Introduction to Machine Learning Methods in Condensed Matter Physics

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Dimension reduction for unsupervised learning

Last class: PCA via eigenvalue problem (orthogonal transformation):

$$C = \frac{X^T X}{n-1} = \frac{\sum_{i=1}^n x_i x_j^T}{n-1}$$

It is often inefficient to sum over the large dataset for the covariance matrix.

PCA through singular value decomposition (SVD):

$$\mathbf{M} = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V^T}$$

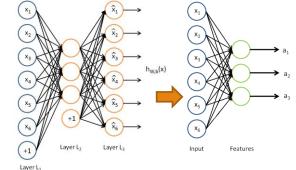
where both U and V are orthogonal and Σ is diagonal.

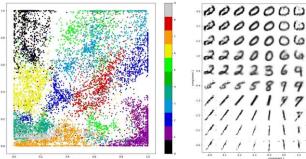
$$C = \frac{X^T X}{n-1} = \frac{V \Sigma^T U^T U \Sigma V^T}{n-1} = V \frac{\Sigma^2}{n-1} V^T$$

For nonlinear dimension reduction, we have the autoencoders:

$$a_i^{(2)} = f\left(\sum_{j=1}^{100} W_{ij}^{(1)} x_j + b_i^{(1)}
ight)$$

each hidden neuron at the bottleneck composes a dimension. MNIST data processed by autoencoders:





 $\lambda_i = \sigma_i^2/(n-1)$

PC-1

Self-taught learning

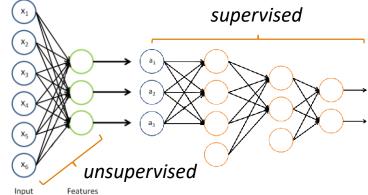
- "Sometimes it's not who has the best algorithm that wins; it's who has the most data."
- We may have a lot of unlabeled data, but only a smaller amount of (expensive) labeled data.

$$\{x_u^{(1)}, x_u^{(2)}, \dots, x_u^{(m_u)}\} \qquad \{(x_l^{(1)}, y^{(1)}), (x_l^{(2)}, y^{(2)}), \dots (x_l^{(m_l)}, y^{(m_l)})\}$$

- Combining unsupervised machine learning and supervised machine learning:
 - Step1. learn a good feature representation of the input from the (large set of) unlabeled data as a preprocessing
 - Step2. apply supervised learning on the this feature representation of the (small set of) labelled data for the classification task

$$\{(a_l^{(1)},y^{(1)}),(a_l^{(2)},y^{(2)}),\dots(a_l^{(m_l)},y^{(m_l)})\} \text{ or } \\ \{((x_l^{(1)},a_l^{(1)}),y^{(1)}),((x_l^{(2)},a_l^{(1)}),y^{(2)}),\dots,((x_l^{(m_l)},a_l^{(1)}),y^{(m_l)})\}$$

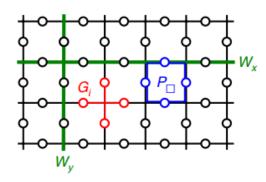
 Step3. an unified ANN: test data should subject to the same preprocessing



Unsupervised machine learning topological states

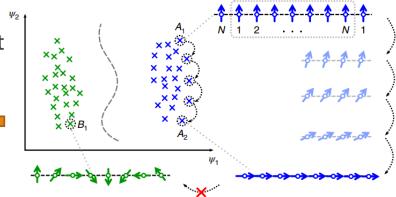
- Topological invariants: via dimension reduction and connectivity analysis:
 - Difference between A_1 and A_2 can be larger than B_1 and A_2
 - Global connectivity instead of local similarity is more important
- Indeed, a good separation without preexisting labels:
- Also applicable to 2D:

The four topological sectors of Z_2 theory: $\psi_1(\times \sqrt{m})$

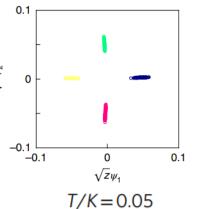


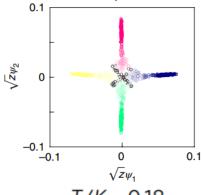
$$E[\{\sigma_b\}] = -K \sum_{\square} P_{\square}, \quad P_{\square} \equiv \prod_{b \in \square} \sigma_b$$

Joaquin F. Rodriguez-Nieva, Mathias S. Scheurer, Nature Physics **15**, 790–795 (2019).



1D chain of N classical XY spins





Sparse modeling

- Other unsupervised machine learning methods: t-SNE and K-means
- Unsupervised machine learning with increased dimensionality: sparse modeling, express data

$$\mathbf{x} = \sum_{i=1}^k a_i \phi_i$$

with an **over-complete** set of basis vectors ϕ_i (k > n) and a_i is sparse (mostly zeros).

Sparsity penalty functions: L_0 : $S(a_i) = \mathbf{1}(|a_i| > 0)$ L_1 : $S(a_i) = |a_i|$ $\log: S(a_i) = \log(1 + a_i^2)$

ullet Probabilistic interpretation: minimize the KL divergence: $\phi^* = rgmax_{\phi} E\left[\log(P(\mathbf{x}\mid\phi))
ight]$

$$D(P^{*}(\mathbf{x})||P(\mathbf{x}\mid\phi)) = \int P^{*}(\mathbf{x})\log\left(\frac{P^{*}(\mathbf{x})}{P(\mathbf{x}\mid\phi)}\right)d\mathbf{x}$$

$$P(\mathbf{x}\mid\mathbf{a},\phi) = \int P(\mathbf{x}\mid\mathbf{a},\phi)P(\mathbf{a})d\mathbf{a}$$

$$P(\mathbf{x}\mid\mathbf{a},\phi) = \frac{1}{Z}\exp\left(-\frac{(\mathbf{x}-\sum_{i=1}^{k}a_{i}\phi_{i})^{2}}{2\sigma^{2}}\right)P(a_{i}) = \frac{1}{Z}\exp(-\beta S(a_{i})) \Rightarrow = \sum_{j=1}^{m}\left\|\mathbf{x}^{(j)} - \sum_{i=1}^{k}a_{i}^{(j)}\phi_{i}\right\|^{2} + \lambda \sum_{i=1}^{k}S(a_{i}^{(j)})$$