

Maxwellove rovnice

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{B} = \mu_0 \left(\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

- zdroj
- rotace

$$\text{div } \vec{r} = \frac{\partial r_x}{\partial x} + \frac{\partial r_y}{\partial y} + \frac{\partial r_z}{\partial z}$$

$$\vec{r} = r(x, y, z)$$

$$\vec{\nabla} = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z}$$

$$r = i r_x + j r_y + k r_z$$

$$i^2 = j^2 = k^2 = 1$$

$$i \cdot j = -j \cdot i = k$$

$$j \cdot k = -k \cdot j = i$$

$$k \cdot i = -i \cdot k = j$$

$$i \cdot i = j \cdot j = k \cdot k = 0$$

$$i \cdot k = -k \cdot i = -j$$

$$j \cdot i = -i \cdot j = -k$$

$$k \cdot j = -j \cdot k = -i$$

$$i \cdot j \cdot k = 1$$

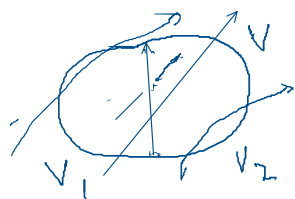
$$j \cdot k \cdot i = 1$$

$$k \cdot i \cdot j = 1$$



$$\Phi = \oint_{\partial V} \vec{r} \cdot d\vec{A} = \oint_{\partial V} \vec{r} \cdot \vec{n} \cdot dA$$

$$\text{div } \vec{r} = \lim_{V \rightarrow 0} \frac{\Phi(V)}{V}$$



$$\Phi(V)$$

$$\Phi(V_1) + \Phi(V_2) = \Phi(V)$$

$$\sum \Phi(V_i) = \Phi$$

$$V_1 + V_2 + \dots = V$$

$$\int d\Phi = \Phi$$

$$\int \underbrace{\frac{d\Phi}{dV}}_{\text{div } \vec{r}} dV = \Phi$$




$$\int_V \text{div } \vec{r} \, dV = \oint_{\partial V} \vec{r} \cdot d\vec{A}$$


$$\text{div } E \rightarrow \frac{\rho}{\epsilon}$$

$$\int \text{div } E \, dV = \frac{1}{\epsilon} \underbrace{\int \rho \, dV}_{Q(V)}$$

$$\oint_{\partial V} E \, d\vec{A} = \frac{Q}{\epsilon}$$



$$\oint_C \vec{E} \cdot d\vec{A} = \int_C \vec{E} \cdot \vec{u} \, dl$$



$$\oint_C d\vec{C} = \oint_C \underbrace{\frac{d\vec{C}}{dA}}_{\text{rot } \vec{v}} dA$$

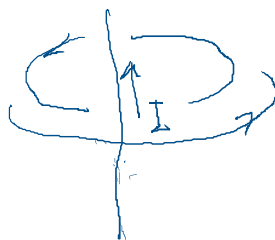
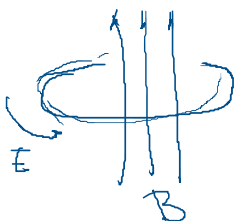
$\sum C_i = C$

$$\text{rot } \vec{v} = \lim_{A \rightarrow 0} \frac{C(A)}{A}$$

$$\text{rot } \vec{v} = \vec{\nabla} \cdot \vec{v} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix} =$$

$$= i \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) - j \left(\frac{\partial v_z}{\partial x} - \frac{\partial v_x}{\partial z} \right) + k \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

$$\oint_A \text{rot } \vec{v} \, dA = \oint_{\partial A} \vec{v} \cdot d\vec{C}$$

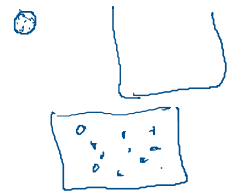


Termodynamika

Teplota

kontakt
žiarenie
veľký počet d.f.
spontánny proces

$$T_1 = T^* = T_2$$



Praca

znena det. parameter



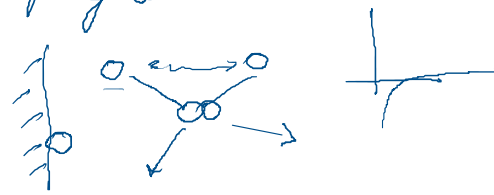
V, p, B, \dots
malý počet d.f.
kontrolovaný proces

Teplota

mera horivosti telesa



Príklad pre tlak ideálneho plynu
(Chceme skontrolovať rovnice IP)



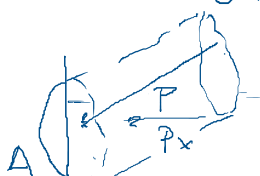
Príkladný odraz od steny

Tlak plynu = $\frac{\text{сила}}{\text{площадь стерж.}}$ $\Rightarrow \Delta p = -2p_x$

$$\ddot{a} = \frac{F}{mV} \quad F = m\ddot{a} = m \frac{dv}{dt} = \frac{dp}{dt}$$

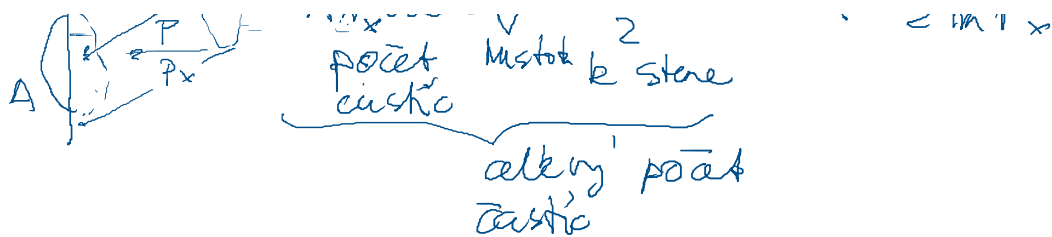
$m \cdot v = p$

$$= \frac{dp}{dt \cdot A} \quad \text{tok hybnosti}$$



$A \cdot \frac{N}{V} \cdot \frac{1}{2}$
počet častíc k stene

$$2 m v_x$$



$$P = \frac{1}{A dt} \left(A v_x dt \cdot \frac{N}{V} \cdot \frac{1}{2} \cdot 2 m v_x \right)$$

$$= 2 \frac{N}{V} \underbrace{\frac{1}{2} m v_x^2} = \frac{2}{3} \frac{N}{V} \left\langle \frac{1}{2} m v^2 \right\rangle$$

$$\left\langle \frac{1}{2} m v^2 \right\rangle = \left\langle \frac{1}{2} m v_x^2 \right\rangle + \left\langle \frac{1}{2} m v_y^2 \right\rangle + \left\langle \frac{1}{2} m v_z^2 \right\rangle$$

$$\left\langle \frac{1}{2} m v_x^2 \right\rangle = \frac{1}{3} \left\langle \frac{1}{2} m v^2 \right\rangle$$

$$\left\langle \frac{1}{2} m v^2 \right\rangle = d.f. \cdot \frac{1}{2} k_B T$$

o
omno

$$P = \frac{N}{V} k_B T$$

$$k_B = 1.381 \cdot 10^{-23} \text{ J/K}$$

$$N = n N_A$$

$$P = \underbrace{\left(\frac{N}{V} \right)}_C \underbrace{N_A k_B T}_R = CRT$$

Nabudúce at 18°.