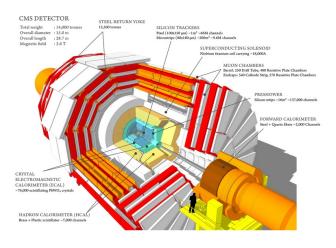
### Presentation draft

Konstantinos Papadimos

## The CMS Experiment overview

#### The CMS detector at the LHC



### Coordinates at the CMS

Given the solenoid geometry of the CMS detector, it is more convenient to use a spherical type of coordinates  $(r, \phi, \theta)$ .

$$p_{x} = P_{T} \cos \phi$$

$$p_{y} = P_{T} \sin \phi$$

$$p_{z} = P_{T} \sinh \eta$$

$$|\vec{P}| = P_{T} \cosh \eta$$
(1)

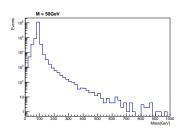
 $\phi \in [0, 2\pi]$  the azimuthal angle, and  $\eta \in [-\infty, +\infty]$  is defined as:

$$\eta \equiv -\ln\left[\tan\left(\frac{\theta}{2}\right)\right] \tag{2}$$

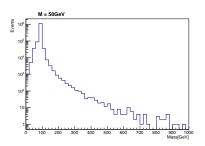
## Decays & Resonances

Not every particle can be detected by the CMS detector(i.e neutrinos)

Detectable Decay Products
 → Resonance



Non Detectable Decay
 Products → Not a resonance



## Calibration and energy scale uncertainties

- Calibration process adjusts energy scale and resolution to match well-known resonances (Z boson, J/psi meson) in data and simulation,
- Imperfect agreement due to subdetector complexities and nonlinear effects

## How do analysis techniques respond to energy scale uncertainties?

Our work will focus on the effects that energy scale uncertainties have, on a traditional fit-based analysis and a more modern Boosted Decision Tree-based analysis, using the generic diobject production process as the working example.

## Classification techniques

#### In our case:

- Signal: a resonant decay Y->xx
- Background: a non resonant process

### How to separate them?

- Boosted Decision Trees
- Fit based analysis

## Supervised Learning

### Supervised learning:

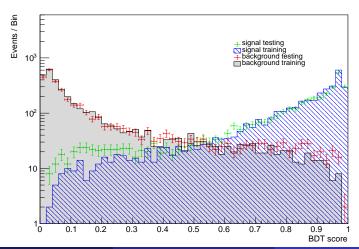
- The model is trained using training data
- The trained model is tested using testing data
- If we like the resulting model, we apply it!

#### but what is this model?

- A function that given the input feautres x, it returns the probability x beeing class A
- The goal of the training is to minimize the difference between the predicted output  $y_i \in [0,1]$  and the real output  $\hat{y_i} = 0$  class B, or  $\hat{y_i} = 1$  class A

### BDT 3: Signal from background separation

Where should we place the cut in order to accept most most of the signal while rejecting most of background?



### Statistical interpretation of results

### Are the signal events we counted, statistically significant?

We use the following metric:

Significance = 
$$\frac{Signal}{\sqrt{Background}}$$
 (3)

 The selected regions of interest both in BDT and Fit based analysis, are those that maximize the significance.

### Searches for $Y \rightarrow XX$

#### Search for heavy $Y \rightarrow XX$

 Mass range from 100GeV up to 300GeV

### Search for light $Y \rightarrow XX$

 Mass range from 50GeV up to 70GeV

### The $Y \rightarrow XX$ channel

The specific characteristics(mass etc.) of each dataset is different but the main idea is the same

- Use a non resonant process for background
- Use a resonant process for signal
- Separate signal from background
- Apply energy scale uncertainties to signal
- Separate again
- Compare the nominal case with the smeared cases

### The $Y \rightarrow XX$ channel: Background

Drell-Yan process

## The $Y \rightarrow XX$ channel: Signal

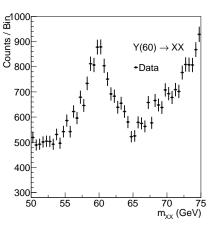


### Search for light $Y \rightarrow XX$

We will study the following smearing cases:

