~2000 LoC)
- Support GPU compute sharing and GPU memory oversubscription
- **Limitations:** Lack of Transparency
  - **Limited use cases:** restricts users to use particular frameworks
  - **Huge operation overhead:** need to maintain custom frameworks

# OS-layer solution: NVIDIA MPS

- A software solution for GPU sharing provided by NVIDIA
- Limitations:
  - Low GPU utilization
    - Does not support GPU memory oversubscription
    - Requires application knowledge to properly set the resource limit
  - Weak fault isolation
    - When a job fails, other jobs may be affected and even fails

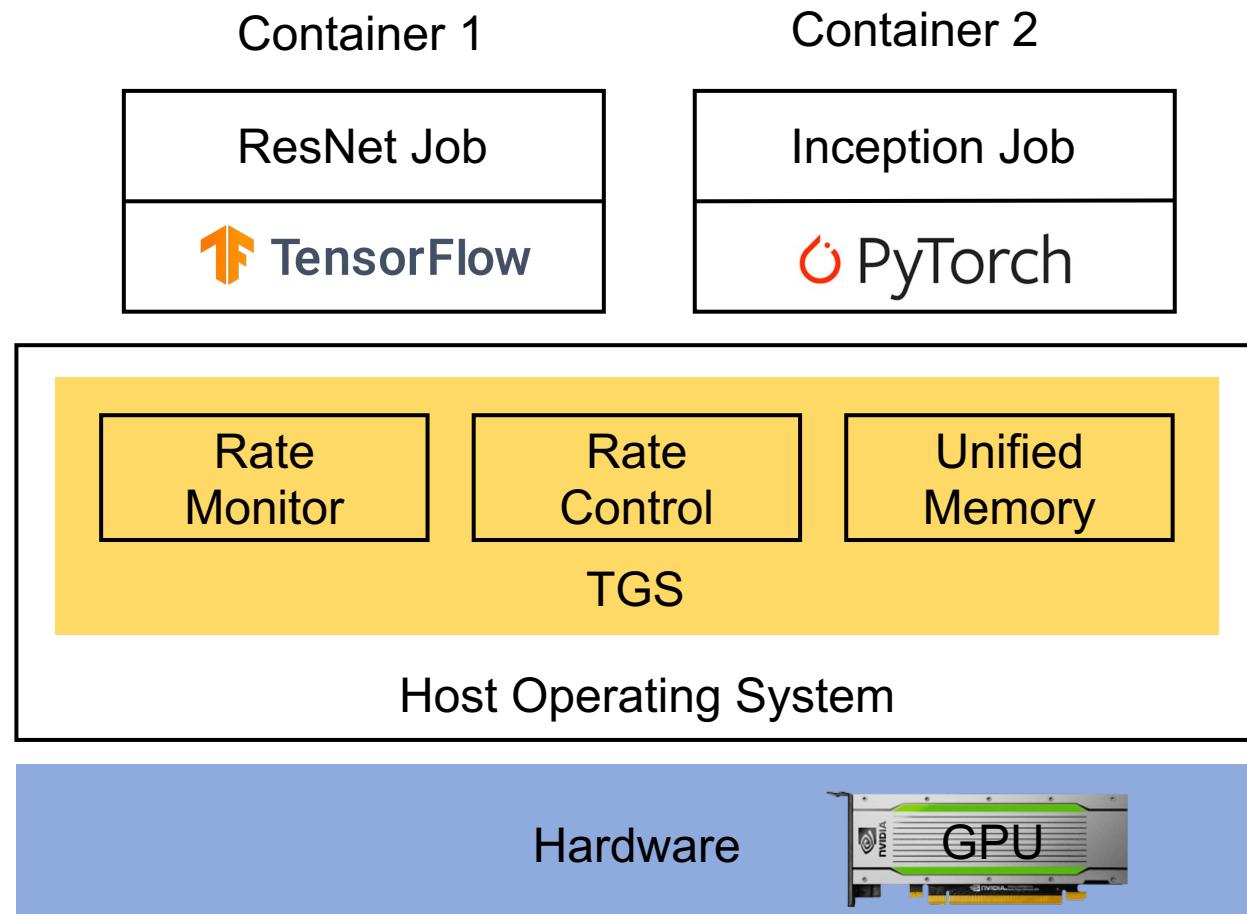
## OS-layer solution: NVIDIA MIG

- A recent hardware solution for GPU sharing provided by NVIDIA
- Limitations:
  - Performance isolation
    - Cannot arbitrarily partition a GPU
    - Cannot dynamically change GPU resources
  - Compatibility
    - Only available on a few high-end GPUs
    - Does not support GPU sharing for the multi-GPU instance