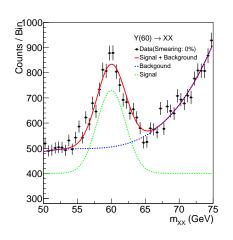
- 0%(Nominal case)
- 5%
- 7%
- 10%
- 12%

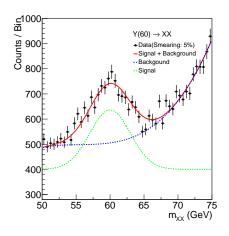
The working mass range is quite small -> smearing has a significant effect real quick



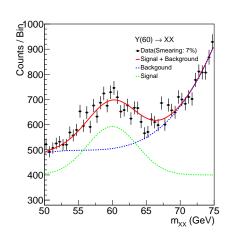
### Fit based approach: Fitting

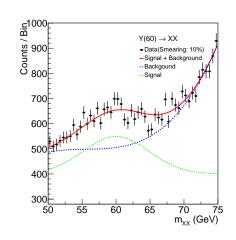
### Then we proceed with the fits!





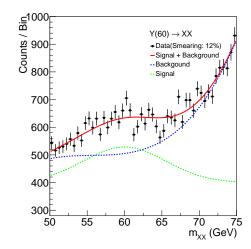
## Fit based approach: Fitting





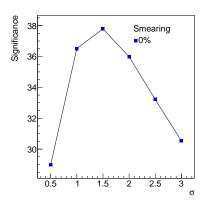
## Fit based approach: Fitting

Any further smearing will make the signal indistiguishable!



## Fit based approach: Signal from background separation

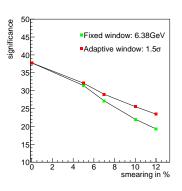
Working in the nominal case, we find the region that yields the best significance, by scanning the ranges  $m = \pm \frac{n}{2}\sigma$ , n = 1, 2, 3, 4, 5, 6



## Fit based approach: Signal from background separation

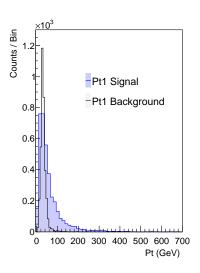
The region of interest that yields the best significance is the  $\pm 1.5\sigma$ . There are two ways to interpret this.

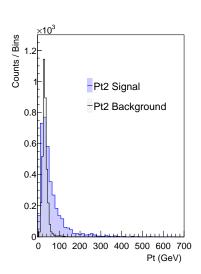
- interpret σ as the the spread of the nominal case -> fixed window
- interpret σ as the the spread of each cases -> adaptive window



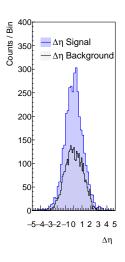
### BDT approach: Feature space

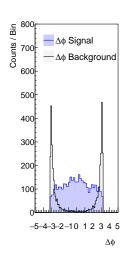
What features of the dataset are best for the classification task?

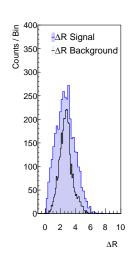




### BDT approach: Feature space

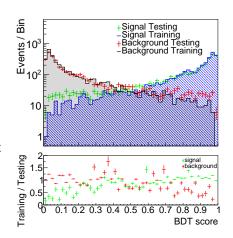






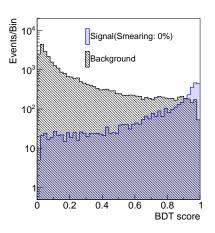
## BDT approach: The model

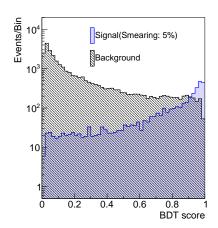
- Trained with approximately 3K events
- To examine overfitting we compare the ratio of training events to testing for each bdt score



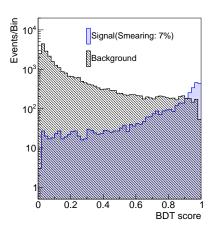
### BDT approach: Application

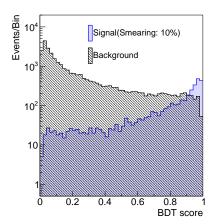
### Feed the application set to the BDT -> BDT plots