# A more practical solution: TGS

|                       | AntMan | MPS | MIG | TGS |
|-----------------------|--------|-----|-----|-----|
| Transparency          |        | ✓   | ✓   | ✓   |
| High utilization      | ✓      |     |     | ✓   |
| Performance isolation | ✓      | ✓   | ✓   | ✓   |
| Fault isolation       | ✓      |     | ✓   | ✓   |

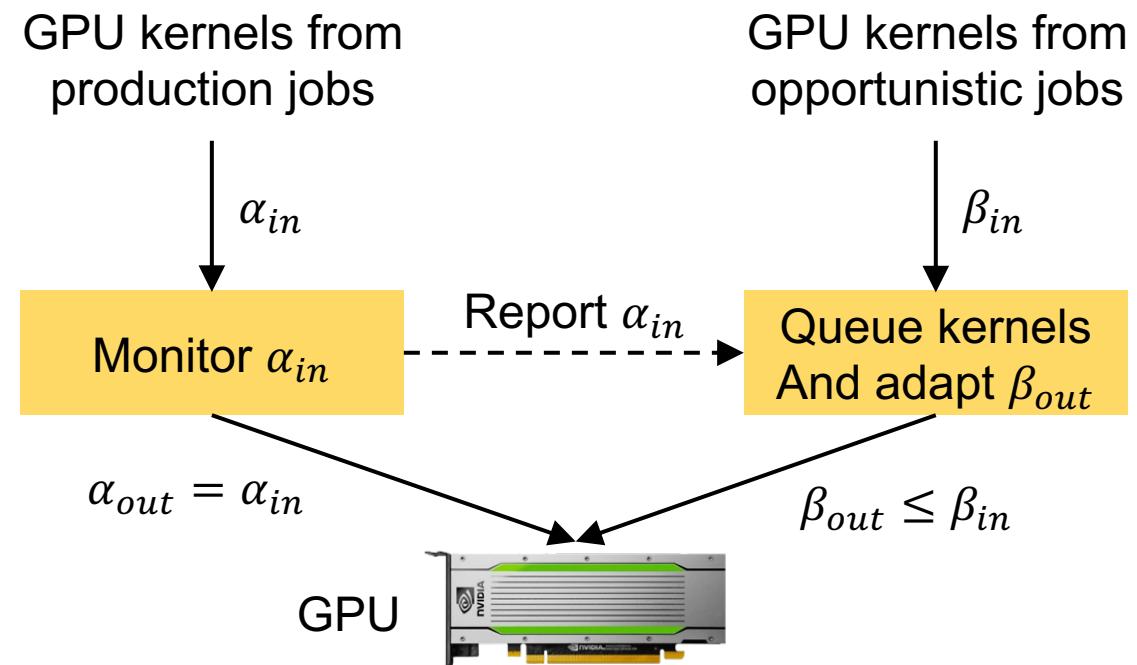
# TGS architecture



# Sharing GPU compute resources

- Strawman solution: priority scheduling
  - Control the opportunistic job based on the GPU kernel queues
- Low GPU utilization:
  - The state of queues do not reflect the remaining GPU resources

# Adaptive rate control of TGS



# Sharing GPU memory resources

- **Weak Fault isolation:** total GPU memory consumption may exceed GPU memory capacity and cause OOM
- **Low GPU utilization:** some jobs always claim all GPU memory
- Application-layer technique cannot be used in the OS layer
  - Cannot directly ask DL framework to release unused GPU memory
  - Cannot directly change pointer address from GPU memory to host memory

# Transparent unified memory of TGS

- **Key ideas:** leverage CUDA unified memory to transparently unify GPU memory and host memory
- **High GPU utilization:** The actual physical GPU memory is allocated when jobs first access to them
- **Fault isolation:** When GPU memory is oversubscribed, TGS changes virtual memory mapping to evict GPU memory of opportunistic job to host memory

# Evaluation setup

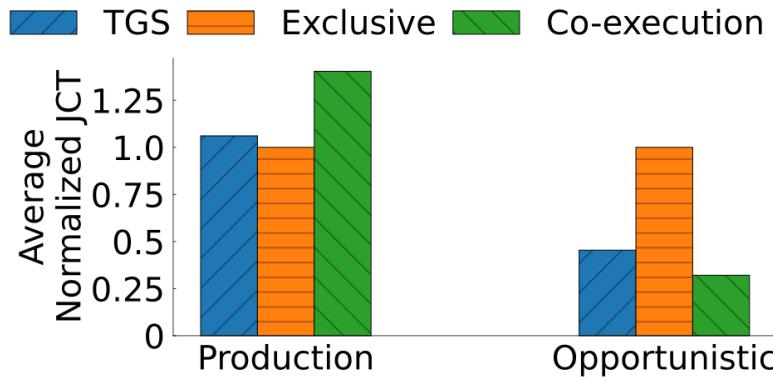
- Implementation: ~3000 LoC C++ & Python
  - Integration with Docker and Kubernetes
- Testbed: NVIDIA A100 GPUs and NVIDIA V100 GPUS
- Trace: Philly Trace from Microsoft [Jeon et al. 2019]
- Models
  - CV: ResNet, ShuffleNet, MobileNet
  - Graph: GCN
  - NLP: Bert, GPT-2
  - Recommendation: DLRM

# Evaluation baselines

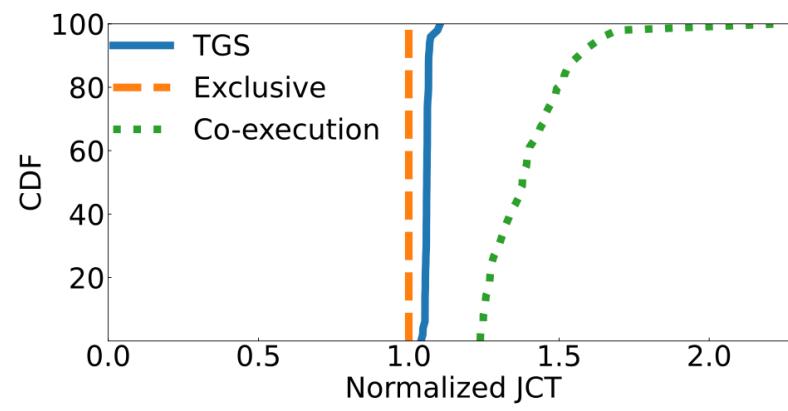
- **TGS**: our work
- **AntMan**: the state-of-the-art application-layer solution
- **MPS**: manually set appropriate limit
- **MIG**: manually set best configuration
- **Exclusive**: give exclusive access to a GPU
- **Co-execution**: share a GPU without any control

# Mixed workload job stream

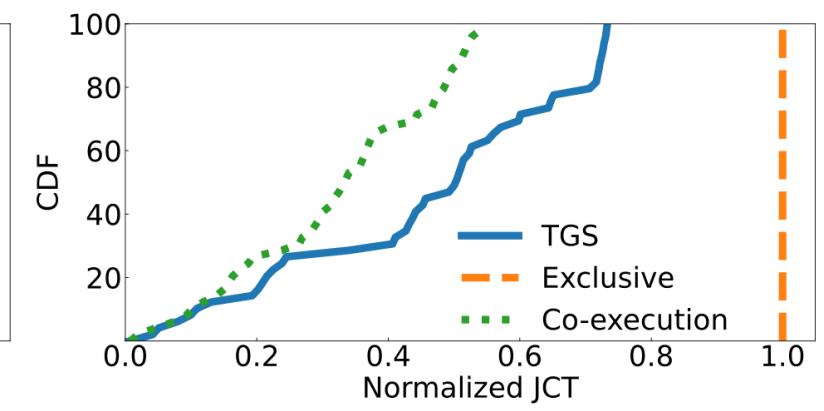
- A job stream contains 50 production jobs and 50 opportunistic jobs
- Opportunistic jobs: **52%** JCT reduction compared to Exclusive
- Production jobs: **21%** JCT reduction compared to Co-execution



(a) Average JCT.