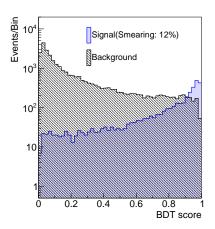


### BDT approach: Application





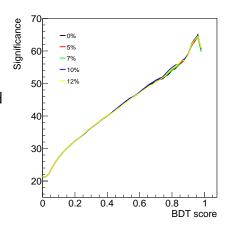
## BDT approach: Application



## BDT approach: Signal from background separation

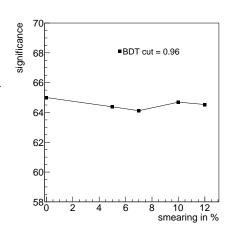
### Where should we place the cut?

- Same philosophy as in the fit based search
- We scan the bdt range to find the best region of interest
- Best cut -> BDT score = 0.96.



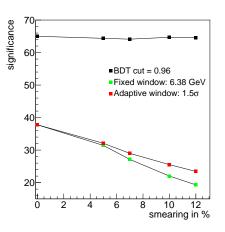
### BDT approach: Signal from background separation

 The performance of the BDT remains invariant under energy scale uncertainties!



### Synopsis

- BDT performs better than the fit based
- Remains invariant under smearing
- Performance of the fit drops



## Search for heavy $Y \rightarrow XX$

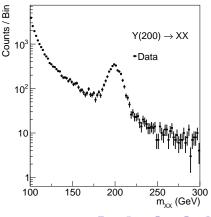
We will study the following smearing cases:

### Medium to extreme cases

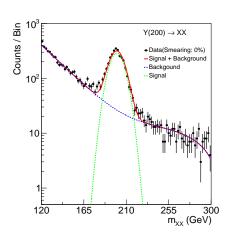
- 0%(Nominal case)
- 5%
- 10%
- 15%
- 20%

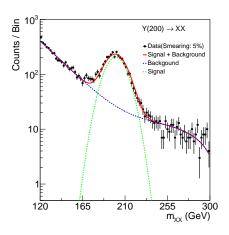
Plus some really extreme cases

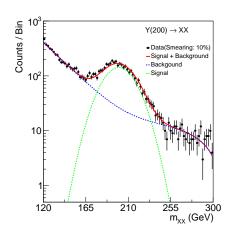
- 30%
- 40%
- 50%

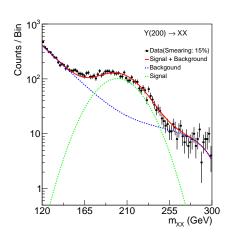


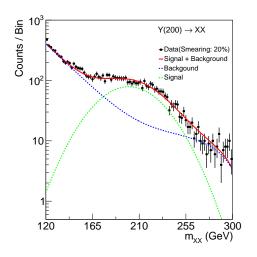
### Then we proceed and fit the signal

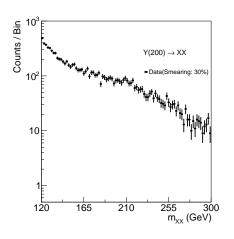


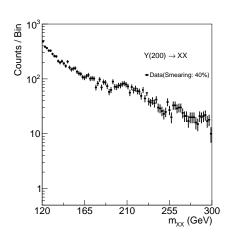


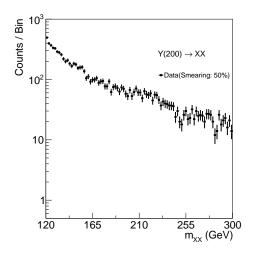






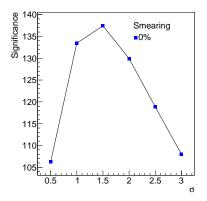






# Fit based approach: Signal from background separation

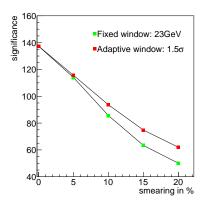
Working in the nominal case, we scan the ranges  $m=\pm \frac{n}{2}\sigma$ , n=1,2,3,4,5,6



# Fit based approach: Signal from background separation

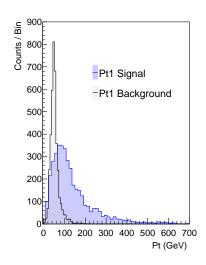
The best significance is in the  $\pm 1.5\sigma$  range.