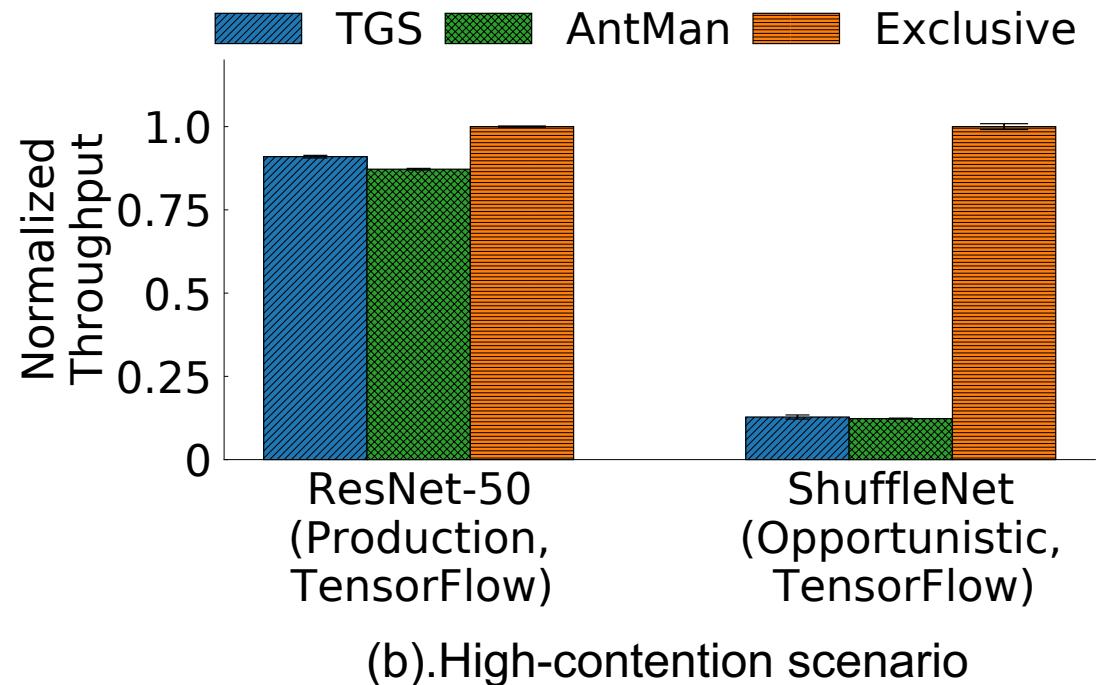
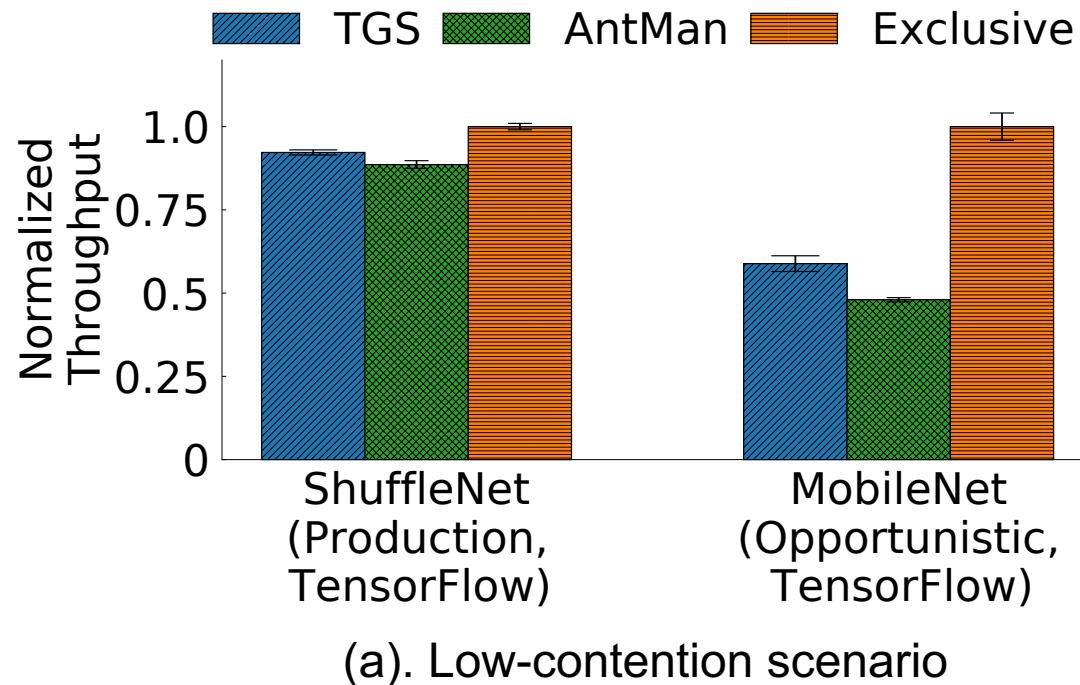
(b) CDF of production jobs.



(c) CDF of opportunistic jobs.

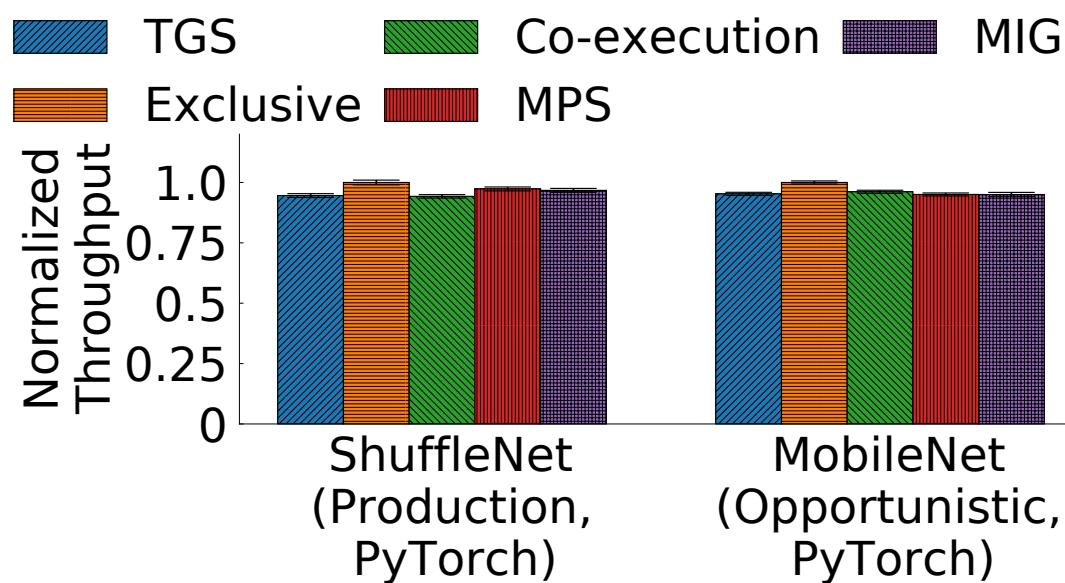
# Comparison with AntMan

- Achieve comparable performance in different contention scenarios
- Provide transparency without sacrificing performance

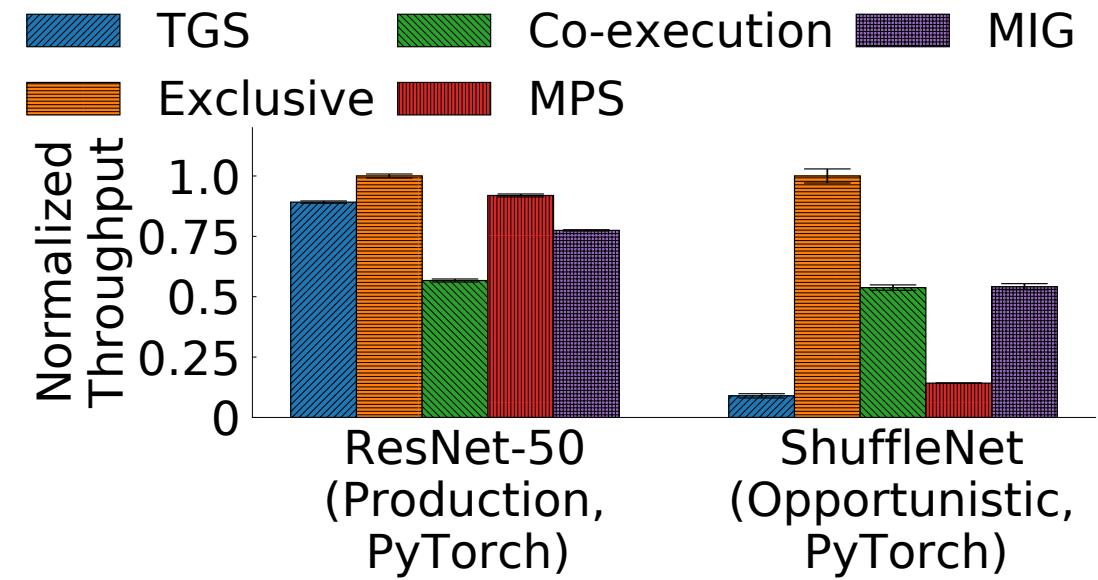


# Adaptive rate control of TGS

- TGS protects productions job with little overhead, while providing remaining GPU resources to opportunistic jobs