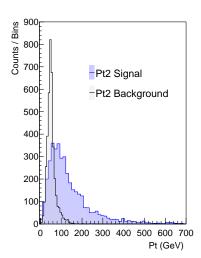
- fixed window
- adaptive window



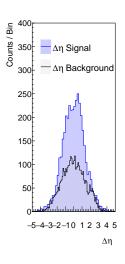
### BDT approach: Feature space

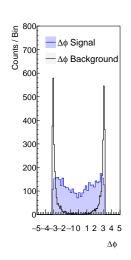
We use the same feature space as with the light mass search

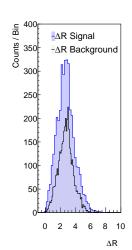




### BDT approach: Feature space

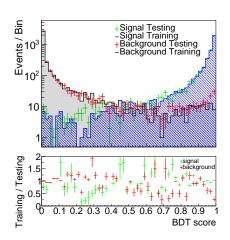




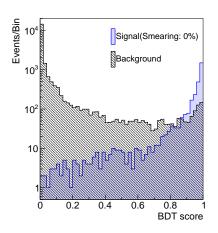


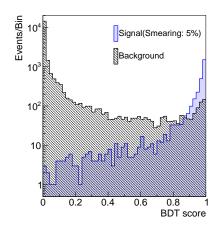
### BDT approach: The model

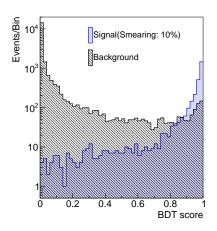
- Trained with approximately 3K events
- To examine overfitting we compare the ratio of training events to testing for each bdt score

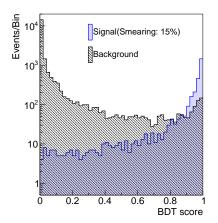


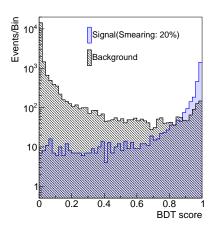
Feed the application set to the BDT -> BDT plots

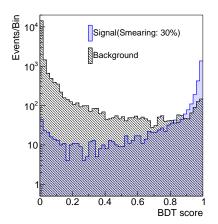


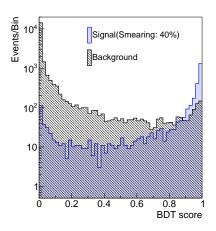


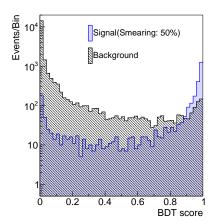








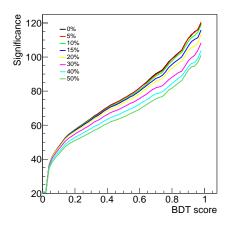




### BDT approach: Signal from background separation

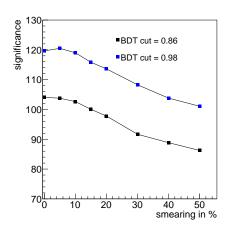
### Where should we place the cut?

- We scan the whole bdt range to find the best region of interest
- Best cut -> BDT score = 0.98.
- This is rather tight, lets see what happens if we place a more relaxed cut at 0.86



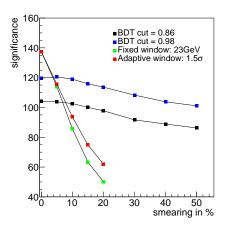
### BDT approach: Signal from background separation

- The performance of the more relaxed cut is not as good as the best cut
- The bdt model is rather robust