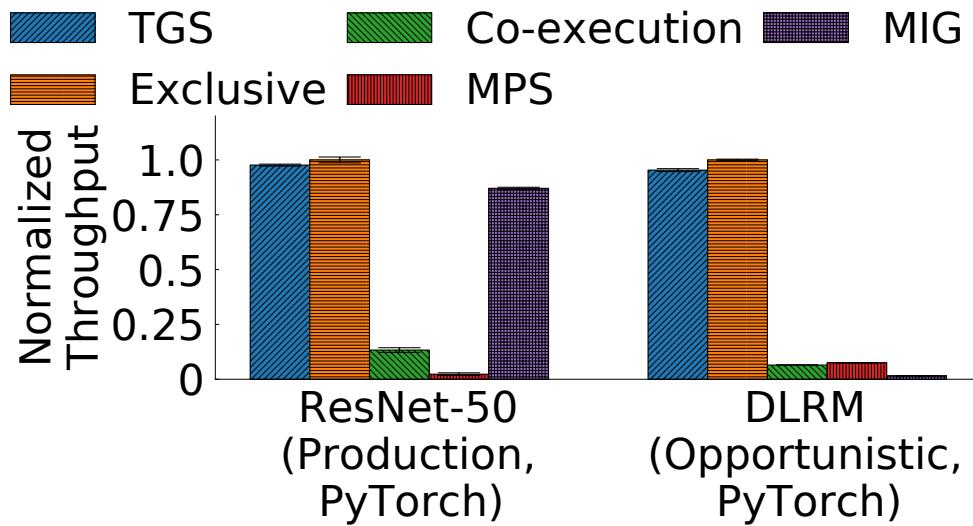
(a). Low-contention scenario



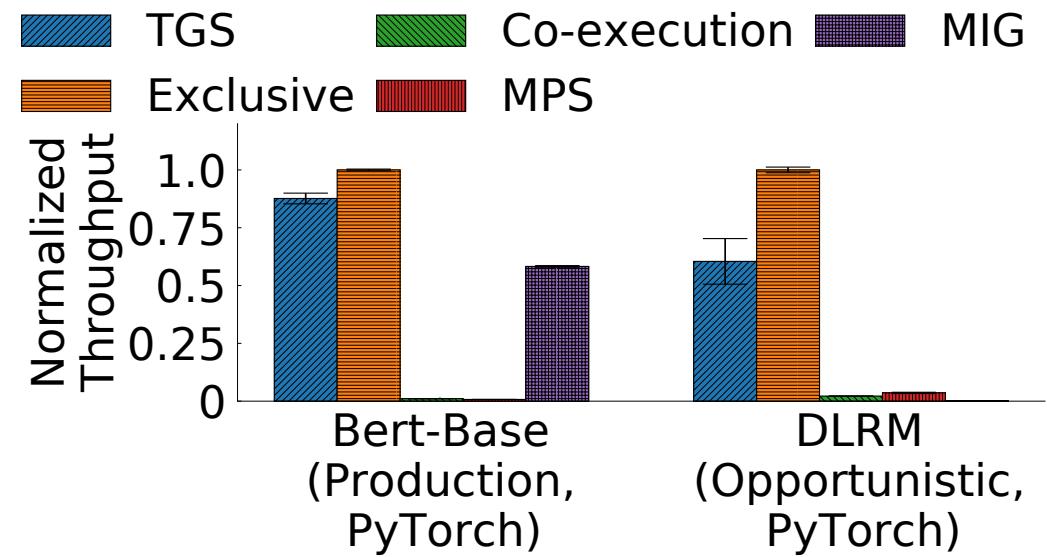
(b). High-contention scenario

# Transparent unified memory of TGS

- TGS protects production jobs under GPU memory oversubscription
- $15\times$  throughput improvement compared to MPS



(a). Low-contention scenario



(b). High-contention scenario

## More experiments in our paper

- System overhead
- Convergence of TGS in different scenarios
  - Convergence of the rate control under dynamic job arrival
  - Convergence of the rate control under dynamic resource usage
- Supporting different DL frameworks
- GPU sharing for large model training

# Conclusion

- TGS provides transparent GPU sharing to DL training in container clouds with four important properties:
  - Transparency
  - Performance isolation
  - High GPU utilization
  - Fault isolation
- TGS improves the throughput of the opportunistic job by up to 15× compared to the existing OS-layer solution MPS



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Thanks!