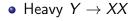
### Synopsis

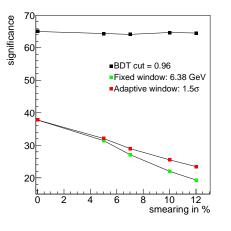
- The perfomance of the BDT and Fit are comparable when smeaing is mild
- Fit perfomance drops dramatically
- BDT is more robust

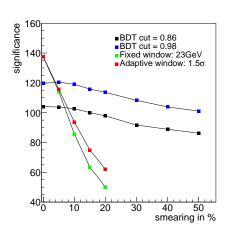


### Results

• Light  $Y \rightarrow XX$ 







### Results

Overall, the BDT is more robust as it learns features that do not get affected by energy scale uncertainties

#### So is the BDT better?

- No: A more carefull event selection can improve the performance of the fit based analysis
- yes: In the presence of energy scale uncertainties, the fit based analysis reaches a "breaking point"

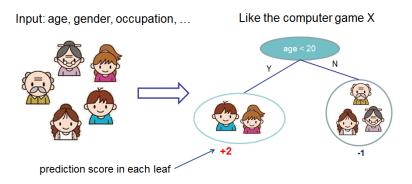
### Unused stuff

Welcome to the backup slides!

### BDT 1a: Boosted decision trees

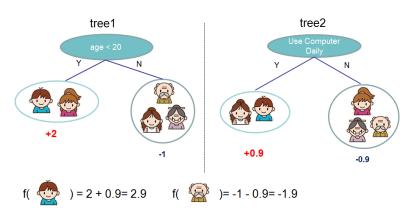
In this study the model of choice is Boosted Decision Trees(BDT).

• It classifies data using decision tree models

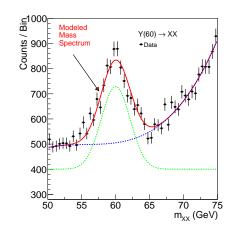


### BDT 2b: Boosted Decision Trees

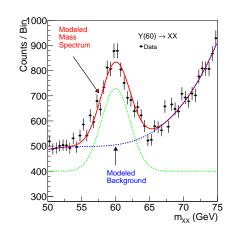
Usually only one tree is not power full enough -> Use more trees in additive manner(Boosting)



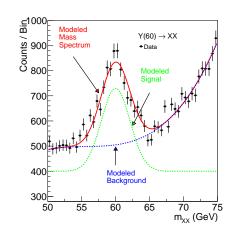
Fit the mass spectrum . . .



... and decompose it to a background component ...



### ... and a signal component



Then we can count the signal and background events, in a region of interest *I*:

$$O = \int_{I} observation(x) dx \tag{4}$$

$$B = \int_{I} bkg(x)dx \tag{5}$$

$$S = O - B \tag{6}$$

### Energy scale uncertainties

To smear the data by x%,

- iterate over every signal event
- multiply each  $P_T$  by a number sampled from a Gaussian distribution of  $\mu=1$  and  $\sigma=x/100$

### Search for light $Y \rightarrow XX$

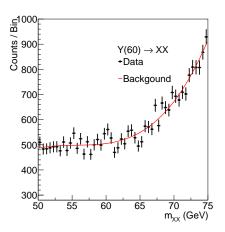
We will study the following smearing cases:

- 0%(Nominal case)
- 5%
- 7%
- 10%
- 12%

The working mass range is quite small -> smearing has a significant effect real quick

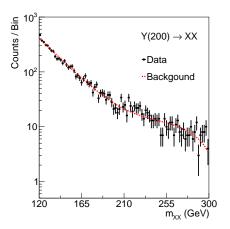
# Fit based approach: Background Fitting light

- To simplify things a bit, we fit the background sepratelly
- The background shape is kept constant throughout the fits
- Shape:  $\alpha + \beta x + \gamma x^2 + \delta x^3$



### Fit based approach: Background Fitting

- The background shape is kept constant
- Shape:  $\alpha + \beta x^{-1/2} + \gamma x^{-1} + \delta x^{3/2}$



# Search for heavy $Y \rightarrow XX$

We will study the following smearing cases:

Medium to extreme cases

- 0%(Nominal case)
- 5%
- 10%
- 15%
- 20%

Plus some really extreme cases

- 30%
- 40%
- 50%